

RAYMOND TIMOTHY TUMIWA

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800 Dongchuan Road, Minhang District, Shanghai, 200240, China

I am a Research Master's student in Control Science and Engineering at the UM-SJTU Joint Institute. My research within the Surgical & Intelligent Robot & Innovative Unmanned Systems (SIRIUS) Laboratory focuses on advancing open-source surgical robotics through mechatronic integration and real-time control. With a Bachelor's degree in Electrical Engineering from The Chinese University of Hong Kong, Shenzhen, I bridge the gap between hardware-software co-design and complex robotic control. I am dedicated to developing accessible, high-precision robotic platforms like opensurgbot and am committed to tackling engineering challenges with persistence and a collaborative work ethic.

Education Level

Shanghai Jiao Tong University - Shanghai, China <i>Master of Science in Control Science and Engineering, 3.62/4.00</i>	Sep 2025 - Feb 2028 (Expected)
• Supervision: Prof. Yutong Ban, SIRIUS Laboratory. • Research: Mechatronics and surgical robotics at the UM-SJTU Joint Institute; focus on open-source platforms.	
The Chinese University of Hong Kong, Shenzhen - Shenzhen, China <i>Bachelor of Engineering in Electronic Information Engineering, Second-Class Honours Upper Division</i>	Aug 2021 - Dec 2024

The University of British Columbia - Vancouver, Canada • Vancouver Summer Program: Introduction to Robotics (94.8%) and Roboethics (86%)	Jul 2024 - Aug 2024
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Work Experiences

UM-SJTU Joint Institute (University of Michigan-Shanghai Jiao Tong University) - Shanghai, China <i>Mechatronics Engineer (Research Intern)</i>	Sep 2025 - Present
• Surgical Robotics Development: Contributing to the development of opensurgbot, an open-source surgical robotics platform, within the SIRIUS (Surgical & Intelligent Robot & Innovative Unmanned Systems) Laboratory. • Real-time Embedded Control: Designing and implementing high-performance control loops on STM32 microcontrollers using C and the HAL library to ensure precision instrument manipulation. • Mechatronic System Integration: Designing the synergy between mechanical hardware and electronic control systems for medical applications under the supervision of Professor Yutong Ban and Professor Shane Johnson.	
Soft Robotics Laboratory CUHK(SZ) - Shenzhen, China <i>Final Year Project Student</i>	Aug 2024 - Present

Soft Robotics Laboratory CUHK(SZ) - Shenzhen, China • Conducted experiments and prototype testing for the '3D Printed Soft Electrostatic Loudspeaker' project in the Soft Robotics Lab under Professor Zhu Jian at CUHKSZ. • Utilized CAD and slicing applications such as Stratos to design and optimize 3D-printed components, achieving a performance improvement with a 50% maximum gain.	Aug 2024 - Present
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The Chinese University of Hong Kong, Shenzhen - Shenzhen, China <i>Undergraduate Student Teaching Fellows (USTF)</i>	Aug 2024 - Dec 2024
• Prepared and delivered tutorial slides with practice problems for ECE3510: Digital Signal Processing, enhancing the clarity of lecture content for a class of 20 undergraduate students. • Compiled and reviewed homework assignments and projects using MATLAB, Python, and LaTeX, ensuring alignment with course objectives and providing effective learning resources. • Developed step-by-step solutions to homework problems via Blackboard, improving student comprehension and engagement in digital signal processing concepts.	

Skills, Achievements & Other Experience

- Projects** (2023): Microprocessor Ball Game Improvement, Audio Signal Processing using Matlab
- Achievements**: Partial Tuition & Full Accommodation Scholarship
- Soft Skills**: Microsoft Office, Python, Electrical Hardware
- Language**: Indonesian (Native), English (IELTS 7.5), Chinese (Conversational), German (Beginner)