Basics

Current, Voltage, Power

$$e = 1.602 \times 10^{-19} \,\mathrm{C}$$

$$I = \frac{\mathrm{d}q}{\mathrm{d}t} \qquad V = \frac{\mathrm{d}W}{\mathrm{d}q} \qquad P = VI$$

Resistors

$$R = \rho \frac{l}{A}$$

$$V = IR \qquad P = I^2 R$$

$$R = R_1 + R_2 + \dots + R_n \qquad \text{(series)}$$

$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}$$
 (parallel)

KCL

$$\sum I_{in} = \sum I_{out}$$

KVL

$$\sum_{loop} \Delta V = 0$$

Current-Voltage Division

$$I_1 = I_2$$
 $V_1 = \frac{R_1}{R_1 + R_2} V$ (series)

$$V_1 = V_2 I_1 = \frac{R_2}{R_1 + R_2} V (parallel)$$

Wye-Delta

$$\Delta \to Y$$
:

$$R_1 = \frac{R_b R_c}{R_a + R_b + R_c}$$

$Y \to \Delta$:

$$R_a = \frac{R_1 R_2 + R_2 R_3 + R_3 R_1}{R_1}$$

Circuit Analysis

Nodal Analysis

- 1. Set reference node voltage to 0.
- 2. Assign variable voltages to other nodes.
- 3. Write KCL at all unknown nodes, then solve.
- 4. Use supernode if necessary.

Mesh Analysis

1. Assign loop currents.

ELEC 204 Formula Sheet

- 2. Write KVL for each loop, then solve.
- 3. Use supermesh if necessary.

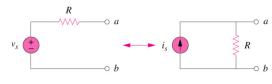
Linearity

We can assume a value, then scale linearly in the end.

Superposition

- 1. Set all independent sources to 0, except one. Repeat for each source, then sum.
- 2. 0 voltage source = wire.
- 3. 0 current source = broken circuit.

Source Transform



$$V = IR$$

Thevenin

- 1. $V_{th} = V_{oc}$, turn off independent sources to get R_{th}
- 2. $V_{th} = V_{oc}$, find I_{sc} then $R_{th} = V_{oc}/I_{sc}$
- 3. Apply test current/test voltage
- 4. Source transform

Norton

$$I_n = V_{th}/R_{th}$$
 $R_n = R_{th}$

Maximum Power

$$R_L = R_{th} \qquad P_{max} = \frac{V^2}{4R_{th}}$$

Capacitors and Inductors

Capacitors

$$q = CV$$
 $i = C\frac{\mathrm{d}v}{\mathrm{d}t}$ $W = \frac{1}{2}Cv^2$

Inductors

$$v = L \frac{\mathrm{d}i}{\mathrm{d}t}$$
 $W = \frac{1}{2}Li^2$

First/Second Order Circuits

First Order

$$\tau = RC$$
 $\tau = \frac{L}{R}$ (use $R = R_{th}$)

$$x(t) = \left[x(t_0^+) - x(\infty) \right] e^{-\frac{t - t_0}{\tau}} + x(\infty)$$

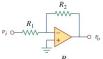
Second Order

Solve second order constant coefficient DE.

OpAmps

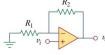
- Saturate at $+V_{cc}$ and $-V_{cc}$
- Amplifier: $V_{out} = AV_{in}$
- Negative feedback: $i_{+} = i_{-} = 0$ $V_{+} = V_{-}$
 - · Inverting amplifier

$$v_o = -\frac{R_2}{R_1} v_i$$



Non-inverting amplifier

$$v_o = \left(1 + \frac{R_2}{R_1}\right) v_i$$



Buffer (voltage follower)

$$v_{o} = v_{i}$$



· Summer (adder)

$$v_o = -\left(\frac{R_f}{R_1}v_1 + \frac{R_f}{R_2}v_2 + \frac{R_f}{R_3}v_1\right)$$



Difference Amplifier

$$v_o = \frac{R_2}{R_1} (v_2 - v_1)$$



Differentiator

$$v_o = -RC \frac{dv_i}{dt}$$



Integrator

$$v_o = -\frac{1}{RC} \int v_i dt$$



Taking natural logarithm

$$v_o = -V_T \ln \left(\frac{v_i}{R \cdot I_s} \right)$$



· Raising to the power of e

$$v_o = -R \cdot I_s e^{\frac{v_i}{V_T}}$$



Sinusoidal Analysis and Power

Sinusoidal Analysis

$$v(t) = V_m \cos(\omega t + \theta) = \text{Re}\left[V_m e^{j\theta} e^{j\omega t}\right]$$

 $v(t) \equiv \text{Re}\left[V_m e^{j\theta}\right] = \text{Re}\left[V_m \underline{/\theta}\right] = \text{Re}\left[V\right]$
 $Z = R + jX$

$$X_L = \omega L$$
 $X_C = -\frac{1}{\omega C}$

- V, I, Z can be treated as V, I, R.
- Thevenin, Nodal, and Mesh analysis ✓

Real Power

$$p = \underbrace{\frac{V_m I_m}{2} \cos(\theta_v - \theta_i)}_{P: \text{ active power}} + \underbrace{\frac{V_m I_m}{2} \cos(\theta_v - \theta_i) \cos 2\omega t}_{Q: \text{ reactive power}} - \underbrace{\frac{V_m I_m}{2} \sin(\theta_v - \theta_i)}_{Q: \text{ reactive power}} \sin 2\omega t$$

Power factor: $pf = \cos(\theta_v - \theta_i)$.

RMS:

$$I_{rms} = I_{eff} = \frac{I}{\sqrt{2}}$$
 $V_{rms} = V_{eff} = \frac{V}{\sqrt{2}}$

Complex Power

$$egin{aligned} oldsymbol{S} &= P + jQ = oldsymbol{V}_{rms} oldsymbol{I}^*_{rms} = rac{1}{2} oldsymbol{V} oldsymbol{I}^* \ oldsymbol{S} &= oldsymbol{Z} oldsymbol{I}_{eff} oldsymbol{I}^* = oldsymbol{Z} oldsymbol{I}_{eff} oldsymbol{I}^2 \ P &= oldsymbol{I}_{eff} oldsymbol{I}^2 R = rac{1}{2} oldsymbol{I} oldsymbol{I}^2 R \ Q &= oldsymbol{I}_{eff} oldsymbol{I}^2 X = rac{1}{2} oldsymbol{I} oldsymbol{I}^2 X \end{aligned}$$

Maximum Power

$$oldsymbol{Z}_L = oldsymbol{Z}_{th}^* \qquad P_{max} = rac{1}{4} rac{\left| oldsymbol{V}_{th}
ight|^2}{R_{th}}$$

Restricted R_L and X_L :

- Adjust X_L to be close to $-X_{th}$
- Adjust R_L to be close to $\sqrt{R_{th}^2 + (X_L + X_{th})^2}$

Fixed angle of \mathbf{Z}_L :

• Set $|\boldsymbol{Z}_L| = |\boldsymbol{Z}_{th}|$

Diodes

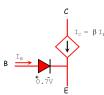
$$i_D = I_0 \left(e^{\frac{v_D}{nV_T}} - 1 \right) \qquad V_T \equiv \frac{kT}{q_e}$$

$$V_D = 0.7 \,\text{V}$$

- 1. Assume whether each diode is on or off, solve for currents/voltage, and check if consistent with assumption
- 2. If inconsistent, try another combination

BJTs - NPN

Linear zone: BE forward biased and BC reverse biased



- 1. DC operating point: turn off AC sources, solve
- 2. AC small-signal: turn off DC sources, use hybrid-pi small signal equivalent

$$g_m = \frac{I_C}{V_T} \qquad r_\pi = \frac{\beta}{g_m} = \frac{\beta V_T}{I_C} = \frac{V_T}{I_B}$$

MOSFETs - NMOS

Activate when $V_{GS} > V_{Th}$

• $V_{DS} \ll V_{GS} - V_{Th}$ (deep triode):

$$I_D = \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{Th}) \cdot V_{DS}$$

• $V_{DS} \leq V_{GS} - V_{Th}$ (triode):

$$I_D = \mu_n C_{ox} \frac{W}{L} \left[(V_{GS} - V_{Th}) \cdot V_{DS} - \frac{1}{2} V_{DS}^2 \right]$$

$$g_m = \mu_n C_{ox} \frac{W}{L} V_{DS}$$

• $V_{DS} > V_{GS} - V_{Th}$ (saturation):

$$I_D = \frac{1}{2}\mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{Th})^2$$
$$g_m = \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{Th})$$

Small signal equivalent:

