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Adaptive Probabilities in Stochastic Optimization Algorithms

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Part A

Non-Uniform Sampling Algorithms

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Problem

Empirical Risk Minimization

$$\min_{\boldsymbol{w} \in \mathbb{R}^n} f(\boldsymbol{w})$$

$$f(\mathbf{w}) := \ell(\mathbf{w}) + \lambda r(\mathbf{w}) \tag{1}$$

where

$$\ell(\mathbf{w}) := \frac{1}{n} \sum_{i=1}^{n} \ell(\langle \mathbf{x}_i, \mathbf{w} \rangle, y_i). \tag{2}$$

and

$$r(\mathbf{w}) := \frac{1}{2} \|\mathbf{w}\|_2^2 \tag{3}$$

Here, $\ell(., y_i) : \mathbb{R} \to \mathbb{R}$ is a loss function and r(.) takes the role of a regularizer.

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Notations

- x_i: feature vector of sample i
- y_i: label of sample i
- p_i : probability that sample i will be selected with $\sum_{i=1}^{n} p_i = 1$
- w: solution of objective function
- η : stepsize for updating \boldsymbol{w}
- χ_i : subgradient of sample i
- \mathbf{g}_i : weighted subgradient of sample i with $\mathbf{g}_i = \frac{\chi_i}{np_i}$ and $\mathbb{E}[\mathbf{g}(\mathbf{w})] = \nabla f(\mathbf{w})$

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NonUnifSGD

Algorithm 1: Non-Uniform Stochastic Gradient Discent

```
Input: \lambda > 0, p_i = \frac{\|x_i\|}{\sum_{i=1}^{n} \|x_i\|}, \forall i \in \{1, \dots, n\}.
Data: \{(x_i, y_i)\}_{i=1}^n.
Initialize: w^1 = 0
for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on \boldsymbol{p};
         Set stepsize \eta_t \leftarrow \frac{1}{\lambda_t};
         Set \chi_{i_t}^t(\mathbf{w}^t) \leftarrow \ell'(\langle \mathbf{w}^t, \mathbf{x}_{i_t} \rangle, y_{i_t}) \mathbf{x}_{i_t} + \lambda \nabla r(\mathbf{w}^t);
       Set \boldsymbol{g}_{i_t}^t \leftarrow \frac{\chi_{i_t}^t(\boldsymbol{w}^t)}{np_{i_t}};
Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^t - \eta_t \boldsymbol{g}_{i_t}^t;
```

end

Output: w^{T+1}

Convergence Theorem

Theorem

Suppose f is a λ -strongly convex function. If we choose the stepsize $\eta_t = \frac{1}{\lambda t}$, then after T iterations of NonUnifSGD (Algorithm 1) starting with $\mathbf{w}^1 = \mathbf{0}$, it holds that

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{\mathbb{E}[\|\boldsymbol{g}_{i_{t}}^{t}\|^{2}]}{t}$$

where $\mathbf{g}_{i_t}^t = \frac{\chi_{i_t}^t(\mathbf{w}^t)}{np_{i_t}}$ and the expectation is taken with respect to the distribution \mathbf{p} .

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Two corollaries

Definition

Define $G:=\max_{i,t}\{\|\boldsymbol{\chi}_i^t(\boldsymbol{w}^t)\|^2\}$ $(i=1\dots n,\ t=1\dots T).$

Define $W := \max_{i,t} \{ \mathbb{E}[\| \chi_i^t(\mathbf{w}^t) \|^2] \}$ (i = 1 ... n, t = 1 ... T).

Corollary

Assume that $\max_t \{ \|\boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t)\|^2 \} \leq G$ or $\mathbb{E}[\|\boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t)\|^2] \leq W$ for all t and $p_i > \epsilon$ for all $i = \{1, \dots, n\}$,

$$\mathbb{E}\left[f\left(\frac{1}{T}\sum_{t=1}^{T}\boldsymbol{w}^{t}\right)\right] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T}\frac{G}{\epsilon nt} \leq \frac{G(\ln T + 1)}{2\lambda \epsilon nT}or$$

$$\mathbb{E}[f\left(\frac{1}{T}\sum_{t=1}^{T} \boldsymbol{w}^{t}\right)] - f(\boldsymbol{w}^{*}) \leq \frac{1}{2\lambda T}\sum_{t=1}^{T} \frac{W}{n^{2}\epsilon^{2}t} \leq \frac{W(\ln T + 1)}{2\lambda Tn^{2}\epsilon^{2}}$$

Another Theorem for SGD

Theorem

Suppose f is a λ -strongly convex function. If we choose the stepsize $\eta_t = \frac{2}{\lambda(t+1)}$, then after T iterations of NonUnifSGD (Algorithm 1) with starting point $\mathbf{w}^1 = \mathbf{0}$, it holds that the weighted average of the iterates satisfies

$$\mathbb{E}\big[f(\frac{2}{T(T+1)}\sum_{t=1}^{T}t\boldsymbol{w}^t)\big] - f(\boldsymbol{w}^*) \leq \frac{2}{\lambda(T+1)}\max_{t}\mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2]$$

where $\mathbf{g}_{i_t}^t = \frac{\chi_{i_t}^t(\mathbf{w}^t)}{np_{i_t}}$, and the expectation is taken with respect to the distribution \mathbf{p} .

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Dual Problem

Dual Objective Function

$$\max_{\boldsymbol{\alpha} \in \mathbb{R}^n} D(\boldsymbol{\alpha}) := \frac{1}{n} \sum_{i=1}^n -\ell_i^*(-\alpha_i) - \lambda r^*(\boldsymbol{v}(\boldsymbol{\alpha})).$$

The relationship between primal variable ${m w}$ and dual variable ${m lpha}$ is

$$\mathbf{w}(\alpha) := \nabla r^*(\mathbf{v}(\alpha)), \mathbf{v}(\alpha) := \frac{1}{\lambda n} \sum_{i=1}^n \alpha_i \mathbf{x}_i$$

where $\alpha \in \mathbb{R}^n$.

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NonUnifSDCA

Algorithm 2: Non-Uniform Stochastic Dual Coordinate Ascent

end

Output: w^{T+1}

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Part B

Adaptive Sampling Algorithms

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Idea behind SGD

According to the SGD theorem, we can reduce the convergence rate by solving the following optimization problem:

$$\min \mathbb{E}[\|oldsymbol{g}_{i_t}^t\|^2].$$

By the Cauchy-Schwarz inequality and the fact that $\sum_{i=1}^{n} p_i = 1$,

$$\mathbb{E}[\|\boldsymbol{g}_{i_t}^t\|^2] = \sum_{i=1}^n \frac{\|\chi_i\|^2}{n^2 p_i} = (\sum_{i=1}^n \frac{\|\chi_i\|^2}{n^2 p_i})(\sum_{i=1}^n p_i) \ge (\sum_{i=1}^n \frac{\|\chi_i\|}{n})^2.$$

The above inequality holds when

$$p_i = \frac{\|\boldsymbol{\chi}_i\|}{\sum_{j=1}^n \|\boldsymbol{\chi}_i\|}.$$

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AdaSGD

```
Algorithm 5: AdaSGD (Adaptive Non-Uniform Stochastic Gradient
Discent)
   Input: \lambda > 0
   Data: \{(x_i, y_i)\}_{i=1}^n
   Initialize: w^0 = 0, probabilities
                      p_i = \frac{\|\mathbf{x}_i\|^2 + \sqrt{\lambda}}{\sum_{i=1}^n \|\mathbf{x}_i\|^2 + \sqrt{\lambda}}, c_i = 0, \forall i \in \{1, \dots, n\}.
   for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on p;
         Set \eta_t \leftarrow \frac{1}{\lambda t};
         Calculate \ell' \leftarrow \ell'(\langle x_i, w^t \rangle, y_i);
         Set \boldsymbol{\chi}_{i_t}^t(\boldsymbol{w}^t) \leftarrow \ell' \boldsymbol{x}_{i_t} + \lambda \nabla r(\boldsymbol{w}^t);
        if (t-1) mod n > n-k then
               for i = 1, 2, ..., n
                     Calculate \ell'(\langle x_i, w^t \rangle, y_i);
                     Set \mathbf{x}_i \leftarrow \ell'(\langle \mathbf{x}_i, \mathbf{w}^t \rangle, \mathbf{y}_i) \mathbf{x}_i + \lambda \nabla r(\mathbf{w}^t);
                     Set c_i \leftarrow \max\{c_i, \|\boldsymbol{\chi}_i\|\};
               end
         end
         if t \mod n = 0 then
               Option I: Run Algorithm 3 (Aggressive Update);
               Option II: Run Algorithm 4 (Conservative Update);
        end
         Set g_{i_t}^t \leftarrow \frac{\chi_{i_t}^t(w^t)}{nv_{i_t}};
         Set \mathbf{w}^{t+1} \leftarrow \mathbf{w}^t - \eta_t \mathbf{g}_{i}^t;
  end
```

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Output: w^{T+1}

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Two Updates

Algorithm 3: Aggressive Probability Update

$$\begin{array}{l} \textbf{for } j = 1, \dots, n \\ \mid & \mathsf{Set} \ p_j \leftarrow \frac{c_j}{\sum_{k=1}^n c_k}; \end{array}$$

end

Algorithm 4: Conservative Probability Update

Set
$$s \leftarrow \sum_{j=1,\dots,n,\mathbf{1}_i=0} c_j$$
;
Set $c \leftarrow |S|$ where $S \leftarrow \{j|\mathbf{1}_i=1\}$;
for $j=1,\dots,n$
 $p_j > 0$? $p_j \leftarrow \frac{c_j}{s+c}$: $p_j \leftarrow \frac{1}{s+c}$;
end

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 $[\]mathbf{1}_i$ is a indicator function which returns 1 if point i is correctly classified during all the k iterations, otherwise returns 0.

AdaSVRG

We add a $\tilde{\boldsymbol{w}}$ (which denotes the \boldsymbol{w} of last epoch) for a new update equation. Therefore, we get

$$\boldsymbol{w}^{t+1} := \boldsymbol{w}^t - \eta_t [\boldsymbol{g}_{i_t}^t(\boldsymbol{w}^t) - \boldsymbol{g}_{i_t}^t(\tilde{\boldsymbol{w}}) - \nabla f(\tilde{\boldsymbol{w}})]$$

The expectation of the update function is still the same as before, because

$$\mathbb{E}[\boldsymbol{g}(\boldsymbol{w}) - \boldsymbol{g}(\tilde{\boldsymbol{w}}) + \nabla f(\tilde{\boldsymbol{w}})] = \mathbb{E}[\boldsymbol{g}(\boldsymbol{w})] - \mathbb{E}[\boldsymbol{g}(\tilde{\boldsymbol{w}})] + \nabla f(\tilde{\boldsymbol{w}}) = \nabla f(\boldsymbol{w}).$$

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Idea behind SDCA

Definition

Define the gap of point i as

$$\sigma_i^t = \ell(\mathbf{x}_i^\mathsf{T} \mathbf{w}^t) + \ell^*(-\alpha_i^t) + \alpha_i^t \mathbf{x}_i^\mathsf{T} \mathbf{w}^t$$

where \mathbf{w}^t here is assumed to be the corresponding primal vector for the current α^t , that is $\mathbf{w}^t(\alpha^t) := \frac{1}{\lambda n} \sum_{i=1}^n \alpha_i \mathbf{x}_i^t$.

The **duality gap** between the primal objective and dual objective at the t-th iteration is defined as

$$f(\mathbf{w}^t) - D(\alpha^t) = \frac{1}{n} \sum_{i=1}^n \sigma_i^t.$$

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AdaSDCA

```
Algorithm 7: AdaSDCA (Adaptive Non-uniform Stochastic Dual Coor-
dinate Ascent)
  Input: \lambda > 0
   Data: \{(x_i, y_i)\}_{i=1}^n
  Initialize: \alpha^1 = 0, w^1 = 0, probabilities p_i = \frac{1 + \frac{1}{\lambda_{n_{T_i}}}}{n + \sum_{i=1}^{n} \frac{1}{\lambda_{n_{T_i}}}} or
                     p_i = \frac{\|x_i\|}{\sum_{i=1}^n \|x_i\|}, c_i = 0, \forall i \in \{1, \dots, n\}.
   for t = 1, 2, ..., T
         Sample i_t from \{1, \ldots, n\} based on p;
         Calculate \Delta \alpha_i^t using following formulas:
         \Delta\alpha_{i_t}^t = \arg\max_{\Delta\alpha_{i_t}^t} [-\frac{\lambda n}{2} \| \boldsymbol{w}^t + \frac{1}{\lambda n} \Delta\alpha_{i_t}^t \boldsymbol{x}_{i_t} \|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta\alpha_{i_t}^t))];
        Set \alpha_{i}^{t+1} \leftarrow \alpha_{i_t}^t + \Delta \alpha_{i_t}^t;
        Set w^{t+1} \leftarrow w^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t x_{i_t};
         if (t-1) mod n > n-k then
               for i = 1, 2, ..., n
                     Calculate \sigma_i^t \leftarrow \ell(\mathbf{x}_i^\mathsf{T} \mathbf{w}^t) + l^*(-\alpha_i^t) + \alpha_i^t \langle \mathbf{x}_i, \mathbf{w}^t \rangle;
                   Set c_i \leftarrow \max\{c_i, \sigma_i^t\};
               end
         if t \mod n = 0 then
               Option I: Run Algorithm 3 (Aggressive Update);
               Option II: Run Algorithm 4 (Conservative Update);
         end
```

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end

AdaSDCAS

```
Algorithm 8: AdaSDCAS (Adaptive Non-uniform Stochastic Dual Co-
ordinate Ascent by Subgradient)
```

```
Input: \lambda > 0
Data: \{(x_i, y_i)\}_{i=1}^n
Initialize: \alpha^1 = \mathbf{0}, w^1 = \mathbf{0}, probabilities p_i = \frac{1 + \frac{1}{\lambda n \gamma_i}}{n + \sum_{i=1}^n \frac{1}{\lambda n \gamma_i}} or
                     p_i = \frac{\|x_i\|}{\sum_{i=1}^n \|x_i\|}, c_i = 0, \forall i \in \{1, \ldots, n\}.
for t = 1, 2, ..., T
       Sample i_t from \{1, ..., n\} based on p;
       Calculate \Delta \alpha_i^t using following formulas:
       \Delta \alpha_{i_t}^t = \arg \max_{\Delta \alpha_{i_t}^t} \left[ -\frac{\lambda n}{2} \| w^t + \frac{1}{\lambda n} \Delta \alpha_{i_t}^t x_{i_t} \|^2 - \ell_{i_t}^* (-(\alpha_{i_t}^t + \Delta \alpha_{i_t}^t)) \right];
      Set \alpha_{i_i}^{t+1} \leftarrow \alpha_{i_i}^t + \Delta \alpha_{i_i}^t;
      Set \boldsymbol{w}^{t+1} \leftarrow \boldsymbol{w}^t + \frac{1}{\lambda_n} \Delta \alpha_{i_*}^t \boldsymbol{x}_{i_*};
       if (t-1) \mod n > n-k then
              for i = 1, 2, ..., n
| Calculate \ell'(\langle x_i, w^t \rangle, y_i);
                  Set \chi_i^t \leftarrow \ell'(\langle x_i, w^t \rangle, y_i) x_i + \lambda \nabla r(w^t);
Record c_i \leftarrow \max\{c_i, \|\chi_i^t\|\};
        end
       if t \mod n = 0 then
              Option I: Run Algorithm 3 (Aggressive Update);
              Option II: Run Algorithm 4 (Conservative Update);
       end
end
```

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Part C

Discussions and Experiments

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Datasets for empirical study

| Dataset | Training(n) | Test | Features (d) | Sparsity $\left(\frac{nnz}{nd}\right)$ |
|----------|-------------|---------|----------------|--|
| rcv1 | 20,242 | 677,399 | 47,236 | 0.16% |
| astro-ph | 29,882 | 32,487 | 99,757 | 0.08% |

• rcv1 is a corpus from Reuters news stories.

• astro-ph is astronomy data.

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Cost per epoch and properties of algorithms

| Algorithm | cost of an epoch | non-uniform | adaptive |
|---------------------|------------------|-------------|----------|
| NonUnifSGD | nnz | ✓ | Х |
| NonUnifSDCA | nnz | ✓ | X |
| AdaSGD | (k+1) nnz | ✓ | ✓ |
| AdaSVRG | nd + k nnz | ✓ | ✓ |
| AdaSDCA | (k+1) nnz | ✓ | ✓ |
| AdaSDCAS | (k+1) nnz | ✓ | ✓ |
| AdaGrad (by Duchi) | 2nd | × | X |
| AdaSDCA (by Csiba) | <i>n</i> nnz | ✓ | ✓ |
| AdaSDCA+ (by Csiba) | 2 nnz | ✓ | ✓ |

nnz: is the number of nonzero elements of the matrix consisting of all the samples in the dataset.

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Test Error with Different Values of λ

| rcv1 | 1e-2 | 5e-3 | 1e-3 | 5e-4 | 1e-4 |
|------------|---------|---------|---------|---------|---------|
| Test Error | 0.05160 | 0.04833 | 0.04713 | 0.04913 | 0.05693 |

| astro-ph | 1e-2 | 5e-3 | 1e-3 | 5e-4 | 1e-4 |
|------------|---------|---------|---------|---------|---------|
| Test Error | 0.04103 | 0.03715 | 0.03441 | 0.03586 | 0.04371 |

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Verifying the Convergence of Duality Gap

Table: Average duality gap at different epochs for $\lambda = 0.001$

| #epoch | duality gap on rcv1 | duality gap on astro-ph |
|--------|---------------------|-------------------------|
| 1 | 0.0863765 | 0.0883917 |
| 3 | 0.0105347 | 6.13163e-03 |
| 10 | 1.7485e-04 | 3.93673e-05 |
| 20 | 2.21547e-05 | 6.24779e-07 |
| 50 | 3.12797e-06 | 6.7474e-10 |
| 100 | 5.47897e-07 | 1.43083e-12 |

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Performance Metrics

Definition

The **primal sub-optimality** of algorithm is defined as $f(\mathbf{w}(\alpha)) - f(\mathbf{w}^*)$.

Definition

Test error is the error rate on test dataset.

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Performance of Two Updating Algorithms

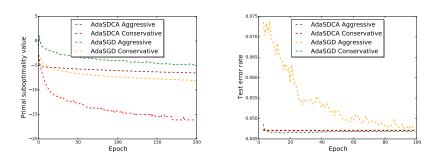


Figure: Comparison of two updating algorithms for AdaSGD and AdaSDCA on rcv1

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Different Adaptive Strategies for AdaSDCA

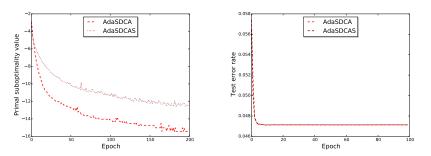


Figure: Comparison of AdaSDCA and AdaSDCAS on rcv1

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Comparison of Average Time

Table: Detailed training time and total running time per epoch

| rcv1 | Training time(s) | Total running time(s) |
|--------------------|--------------------------|------------------------------|
| AdaSGD | 0.04765 | 0.2059 |
| AdaSDCA | 0.05042 | 0.2064 |
| NonUnifSGD | 0.04244 | 0.1988 |
| NonUnifSDCA | 0.04716 | 0.2037 |
| | | |
| astro-ph | Training time(s) | Total running time(s) |
| astro-ph AdaSGD | Training time(s) 0.07236 | Total running time(s) 0.1363 |
| | | • () |
| AdaSGD | 0.07236 | 0.1363 |

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Comparison of Adaptive Algorithms

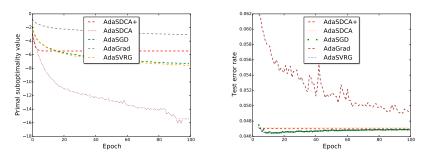


Figure: Comparison of five adaptive algorithms on rcv1

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Comparison of Adaptive Algorithms cont.

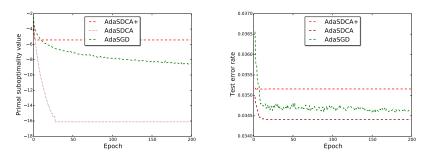


Figure: Comparison of three adaptive algorithms on astro-ph

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Comparison of Time

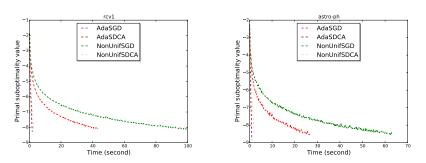


Figure: Comparison of the total running time to reach the same optimality

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Same Level of Optimality

Table: The number of epochs taken to reach the same level of optimality

| rcv1 | AdaSDCA | NonUnifSDCA | AdaSGD | NonUnifSGD |
|----------|---------|-------------|--------|------------|
| #epochs | 9 | 35 | 210 | 500 |
| astro-ph | AdaSDCA | NonUnifSDCA | AdaSGD | NonUnifSGD |
| #epochs | 0 | 28 | 195 | 500 |

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Comparison of Vector Operation

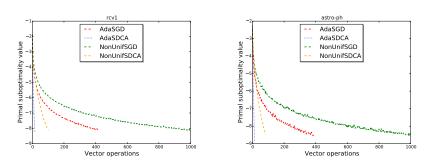


Figure: Comparison of the vector operations taken to reach the same optimality

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Adaptive vs. Non-Uniform Algorithms

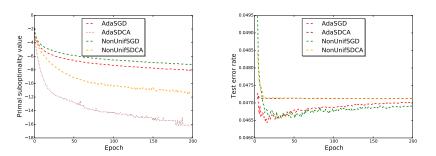


Figure: Comparison of adaptive algorithms with non-adaptive algorithms on rcv1

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Adaptive vs. Non-Uniform Algorithms cont.

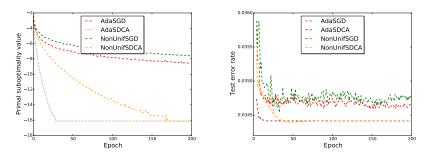


Figure: Comparison of adaptive algorithms with non-adaptive algorithms on astro-ph

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Summary

- We chose $\lambda = 0.001$ for both rcv1 and astro-ph.
- We compare the performance of Conservative Update and Aggressive Update on AdaSGD and AdaSDCA. Conservative Update works better on AdaSGD while Aggressive Update works better on AdaSDCA.
- AdaSDCA (adaptive algorithm with duality gap) performs better than AdaSDCAS (adaptive algorithm with subgradients).
- AdaSDCA has the best performance among all the adaptive algorithms (AdaSDCA, AdaSGD, AdaSVRG, AdaGrad and AdaSDCA+) and AdaSGD is the second best.
- AdaSVRG achieves a slightly better performance per epoch than AdaSGD but sacrifices the running time on sparse datasets.

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Q&A



Thank You!

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