

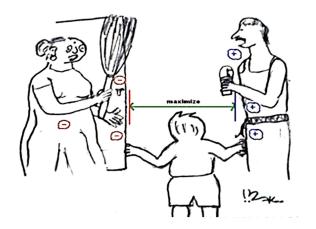
Primal estimated sub-gradient solver for SVM

Lei Zhong Advanced Topics in Machine Learning

Nov. 4, 2014

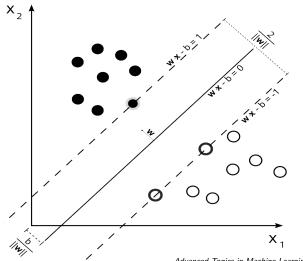
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Family Support Machine



From Peter Richtárik's slides

Motivating example



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Support Vector Machine: Primal Problem

Data:

$$\{(\mathbf{x}_i, y_i) \in \mathbb{R}^d \times \{+1, -1\} : i \in S \stackrel{def}{=} \{1, 2, \dots, n\}\}$$

- > Example: x_1, \ldots, x_n (assumption: $\max_i ||x_i||_2 \le R$)
- \triangleright Labels: $y_i \in \{+1, -1\}$

Optimization formulation of SVM:

$$\min_{\boldsymbol{w} \in \mathbb{R}^d} \{ f(\boldsymbol{w}) := \hat{L}_{S}(\boldsymbol{w}) + \frac{\lambda}{2} \|\boldsymbol{w}\|^2 \}$$

where

 \triangleright $\hat{L}_A(\mathbf{w}) \stackrel{\text{def}}{=} \frac{1}{|A|} \sum_{i \in A} L_i$ (average loss on examples in A)

Loss Function and Subgradient

Definition

- Loss: $L_i := \ell(\langle \mathbf{x}_i, \mathbf{w} \rangle, y_i)$
- Subgradient: $I'(\langle \mathbf{x}_i, \mathbf{w} \rangle, y_i)$ with the assumption of $||I'|| \leq \mathbb{L}$

Use the notation $z = \langle \mathbf{w}, \mathbf{x}_i \rangle$, sample loss functions:

Loss function	Subgradient
$I(z,y_i) = \max\{0,1-y_iz\}$	$I' = egin{cases} -y_i oldsymbol{x}_i & ext{if } y_i z < 1 \ 0 & ext{otherwise} \end{cases}$
$I(z,y_i) = \log(1+e^{-y_iz})$	$I' = -rac{y_i}{1+e^{y_i z}} oldsymbol{x}_i$
$I(z, y_i) = \max\{0, y_i - z - \epsilon\}$	$l' = \begin{cases} \mathbf{x}_i & \text{if } z - y_i > \epsilon \\ -\mathbf{x}_i & \text{if } y_i - z > \epsilon \\ 0 & \text{otherwise} \end{cases}$

Previous Work

- Dual-based methods
 - Interior Point
 - Memory: n^2 , time: $n^3 \log(\log(1/\epsilon))$, run time per iteration n^3
 - Decomposition
 - Memory: n, time complexity: super-linear in n, slow convergence
- Online learning & Stochastic Gradient
 - Memory: O(1), time: $1/\epsilon^2$ (linear kernel), run-time per iteration: O(d)

Better rates for finite dimensional instances (Murata, Bottou)

Typically, online learning algorithms do not converge to the optimal solution of SVM

Basic Pegasos Algorithm (SGD)

- ① Choose $\mathbf{w}_1 = 0 \in \mathbb{R}^d$
- 2 Iterate for $t = 1, 2, \dots, T$
 - Choose $A_t \subset S = \{1, 2, ..., n\}, |A_t| = k$, uniformly at random
 - 2 Set stepsize $\eta_t \leftarrow \frac{1}{\lambda_t}$
 - 3 Update $w^{(t+1)} \leftarrow w^{(t)} \eta_t \partial f_{A_t}(\mathbf{w}^{(t)})$

Theorem

For $\overline{\boldsymbol{w}} = \frac{1}{T} \sum_{t=1}^{T} \boldsymbol{w}_t$, we have:

$$\mathbb{E}[f(\overline{\boldsymbol{w}})] \leq f(w^*) + \frac{1 + \ln(T)}{2\lambda T}$$

where $c = 4R^2$.

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 - 2 Set stepsize $\eta_t \leftarrow \frac{1}{\lambda_t}$
 - **3** Update $w^{(t+1)} \leftarrow (1 \eta_t \lambda) w^{(t)} + \frac{\eta_t}{k} \sum_{i \in A_t} l' x_i$

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Run-Time of Pegasos

- Choosing $|A_t| = 1$
 - \rightarrow Run-time required for Pegasos to find ϵ accurate solution

$$\tilde{O}(\frac{d}{\lambda\epsilon})$$

- Run-time does not depends on #examples, suited for learning form large datasets
- ullet Depends on "difficulty" of problem (both λ and ϵ)

How to achieve this?

$$\|\mathbf{w}^{(t+1)} - \mathbf{w}^*\|^2 = \|\mathbf{w}^{(t)} - \eta_t \chi_i^{(t)} - \mathbf{w}^*\|^2$$

= $\|\mathbf{w}^{(t)} - \mathbf{w}^*\|^2 + \eta_t^2 \|\chi_i^{(t)}\|^2 - 2\eta_t \chi_i^{(t)} (\mathbf{w}^{(t)} - \mathbf{w}^*)$

Taking the expectation on both sides over the recent step

$$\mathbb{E}_{i^{(t)}}[\|\boldsymbol{w}^{(t+1)} - \boldsymbol{w}^*\|^2 \mid \boldsymbol{w}^t]$$

$$= \|\boldsymbol{w}^{(t)} - \boldsymbol{w}^*\|^2 + \eta_t^2 \mathbb{E}_{i^{(t)}} \|\boldsymbol{\chi}_i^{(t)}\|^2 - 2\eta_t \boldsymbol{\chi}_i^{(t)} (\boldsymbol{w}^{(t)} - \boldsymbol{w}^*)$$

$$\leq \|\boldsymbol{w}^{(t)} - \boldsymbol{w}^*\|^2 + \eta_t^2 \mathbb{E}_{i^{(t)}} \|\boldsymbol{\chi}_i^{(t)}\|^2 - 2\eta_t [f(\boldsymbol{w}^{(t)}) - f(\boldsymbol{w}^*) + \frac{\lambda}{2} \|\boldsymbol{w}^{(t)} - \boldsymbol{w}^*\|^2].$$

Re-arranging and taking expectation over the whole process again

$$\mathbb{E}f(\boldsymbol{w}^{(t)}) - f(\boldsymbol{w}^*) \leq \frac{\eta_t}{2} \mathbb{E}_{i^{(t)}} \|\boldsymbol{\chi}_i^{(t)}\|^2 + \frac{1 - \lambda \eta_t}{2\eta_t} \mathbb{E} \|\boldsymbol{w}^{(t)} - \boldsymbol{w}^*\|^2$$
$$-\frac{1}{2\eta_t} \mathbb{E} \left[\|\boldsymbol{w}^{(t+1)} - \boldsymbol{w}^*\|^2 \mid \boldsymbol{w}^t \right]$$

Lemma

With the Lipschitz assumption on I(y,u) that $||I'(y,u)|| \leq \mathbb{L}$, and assuming that $||\mathbf{x}_i|| \leq R \ \forall i$ where i is picked according to p_i , it holds that

$$\mathbb{E}_{i(t)} \| \boldsymbol{\chi}_i^{(t)} \| \leq 4 \mathbb{L}^2 R^2$$

where I'(y, u) denotes any subgradient with respect to the second variable.

How to prove it?

Minkowski inequality

$$\sqrt{\mathbb{E}(X+Y)^2} \le \sqrt{\mathbb{E}X^2} + \sqrt{\mathbb{E}Y^2}$$

$$\begin{split} \boldsymbol{\chi}_{i}^{(t)}(\boldsymbol{w}^{(t)}) &= l' \boldsymbol{x}_{i} + \boldsymbol{w}^{(t)}, \boldsymbol{w}^{(t+1)} = \boldsymbol{w}^{(t)} + l' \boldsymbol{x}_{i} \\ \sqrt{\mathbb{E}_{i^{(t)}} \|\boldsymbol{\chi}_{i}^{(t)}\|^{2}} &\leq \sqrt{\mathbb{E}_{i^{(t)}} \|l' \boldsymbol{x}_{i}\|^{2}} + \lambda \sqrt{\mathbb{E}_{i^{(1:t-1)}} \|\boldsymbol{w}^{(t)}\|^{2}} \\ \sqrt{\mathbb{E}_{i^{(1:t)}} \|\boldsymbol{w}^{(t+1)}\|^{2}} &\leq (1 - \lambda \eta_{t}) \sqrt{\mathbb{E}_{i^{(1:t-1)}} \|\boldsymbol{w}^{(t)}\|^{2}} + \eta_{t} \sqrt{\mathbb{E}_{i(t)} \|l' \boldsymbol{x}_{i}\|^{2}} \end{split}$$

Why we don't need projection?

Analysis from Lacoste-Julien et.al.[2]

- Classical analysis: $\eta_t = \frac{1}{\lambda t}$
 - $\mathbb{E}f\left(\frac{1}{T}\sum_{t=1}^{T} \boldsymbol{w}^{(t)}\right) f(\boldsymbol{w}^*) \leq \frac{2\mathbb{L}^2 R^2}{\lambda T}(\ln T + 1)$
 - For Hinge loss $\mathbb{L}=1$, the result is same as before.
- New analysis: $\eta_t = \frac{2}{\lambda(t+1)}$
 - $\mathbb{E}f(\frac{2}{T(T+1)}\sum_{t=1}^{T}tw^{(t)}) f(w^*) \leq \frac{8\mathbb{L}^2R^2}{\lambda(T+1)}$
 - $\mathbb{E}_{i(T)}\left[\|\mathbf{w}^{(T+1)} \mathbf{w}^*\|^2\|\mathbf{w}^t\right] \leq \frac{16\mathbb{L}^2R^2}{\lambda^2(T+1)}$
 - In this case, $\overline{w}^{(T)} \doteq \frac{2}{T(T+1)} \sum_{t=1}^{T} t \, \pmb{w}^{(t)}$

Stochastic Dual Coordinate Ascent

Dual problem

$$\max_{\boldsymbol{\alpha} \in \mathbb{R}^n, 0 \leq \alpha_i \leq 1} D(\boldsymbol{\alpha}) := \frac{1}{n} \sum_{i=1}^n \alpha_i - \frac{1}{2\lambda n^2} \sum_{i=1}^n \boldsymbol{\alpha}^T \boldsymbol{Q} \boldsymbol{\alpha}.$$

where

$$\mathbf{Q} \in \mathbb{R}^{n \times n}, \mathbf{Q}_{i,j} = y_i y_j \langle \mathbf{x}_i, \mathbf{x}_j \rangle,$$

Relationship with primal variable:

$$\mathbf{w}(\alpha) := \frac{1}{\lambda n} \sum_{i=1}^{n} \alpha_i y_i \mathbf{x}_i.$$

Traditional SDCA

$$\alpha_i^{(t+1)} = \alpha_i^{(t)} + \delta_i^{(t)} e_i$$

Experiments

- 3 datasets (provided by Joachims)
 - Reuters CCAT (800K examples, 47k features)
 - Covertype (581k examples, 54 features)
 - Physics ArXiv (62k examples, 100k features)
- 4 competing algorithms
 - SVM-Perf (Joachims'06)
 - SVM-light (Joachims)
 - Norma (Kivinen, Smola, Williamson '02)
 - Zhang'04 (stochastic gradient descent)

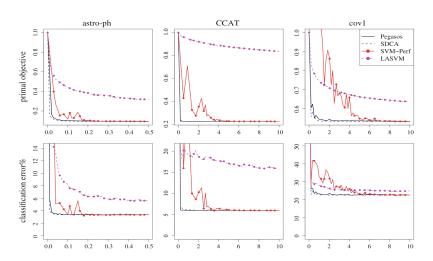
Dataset characteristics

Dataset	Training	Testing	Features	Sparsity(%)	λ
astro-ph	29,882	32,487	99,757	0.08	$5 imes 10^{-5}$
CCAT	781,265	23,149	47,236	0.16	10^{-4}
cov1	522,911	58,101	54	22.22	10^{-6}

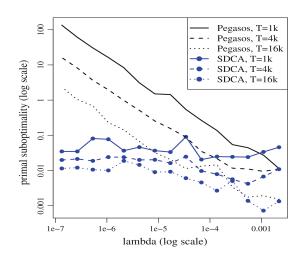
Training runtime and test error

Dataset	Pegasos	SDCA	SVM-Perf	LASVM
astro-ph	0.04s(3.56%)	0.03s(3.49%)	0.1s(3.39%)	54s(3.65%)
CCAT	0.16s(6.16%)	0.36s(6.57%)	3.6s(5.93%)	>18000 s
cov1	0.32s(23.2%)	0.20s(22.9%)	4.2s(23.9%)	210s(23.8%)

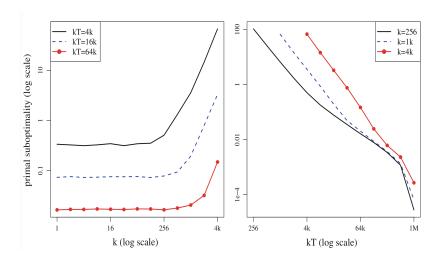
Comparison of linear SVM optimizers



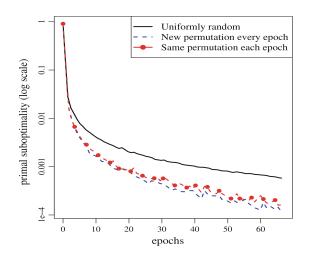
Effect of regularization parameter λ



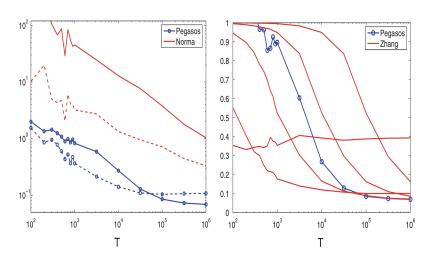
Experiments with the mini-batch variant



Comparison of sampling procedures



Compare to Norma and Zhang (on Physics)



Kernels

The basic Pegasos algorithm can easily be implemented using only kernel evaluations.

- For each t let $\alpha_{t+1} \in R^n$ be the vector such that $\alpha_{t+1}[j]$ counts how many times example j has been selected so far and we had a non-zero loss on it, namely,
 - $\alpha_{t+1}[j] = |t' \leq t : i_{t'} = j \land y_j \langle \mathbf{w}_{t'}, \phi(\mathbf{x}_j) \rangle < 1|.$
- Represent $\mathbf{w}_{t+1} = \frac{1}{\lambda t} \sum_{j=1}^{m} \alpha_{t+1}[j] y_j \phi(\mathbf{x}_j)$
- Cons: overall runtime $\tilde{O}(nd/(\lambda\epsilon))$

Summary

- Pegasos: Simple & Efficient solver for SVM
- Faster convergence rate
 - Choose of different step size
- Extension
 - Bound on ∇f is enough
 - Non-uniform sampling

Reference

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Q&A



Thank You!

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