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# Adaptive Probabilities in Stochastic Optimization Algorithms

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#### Part A

# Non-Uniform Sampling Algorithms

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#### **Problem**

$$f(\mathbf{w}) := \ell(\mathbf{w}) + \lambda r(\mathbf{w}) \tag{1}$$

where

$$\ell(\mathbf{w}) := \frac{1}{n} \sum_{i=1}^{n} \ell(\langle \mathbf{x}_i, \mathbf{w} \rangle, y_i). \tag{2}$$

and

$$r(\mathbf{w}) := \frac{1}{2} \|\mathbf{w}\|_2^2 \tag{3}$$

Here,  $\ell(., y_i) : \mathbb{R} \to \mathbb{R}$  is a loss function and r(.) takes the role of a regularizer.

## **Empirical Risk Minimisation**

 $\min_{\boldsymbol{w} \in \mathbb{R}^n} f(\boldsymbol{w})$ 

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#### **Notations**

- $x_i$ : feature vector of sample i
- y<sub>i</sub>: label of sample i
- $p_i$ : probability that sample i will be selected with  $\sum_{j=1}^{n} p_j = 1$
- $\chi_i$ : subgradient of sample i
- ${m g}_i$ : subgradient of sample i with  ${m g}_i = \frac{\chi_i}{p_i}$
- w: solution of function
- $\eta$ : stepsize for updating

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#### **NonUnifSGD**

#### Algorithm 1: Non-Uniform Stochastic Gradient Discent

```
Input: \lambda > 0, p_i = \frac{\|x_i\|}{\sum_{i=1}^{n} \|x_i\|}, \forall i \in \{1, \dots, n\}.
Data: \{(x_i, y_i)\}_{i=1}^n.
Initialize: w^1 = 0
for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on \boldsymbol{p};
         Set stepsize \eta_t \leftarrow \frac{1}{\lambda_t};
         Set \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \leftarrow \ell'(\langle \boldsymbol{w}^t, \boldsymbol{x}_{i_t} \rangle, y_{i_t}) \boldsymbol{x}_{i_t} + \lambda \nabla r(\boldsymbol{w}^t);
        Set \boldsymbol{g}_{i_t}^t \leftarrow \frac{\chi_{i_t}^t(\boldsymbol{w}^t)}{np_{i_t}};
Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^t - \eta_t \boldsymbol{g}_{i_t}^t;
```

end

Output:  $w^{T+1}$ 

## **Key inequality**

$$\begin{split} & \mathbb{E}[f(\boldsymbol{w}^t)] - f(\boldsymbol{w}^*) \leq \\ & \frac{\eta_t}{2} \mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2] + \frac{1 - \lambda \eta_t}{2\eta_t} \mathbb{E}[\|\boldsymbol{w}^t - \boldsymbol{w}^*\|^2] - \frac{1}{2\eta_t} \mathbb{E}[\|\boldsymbol{w}^{t+1} - \boldsymbol{w}^*\|^2] \end{split}$$

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## **Convergence Theorem**

#### **Theorem**

Suppose f is a  $\lambda$ -strongly convex function. If we choose the stepsize  $\eta_t = \frac{1}{\lambda t}$ , then after T iterations of NonUnifSGD (Algorithm 1) starting with  $\mathbf{w}^1 = \mathbf{0}$ , it holds that

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{\mathbb{E}[\|\boldsymbol{g}_{i_{t}}^{t}\|^{2}]}{t}$$

where  $\mathbf{g}_{i_t}^t = \frac{\chi_{i_t}^t(\mathbf{w}^t)}{np_{i_t}}$  and the expectation is taken with respect to the distribution  $\mathbf{p}$ .

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## **Proof Snapshot**

**Proof** With stepsize  $\eta_t = \frac{1}{\lambda t}$  plugged into (4.6), we have

$$\mathbb{E}[f(\boldsymbol{w}^t)] - f(\boldsymbol{w}^*) \le \frac{1}{2\lambda t} \mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2] + \frac{\lambda(t-1)}{2} \mathbb{E}[\|\boldsymbol{w}^t - \boldsymbol{w}^*\|^2] - \frac{\lambda t}{2} \mathbb{E}[\|\boldsymbol{w}^{t+1} - \boldsymbol{w}^*\|^2]$$
(4.7)

We use convexity of the function f, as given by Jensen's inequality:

$$\mathbb{E}\big[f\bigg(\frac{1}{T}\sum_{t=1}^{T} \boldsymbol{w}^t\bigg)\,\big] - f(\boldsymbol{w}^*) \overset{\textit{Jensen}}{\leq} \mathbb{E}\big[\frac{1}{T}\sum_{t=1}^{T} f(\boldsymbol{w}^t)] - f(\boldsymbol{w}^*)$$

Summing up (4.7) over all steps t = 1...T, we can bound the right hand side of the above inequality

$$=\frac{1}{T}\sum_{t=1}^T\mathbb{E}[f(\boldsymbol{w}^t)]-f(\boldsymbol{w}^*)\leq \frac{1}{T}\sum_{t=1}^T\frac{\mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2]}{2\lambda}\frac{1}{t}-\frac{\lambda}{2}\mathbb{E}[\|\boldsymbol{w}^{T+1}-\boldsymbol{w}^*\|^2]$$

(where we have used the telescoping sum of the norm terms.)

Re-arranging terms, and trivially bounding the left hand side of Jensen's inequality by  $0 \le \mathbb{E}\left[f(\frac{1}{T}\sum_{t=1}^{T} w^t)\right] - f(w^*)$ , we obtain the claimed bound

$$\mathbb{E}[\|m{w}^{T+1} - m{w}^*\|^2] \leq rac{1}{\lambda^2 T} \sum_{t=1}^T rac{\mathbb{E}[\|m{g}_{i_t}^t\|]^2}{t}.$$

#### Two corollaries

#### Definition

Define  $G := \max_{i,t} \{ \| \chi_i^t(\mathbf{w}^t) \|^2 \}$  (i = 1 ... n, t = 1 ... T). Define  $W := \max_{i,t} \{ \mathbb{E}[\| \chi_i^t(\mathbf{w}^t) \|^2 ] \}$  (i = 1 ... n, t = 1 ... T).

#### Corollary

Assume that  $\max_t \{ \| \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \|^2 \} \le G$  for all t.  $\mathbb{E}[\| \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \|^2 ] \le W$  for all t and  $p_i > \epsilon$  for all  $i = \{1, ..., n\}$ ,

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{G}{\epsilon nt} \leq \frac{G(\ln T + 1)}{2\lambda \epsilon nT}$$

$$\mathbb{E}[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{W}{n^{2}\epsilon^{2}t} \leq \frac{W(\ln T + 1)}{2\lambda Tn^{2}\epsilon^{2}}$$

## **Dual of Primal Objective**

$$\max_{\alpha \in \mathbb{R}^n} D(\alpha) := \frac{1}{n} \sum_{i=1}^n -\ell_i^*(-\alpha_i) - \lambda r^*(\mathbf{v}(\alpha)). \tag{4}$$

The relationship between primal variable  $oldsymbol{w}$  and dual variable lpha is

$$\mathbf{w}(\alpha) := \nabla r^*(\mathbf{v}(\alpha)), \mathbf{v}(\alpha) := \frac{1}{\lambda n} \sum_{i=1}^n \alpha_i \mathbf{x}_i$$
 (5)

where  $\alpha \in \mathbb{R}^n$ .

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#### **NonUnifSDCA**

#### Algorithm 2: Non-Uniform Stochastic Dual Coordinate Ascent

Input: 
$$\lambda > 0$$
,  $p_i = \frac{\|\mathbf{x}_i\|}{\sum_{j=1}^n \|\mathbf{x}_j\|}$ ,  $\forall i \in \{1, \dots, n\}$ .

Data:  $\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^n$ 
Initialize:  $\alpha^1 = \mathbf{0}$ ,  $\mathbf{w}^1 = \mathbf{0}$ .

for  $t = 1, 2, \dots, T$ 
| Sample  $i_t$  from  $\{1, \dots, n\}$  based on  $\mathbf{p}$ ;

Calculate  $\Delta \alpha_{i_t}^t = \arg\max_{\Delta \alpha_{i_t}^t} [-\frac{\lambda n}{2} \|\mathbf{w}^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t \mathbf{x}_{i_t}\|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta \alpha_{i_t}^t))];$ 

Set  $\alpha_{i_t}^{t+1} \leftarrow \alpha_{i_t}^t + \Delta \alpha_{i_t}^t;$ 

Set  $\mathbf{w}^{t+1} \leftarrow \mathbf{w}^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t \mathbf{x}_{i_t};$ 

end

Output:  $w^{T+1}$ 

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#### Part B

# Adaptive Sampling Algorithms

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#### Idea behind SGD

$$\begin{split} & \mathbb{E}[f(\boldsymbol{w}^{t+1})] - \mathbb{E}[f(\boldsymbol{w}^{t})] \\ &= \frac{\eta_{t}}{2}(1 + \lambda \eta_{t})\mathbb{E}[\|\boldsymbol{g}_{i_{t}}^{t}\|^{2}] - \eta_{t}\langle \boldsymbol{\chi}_{i_{t}}^{t}, \nabla \ell(\boldsymbol{w}^{t})\rangle + \lambda \eta_{t}\langle \boldsymbol{w}^{t}, \boldsymbol{\chi}_{i_{t}}^{t}\rangle. \end{split}$$

#### Goal

 $\min \mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2].$ 

$$p_i = \frac{\|\chi_i\|}{\sum_{i=1}^n \|\chi_i\|}.$$
 (6)

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## **Two Updates**

#### Algorithm 3: Aggressive Probability Update

$$\begin{array}{l} \textbf{for } j = 1, \dots, n \\ \mid & \mathsf{Set} \ p_j \leftarrow \frac{c_j}{\sum_{k=1}^n c_k}; \end{array}$$

#### end

#### Algorithm 4: Conservative Probability Update

Set 
$$s \leftarrow \sum_{j=1,...,n,\mathbf{1}_i=0} c_j$$
;  
Set  $c \leftarrow |S|$  where  $S \leftarrow \{j|\mathbf{1}_i=1\}$ ;  
for  $j=1,\ldots,n$   
 $p_j > 0$ ?  $p_j \leftarrow \frac{c_j}{s+c}$ :  $p_j \leftarrow \frac{1}{s+c}$ ;  
end

 $\mathbf{1}_i$  is a indicator function which returns 1 if point i is correctly classified during all the k iterations, otherwise returns 0.

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#### AdaSGD

```
Algorithm 5: AdaSGD (Adaptive Non-Uniform Stochastic Gradient
Discent)
   Input: \lambda > 0
   Data: \{(x_i, y_i)\}_{i=1}^n
   Initialize: w^0 = 0, probabilities
                      p_i = \frac{\|\mathbf{x}_i\|^2 + \sqrt{\lambda}}{\sum_{i=1}^n \|\mathbf{x}_i\|^2 + \sqrt{\lambda}}, c_i = 0, \forall i \in \{1, \dots, n\}.
   for t = 1, 2, ..., T
         Sample i_t from \{1, ..., n\} based on p;
         Set \eta_t \leftarrow \frac{1}{\lambda t};
         Calculate \ell' \leftarrow \ell'(\langle x_i, w^t \rangle, y_i);
         Set \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \leftarrow \ell' \boldsymbol{x}_{i_t} + \lambda \nabla r(\boldsymbol{w}^t);
         if (t-1) \mod n > n-k then
               for i = 1, 2, ..., n
                     Calculate \ell'(\langle x_i, w^t \rangle, y_i);
                     Set \mathbf{x}_i \leftarrow \ell'(\langle \mathbf{x}_i, \mathbf{w}^t \rangle, \mathbf{y}_i) \mathbf{x}_i + \lambda \nabla r(\mathbf{w}^t);
                     Set c_i \leftarrow \max\{c_i, ||x_i||\}:
               end
         end
         if t \mod n = 0 then
               Option I: Run Algorithm 3 (Aggressive Update);
               Option II: Run Algorithm 4 (Conservative Update);
         end
         Set g_{i_t}^t \leftarrow \frac{\chi_{i_t}^t(w^t)}{n p_{i_t}};
         Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^t - \eta_t \boldsymbol{g}_i^t;
  end
```

Output:  $w^{T+1}$ 

#### Idea behind SDCA

#### Definition

Define the gap of point i as

$$\sigma_i^t = \ell(\mathbf{x}_i^\mathsf{T} \mathbf{w}^t) + \ell^*(-\alpha_i^t) + \alpha_i^t \mathbf{x}_i^\mathsf{T} \mathbf{w}^t$$

where  $\mathbf{w}^t$  here is assumed to be the corresponding primal vector for the current  $\alpha^t$ , that is  $\mathbf{w}^t(\alpha^t) := \frac{1}{\lambda n} \sum_{i=1}^n \alpha_i \mathbf{x}_i^t$ .

The duality gap between the primal objective and dual objective at the *t*-th iteration is defined as

$$f(\mathbf{w}^t) - D(\alpha^t) = \frac{1}{n} \sum_{i=1}^n \sigma_i^t.$$

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#### AdaSDCA

```
Algorithm 7: AdaSDCA (Adaptive Non-uniform Stochastic Dual Coordinate Ascent)
```

```
Input: \lambda > 0
Data: \{(x_i, y_i)\}_{i=1}^n
Initialize: \alpha^1 = \mathbf{0}, w^1 = \mathbf{0}, probabilities p_i = \frac{1 + \frac{1}{\lambda n \gamma_i}}{n + \sum_{i=1}^{n} \frac{1}{1 - i}} or
                    p_i = \frac{\|x_i\|}{\sum_{i=1}^n \|x_i\|}, c_i = 0, \forall i \in \{1, \dots, n\}.
for t = 1, 2, ..., T
       Sample i_t from \{1, \ldots, n\} based on p;
       Calculate \Delta \alpha_i^t using following formulas:
       \Delta \alpha_{i_t}^t = \arg \max_{\Delta \alpha_{i_t}^t} \left[ -\frac{\lambda n}{2} \| \boldsymbol{w}^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t \boldsymbol{x}_{i_t} \|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta \alpha_{i_t}^t)) \right];
      Set \alpha_{i_t}^{t+1} \leftarrow \alpha_{i_t}^t + \Delta \alpha_{i_t}^t;
      Set w^{t+1} \leftarrow w^t + \frac{1}{\lambda n} \Delta \alpha_i^t x_i;
       if (t-1) \mod n > n-k then
              for i = 1, 2, ..., n
                    Calculate \sigma_i^t \leftarrow \ell(\mathbf{x}_i^\mathsf{T} \mathbf{w}^t) + l^*(-\alpha_i^t) + \alpha_i^t \langle \mathbf{x}_i, \mathbf{w}^t \rangle;
                Set c_i \leftarrow \max\{c_i, \sigma_i^t\};
              end
       end
       if t \mod n = 0 then
              Option I: Run Algorithm 3 (Aggressive Update);
              Option II: Run Algorithm 4 (Conservative Update);
       end
end
```

Output:  $w^{T+1}$ 

#### Part C

## Discussions and Experiments

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## Cost per epoch and properties of algorithms

Algorithm	cost of an epoch	non-uniform	adaptive
NonUnifSGD	nnz	✓	Х
NonUnifSDCA	nnz	✓	X
AdaSGD	(k+1) nnz	✓	<b>✓</b>
AdaSVRG	nd + k nnz	✓	<b>✓</b>
AdaSDCA	(k+1) nnz	✓	<b>✓</b>
AdaSDCAS	(k+1) nnz	✓	<b>✓</b>
AdaGrad	2nd	×	X
Csiba-AdaSDCA	<i>n</i> nnz	✓	<b>✓</b>
Csiba-AdaSDCA+	2 nnz	✓	<b>✓</b>

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## Datasets for empirical study

Dataset	Training(n)	Test	Features (d)	Sparsity $\left(\frac{nnz}{nd}\right)$
rcv1	20,242	677,399	47,236	0.16%
astro-ph	29,882	32,487	99,757	0.08%

 ${f rcv1}$  is a corpus from Reuters news stories.  ${f astro-ph}$  is astronomy data.

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## **Selected Competing Algorithms**

- NonUnifSGD
- NonUnifSDCA
- AdaSGD
- AdaSVRG
- AdaSDCA
- AdaSDCAS
- AdaGrad
- Csiba-AdaSDCA+

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## Test error with different values of $\lambda$ on dataset

rcv1	1e-2	5e-3	1e-3	5e-4	1e-4
Test Error	0.05160	0.04833	0.04713	0.04913	0.05693
astro-ph	1e-2	5e-3	1e-3	5e-4	1e-4

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## Verifying the convergence of duality gap

Table: Average duality gap at different epochs for  $\lambda = 0.001$ 

#epoch	duality gap on rcv1	duality gap on astro-ph
1	0.0863765	0.0883917
3	0.0105347	6.13163e-03
10	1.7485e-04	3.93673e-05
20	2.21547e-05	6.24779e-07
50	3.12797e-06	6.7474e-10
100	5.47897e-07	1.43083e-12

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## **Performance of Two Updating Algorithms**

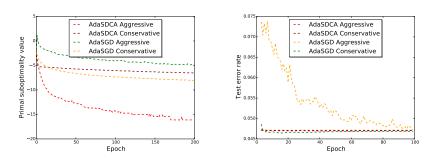


Figure: Comparison of two updating algorithms for AdaSGD and AdaSDCA on rcv1

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## **Different Adaptive Strategies for AdaSDCA**

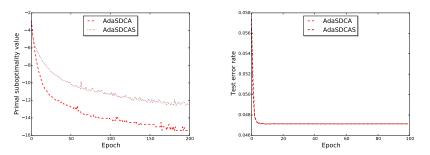


Figure: Comparison of AdaSDCA and AdaSDCAS on rcv1

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## **Comparison of Average Time**

Table: Detailed training time and total running time per epoch

rcv1	Training time(s)	Total running time(s)
AdaSGD	0.04765	0.2059
AdaSDCA	0.05042	0.2064
NonUnifSGD	0.04244	0.1988
NonUnifSDCA	0.04716	0.2037
astro-ph	Training time(s)	Total running time(s)
astro-ph AdaSGD	Training time(s) 0.07236	Total running time(s) 0.1363
	- ( )	• ( /
AdaSGD	0.07236	0.1363

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#### **Performance Metrics**

#### Definition

The **primal sub-optimality** of algorithm is defined as  $P(\mathbf{w}(\alpha)) - P(\mathbf{w}^*)$ .

#### Definition

**Test error** is the error rate on test dataset.

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## **Comparison of Adaptive Algorithms**

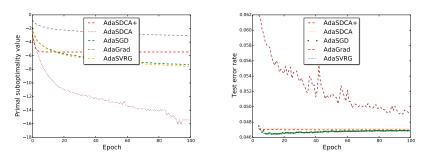


Figure: Comparison of five adaptive algorithms on rcv1

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## Comparison of Adaptive Algorithms cont.

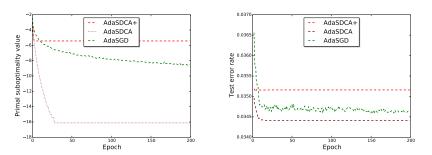


Figure: Comparison of three adaptive algorithms on astro-ph

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## Same Level of Optimality

Table: The number of epochs taken to reach the same level of optimality

rcv1	AdaSDCA	NonUnifSDCA	AdaSGD	NonUnifSGD
#epochs	9	35	210	500
astro-ph	AdaSDCA	NonUnifSDCA	AdaSGD	NonUnifSGD
#epochs	8	28	195	500

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## **Comparison of Time**

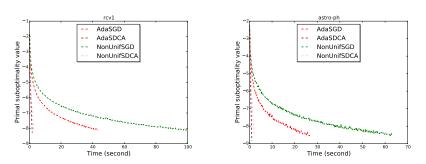


Figure: Comparison of the total running time to reach the same optimality

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## **Comparison of Vector Operation**

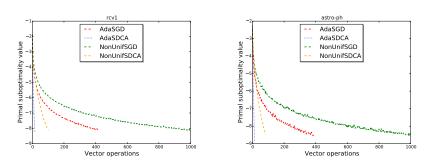


Figure: Comparison of the vector operations taken to reach the same optimality

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## Adaptive vs. Non-Uniform Algorithms

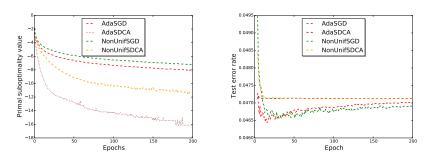


Figure: Comparison of adaptive algorithms with non-adaptive algorithms on rcv1

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## Adaptive vs. Non-Uniform Algorithms cont.

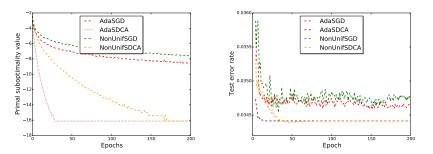


Figure: Comparison of adaptive algorithms with non-adaptive algorithms on astro-ph

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## **Summary**

- We chose  $\lambda = 0.001$  for both rcv1 and astro-ph.
- We compare the performance of Conservative Update and Aggressive Update on AdaSGD and AdaSDCA. Conservative Update works better on AdaSGD while Aggressive Update works better on AdaSDCA.
- AdaSDCA (adaptive algorithm with duality gap) performs better than AdaSDCAS (adaptive algorithm with subgradients).
- AdaSDCA has the best performance among all the adaptive algorithms (AdaSDCA, AdaSGD, AdaSVRG, AdaGrad and AdaSDCA+) and AdaSGD is the second best.

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## **Summary cont.**

- AdaSVRG achieves a slightly better performance per epoch than AdaSGD but sacrifices the running time on sparse datasets.
- To reach the same optimality given by 500 epochs run on NonUnifSGD, AdaSGD takes only around 200 epochs, whereas NonUnifSDCA takes around 30 which is three times more than AdaSDCA does.

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## Q&A



## Thank You!

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