

HW#3 Adding an I/O Controller



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Homework Goal

- ❑ Add a text-LCD controller to the Aquila SoC, and provide a demo program that print to the LCD screen
- ❑ Two ways to design the controller:
 - A GPIO device (simple HW, complex SW)
 - A text-screen buffer device (complex HW, simple SW)
- ❑ Upload your report and **HW/SW code** to E3 by 11/30, 17:00.

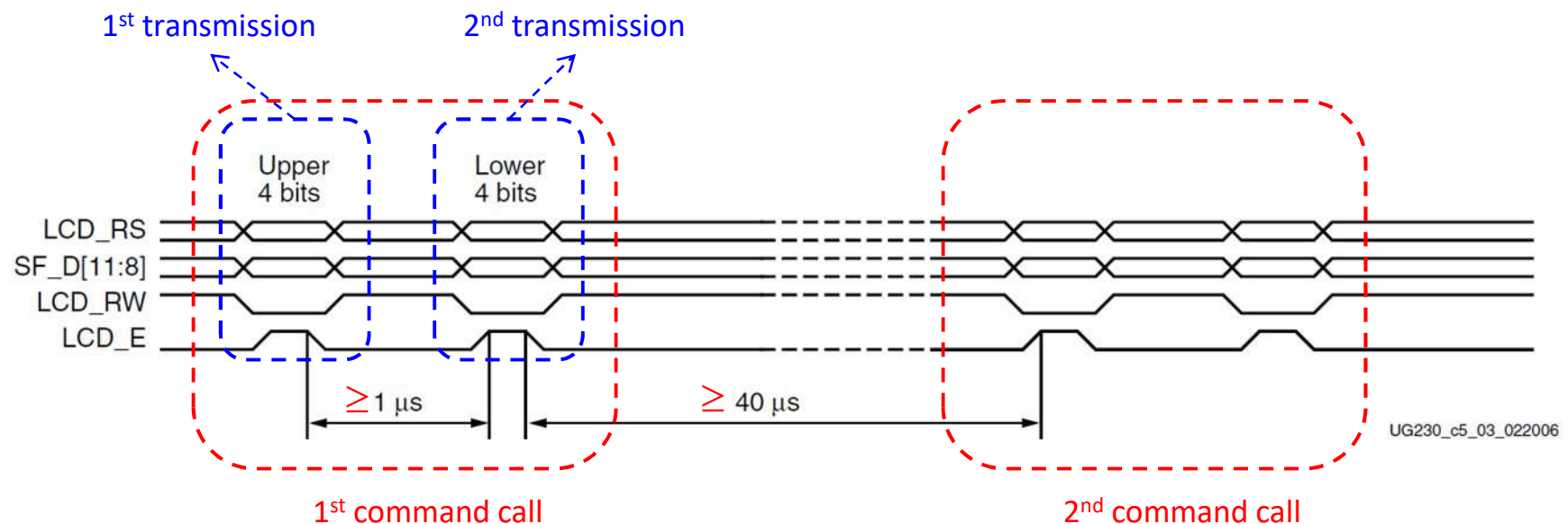
Review on 1602 LCD Device

- ❑ There is an 1602 LCD display on the Aquila platform
 - Displays two-lines of text, each has 16 characters.
 - Operating in 4-bit 1602 LCD mode
 - The LCD is driven by 3 control wires (LCD_E, LCD_RS, LCD_RW) and 4 data wires (DB4~DB7)



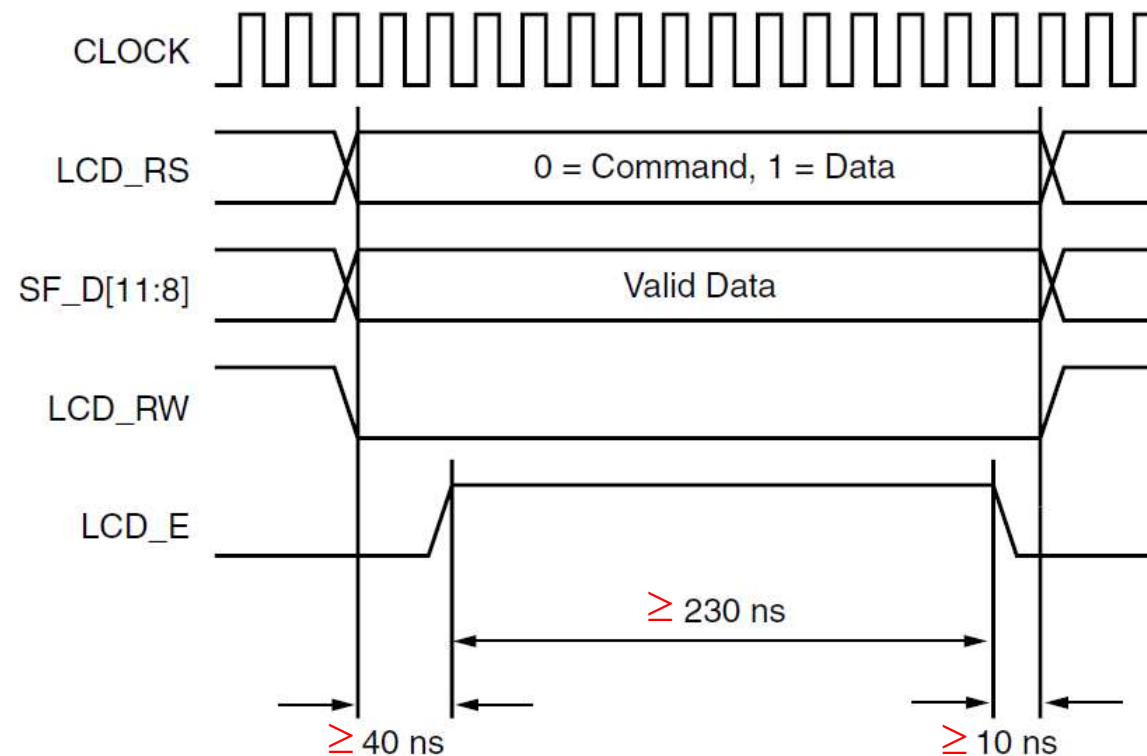
Character LCD Interface

- ❑ For the 4-bit operating mode:
 - Each command will need two transmissions, using only E, RS, RW, and DB4~DB7
 - For example, to write a ASCII to the current cursor position, you must set RS to 1, RW to 0, then sent 8-bit ASCII code in two transmissions



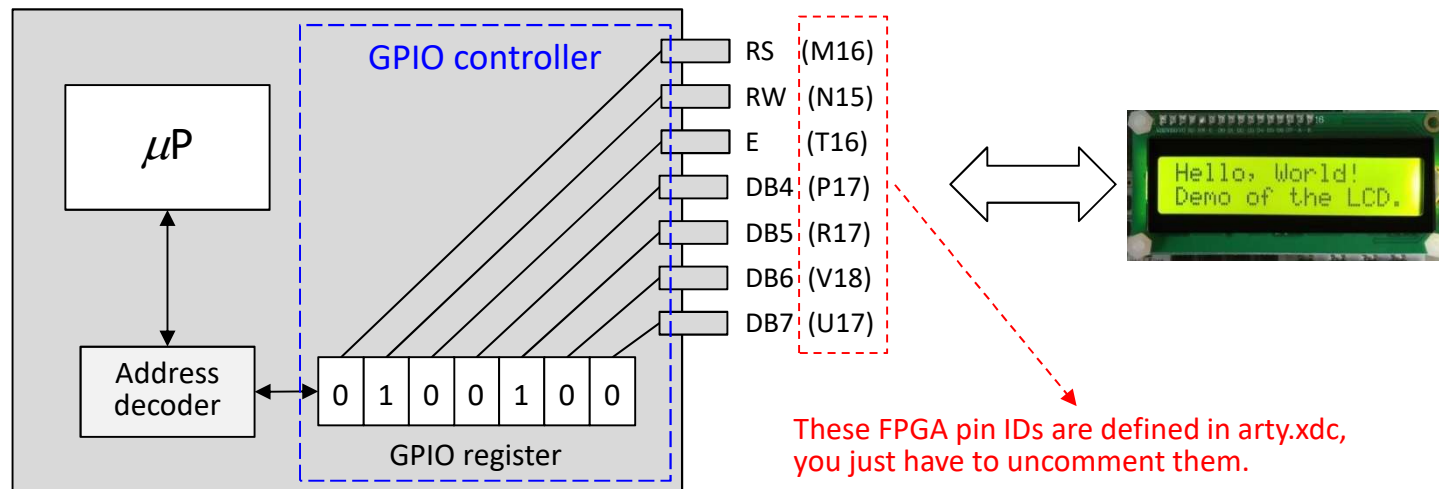
Timing Diagrams for Transmission

- The timing of one transmission in 4-bit mode:
 - Note that execution of a function requires two transmissions



Method #1: GPIO Controller

- ❑ A GPIO device allows a microprocessor to generate specific waveforms
 - The switching frequency is limited by the CPU clock rate
 - Fast enough for the 1602 LCD module
 - Typical GPIO ports (RS ~ DB7) are declared as `inout` ports. However, `output` declaration is good enough for us here.



These FPGA pin IDs are defined in `arty.xdc`, you just have to uncomment them.

Note that DB7 ~ DB4 are named `LCD_D[3:0]` in the constraint file.

μ P Interface for GPIO Register

- ❑ A design example would be the CLINT device

```
module clint
#( parameter TIMER = 100_000, parameter XLEN = 32 )
(
    input                clk_i,
    input                rst_i,

    input                en_i,
    input                we_i,
    input [2 : 0]        addr_i,
    input [XLEN-1 : 0]    data_i,
    output reg [XLEN-1 : 0] data_o,
    output reg           data_ready_o,

    output                tmr_irq_o,
    output                sft_irq_o
);

reg [XLEN-1 : 0] clint_mem[0: 4];
wire [63: 0] mtime = { clint_mem[1], clint_mem[0] };
wire [63: 0] mtimecmp = { clint_mem[3], clint_mem[2] };
wire [XLEN-1 : 0] msip = clint_mem[4];
```

```
always @(posedge clk_i) /* register write */
begin
    if (rst_i)
        begin
            clint_mem[0] <= 32'b0; clint_mem[1] <= 32'b0;
            clint_mem[2] <= 32'b0; clint_mem[3] <= 32'b0;
            clint_mem[4] <= 32'b0;
        end
    else if (we_i)
        clint_mem[addr_i] <= data_i;
        ...
end

always @(posedge clk_i) /* register read */
begin
    if (en_i)
        begin
            data_o <= clint_mem[addr_i];
            data_ready_o <= 1;
        end
    else
        data_ready_o <= 0;
end
```

Address Assignment

- ❑ We can assign an address to the register in the bus decoder logic (in `aquila_top.v`)

```
// ----- System Memory Map: DDRx DRAM, Devices, or CLINT -----  
// [0] 0x0000_0000 - 0x0FFF_FFFF : Tightly-Coupled Memory (TCM)  
// [1] 0x8000_0000 - 0xBFFF_FFFF : DDRx DRAM memory (cached)  
// [2] 0xC000_0000 - 0xCFFF_FFFF : device memory (uncached)  
// [3] 0xF000_0000 - 0xF000_0010 : CLINT I/O registers (uncached)  
//  
wire [3 : 0] code_segment, data_segment;  
  
assign data_segment = p_d_addr[XLEN-1:XLEN-4];  
  
assign data_sel = (data_segment == 4'h0)? 0 :  
                  (data_segment == 4'hC)? 2 :    // used by UART  
                  (data_segment == 4'hF)? 3 :    // used by CLINT  
                  1;
```

```
clint #( .TIMER(50_000) )  
CLINT(  
    .clk_i(clk_i),  
    .rst_i(rst_i),  
    .en_i(data_sel == 3),  
    .we_i(data_rw && (data_sel == 3)),  
    .addr_i({6'b0, p_d_addr[XLEN - 5 : 2]}),  
    .data_i(p_d_core2mem),  
    .data_o(data_from_clint),  
    .data_ready_o(clint_d_ready),  
  
    .tmr_irq_o(tmr_irq),  
    .sft_irq_o(sft_irq)  
);
```


LCD Control in SW

- ❑ For 1602 LCD I/O software using GPIO device, you can Google for the example of Arduino
 - For example, to send an ASCII code to the LCD:

```
void digitalWrite(int port, Xuint32 value)
{
    Xuint32 temp = gpio_read();
    temp &= (0xFFFFFFFF - port_mask[port]);
    temp |= value << port;
    gpio_write(temp);
}

void cputch(uint8_t code)
{
    digitalWrite(LCD_RS, 1);
    digitalWrite(LCD_RW, 0);

    write4bits(code>>4); // write upper nibble
    write4bits(code);    // write lower nibble
}
```

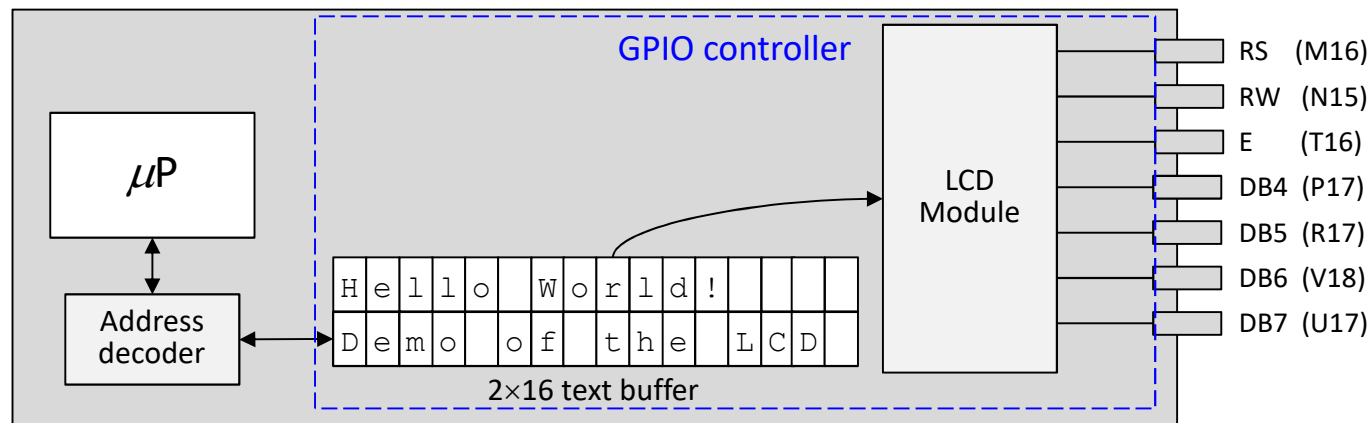
```
void write4bits(uint8_t value)
{
    digitalWrite(LCD_D4, (value >> 0) & 0x01);
    digitalWrite(LCD_D5, (value >> 1) & 0x01);
    digitalWrite(LCD_D6, (value >> 2) & 0x01);
    digitalWrite(LCD_D7, (value >> 3) & 0x01);

    // pulse enable
    digitalWrite(LCD_E, LOW);
    delayMicroseconds(1);
    digitalWrite(LCD_E, HIGH);
    delayMicroseconds(1); // enable pulse must be >450ns
    digitalWrite(LCD_E, LOW);
    delayMicroseconds(100); // commands need > 37us to settle
}
```

The delay function can be implemented using the clock() function.

Method #2: Text Screen Buffer Device

- ❑ Another way to implement the LCD controller is to design a frame buffer device
 - The control signals are generated by the HW controller
 - A text buffer array can be accessed by the CPU (like a memory device) to provide the content of the screen
 - The HW controller scans the text buffer a few times a second to update the LCD screen



The LCD Module

- ❑ The LCD module is a bit tricky to implement, but you can reuse the one you got in D-Lab (available on E3):

```
module LCD_module(  
    input clk,  
    input reset,  
    input [127:0] row_A,  
    input [127:0] row_B,  
    output reg LCD_E,  
    output reg LCD_RS,  
    output reg LCD_RW,  
    output reg [3:0] LCD_D);  
    );
```

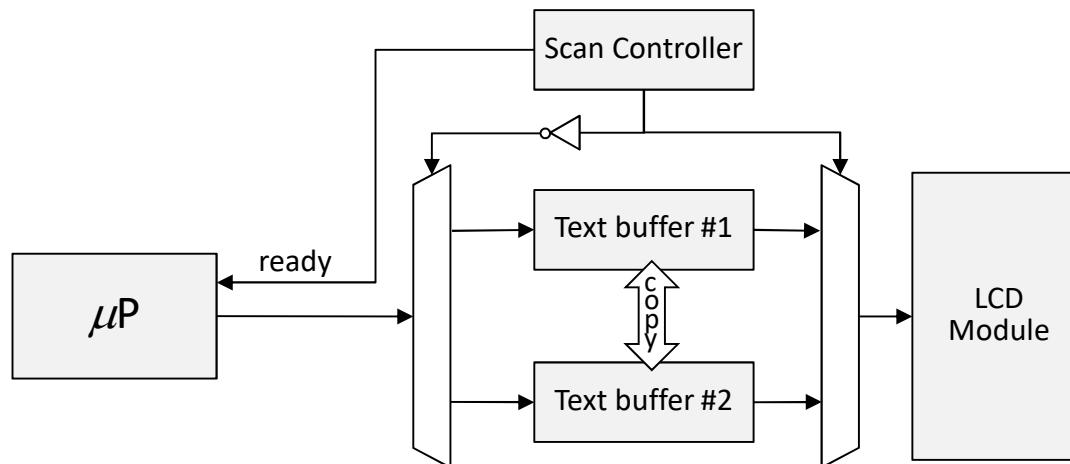
top-row of text

bottom-row of text

- ❑ What you need to do for Method #2:
 - Create a text buffer, wire it to row_A & row_B
 - Create an interface for the μ P to write the text buffer

LCD Flickering Issue (Optional)

- ❑ Note that the LCD device is a slow device that can only be updated 5 ~ 6 times a second
- ❑ If μP write to the text buffer while the LCD is scanning & updating the screen, flicker may happen
 - You can use a pair of text buffers to resolve this issue
 - When the scan controller swap the buffer, it has to copy the buffers and pause the μP 's write operation



Your Homework

- ❑ Implement the LCD controller using method #1, #2, or both. Also, provide a demo C code that print to the LCD
- ❑ Write a report discuss your implementation and problems you have encountered
- ❑ You must upload the `*.v` files of your controller and the `*.c/* .h` files of your demo program
 - I will use these files to make sure you do the homework by yourself.
 - Do not upload the workspace, just put new files and your modifications (e.g. `aquila_top.v`, `soc_top.v`) in a zip file.