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Adaptive Probabilities in Stochastic Optimization Algorithms

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Part A

Non-Uniform Sampling Algorithms

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Problem

$$f(\mathbf{w}) := \ell(\mathbf{w}) + \lambda r(\mathbf{w}) \tag{1}$$

where

$$\ell(\mathbf{w}) := \frac{1}{n} \sum_{i=1}^{n} \ell(\langle \mathbf{x}_i, \mathbf{w} \rangle, y_i). \tag{2}$$

and

$$r(\mathbf{w}) := \frac{1}{2} \|\mathbf{w}\|_2^2 \tag{3}$$

Here, $\ell(., y_i) : \mathbb{R} \to \mathbb{R}$ is a loss function and r(.) takes the role of a regularizer.

Empirical Risk Minimization

 $\min_{\boldsymbol{w} \in \mathbb{R}^n} f(\boldsymbol{w})$

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Notations

- x_i: feature vector of sample i
- y_i : label of sample i
- p_i : probability that sample i will be selected with $\sum_{j=1}^{n} p_j = 1$
- χ_i : subgradient of sample i
- \mathbf{g}_i : subgradient of sample i with $\mathbf{g}_i = \frac{\chi_i}{n\mathbf{p}_i}$
- w: solution of objective function
- η : stepsize for updating w

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NonUnifSGD

Algorithm 1: Non-Uniform Stochastic Gradient Discent

```
Input: \lambda > 0, p_i = \frac{\|x_i\|}{\sum_{i=1}^{n} \|x_i\|}, \forall i \in \{1, \dots, n\}.
Data: \{(x_i, y_i)\}_{i=1}^n.
Initialize: w^1 = 0
for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on \boldsymbol{p};
         Set stepsize \eta_t \leftarrow \frac{1}{\lambda_t};
         Set \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \leftarrow \ell'(\langle \boldsymbol{w}^t, \boldsymbol{x}_{i_t} \rangle, y_{i_t}) \boldsymbol{x}_{i_t} + \lambda \nabla r(\boldsymbol{w}^t);
        Set \boldsymbol{g}_{i_t}^t \leftarrow \frac{\chi_{i_t}^t(\boldsymbol{w}^t)}{np_{i_t}};
Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^t - \eta_t \boldsymbol{g}_{i_t}^t;
```

end

Output: w^{T+1}

Key inequality

Taking the expectation over the random sampling at each step, we have the following bound:

$$\begin{split} \mathbb{E}[f(\boldsymbol{w}^t)] - f(\boldsymbol{w}^*) &\leq \frac{\eta_t}{2} \mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2] \\ &+ \frac{1 - \lambda \eta_t}{2\eta_t} \mathbb{E}[\|\boldsymbol{w}^t - \boldsymbol{w}^*\|^2] - \frac{1}{2\eta_t} \mathbb{E}[\|\boldsymbol{w}^{t+1} - \boldsymbol{w}^*\|^2] \end{split}$$

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Convergence Theorem

Theorem

Suppose f is a λ -strongly convex function. If we choose the stepsize $\eta_t = \frac{1}{\lambda t}$, then after T iterations of NonUnifSGD (Algorithm 1) starting with $\mathbf{w}^1 = \mathbf{0}$, it holds that

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{\mathbb{E}[\|\boldsymbol{g}_{i_{t}}^{t}\|^{2}]}{t}$$

where $\mathbf{g}_{i_t}^t = \frac{\chi_{i_t}^t(\mathbf{w}^t)}{np_{i_t}}$ and the expectation is taken with respect to the distribution \mathbf{p} .

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Proof Snapshot

Proof With stepsize $\eta_t = \frac{1}{\lambda t}$ plugged into (4.6), we have

$$\mathbb{E}[f(\boldsymbol{w}^t)] - f(\boldsymbol{w}^*) \le \frac{1}{2\lambda t} \mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2] + \frac{\lambda(t-1)}{2} \mathbb{E}[\|\boldsymbol{w}^t - \boldsymbol{w}^*\|^2] - \frac{\lambda t}{2} \mathbb{E}[\|\boldsymbol{w}^{t+1} - \boldsymbol{w}^*\|^2]$$
(4.7)

We use convexity of the function f, as given by Jensen's inequality:

$$\mathbb{E}\big[f\bigg(\frac{1}{T}\sum_{t=1}^{T} \boldsymbol{w}^t\bigg)\,\big] - f(\boldsymbol{w}^*) \overset{\textit{Jensen}}{\leq} \mathbb{E}\big[\frac{1}{T}\sum_{t=1}^{T} f(\boldsymbol{w}^t)] - f(\boldsymbol{w}^*)$$

Summing up (4.7) over all steps t = 1...T, we can bound the right hand side of the above inequality

$$= \frac{1}{T} \sum_{t=1}^{T} \mathbb{E}[f(\boldsymbol{w}^{t})] - f(\boldsymbol{w}^{*}) \leq \frac{1}{T} \sum_{t=1}^{T} \frac{\mathbb{E}[\|g_{t_{t}}^{t}\|^{2}]}{2\lambda} \frac{1}{t} - \frac{\lambda}{2} \mathbb{E}[\|\boldsymbol{w}^{T+1} - \boldsymbol{w}^{*}\|^{2}]$$

(where we have used the telescoping sum of the norm terms.)

Re-arranging terms, and trivially bounding the left hand side of Jensen's inequality by $0 \le \mathbb{E}\left[f(\frac{1}{T}\sum_{t=1}^{T} \boldsymbol{w}^{t})\right] - f(\boldsymbol{w}^{*})$, we obtain the claimed bound

$$\mathbb{E}[\|m{w}^{T+1} - m{w}^*\|^2] \leq rac{1}{\lambda^2 T} \sum_{t=1}^T rac{\mathbb{E}[\|m{g}_{i_t}^t\|]^2}{t}.$$

Two corollaries

Definition

Define $G := \max_{i,t} \{ \| \chi_i^t(\mathbf{w}^t) \|^2 \}$ (i = 1 ... n, t = 1 ... T). Define $W := \max_{i,t} \{ \mathbb{E}[\| \chi_i^t(\mathbf{w}^t) \|^2] \}$ (i = 1 ... n, t = 1 ... T).

Corollary

Assume that $\max_t \{ \| \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \|^2 \} \le G$ for all t. $\mathbb{E}[\| \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \|^2] \le W$ for all t and $p_i > \epsilon$ for all $i = \{1, ..., n\}$,

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{G}{\epsilon nt} \leq \frac{G(\ln T + 1)}{2\lambda \epsilon nT}$$

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{W}{n^{2}\epsilon^{2}t} \leq \frac{W(\ln T + 1)}{2\lambda Tn^{2}\epsilon^{2}}$$

Dual Problem

Dual Objective Function

$$\max_{\boldsymbol{\alpha} \in \mathbb{R}^n} D(\boldsymbol{\alpha}) := \frac{1}{n} \sum_{i=1}^n -\ell_i^*(-\alpha_i) - \lambda r^*(\boldsymbol{v}(\boldsymbol{\alpha})).$$

The relationship between primal variable ${m w}$ and dual variable ${m lpha}$ is

$$\boldsymbol{w}(\alpha) := \nabla r^*(\boldsymbol{v}(\alpha)), \boldsymbol{v}(\alpha) := \frac{1}{\lambda n} \sum_{i=1}^n \alpha_i \boldsymbol{x}_i$$

where $\alpha \in \mathbb{R}^n$.

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NonUnifSDCA

Algorithm 2: Non-Uniform Stochastic Dual Coordinate Ascent

Input:
$$\lambda > 0$$
, $p_i = \frac{\|\mathbf{x}_i\|}{\sum_{j=1}^n \|\mathbf{x}_j\|}$, $\forall i \in \{1, \dots, n\}$.

Data: $\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^n$
Initialize: $\alpha^1 = \mathbf{0}$, $\mathbf{w}^1 = \mathbf{0}$.

for $t = 1, 2, \dots, T$
| Sample i_t from $\{1, \dots, n\}$ based on \mathbf{p} ;

Calculate $\Delta \alpha_{i_t}^t = \arg\max_{\Delta \alpha_{i_t}^t} [-\frac{\lambda n}{2} \|\mathbf{w}^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t \mathbf{x}_{i_t}\|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta \alpha_{i_t}^t))];$

Set $\alpha_{i_t}^{t+1} \leftarrow \alpha_{i_t}^t + \Delta \alpha_{i_t}^t;$

Set $\mathbf{w}^{t+1} \leftarrow \mathbf{w}^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t \mathbf{x}_{i_t};$

end

Output: w^{T+1}

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Part B

Adaptive Sampling Algorithms

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Idea behind SGD

$$\begin{split} \mathbb{E}[f(\boldsymbol{w}^{t+1})] - \mathbb{E}[f(\boldsymbol{w}^{t})] \\ &= \frac{\eta_{t}}{2}(1 + \lambda \eta_{t})\mathbb{E}[\|\boldsymbol{g}_{i_{t}}^{t}\|^{2}] - \eta_{t}\langle \boldsymbol{\chi}_{i_{t}}^{t}, \nabla \ell(\boldsymbol{w}^{t})\rangle + \lambda \eta_{t}\langle \boldsymbol{w}^{t}, \boldsymbol{\chi}_{i_{t}}^{t}\rangle. \\ & \min \mathbb{E}[\|\boldsymbol{g}_{i_{t}}^{t}\|^{2}] \stackrel{\textit{solution}}{\longrightarrow} \rho_{i} = \frac{\|\boldsymbol{\chi}_{i}\|}{\sum_{i=1}^{n} \|\boldsymbol{\chi}_{i}\|}. \end{split}$$

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Two Updates

Algorithm 3: Aggressive Probability Update

$$\begin{array}{l} \textbf{for } j = 1, \dots, n \\ \mid & \mathsf{Set} \ p_j \leftarrow \frac{c_j}{\sum_{k=1}^n c_k}; \end{array}$$

end

Algorithm 4: Conservative Probability Update

Set
$$s \leftarrow \sum_{j=1,\dots,n,\mathbf{1}_i=0} c_j$$
;
Set $c \leftarrow |S|$ where $S \leftarrow \{j|\mathbf{1}_i=1\}$;
for $j=1,\dots,n$
 $p_j > 0$? $p_j \leftarrow \frac{c_j}{s+c}$: $p_j \leftarrow \frac{1}{s+c}$;
end

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 $[\]mathbf{1}_i$ is a indicator function which returns 1 if point i is correctly classified during all the k iterations, otherwise returns 0.

AdaSGD

```
Algorithm 5: AdaSGD (Adaptive Non-Uniform Stochastic Gradient
Discent)
   Input: \lambda > 0
   Data: \{(x_i, y_i)\}_{i=1}^n
   Initialize: w^0 = 0, probabilities
                       p_i = \frac{\|\mathbf{x}_i\|^2 + \sqrt{\lambda}}{\sum_{i=1}^n \|\mathbf{x}_i\|^2 + \sqrt{\lambda}}, c_i = 0, \forall i \in \{1, \dots, n\}.
   for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on p;
         Set \eta_t \leftarrow \frac{1}{\lambda t};
         Calculate \ell' \leftarrow \ell'(\langle x_i, w^t \rangle, y_i);
         Set \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \leftarrow \ell' \boldsymbol{x}_{i_t} + \lambda \nabla r(\boldsymbol{w}^t);
        if (t-1) mod n > n-k then
               for i = 1, 2, ..., n
                     Calculate \ell'(\langle x_i, w^t \rangle, y_i);
                     Set \mathbf{x}_i \leftarrow \ell'(\langle \mathbf{x}_i, \mathbf{w}^t \rangle, \mathbf{y}_i) \mathbf{x}_i + \lambda \nabla r(\mathbf{w}^t);
                     Set c_i \leftarrow \max\{c_i, \|\boldsymbol{\chi}_i\|\};
               end
         end
         if t \mod n = 0 then
               Option I: Run Algorithm 3 (Aggressive Update);
               Option II: Run Algorithm 4 (Conservative Update);
        end
         Set g_{i_t}^t \leftarrow \frac{\chi_{i_t}^t(w^t)}{nv_{i_t}};
         Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^{t} - \eta_{t} \boldsymbol{g}_{i}^{t};
```

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end

Output: w^{T+1}

AdaSVRG

We add a $\tilde{\boldsymbol{w}}$ (which denotes the \boldsymbol{w} of last epoch) for a new update equation. Therefore, we get

$$\boldsymbol{w}^{t+1} := \boldsymbol{w}^t - \eta_t[\boldsymbol{g}_{i_t}^t(\boldsymbol{w}^t) - \boldsymbol{g}_{i_t}^t(\tilde{\boldsymbol{w}}) - \nabla f(\tilde{\boldsymbol{w}})]$$

The expectation of the update function is still the same as before, because

$$\mathbb{E}[\boldsymbol{g}(\boldsymbol{w}) - \boldsymbol{g}(\tilde{\boldsymbol{w}}) + \nabla f(\tilde{\boldsymbol{w}})] = \mathbb{E}[\boldsymbol{g}(\boldsymbol{w})] - \mathbb{E}[\boldsymbol{g}(\tilde{\boldsymbol{w}})] + \nabla f(\tilde{\boldsymbol{w}}) = \nabla f(\boldsymbol{w}).$$

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Idea behind SDCA

Definition

Define the gap of point i as

$$\sigma_i^t = \ell(\boldsymbol{x}_i^\intercal \boldsymbol{w}^t) + \ell^*(-\alpha_i^t) + \alpha_i^t \boldsymbol{x}_i^\intercal \boldsymbol{w}^t$$

where \mathbf{w}^t here is assumed to be the corresponding primal vector for the current α^t , that is $\mathbf{w}^t(\alpha^t) := \frac{1}{\lambda n} \sum_{i=1}^n \alpha_i \mathbf{x}_i^t$.

The **duality gap** between the primal objective and dual objective at the t-th iteration is defined as

$$f(\mathbf{w}^t) - D(\alpha^t) = \frac{1}{n} \sum_{i=1}^n \sigma_i^t.$$

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AdaSDCA

```
Algorithm 7: AdaSDCA (Adaptive Non-uniform Stochastic Dual Coor-
dinate Ascent)
  Input: \lambda > 0
   Data: \{(x_i, y_i)\}_{i=1}^n
  Initialize: \alpha^1 = 0, w^1 = 0, probabilities p_i = \frac{1 + \frac{1}{\lambda_{n_{T_i}}}}{n + \sum_{i=1}^{n} \frac{1}{\lambda_{n_{T_i}}}} or
                     p_i = \frac{\|x_i\|}{\sum_{i=1}^n \|x_i\|}, c_i = 0, \forall i \in \{1, \dots, n\}.
   for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on p;
         Calculate \Delta \alpha_i^t using following formulas:
         \Delta\alpha_{i_t}^t = \arg\max_{\Delta\alpha_{i_t}^t} [-\frac{\lambda n}{2} \| \boldsymbol{w}^t + \frac{1}{\lambda n} \Delta\alpha_{i_t}^t \boldsymbol{x}_{i_t} \|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta\alpha_{i_t}^t))];
        Set \alpha_{i}^{t+1} \leftarrow \alpha_{i_t}^t + \Delta \alpha_{i_t}^t;
        Set w^{t+1} \leftarrow w^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t x_{i_t};
         if (t-1) mod n > n-k then
               for i = 1, 2, ..., n
                     Calculate \sigma_i^t \leftarrow \ell(\mathbf{x}_i^\mathsf{T} \mathbf{w}^t) + l^*(-\alpha_i^t) + \alpha_i^t \langle \mathbf{x}_i, \mathbf{w}^t \rangle;
                   Set c_i \leftarrow \max\{c_i, \sigma_i^t\};
               end
         end
         if t \mod n = 0 then
               Option I: Run Algorithm 3 (Aggressive Update);
               Option II: Run Algorithm 4 (Conservative Update);
         end
```

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end

Output: w^{T+1}

AdaSDCAS

```
Algorithm 8: AdaSDCAS (Adaptive Non-uniform Stochastic Dual Coordinate Ascent by Subgradient)
```

```
Input: \lambda > 0
Data: \{(x_i, y_i)\}_{i=1}^n
Initialize: \alpha^1 = \mathbf{0}, w^1 = \mathbf{0}, probabilities p_i = \frac{1 + \frac{1}{\lambda n \gamma_i}}{n + \sum_{i=1}^n \frac{1}{\lambda n \gamma_i}} or
                     p_i = \frac{\|x_i\|}{\sum_{i=1}^n \|x_i\|}, c_i = 0, \forall i \in \{1, \ldots, n\}.
for t = 1, 2, ..., T
       Sample i_t from \{1, ..., n\} based on p;
       Calculate \Delta \alpha_i^t using following formulas:
       \Delta \alpha_{i_t}^t = \arg \max_{\Delta \alpha_{i_t}^t} \left[ -\frac{\lambda n}{2} \| w^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t x_{i_t} \|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta \alpha_{i_t}^t)) \right];
      Set \alpha_{i_i}^{t+1} \leftarrow \alpha_{i_i}^t + \Delta \alpha_{i_i}^t;
      Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^t + \frac{1}{\lambda_n} \Delta \alpha_{i_*}^t \boldsymbol{x}_{i_*};
       if (t-1) \mod n > n-k then
              for i = 1, 2, ..., n
| Calculate \ell'(\langle x_i, w^t \rangle, y_i);
                  Set \chi_i^t \leftarrow \ell'(\langle x_i, w^t \rangle, y_i) x_i + \lambda \nabla r(w^t);
Record c_i \leftarrow \max\{c_i, \|\chi_i^t\|\};
        end
       if t \mod n = 0 then
              Option I: Run Algorithm 3 (Aggressive Update);
              Option II: Run Algorithm 4 (Conservative Update);
       end
end
```

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Part C

Discussions and Experiments

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Datasets for empirical study

Dataset	Training(n)	Test	Features (d)	Sparsity $\left(\frac{nnz}{nd}\right)$
rcv1	20,242	677,399	47,236	0.16%
astro-ph	29,882	32,487	99,757	0.08%

- rcv1 is a corpus from Reuters news stories.
- astro-ph is astronomy data.

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Cost per epoch and properties of algorithms

Algorithm	cost of an epoch	non-uniform	adaptive
NonUnifSGD	nnz	✓	Х
NonUnifSDCA	nnz	✓	Х
AdaSGD	(k+1) nnz	✓	✓
AdaSVRG	nd + k nnz	✓	✓
AdaSDCA	(k+1) nnz	✓	✓
AdaSDCAS	(k+1) nnz	✓	✓
AdaGrad (by Duchi)	2nd	×	Х
AdaSDCA (by Csiba)	<i>n</i> nnz	✓	✓
AdaSDCA+ (by Csiba)	2 nnz	✓	✓

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Test Error with Different Values of λ

rcv1	1e-2	5e-3	1e-3	5e-4	1e-4
Test Error	0.05160	0.04833	0.04713	0.04913	0.05693
	1	ı			
astro-ph	1e-2	5e-3	1e-3	5e-4	1e-4

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Verifying the Convergence of Duality Gap

Table: Average duality gap at different epochs for $\lambda = 0.001$

#epoch	duality gap on rcv1	duality gap on astro-ph
1	0.0863765	0.0883917
3	0.0105347	6.13163e-03
10	1.7485e-04	3.93673e-05
20	2.21547e-05	6.24779e-07
50	3.12797e-06	6.7474e-10
100	5.47897e-07	1.43083e-12

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Performance Metrics

Definition

The **primal sub-optimality** of algorithm is defined as $P(\mathbf{w}(\alpha)) - P(\mathbf{w}^*)$.

Definition

Test error is the error rate on test dataset.

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Performance of Two Updating Algorithms

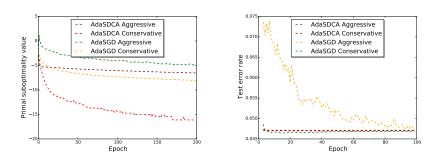


Figure: Comparison of two updating algorithms for AdaSGD and AdaSDCA on rcv1

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Different Adaptive Strategies for AdaSDCA

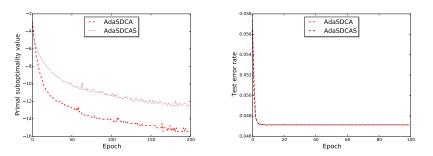


Figure: Comparison of AdaSDCA and AdaSDCAS on rcv1

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Comparison of Average Time

Table: Detailed training time and total running time per epoch

rcv1	Training time(s)	Total running time(s)
AdaSGD	0.04765	0.2059
AdaSDCA	0.05042	0.2064
NonUnifSGD	0.04244	0.1988
NonUnifSDCA	0.04716	0.2037
astro-ph	Training time(s)	Total running time(s)
AdaSGD	0.07236	0.1363
AdaSDCA	0.07050	0.1343
NonUnifSGD	0.06284	0.1259
NonUnifSDCA	0.07054	0.1339

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Comparison of Adaptive Algorithms

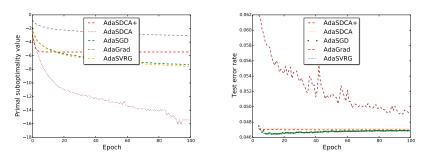


Figure: Comparison of five adaptive algorithms on rcv1

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Comparison of Adaptive Algorithms cont.

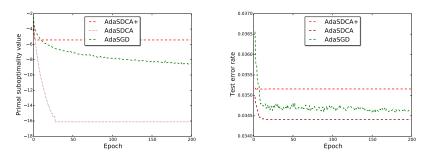


Figure: Comparison of three adaptive algorithms on astro-ph

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Same Level of Optimality

Table: The number of epochs taken to reach the same level of optimality

rcv1	AdaSDCA	NonUnifSDCA	AdaSGD	NonUnifSGD
#epochs	9	35	210	500
astro-ph	AdaSDCA	NonUnifSDCA	AdaSGD	NonUnifSGD
#epochs	0	28	195	500

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Comparison of Time

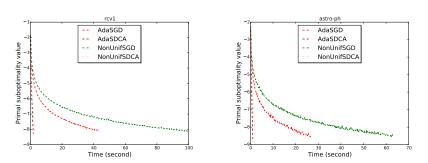


Figure: Comparison of the total running time to reach the same optimality

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Comparison of Vector Operation

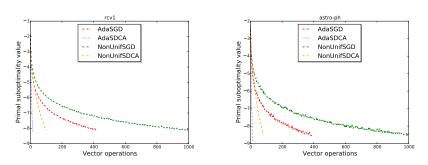


Figure: Comparison of the vector operations taken to reach the same optimality

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Adaptive vs. Non-Uniform Algorithms

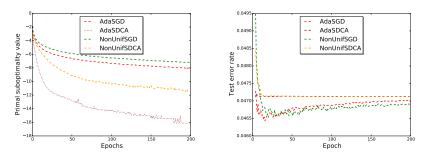


Figure: Comparison of adaptive algorithms with non-adaptive algorithms on rcv1

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Adaptive vs. Non-Uniform Algorithms cont.

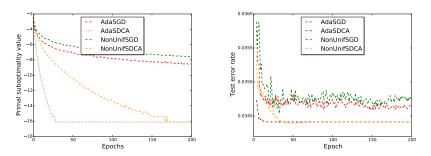


Figure: Comparison of adaptive algorithms with non-adaptive algorithms on astro-ph

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Summary

- We chose $\lambda = 0.001$ for both rcv1 and astro-ph.
- We compare the performance of Conservative Update and Aggressive Update on AdaSGD and AdaSDCA. Conservative Update works better on AdaSGD while Aggressive Update works better on AdaSDCA.
- AdaSDCA (adaptive algorithm with duality gap) performs better than AdaSDCAS (adaptive algorithm with subgradients).
- AdaSDCA has the best performance among all the adaptive algorithms (AdaSDCA, AdaSGD, AdaSVRG, AdaGrad and AdaSDCA+) and AdaSGD is the second best.

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Summary cont.

- AdaSVRG achieves a slightly better performance per epoch than AdaSGD but sacrifices the running time on sparse datasets.
- To reach the same optimality given by 500 epochs run on NonUnifSGD, AdaSGD takes only around 200 epochs, whereas NonUnifSDCA takes around 30 which is three times more than AdaSDCA does.

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Q&A



Thank You!

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