

Synthesis Algorithms

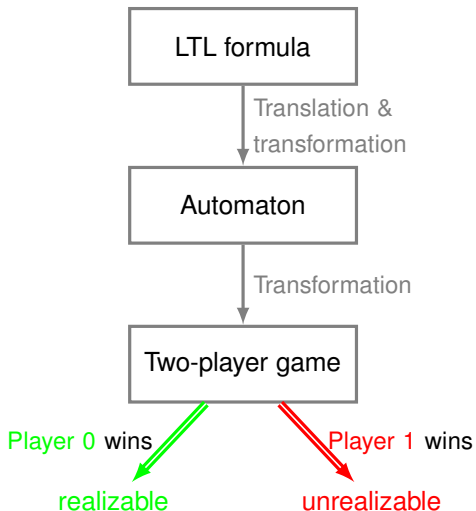
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Midlands Graduate School 2019

Acknowledgement: Many slides courtesy of Bernd Finkbeiner.

Synthesis from LTL specifications



Monday

Tuesday

LTL Realizability

Given φ , does there exist a strategy f that satisfies φ ?

Approach: Construct a game between environment (providing input), and system (choosing output). Check if system has a winning strategy.

Attempt: Let $\mathcal{A}_\varphi = (\Sigma, Q, Q_0, \delta, F)$ be an NBA for φ

- ▶ System chooses output value $o \in \Sigma_O$
- ▶ Environment chooses output value $i \in \Sigma_I$
- ▶ **Round:** system and environment set their variables
- ▶ **Play:** infinite word in Σ^ω
- ▶ System wins if infinite play accepted by \mathcal{A}_φ

Problem: In a **nondeterministic automaton**, an accepted word can also have rejecting runs. Mismatch between nondeterminism and strategic choice: the system can lose just because the wrong run was chosen.

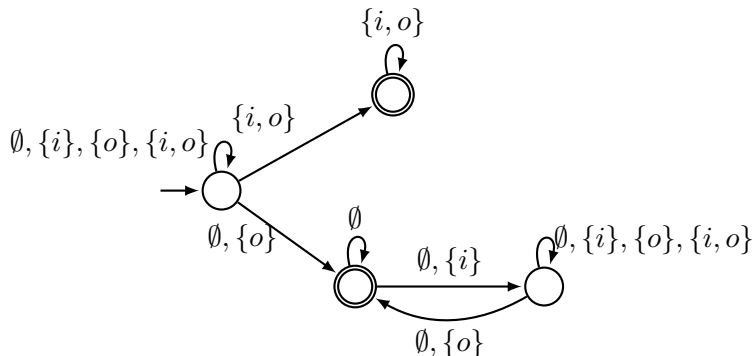
Why are nondeterministic automata not suitable?

Nondeterministic automata have perfect foresight.

Strategies have no foresight.

Example: $(FG(i \wedge Xo)) \vee (GF(\neg i \wedge X\neg o))$

- ▶ System has winning strategy (copy input to output).
- ▶ The system cannot choose between the two disjuncts.



Deterministic Büchi automata (DBA)

A NBA \mathcal{A} is a **DBA** iff

$$|Q_0| \leq 1 \quad \text{and} \quad |\delta(q, \sigma)| \leq 1 \quad \text{for all } q \in Q \text{ and } \sigma \in \Sigma$$

A DBA \mathcal{A} is **complete** iff

$$|Q_0| = 1 \quad \text{and} \quad |\delta(q, \sigma)| = 1 \quad \text{for all } q \in Q \text{ and } \sigma \in \Sigma$$

Complete DBAs have a **unique** run for every input word.

Not every LTL formula can be translated into an equivalent DBA.

Acceptance conditions: Parity

A **parity condition** is a coloring function $\alpha : Q \rightarrow \mathbb{N}$.

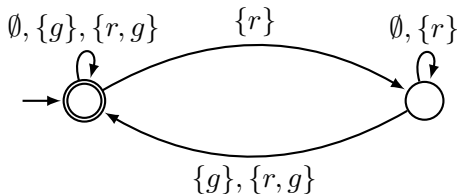
An infinite sequence $q_0q_1q_2 \dots \in Q^\omega$ is **max-parity-accepted** iff the highest color k that appears infinitely often is **even**.

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DBA:

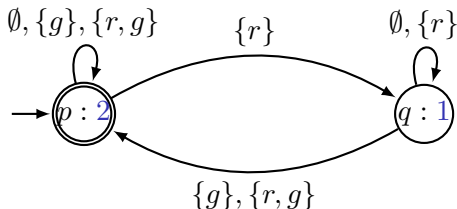


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DPA:



Deterministic parity automata (DPA)

Theorem [McNaughton 1966]

For each NBA there is an equivalent deterministic ω -automaton.

Theorem [Piterman'07]

For every NBA \mathcal{N} with n states there exists a DPA \mathcal{D} with $2n^n n!$ states and $2n$ colors such that $\mathcal{L}_\omega(\mathcal{D}) = \mathcal{L}_\omega(\mathcal{N})$.

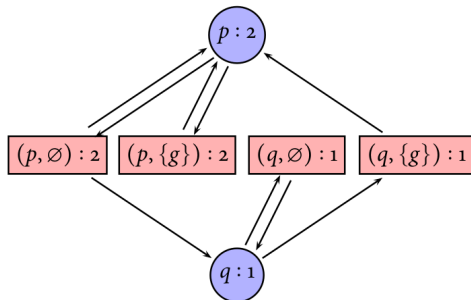
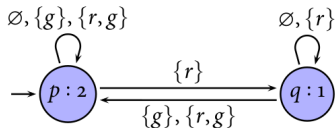
The exponential blow-up is unavoidable.

From deterministic ω -automata to games

A **game arena** $\mathcal{A} = (V, V_0, V_1, E)$ consists of

- ▶ a finite set of states V ,
- ▶ a subset $V_0 \subseteq V$ of states owned by **Player 0 (circles)**,
- ▶ a subset $V_1 = V \setminus V_0$ of states owned by **Player 1 (boxes)**,
- ▶ an edge relation $E \subseteq V \times V$, such that every $v \in V$ has at least one outgoing edge $(v, v') \in E$. E represents the possible moves.

Player 0 = system, Player 1 = environment



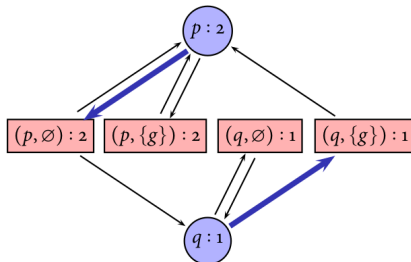
Plays and strategies in a graph game

A **play** is an infinite path through \mathcal{A} .

A **strategy** for player i is a function $f_i : V^* \cdot V_i \rightarrow V$ such that $(v, v') \in E$ whenever $f(\pi \cdot v) = v'$.

A play $\pi = v_0, v_1, \dots$ **conforms to** strategy f_i of player i if $v_{n+1} = f_i(v_0, \dots, v_n)$ whenever $v_n \in V_i$.

Strategy for Player 0



Winning conditions

- ▶ A **parity game** $\mathcal{G} = (\mathcal{A}, \alpha)$ consists of an arena \mathcal{A} and a coloring function $\alpha : V \rightarrow \mathbb{N}$. **Player 0** wins play π if the highest color that is seen infinitely often is even, otherwise **Player 1** wins.
- ▶ A **Büchi game** $\mathcal{G} = (\mathcal{A}, F)$ consists of an arena \mathcal{A} and a set $F \subseteq V$. **Player 0** wins a play π if π visits F infinitely often, otherwise **Player 1** wins.
- ▶ A **reachability game** $\mathcal{G} = (\mathcal{A}, R)$ consists of a game arena \mathcal{A} and a set of states $R \subseteq V$. **Player 0** wins a play π if π visits R at least once, otherwise **Player 1** wins.

Winning regions

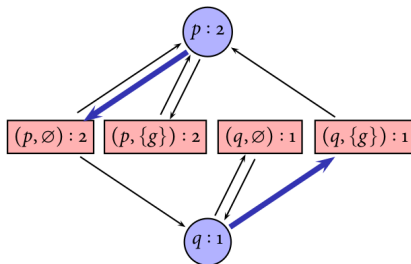
A strategy f_i is **winning** for player i from some state v if all plays that conform to f_i and that start in v are won by Player i .

The **winning region** W_i for player i is the set of states from which Player i has a winning strategy.

A game is **determined** if $V = W_0 \cup W_1$.

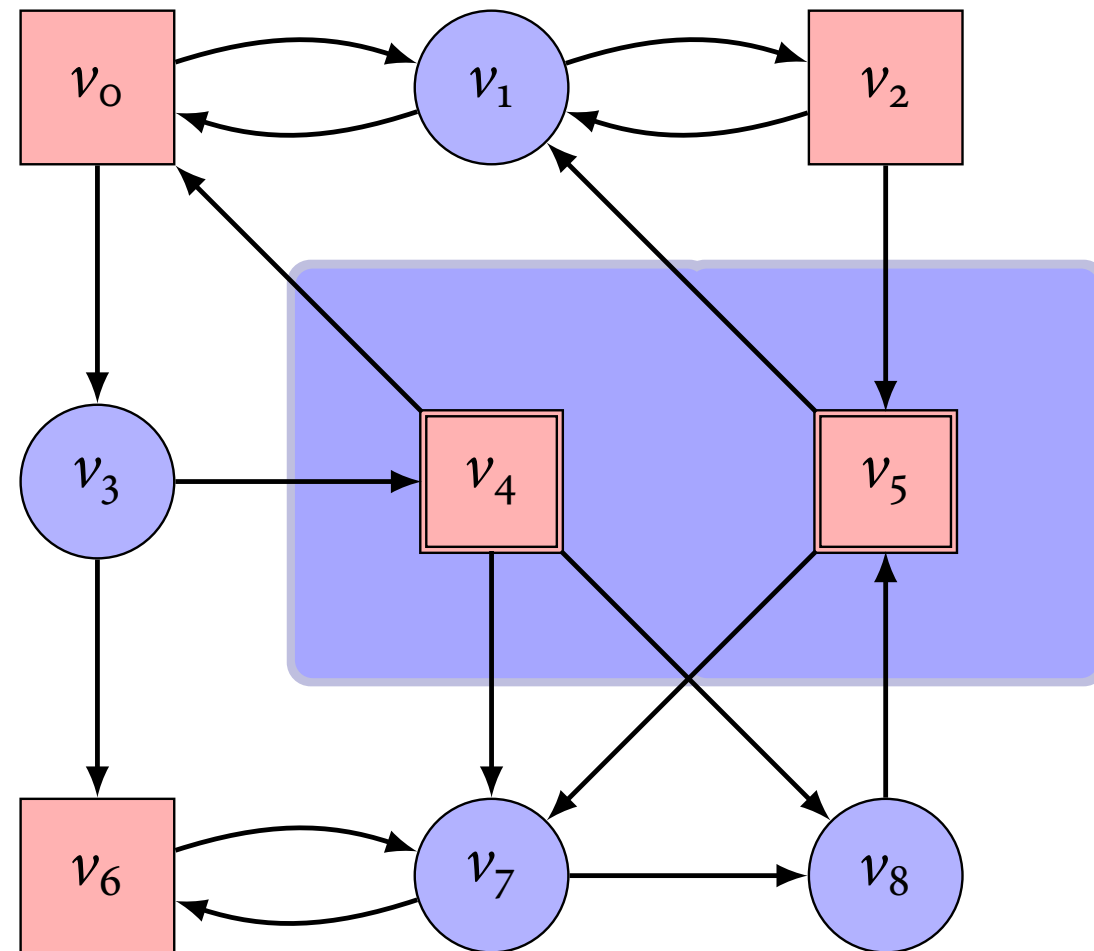
Solving a game means to determine the winning region and the winning strategies.

Winning strategy for Player 0



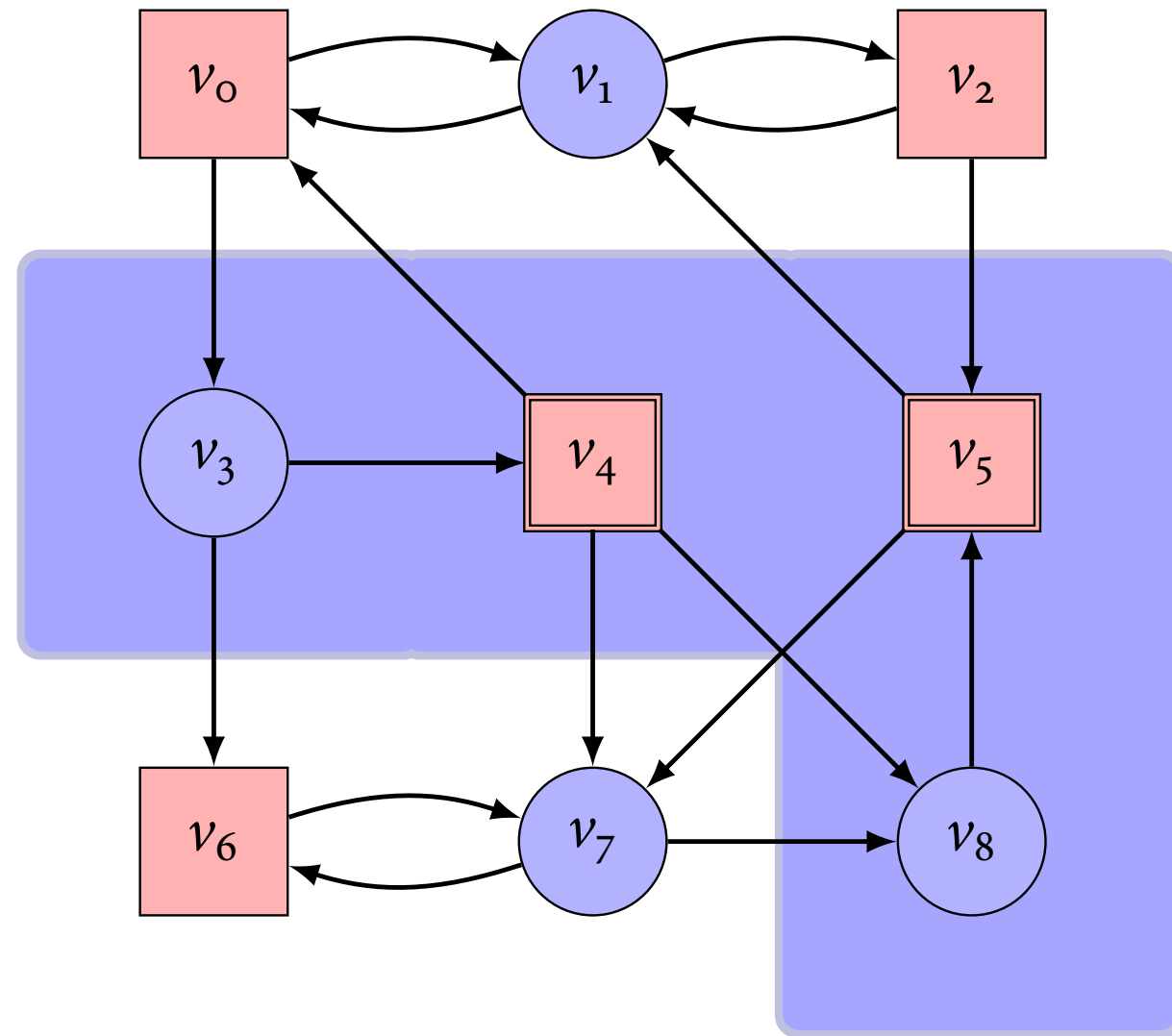
Reachability games

Reachability game: Player 0 wins a play π if π visits R at least once



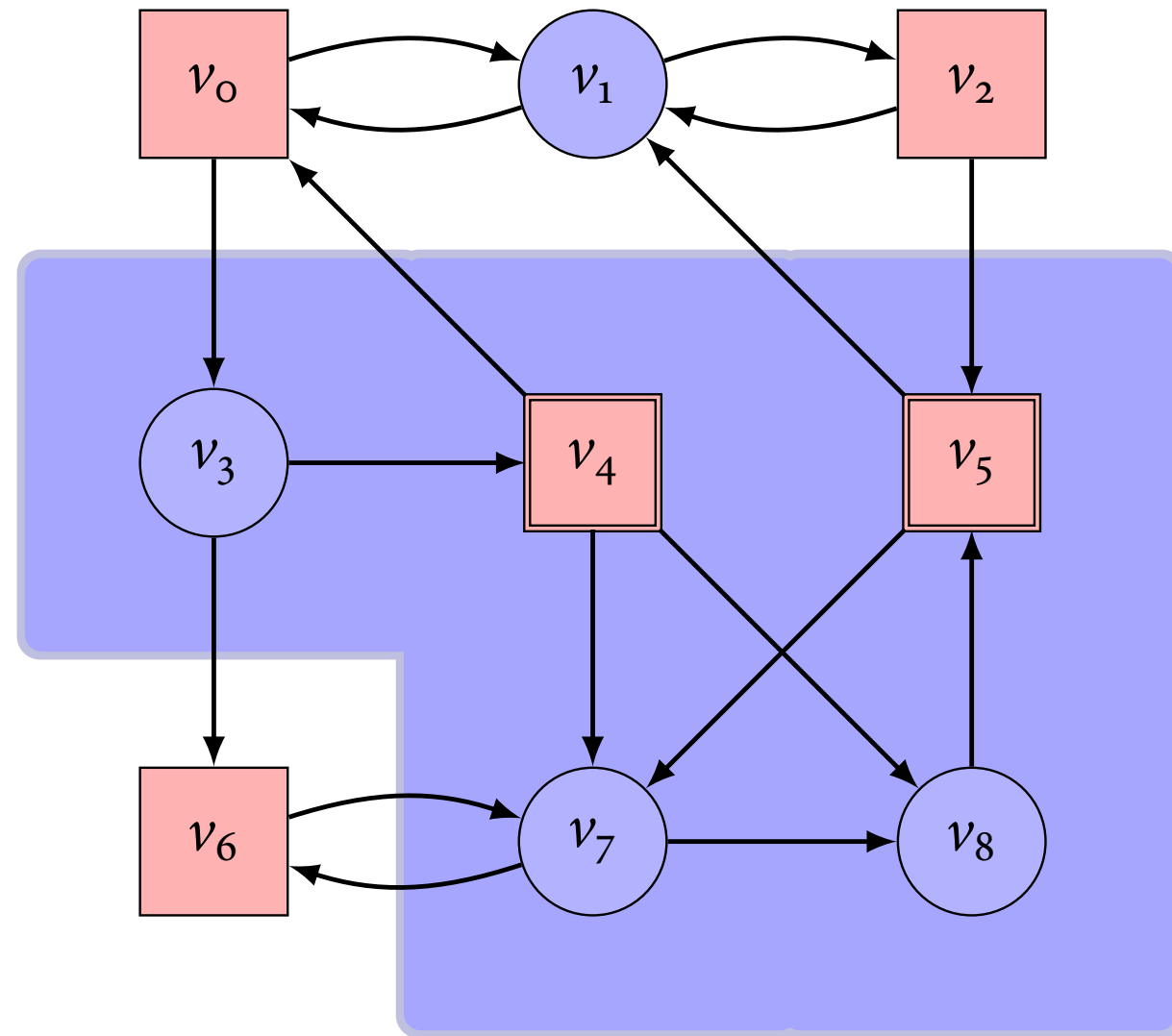
Reachability games

Reachability game: Player o wins a play π if π visits R at least once



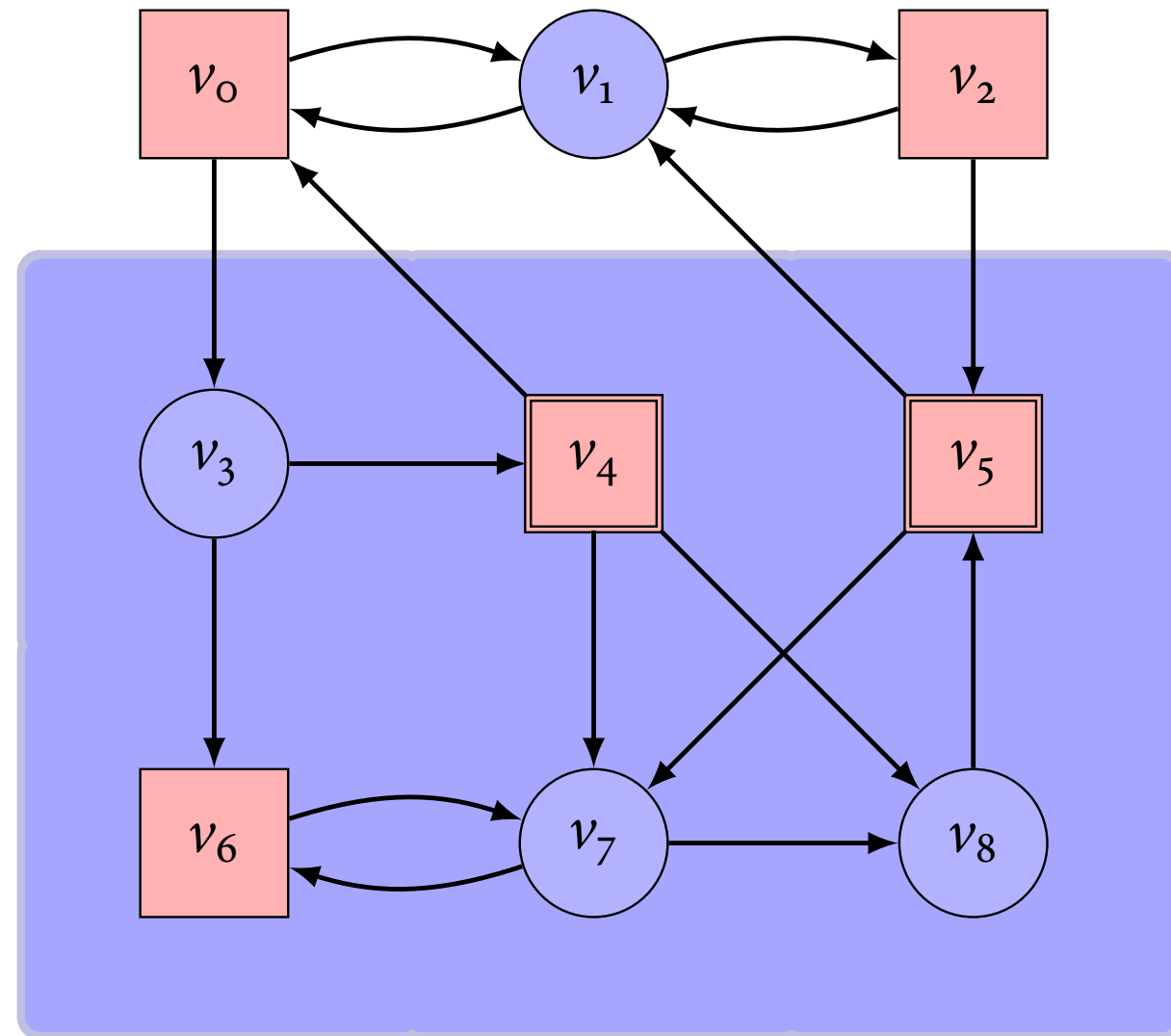
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Attractor construction

$$\begin{aligned}Attr_i^0(R) &= R \\Attr_i^{n+1}(R) &= Attr_i^n(R) \cup CPre_i(Attr_i^n(R))\end{aligned}$$

$$Attr_i(R) = \bigcup_{n \in \mathbb{N}} Attr_i^n(R)$$

where

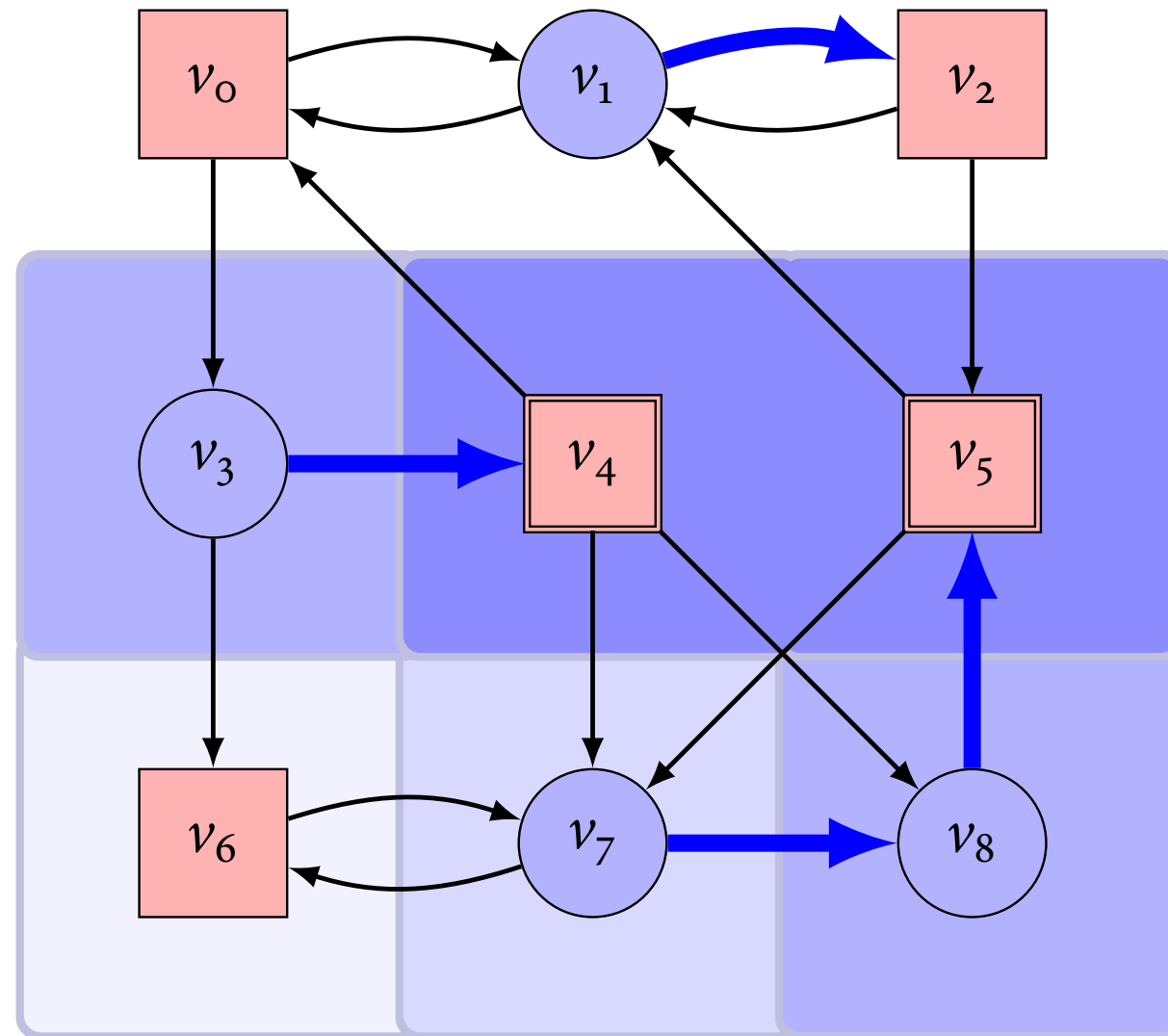
$$\begin{aligned}CPre_i(R) &= \{ v \in V_i \mid \exists v' \in V. (v, v') \in E \wedge v' \in R \} \\&\quad \cup \{ v \in V_{1-i} \mid \forall v' \in V. (v, v') \in E \Rightarrow v' \in R \}\end{aligned}$$

Winning regions of a reachability game

Winning region of **Player 0**: $W_0(\mathcal{G}) = Attr_0(R)$

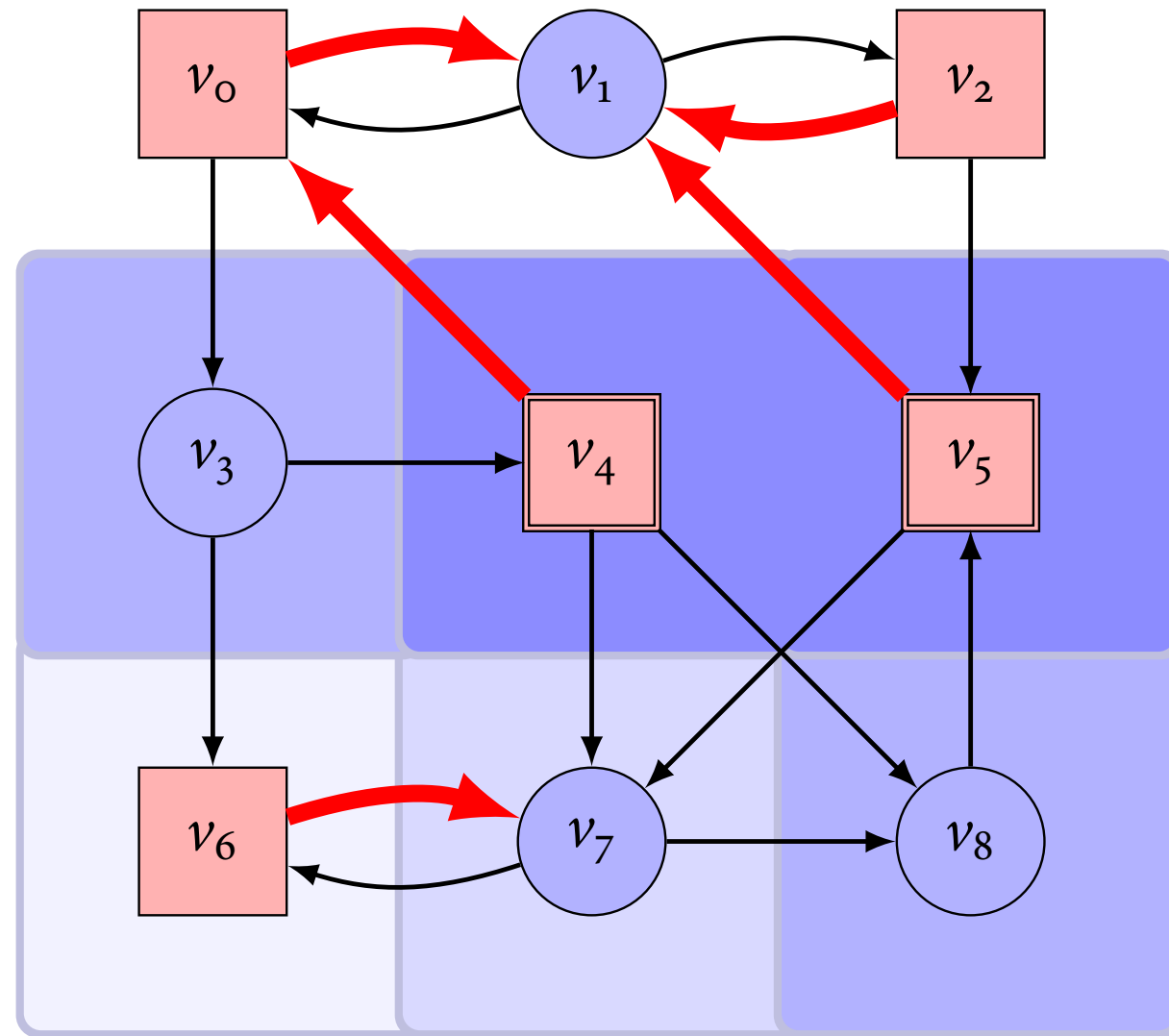
Winning region of **Player 1**: $W_1(\mathcal{G}) = V \setminus Attr_0(R)$

Winning strategy of Player o (Attractor Strategy)



The winning strategy for **Player o** always moves to $Attr_o^n(R)$ for the smallest possible n .

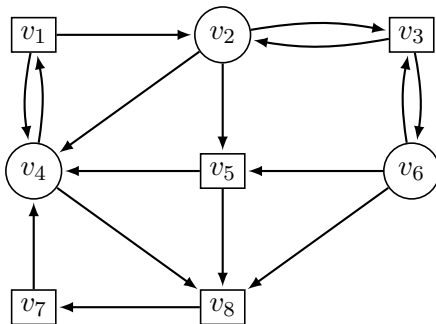
Winning strategy of **Player 1** (Safety Strategy)



The winning strategy for **Player 1** always avoids $Attr_o(R)$.

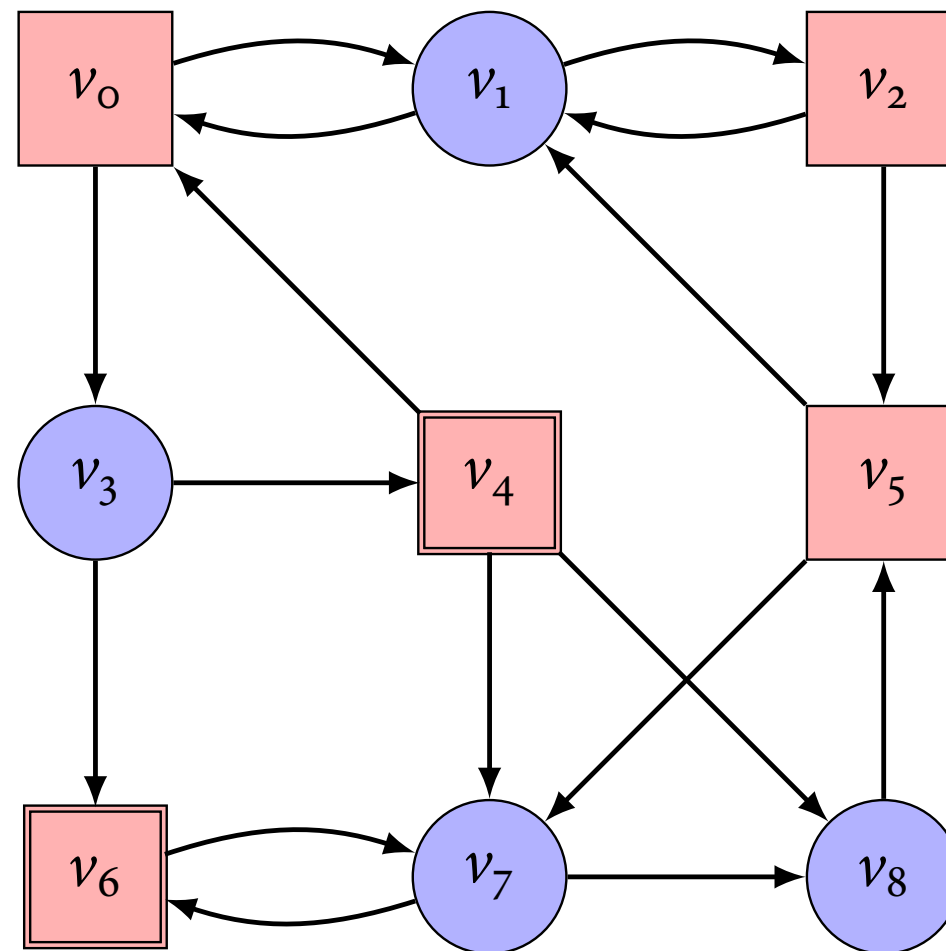
Exercise

Consider the game arena given below and the winning condition defined as follows: Player 0 wins a play π if π visits the state v_4 at least once and π never leaves the set of nodes $\{v_1, v_2, v_3, v_4, v_5, v_6\}$. Describe how you can compute the winning region for Player 0.



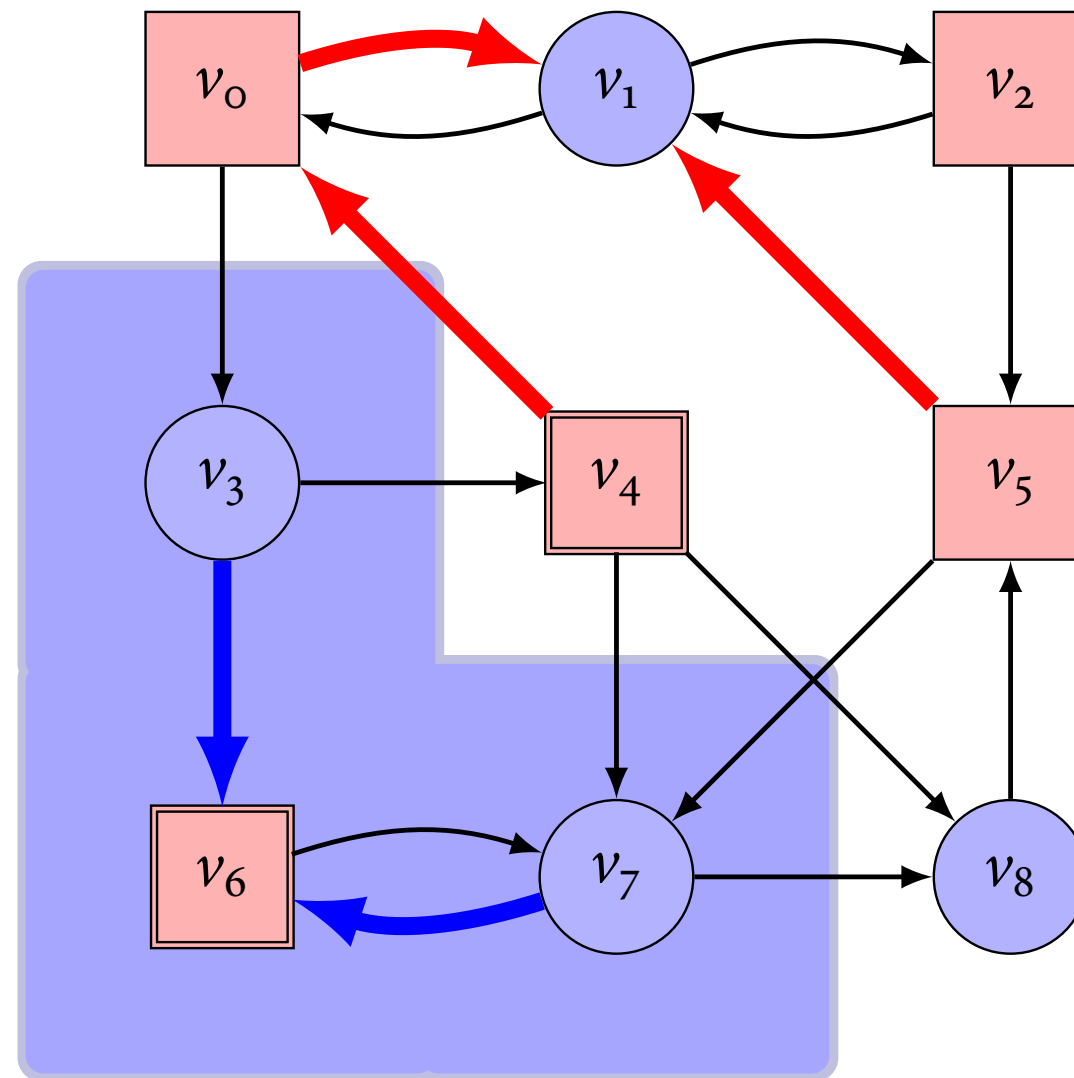
Büchi games

Büchi game: **Player 0** wins a play π if π visits F infinitely often, otherwise **Player 1** wins.



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Recurrence construction

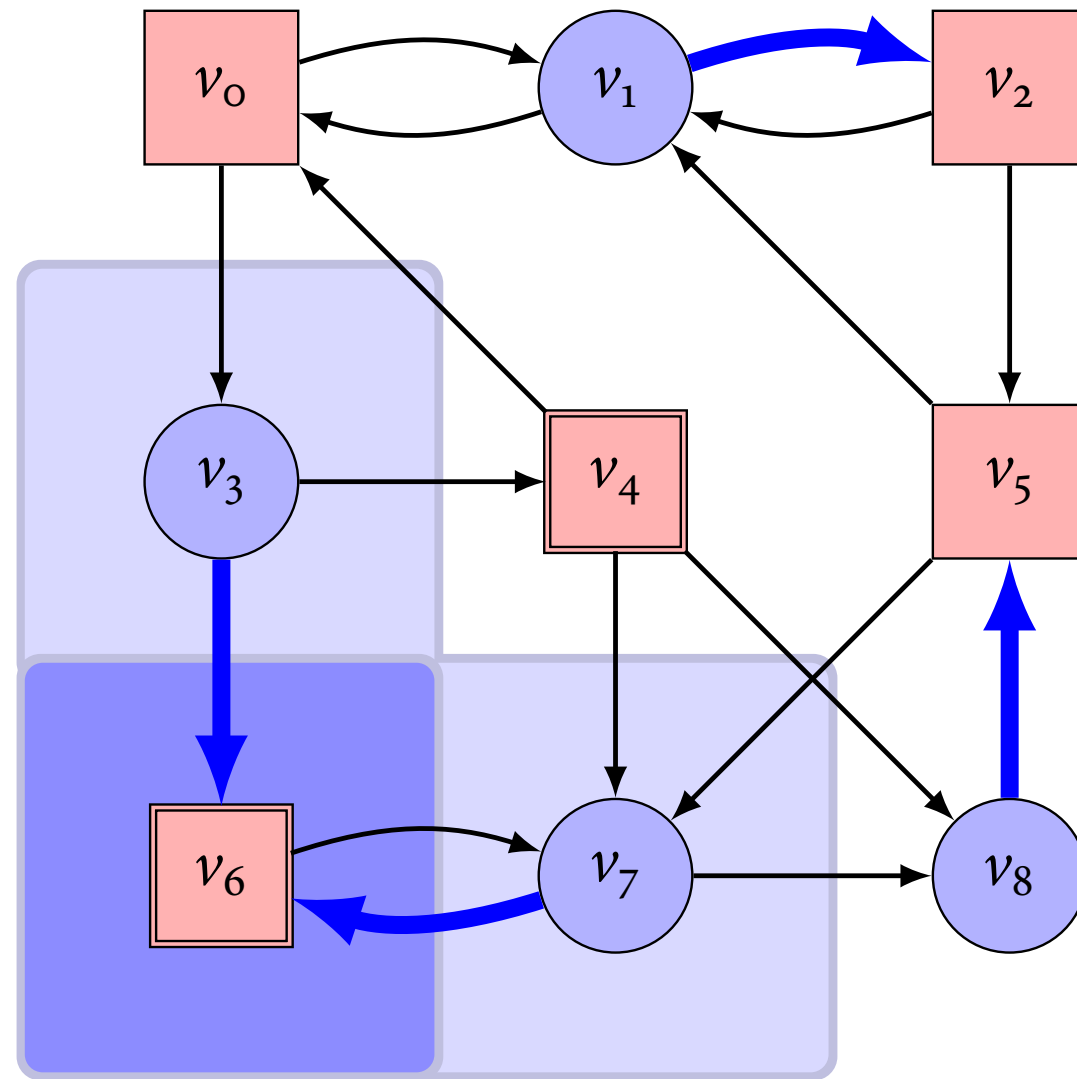
$$\begin{aligned} \text{Recur}^0(F) &= F \\ W_1^n(F) &= V \setminus \text{Attr}_o(\text{Recur}^n(F)) \\ \text{Recur}^{n+1}(F) &= \text{Recur}^n(F) \setminus \text{CPre}_1(W_1^n(F)) \end{aligned}$$

$$\text{Recur}(F) = \bigcap_{n \in \mathbb{N}} \text{Recur}^n(F)$$

Winning regions of a Büchi game

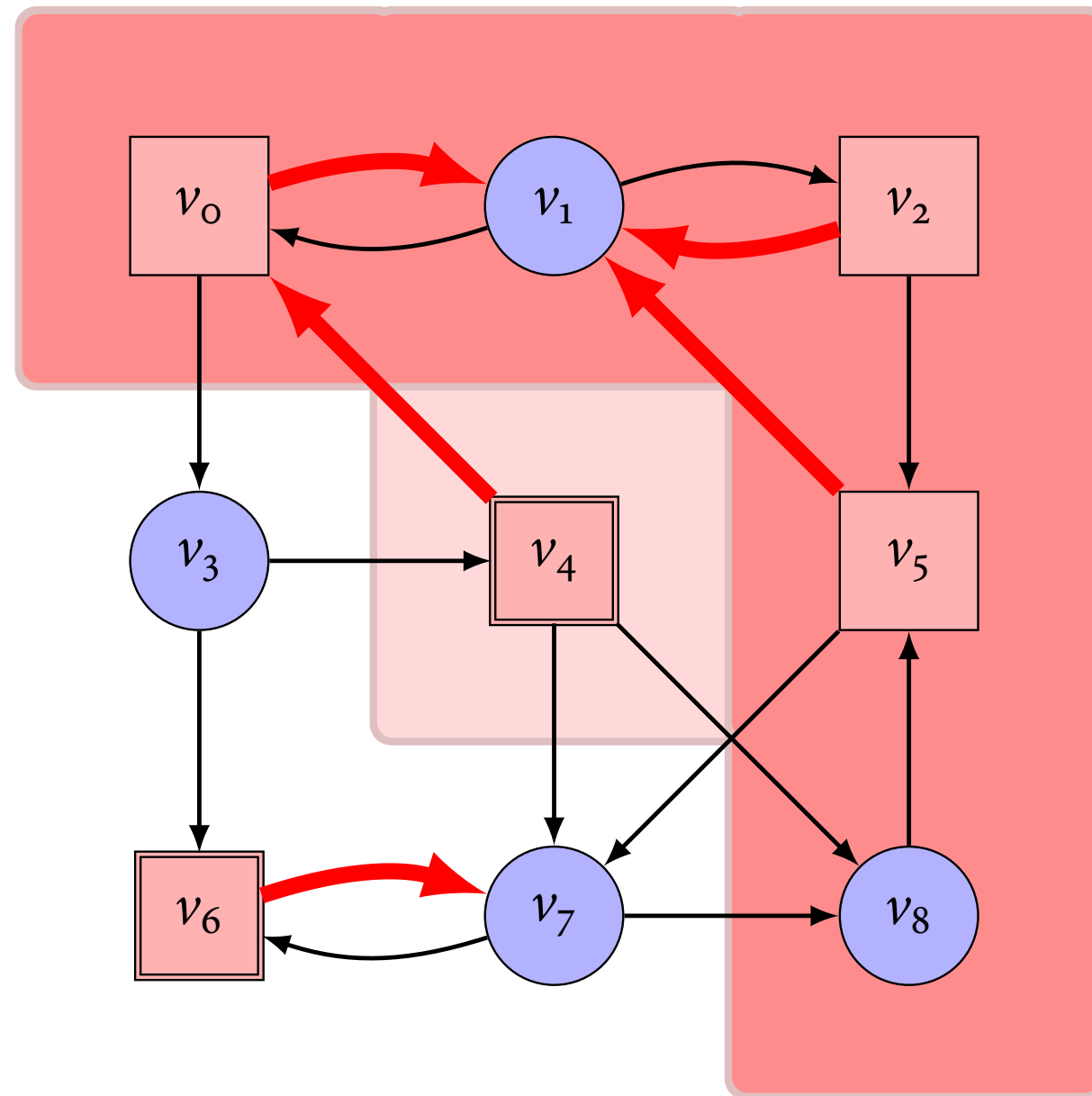
$$\begin{aligned} \text{Winning region of Player } o: & \quad W_o(\mathcal{G}) = \text{Attr}_o(\text{Recur}(F)) \\ \text{Winning region of Player } 1: & \quad W_1(\mathcal{G}) = V \setminus \text{Attr}_o(\text{Recur}(F)) \end{aligned}$$

Winning strategy of Player o (Büchi Strategy)



The winning strategy for **Player o** always moves to $Attr_o^n(Recur(F))$ for the smallest possible n .

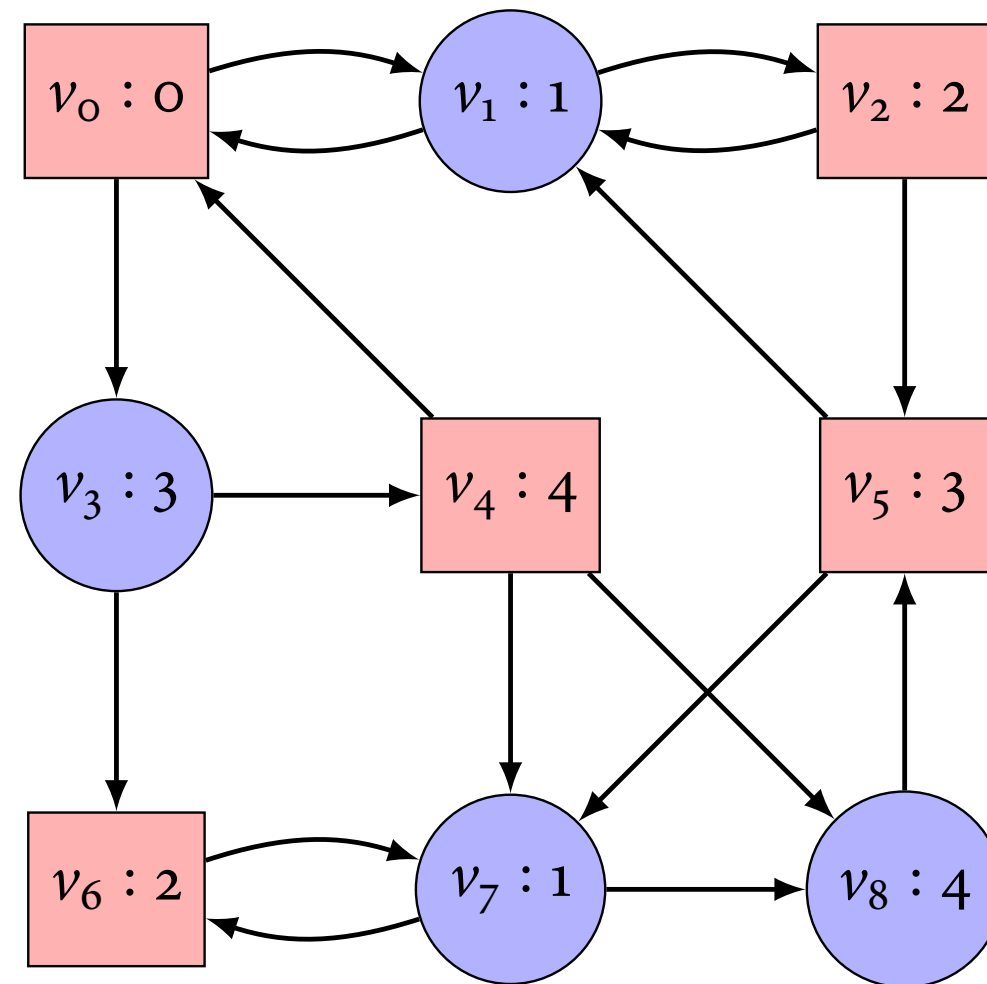
Winning strategy of **Player 1** (co-Büchi Strategy)



The winning strategy for **Player 1** moves from a state in W_1^n to W_1^{n-1} whenever possible, and stays in W_1^n otherwise.

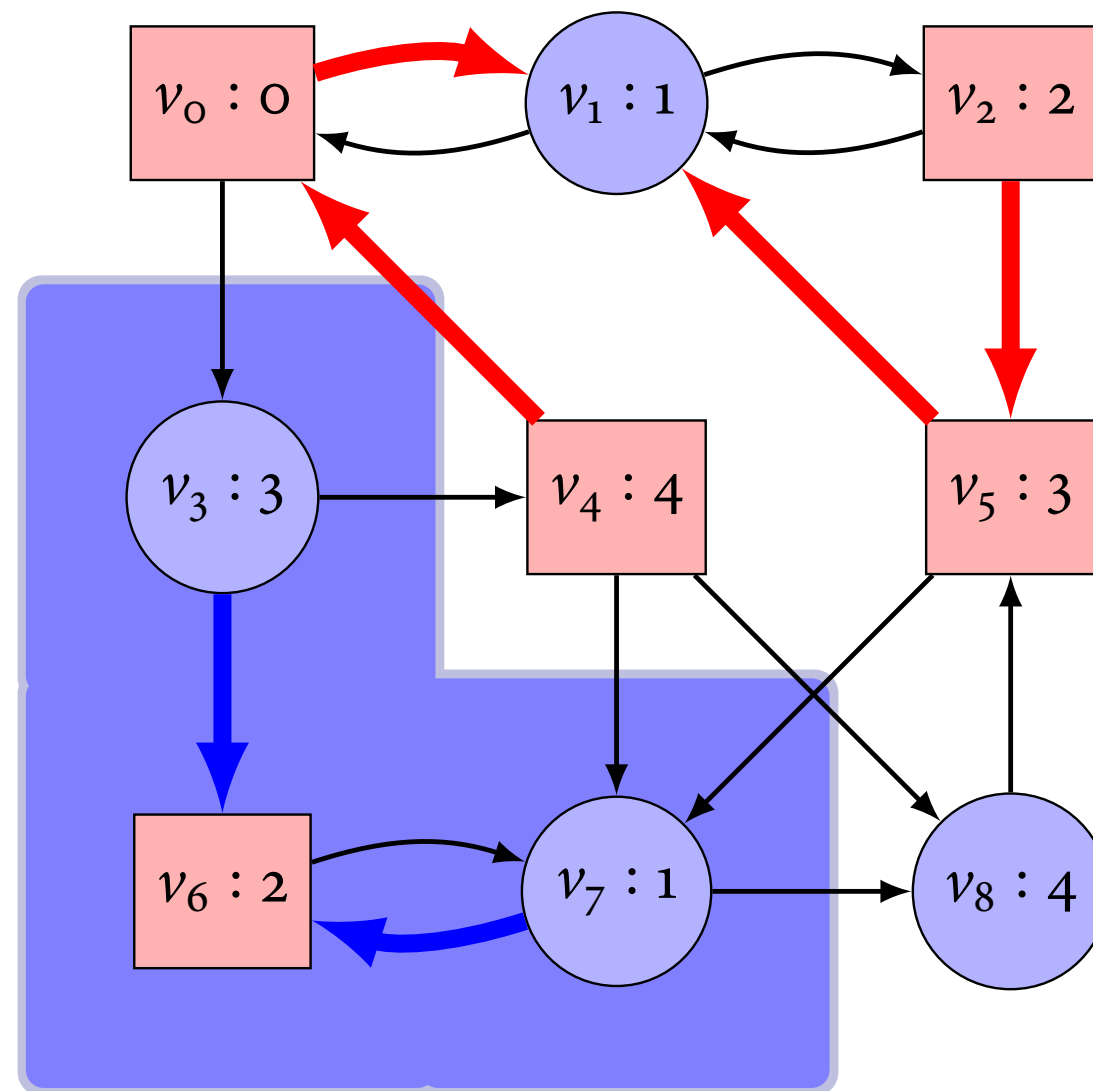
Parity games

Parity game: **Player o** wins a play π if the highest color that is seen infinitely often is even.



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McNaughton's Algorithm: Solving parity games

McNaughton(\mathcal{G})

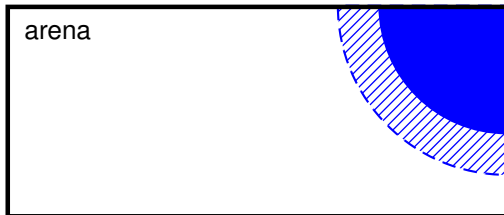
1. $c :=$ highest color in \mathcal{G}
2. if $c = 0$ or $V = \emptyset$
 then return (V, \emptyset)
3. set i to $c \bmod 2$
4. set W_{1-i} to \emptyset
5. repeat
 - 5.1 $\mathcal{G}' := \mathcal{G} \setminus \text{Attr}_i(\alpha^{-1}(c), \mathcal{G})$
 - 5.2 $(W'_0, W'_1) := \text{McNaughton}(\mathcal{G}')$
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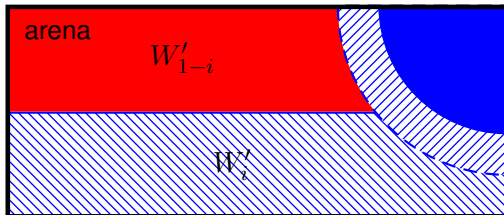
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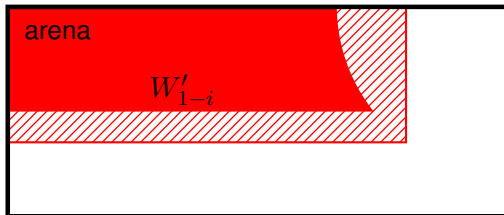
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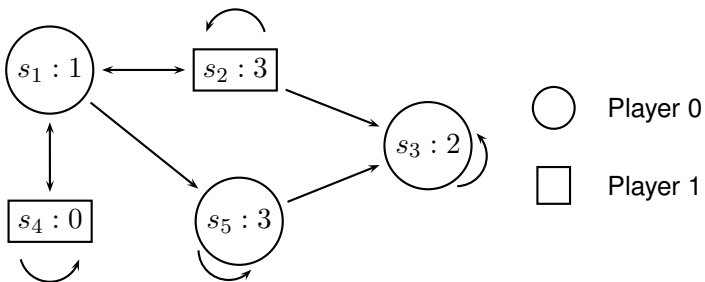
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Example



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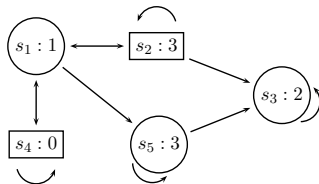
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► $k = 3, c^{-1}(3) = \{s_2, s_5\}, i = 1$

► $\mathcal{G}' := \mathcal{G} \setminus Attr_1(\{s_2, s_5\}, \mathcal{G}) = \{s_1, s_4, s_3\}$

► $(\{s_3\}, \{s_1, s_4\}) = McNaughton(\mathcal{G}')$

► $W_0 := \emptyset \cup Attr_0(\{s_3\}, \mathcal{G}) = \{s_1, s_3, s_5\}$

► $\mathcal{G} := \mathcal{G} \setminus Attr_0(\{s_3\}, \mathcal{G}) = \{s_2, s_4\}$

► $\mathcal{G}' := \mathcal{G} \setminus Attr_1(\{s_2\}, \mathcal{G}) = \{s_4\}$

► $(\{s_4\}, \emptyset) = McNaughton(\mathcal{G}')$

► $W_0 = \{s_1, s_3, s_5\} \cup \{s_4\}$

► $\mathcal{G} := \mathcal{G} \setminus \{s_4\} = \{s_2\}$

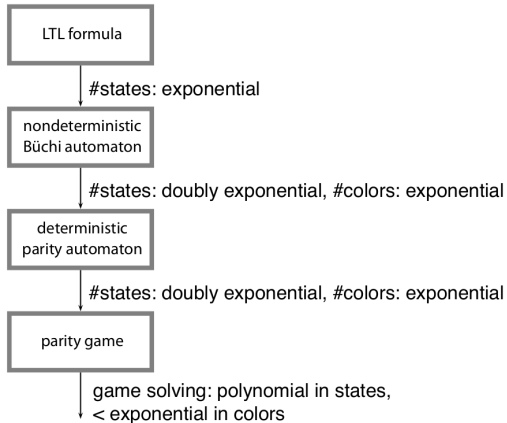
► $\mathcal{G}' = \mathcal{G} \setminus Attr_1(\{s_2\}, \mathcal{G}) = \emptyset$

► $(\emptyset, \emptyset) = McNaughton(\mathcal{G}')$

► $W_1 = V \setminus \{s_1, s_3, s_4, s_5\} = \{s_2\}$

► return ($\{s_1, s_3, s_4, s_5\}, \{s_2\}$)

LTL synthesis



LTL synthesis

LTL synthesis is 2EXPTIME-complete.