# INTRODUCTORY APPLIED MACHINE LEARNING

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#### Today:

- Linear discriminant analysis
- General discriminant analysis

### **Outline**

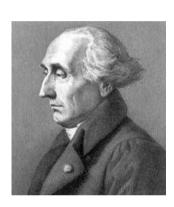
- Goal of the lecture
- Math review Lagrange multiplier
- Linear discriminant analysis
- General discriminant analysis

### Goals

- After this, you should be able to:
  - Understand basic principals of discriminant analysis
  - Perform discriminant analysis
  - Be able to determine what type of discriminant analysis to be carried out

# History of Lagrange Multiplier

Named after Joseph Louis Lagrange



- A strategy for finding the maxima/minima of a function subject to constraints
- Provides a <u>necessary condition</u> for optimality in constrained problems

# Lagrange Multiplier

Consider an optimization problem

Minimize f(x, y)

subject to g(x, y) = c

Lagrangian:

$$L(x, y, \lambda) = f(x, y) - \lambda(g(x, y) - c),$$

where  $\lambda \in \Re$  is the Lagrange multiplier

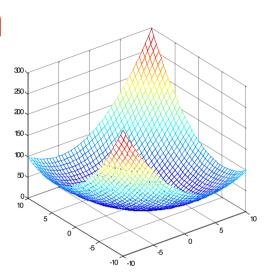
• Let  $(x^*, y^*)$  be a local minimizer of  $f(\cdot)$  subject to  $g(\cdot)$ , then there exists  $\lambda$  such that the partial derivatives of  $L(x, y, \lambda)$  are zero

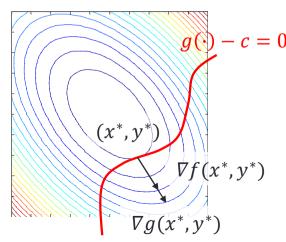
# Geometric Explanation

Example function:

$$f(x,y) = x^2 + xy + y^2$$

- The value of  $f(\cdot)$  can vary while moving along the contour line for  $g(\cdot) = c$
- Only when the contour line for  $g(\cdot) = c$  meets contour lines of  $f(\cdot)$  tangentially, the value of  $f(\cdot)$  does not increase or decrease
- Hence a local minimum or maximum





# Geometric Explanation Matlab Code

```
% plot quadratic function and contour lines
[x, y] = meshgrid(-10:.5:10,-10:.5:10);
z = x.^2 + x.*y + y.^2; % x^2 + x*y + y^2
mesh(x, y, z);
xlim([-10 10]); ylim([-10 10]);
xlabel('x_1'); ylabel('x_2'); zlabel('f(x_1,x_2)');
set(gcf, 'Color', 'w')

figure;
[C,h] = contour(x, y, z, 20); set(gcf, 'Color', 'w')
xlim([-10 10]); ylim([-10 10]); xlabel('x_1');
ylabel('x_2');
```

# Lagrange Multiplier (Cont'd)

• At the local minimum or maximum( $x^*, y^*$ ),

$$\nabla f(x^*, y^*) = \lambda \nabla g(x^*, y^*)$$

 To incorporate these conditions into one equation, we introduce an auxiliary function

$$L(x, y, \lambda) = f(x, y) - \lambda(g(x, y) - c),$$

and solve

$$\nabla L(x,y,\lambda) = \mathbf{0}$$

# Example

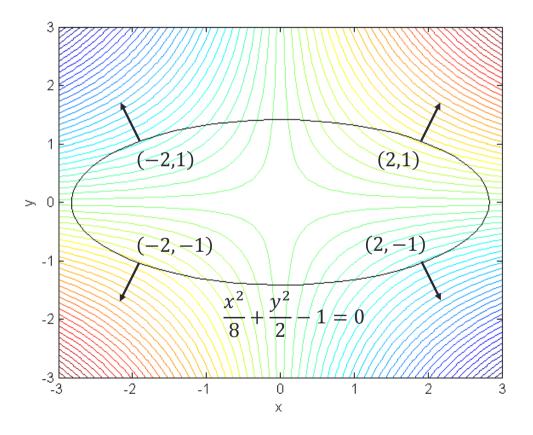
• Function f(x, y) = xy

subject to 
$$g(x, y) = \frac{x^2}{8} + \frac{y^2}{2} - 1$$

• Lagrangian:  $L(x, y, \lambda) = xy - \lambda \left(\frac{x^2}{8} + \frac{y^2}{2} - 1\right)$ 

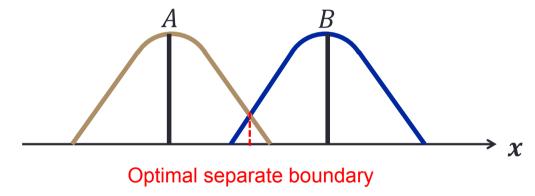
• Gradient of Lagrangian:  $\nabla L(x, y, \lambda) = \begin{pmatrix} y - \frac{\lambda x}{4} \\ x - \lambda y \\ \frac{x^2}{8} + \frac{y^2}{2} - 1 \end{pmatrix} = \mathbf{0}$ 

# Geometric Explanation of the Example



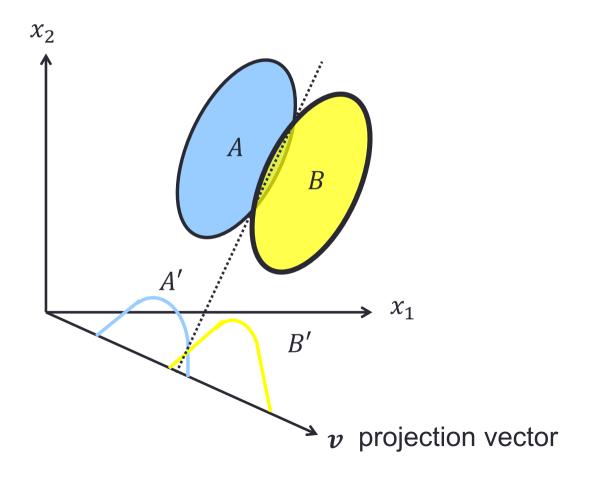
# Discriminant Analysis

- The objective is to identify boundaries between groups of objects, i.e., classification
- Example: univariate discriminant analysis:



- Usually applied on high-dimensional data
- Perform dimensionality reduction while preserving as much of the class discriminatory information as possible

### Illustration of Two-group Discriminant Analysis



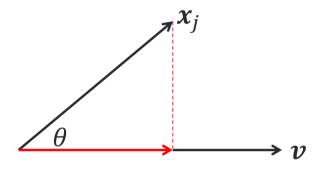
# Linear Discriminant Analysis (LDA)

- Originally developed in 1936 by R. A. Fisher
- Split the total scatter into <u>within-classes</u> scatter as well as the <u>between-classes</u> scatter (brought from the idea of ANOVA)
- In LDA, the objective is to find a projection vector v such that:



- The distance of projections of class means is the largest
- The distance between projections of samples in every class and the projection of corresponding class mean is the smallest

# Recall: Vector Projection



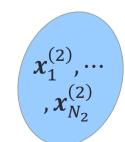
$$(\|x_j\|\cos\theta)\frac{v}{\|v\|} = \|x_j\|\frac{x_j^{\mathrm{T}}v}{\|x_i\|\|v\|}\frac{v}{\|v\|} = \frac{x_j^{\mathrm{T}}v}{\|v\|^2}v$$

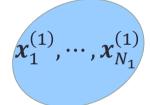
If 
$$||v|| = 1$$
, then  $(||x_j|| \cos \theta) \frac{v}{||v||} = (x_j^T v) v$ 

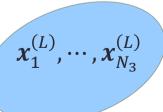
### **Notations**

- $x_j^{(i)} \in \mathbb{R}^d$ : the *j*th sample in class *i*, where  $j = 1 \dots N_i$  and  $i = 1 \dots L$
- N<sub>i</sub>: number of samples in class i
- L: number of classes
- N: number of all samples, i.e.,  $N = \sum_i N_i$
- $m_i \in \mathbb{R}^d$ : the mean of class i, i.e.,

$$\boldsymbol{m}_i = \frac{1}{N_i} \sum_{i=1}^{N_i} \boldsymbol{x}_j^{(i)}$$



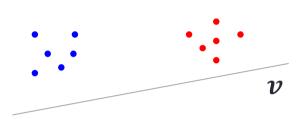




# Objective and Strategy

### Objective:

Find a vector v such that the projected distance of the data points between different classes on v are maximized



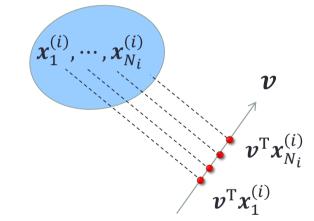
### Strategy:

- 1. Define the <u>between-class</u> scatter matrix  $S_b^{LDA} \in \Re^{d \times d}$  and within-class scatter matrix  $S_w^{LDA} \in \Re^{d \times d}$
- Find v with which the <u>between-class</u> variance  $v^{T}S_{b}^{LDA}v$  is maximized while the <u>within-class</u> variance  $v^{T}S_{w}^{LDA}v$  is minimized

# Mean of Projected Data Points

• For a given fector  $v \in \mathbb{R}^d$ , the projections of all the points  $x_j^{(i)}$  onto it are

$$v^{\mathrm{T}}x_{1}^{(1)}, \cdots, v^{\mathrm{T}}x_{N_{1}}^{(1)}, \dots, v^{\mathrm{T}}x_{N_{2}}^{(1)}, \dots, v^{\mathrm{T}}x_{N_{2}}^{(2)}, \dots$$
 $v^{\mathrm{T}}x_{1}^{(L)}, \cdots, v^{\mathrm{T}}x_{N_{I}}^{(L)}, \dots$ 



The mean of the projected data points of class i is

$$\overline{m}_i = \frac{1}{N_i} \sum_{i=1}^{N_i} \boldsymbol{v}^{\mathrm{T}} \boldsymbol{x}_j^{(i)} = \boldsymbol{v}^{\mathrm{T}} (\frac{1}{N_i} \sum_{i=1}^{N_i} \boldsymbol{x}_j^{(i)}) = \boldsymbol{v}^{\mathrm{T}} \boldsymbol{m}_i$$

 $m_1$ 

 $m_3$ 

 $m_1$ 

 $\overline{m}_3$ 

 $\overline{m}_2$ 

### Between-class Scatter

 Define the projected <u>sum of squared</u> between-class variance:

$$\sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_i}{N} \frac{N_j}{N} (\overline{m}_i - \overline{m}_j)^2 \in \Re$$

$$= \sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_i}{N} \frac{N_j}{N} (\overline{m}_i - \overline{m}_j) (\overline{m}_i - \overline{m}_j)^{\mathrm{T}}$$

$$= \sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_i}{N} \frac{N_j}{N} (\boldsymbol{v}^{\mathrm{T}} \boldsymbol{m}_i - \boldsymbol{v}^{\mathrm{T}} \boldsymbol{m}_j) (\boldsymbol{v}^{\mathrm{T}} \boldsymbol{m}_i - \boldsymbol{v}^{\mathrm{T}} \boldsymbol{m}_j)^{\mathrm{T}}$$

### Between-class Scatter

$$= \sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_i}{N} \frac{N_j}{N} v^{\mathrm{T}} (\boldsymbol{m}_i - \boldsymbol{m}_j) (\boldsymbol{m}_i - \boldsymbol{m}_j)^{\mathrm{T}} v$$

$$= v^{\mathrm{T}} \left( \sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_i}{N} \frac{N_j}{N} (\boldsymbol{m}_i - \boldsymbol{m}_j) (\boldsymbol{m}_i - \boldsymbol{m}_j)^{\mathrm{T}} \right) v$$

$$= v^{\mathrm{T}} S_b^{LDA} v \in \Re$$

- Define  $\mathbf{S}_b^{LDA} \in \mathbb{R}^{d \times d}$  as between-class scatter matrix, which is independent of  $\mathbf{v}$
- $S_b^{LDA}$  is a <u>symmetric positive-definite</u> matrix and is of rank d-1 or less

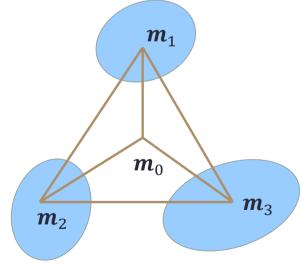
# Geometric Interpretation of $S_b^{LDA}$

The between-class scatter matrix:

$$S_b^{LDA} = \sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_i}{N} \frac{N_j}{N} (\boldsymbol{m}_i - \boldsymbol{m}_j) (\boldsymbol{m}_i - \boldsymbol{m}_j)^{\mathrm{T}}$$

$$= \sum_{i=1}^{L} \frac{N_i}{N} (\boldsymbol{m}_i - \boldsymbol{m}_0) (\boldsymbol{m}_i - \boldsymbol{m}_0)^{\mathrm{T}}$$

• Define 
$$m_0 \equiv \sum_{i=1}^L \frac{N_i}{N} m_i$$



# Between-class Scatter Matrix $S_b^{LDA}$

$$S_{b}^{LDA} = \sum_{i=1}^{L-1} \sum_{j=i+1}^{L} \frac{N_{i}}{N} \frac{N_{j}}{N} (m_{i} - m_{j}) (m_{i} - m_{j})^{T}$$

$$= \frac{1}{2} \sum_{i=1}^{L} \sum_{j=1}^{L} \frac{N_{i}}{N} \frac{N_{j}}{N} (m_{i} - m_{j}) (m_{i} - m_{j})^{T}$$

$$= \frac{1}{2} \sum_{i=1}^{L} \sum_{j=1}^{L} \frac{N_{i}}{N} \frac{N_{j}}{N} (m_{i} m_{i}^{T} - m_{i} m_{j}^{T} - m_{j} m_{i}^{T} + m_{j} m_{j}^{T})$$

$$= \frac{1}{2} \left( \sum_{i=1}^{L} \sum_{j=1}^{L} \frac{N_{i}}{N} \frac{N_{j}}{N} m_{i} m_{i}^{T} - \sum_{i=1}^{L} \sum_{j=1}^{L} \frac{N_{i}}{N} \frac{N_{j}}{N} m_{i} m_{j}^{T} \right)$$

# Between-class Scatter Matrix $S_b^{LDA}$ (Cont'd)

$$S_b^{LDA} = \frac{1}{2} \left( \sum_{j=1}^{L} \frac{N_j}{N} \sum_{i=1}^{L} \frac{N_i}{N} \boldsymbol{m}_i \boldsymbol{m}_i^{\mathrm{T}} - \sum_{i=1}^{L} \frac{N_i}{N} \boldsymbol{m}_i \sum_{j=1}^{L} \frac{N_j}{N} \boldsymbol{m}_j^{\mathrm{T}} \right)$$

$$-\sum_{j=1}^{L} \frac{N_j}{N} \boldsymbol{m}_j \sum_{i=1}^{L} \frac{N_i}{N} \boldsymbol{m}_i^{\mathrm{T}} + \sum_{i=1}^{L} \frac{N_i}{N} \sum_{j=1}^{L} \frac{N_j}{N} \boldsymbol{m}_j \boldsymbol{m}_j^{\mathrm{T}} \right)$$

• Define 
$$m_0 \equiv \sum_{i=1}^L \frac{N_i}{N} m_i$$

# Between-class Scatter Matrix $S_b^{LDA}$ (Cont'd)

$$S_{b}^{LDA} = \frac{1}{2} \left( \sum_{i=1}^{L} \frac{N_{i}}{N} \boldsymbol{m}_{i} \boldsymbol{m}_{i}^{T} - \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T} - \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T} + \sum_{j=1}^{L} \frac{N_{j}}{N} \boldsymbol{m}_{j} \boldsymbol{m}_{j}^{T} \right)$$

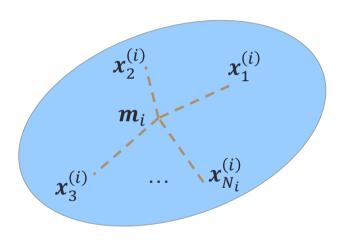
$$= \sum_{i=1}^{L} \frac{N_{i}}{N} \boldsymbol{m}_{i} \boldsymbol{m}_{i}^{T} - \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T} - \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T} + \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T}$$

$$= \sum_{i=1}^{L} \frac{N_{i}}{N} \boldsymbol{m}_{i} \boldsymbol{m}_{i}^{T} - \sum_{i=1}^{L} \frac{N_{i}}{N} \boldsymbol{m}_{i} \boldsymbol{m}_{0}^{T} - \boldsymbol{m}_{0} \left( \sum_{i=1}^{L} \frac{N_{i}}{N} \boldsymbol{m}_{i} \right)^{T} + \sum_{i=1}^{L} \frac{N_{i}}{N} \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T}$$

$$= \sum_{i=1}^{L} \frac{N_{i}}{N} \left[ \boldsymbol{m}_{i} \boldsymbol{m}_{i}^{T} - \boldsymbol{m}_{i} \boldsymbol{m}_{0}^{T} - \boldsymbol{m}_{0} \boldsymbol{m}_{i}^{T} + \boldsymbol{m}_{0} \boldsymbol{m}_{0}^{T} \right]$$

$$= \sum_{i=1}^{L} \frac{N_{i}}{N} \left( \boldsymbol{m}_{i} - \boldsymbol{m}_{0} \right) (\boldsymbol{m}_{i} - \boldsymbol{m}_{0})^{T}$$

# Within-class Scatter Matrix $S_w^{LDA}$



# Within-class Scatter Matrix $S_w^{LDA}$

Define the projected sum of squared within-class variance:

$$\sum_{i=1}^{L} \sum_{j=1}^{N_i} \frac{1}{N_i} (v^{T} x_j^{(i)} - \overline{m}_i) (v^{T} x_j^{(i)} - \overline{m}_i)^{T} \in \Re$$

$$= \sum_{i=1}^{L} \sum_{j=1}^{N_i} \frac{1}{N_i} v^{T} (x_j^{(i)} - m_i) (x_j^{(i)} - m_i)^{T} v$$

$$= v^{T} \left( \sum_{i=1}^{L} \sum_{j=1}^{N_i} \frac{1}{N_i} (x_j^{(i)} - m_i) (x_j^{(i)} - m_i)^{T} \right) v = v^{T} S_w^{LDA} v$$

• Define  $S_w^{LDA} \in \Re^{d \times d}$  as within-class scatter matrix, which is symmetric positive-semidefinite

### **LDA Formulation**

• The optimal projection vector v can be found by the following equation:

$$v = \underset{v \in \mathbb{R}^d}{\operatorname{arg max}} \frac{v^{\mathrm{T}} S_b^{LDA} v}{v^{\mathrm{T}} S_w^{LDA} v} = \underset{v^{\mathrm{T}} S_w^{LDA} v = 1}{\operatorname{arg max}} v^{\mathrm{T}} S_b^{LDA} v$$

or equivalently in Lagrange form:

$$f(\boldsymbol{v}, \lambda) = \boldsymbol{v}^{\mathrm{T}} \boldsymbol{S}_{b}^{LDA} \boldsymbol{v} - \lambda (\boldsymbol{v}^{\mathrm{T}} \boldsymbol{S}_{w}^{LDA} \boldsymbol{v} - 1)$$

# Solving LDA Problem

Lagrangian:

$$\frac{\partial f}{\partial \boldsymbol{v}} = 2\boldsymbol{S}_b^{LDA} \boldsymbol{v} - 2\lambda \boldsymbol{S}_w^{LDA} \boldsymbol{v} = 0$$
$$\Rightarrow \boldsymbol{S}_b^{LDA} \boldsymbol{v} = \lambda \boldsymbol{S}_w^{LDA} \boldsymbol{v}$$

- This is a generalized eigenvalue problem
- Since  $\mathbf{S}_b^{LDA}$  is symmetric positive-definite, it can be written as

$$\boldsymbol{S}_b^{LDA} = (\boldsymbol{S}_b^{LDA})^{\frac{1}{2}} (\boldsymbol{S}_b^{LDA})^{\frac{1}{2}}$$

where  $(S_b^{LDA})^{\frac{1}{2}}$  is constructed from eigenvalue decomposition, i.e.,  $S_b^{LDA} = U\Lambda U^{\rm T}$  and  $(S_b^{LDA})^{\frac{1}{2}} = U\Lambda^{\frac{1}{2}}U^{\rm T}$ 

# Solving LDA Problem (Cont'd)

• Defining  $w = (S_b^{LDA})^{\frac{1}{2}}v$ , one get

$$(S_{w}^{LDA})^{-1} (S_{b}^{LDA})^{\frac{1}{2}} (S_{b}^{LDA})^{\frac{1}{2}} v = \lambda v$$

$$\Rightarrow (S_{b}^{LDA})^{\frac{1}{2}} (S_{w}^{LDA})^{-1} (S_{b}^{LDA})^{\frac{1}{2}} w = \lambda (S_{b}^{LDA})^{\frac{1}{2}} v$$

$$\Rightarrow (S_{b}^{LDA})^{\frac{1}{2}} (S_{w}^{LDA})^{-1} (S_{b}^{LDA})^{\frac{1}{2}} w = \lambda w (*)$$

which is a regular eigenvalue problem for a symmetric, positive definite matrix  $(S_b^{LDA})^{\frac{1}{2}}(S_w^{LDA})^{-1}(S_b^{LDA})^{\frac{1}{2}}$ 

• Find solution of w from (\*) and one can get v from this relationship:  $v = (S_b^{LDA})^{\frac{-1}{2}}w$ 

# Optimal Project Vector of Two-class LDA

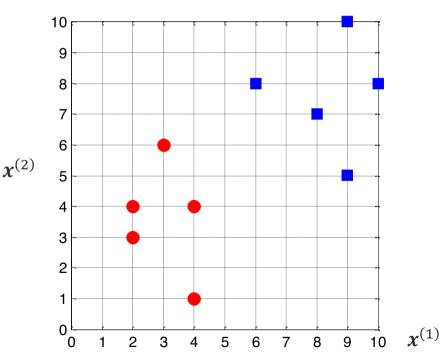
- Suppose there are only two classes, i.e., L=2
- ullet The optimal projection vector  $oldsymbol{v}$  is

$$v = (S_w^{LDA})^{-1}(m_1 - m_2)$$
 .....(@)

# Example

Compute the LDA projection for the following 2D dataset

$$\mathbf{x}^{(1)} = \{(4,1), (2,4), (2,3), (3,6), (4,4)\}$$
  
 $\mathbf{x}^{(2)} = \{(9,10), (6,8), (9,5), (8,7), (10,8)\}$ 



# **Example Solution**

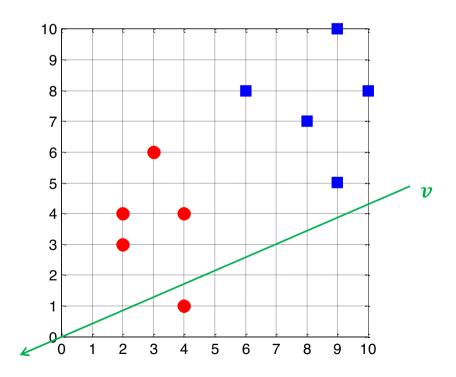
• The class means,  $S_h^{LDA}$ , and  $S_w^{LDA}$  are

$$m_1 = \begin{bmatrix} 3.0 \\ 3.6 \end{bmatrix}, \qquad m_2 = \begin{bmatrix} 8.4 \\ 7.6 \end{bmatrix}$$
 $S_b^{LDA} = \begin{bmatrix} 29.16 & 21.6 \\ 21.6 & 16.0 \end{bmatrix}, \qquad S_w^{LDA} = \begin{bmatrix} 2.64 & -.44 \\ -.44 & 5.28 \end{bmatrix}$ 

• Directly by (@), the optimal projection vector v is

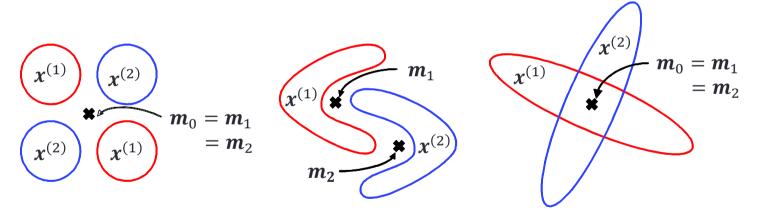
$$v = \begin{pmatrix} \begin{bmatrix} 2.64 & -.44 \\ -.44 & 5.28 \end{bmatrix} \end{pmatrix}^{-1} \begin{pmatrix} \begin{bmatrix} 3.0 \\ 3.6 \end{bmatrix} - \begin{bmatrix} 8.4 \\ 7.6 \end{bmatrix} \end{pmatrix} = \begin{bmatrix} -.91 \\ -.39 \end{bmatrix}$$

# The Optimal Projection Vector *v*



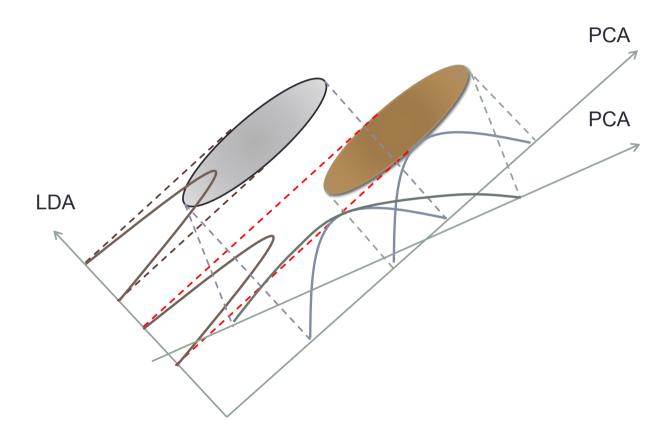
### Limitation of LDA

- LDA produces at most L-1 feature projections
- LDA is a parametric method (such that it assumes the data points are in Gaussian distribution)

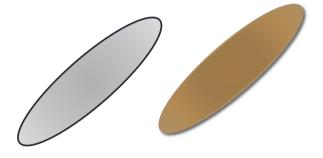


 LDA also fails if discriminatory information is not in the mean but in the variance of the data

### LDA vs. PCA



### LDA vs. PCA



# Generalized Discriminant Analysis (GDA)

- What if the separation of the data points with LDA is not good?
- One solution is to apply kernel methods to the LDA problem – called generalized discriminant analysis (GDA)
- Suppose kernel function  $\phi(\cdot)$ :  $\Re^d \ni x_j^{(i)} \to \phi(x_j^{(i)}) \in \Re^p$  is applied
- Perform LDA on  $\phi(x_i^{(i)})$  instead
- Remember, we only know  $<\phi\left(x_{j}^{(i)}\right)$  ,  $\phi\left(x_{j}^{(i)}\right)>$  , not  $\phi(x_{j}^{(i)})$

### **Notations**

- L: number of classes
- N<sub>i</sub>: number of samples in class i
- N: number of all samples, i.e.,  $N = \sum_i N_i$
- $\phi(x_i^{(i)}) \in \Re^p$ : the jth sample in class i
- $\cdot \mathbf{X}_{i}^{\mathrm{T}} = \left[\phi(\mathbf{x}_{1}^{(i)}), \dots, \phi(\mathbf{x}_{N_{i}}^{(i)})\right]$
- $\bullet X^{\mathrm{T}} = \begin{bmatrix} X_1^{\mathrm{T}}, \dots, X_L^{\mathrm{T}} \end{bmatrix}$

### Within- and Between- class Scatter Matrices

• Suppose that the samples in the  ${\mathcal H}$  space are centered, i.e.,

$$m_0 = 0$$

The within-class scatter matrix:

$$S_w^{GDA} = \sum_{i=1}^{L} \sum_{j=1}^{N_i} \frac{1}{N} \phi(x_j^{(i)}) \phi(x_j^{(i)})^{\mathrm{T}}$$

The between-class scatter matrix:

$$\boldsymbol{S}_b^{GDA} = \sum_{i=1}^L \frac{N_i}{N} (\boldsymbol{m}_i - \boldsymbol{m}_0) (\boldsymbol{m}_i - \boldsymbol{m}_0)^{\mathrm{T}} = \sum_{i=1}^L \frac{N_i}{N} \boldsymbol{m}_i \boldsymbol{m}_i^{\mathrm{T}}$$

### **Between-class Scatter Matrix**

From the definition

$$\boldsymbol{m}_{i} = \frac{1}{N_{i}} \sum_{j=1}^{N_{i}} \phi(\boldsymbol{x}_{j}^{(i)}) = \frac{1}{N_{i}} \left[ \phi(\boldsymbol{x}_{1}^{(i)}), \dots, \phi(\boldsymbol{x}_{N_{i}}^{(i)}) \right] \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}_{N_{i} \times 1}$$
$$= \frac{1}{N_{i}} \boldsymbol{X}_{i}^{\mathrm{T}} \boldsymbol{1}_{N_{i} \times 1}$$

And

$$\boldsymbol{m}_{i}\boldsymbol{m}_{i}^{T} = \frac{1}{N_{i}^{2}}\boldsymbol{X}_{i}^{T}\boldsymbol{1}_{N_{i}\times1}\boldsymbol{1}_{1\times N_{i}}\boldsymbol{X}_{i} = \frac{1}{N_{i}^{2}}\boldsymbol{X}_{i}^{T}\boldsymbol{1}_{N_{i}\times N_{i}}\boldsymbol{X}_{i} = \frac{1}{N_{i}}\boldsymbol{X}_{i}^{T}\boldsymbol{B}_{i}\boldsymbol{X}_{i}$$

where

$$\boldsymbol{B}_i = \frac{1}{N_i} \mathbf{1}_{N_i \times N_i}$$

# Between-class Scatter Matrix (Cont'd)

$$S_b^{GDA} = \sum_{i=1}^L \frac{N_i}{N} \boldsymbol{m}_i \boldsymbol{m}_i^{\mathrm{T}} = \frac{1}{N} \sum_{i=1}^L N_i \frac{1}{N_i} \boldsymbol{X}_i^{\mathrm{T}} \boldsymbol{B}_i \boldsymbol{X}_i = \frac{1}{N} \sum_{i=1}^L \boldsymbol{X}_i^{\mathrm{T}} \boldsymbol{B}_i \boldsymbol{X}_i$$

$$= \frac{1}{N} [\boldsymbol{X}_1^T, \dots, \boldsymbol{X}_L^T] \begin{bmatrix} \boldsymbol{B}_1 & 0 \\ 0 & \boldsymbol{B}_L \end{bmatrix} \begin{bmatrix} \boldsymbol{X}_1 \\ \vdots \\ \boldsymbol{X}_L \end{bmatrix} = \frac{1}{N} \boldsymbol{X}^{\mathrm{T}} \boldsymbol{B} \boldsymbol{X}$$

where 
$$\mathbf{B} = \begin{bmatrix} \mathbf{B}_1 & & 0 \\ & \ddots & \\ 0 & & \mathbf{B}_L \end{bmatrix}$$

### Within-class Scatter Matrix

$$S_{W}^{GDA} = \sum_{i=1}^{L} \sum_{j=1}^{N_{i}} \frac{1}{N} \phi(x_{j}^{(i)}) \phi(x_{j}^{(i)})^{T}$$

$$= \frac{1}{N} \sum_{i=1}^{L} \left[ \phi(x_{1}^{(i)}), \dots, \phi(x_{N_{i}}^{(i)}) \right] \begin{bmatrix} \phi(x_{1}^{(i)}) \\ \vdots \\ \phi(x_{N_{i}}^{(i)}) \end{bmatrix}$$

$$= \frac{1}{N} \sum_{i=1}^{L} X_{i}^{T} X_{i} = \frac{1}{N} [X_{1}^{T}, \dots, X_{L}^{T}] \begin{bmatrix} X_{1} \\ \vdots \\ X_{I} \end{bmatrix} = \frac{1}{N} X^{T} X$$

### **GDA** Formulation

 The optimal projection vector v can be found by the following equation:

$$S_b^{GDA}v = \lambda S_w^{GDA}v$$

i.e.,

$$(\frac{1}{N}X^{\mathrm{T}}BX)v = \lambda(\frac{1}{N}X^{\mathrm{T}}X)v$$

where we know  $X^{T}X$  but not X

# Solving GDA Problem

 Suppose that v is a linear combination of all training samples, i.e.,

$$v = \sum_{i=1}^{L} \sum_{j=1}^{N_i} \alpha_j^{(i)} \phi(x_j^{(i)}) = X^{\mathrm{T}} \alpha$$
 where  $\alpha =$ 

# Solving GDA Problem (Cont'd)

The GDA problem:

$$S_b^{GDA} v = \lambda S_w^{GDA} v$$
$$(\frac{1}{N} X^T B X) v = \lambda (\frac{1}{N} X^T X) v$$
$$X^T B X X^T \alpha = \lambda X^T X X^T \alpha$$
$$X X^T B X X^T \alpha = \lambda X X^T X X^T \alpha$$

• Let  $K = XX^{T}$ , the problem can be re-written as:

$$(KBK)\alpha = \lambda(KK)\alpha$$

• Note we only obtain  $\alpha$ , not  $\nu$  explicitly

### **GDA Classifier**

 To classify an unknown sample point x, the following formulation is applied:

$$v^{T}\phi(x) = (X^{T}\alpha)^{T}\phi(x) = \alpha^{T}X\phi(x)$$

$$= \alpha^{T} \begin{bmatrix} \phi\left(x_{1}^{(i)}\right)^{T} \\ \vdots \\ \phi\left(x_{N_{i}}^{(L)}\right)^{T} \end{bmatrix} \phi(x)$$

$$= \alpha^{T} \begin{bmatrix} <\phi\left(x_{1}^{(i)}\right), \phi(x) > \\ \vdots \\ <\phi\left(x_{N_{i}}^{(L)}\right), \phi(x) > \end{bmatrix}$$

$$= \alpha^{T} \begin{bmatrix} <\phi\left(x_{1}^{(i)}\right), \phi(x) > \\ \vdots \\ <\phi\left(x_{N_{i}}^{(L)}\right), \phi(x) > \end{bmatrix}$$

# Summary

- LDA and GDA reduce dimension of data while preserving as much of the class discriminatory information as possible
- Kernel methods are applied on problems that cannot be solved with LDA

### References

 G. McLachlan, Discriminant Analysis and Statistical Pattern Recognition