

<div>Section 3 : Concurrency/Synchronization</div>		<div>Solutions to the critical section problem</div>		<div>Blocking vs Busy Waiting</div>	
<div>Synchronization Constructs</div> <div>Mutex (Mutual Exclusion Lock)</div> <p>A mutex is a simple lock that makes sure only one thread can enter the critical section at a time.</p> <div>How does it work?</div> <ul style="list-style-type: none"><li>A thread that wants to enter a critical section locks the mutex</li><li>If another thread tries to lock it while its already taken, it has to wait</li><li>Once the thread is done, it unlocks the mutex, letting another one in.</li></ul> <p>Ensures mutual exclusion. May cause busy waiting or put threads to sleep depending on implementation</p> <div>Semaphores</div> <p>Flexible synchronization tool based on an integer counter. Allows multiple threads to access shared resources up to a limit.</p> <div>How does it work?</div> <ul style="list-style-type: none"><li>wait() (P) decreases semaphore value, if value is already 0, thread blocks or spins (waits)</li><li>signal() (also called V) increases the value, possibly waking up a waiting thread.</li></ul> <div>Two types</div> <ol style="list-style-type: none"><li>Counting Semaphore<ul style="list-style-type: none"><li>Value can be greater than 1, used when you'd have multiple identical resources</li></ul></li><li>Binary Semaphore<ul style="list-style-type: none"><li>Value is either 0 or 1, acts exactly like a mutex</li></ul></li></ol> <div>Analogy:</div> <p>Think of a parking lot</p> <ul style="list-style-type: none"><li>wait() means you enter and use a spot (counter goes down)</li><li>signal() means you leave, freeing a spot (counter goes up)</li><li>If its full (value = 0), you have to wait until someone leaves</li></ul>		<div>a. Software-only (Peterson's Algorithm)</div> <p>Peterson's algorithm is a class software based method that provides a solution to the critical section problem for two threads</p> <div>Key Ideas</div> <ul style="list-style-type: none"><li>Each thread has a flag to say "I'm interested in the critical section"</li><li>A shared turn variable decides whose turn it is to enter the critical section</li><li>Both threads cooperate and check these two variables before proceeding</li></ul> <div>Downside</div> <ul style="list-style-type: none"><li>It relies on busy waiting, meaning the thread constantly checks a condition in a loop (also called a <b>spinlock</b>). This wastes CPU cycles while waiting</li></ul> <div>Def - Spinlock</div> <p>A type of lock here a thread waits in a loop (spins), constantly checking if it can enter the critical section.</p> <ul style="list-style-type: none"><li>It keeps checking a condition until the lock becomes available</li><li>No sleeping, just checking over and over, which wastes CPU cycles, but can be fast if the wait time is short.</li></ul> <div>b. Hardware Support</div> <div>a. Test and set</div> <p>This is an atomic instruction that test the value of a variable and sets it to true (locked)</p> <ul style="list-style-type: none"><li>If the var was already true (locked), the thread waits, if false, locks and proceeds</li><li>Useful for implementing basic locks, but also uses busy waiting</li></ul> <div>b. Compare and Swap (CAS)</div> <p>Also atomic, checks whether a value matches an expected value, and only then updates</p> <ul style="list-style-type: none"><li>This is more flexible and powerful than test and set</li><li>Commonly used in <b>lock free data structure</b>, and modern mutex implementations</li></ul> <div>c. Disabling Interrupts (Kernel Only)</div> <p>Sometimes need to disable interrupts before entering critical section so no other thread can preempt current one.</p> <ul style="list-style-type: none"><li>This works only in single CPU systems or inside the kernel</li><li>Not recommended in user space or multicore environments</li></ul>		<div>Busy Waiting</div> <ul style="list-style-type: none"><li>The thread spins checking a condition repeatedly</li><li>Wastes CPU cycles - bad for performance</li></ul> <div>Blocking</div> <ul style="list-style-type: none"><li>The OS suspends the thread until it can enter the critical section</li><li>More efficient, especially with many threads</li></ul>	
<div>Classic Synchronization Problems</div> <div>a. Producer-Consumer (Bounded Buffer)</div> <ul style="list-style-type: none"><li>Shared buffer between a producer (writes data) and consumer (reads it)</li><li>Use semaphores to track<ul style="list-style-type: none"><li>Empty slots, Filled slots, Mutual exclusion for buffer access</li></ul></li></ul> <div>b. Readers-Writers</div> <ul style="list-style-type: none"><li>Multiple readers can access data simultaneously</li><li>But only one write can update at a time - and no readers during writing</li></ul> <div>Variations</div> <ul style="list-style-type: none"><li>First readers' problem (writer starvation possible)</li><li>First writers' problem (reader starvation possible)</li></ul> <div>c. Dining Philosophers</div> <ul style="list-style-type: none"><li>Five philosophers sharing five forks</li><li>Must grab two forks (shared resources) to eat</li><li>Can lead to: deadlock, starvation, or livelock depending on implementation</li></ul>		<div>Critical Section</div> <p>A critical section is any code that accesses shared resources that must not be concurrently modified. They key rule is : only one thread/process should access the critical section at a time.</p> <div>The problem</div> <p>If multiple threads/processes access shared resources <b>w/out coordination</b> → race conditions</p> <div>Def - Race Condition</div> <p>Happens when two or more threads race to read and write the same data at the same time. It can lead to unpredictable results.</p> <div>Def - Atomic Instruction</div> <p>A low level CPU operation that runs completely without interruption - meaning no other thread or process can interfere while its happening/</p> <ul style="list-style-type: none"><li>It is indivisible - either it finishes entirely or it doesn't happen at all</li><li>This is important for synchronization, because it avoids race conditions.</li></ul>		<div>What is Synchronization</div> <p>Synchronization is the coordination of multiple threads or processes so shared resources are accessed safely &amp; program behaves correctly even when many things are happening at once.</p> <div>Requirements for a correct solution</div> <div>Mutual Exclusion</div> <p>Only one process/thread in the critical section (CS) at a time</p> <div>Why its important</div> <p>If two threads modify the same resource at once, you get data corruption or race conditions.</p> <div>Progress</div> <p>If no process is in critical section, and some threads want to enter, the system must allow one of them to go in without unnecessary delay</p> <div>Why its important</div> <p>We want the system to be fair and efficient. If the critical section is free, we shouldn't block everyone just because the program is indecisive or stuck</p> <div>Bounded waiting</div> <p>Every thread should get a fair turn. If a thread wants to enter critical section, there should be a limit on how many times other threads cut in line before it gets a chance</p> <div>Why its important</div> <p>Without bounded waiting, threads can be starved, never get their turn</p>	
<div>Monitors (High level Abstraction)</div> <p>Built in synchronization feature provided by some programming languages that combines</p> <ul style="list-style-type: none"><li>A mutex to control who can enter the critical section</li><li>Condition variables for threads to wait and signal each other inside the monitor</li></ul> <div>Features</div> <ul style="list-style-type: none"><li>Monitors abstract away the complexity - you don't need to manually lock/unlock</li><li>They bundle data and synchronization logic together</li><li>Internally, they use <u>mutexes</u> and condition variables</li></ul> <div>Def - Condition Variable</div> <p>Allows threads to wait for certain conditions to become true and lets other threads signal when those conditions are met</p> <div>Def - trylock()</div> <p>Non blocking version of lock().</p> <ul style="list-style-type: none"><li>It tries to acquire the lock, if the lock is already held by another thread, it doesn't wait - it just returns an error (or false), if it succeeds, the thread enters the critical section.</li></ul>		<div>What is Concurrency</div> <p>Concurrency is the ability of a system to allow multiple tasks (processes or threads) to make progress a the <i>same logical time</i>. It doesn't require multiple CPUs.</p> <p>Logical concurrency can be achieved even on a single core processor by interleaving execution.</p> <div>Def: Interleaving</div> <p>Alternating the execution of instructions from multiple tasks on a single CPU, so that it appears as if tasks are running at the same time.</p> <ul style="list-style-type: none"><li>A single core processor can only execute one single instruction at a time, the OS rapidly switches between tasks - this is called <b>context switching</b>. Doing this frequently creates the illusion of tasks progressing simultaneously, even though only one is running.</li></ul> <div>Types of Concurrency</div> <ul style="list-style-type: none"><li>Logical Concurrency - Tasks <i>appear</i> to run simultaneously</li><li>Physical Concurrency - Tasks <i>actually</i> run at the same time</li></ul> <div>Why do we care?</div> <ul style="list-style-type: none"><li>OS's must handle multiple active entities at once : processes, IO, user interaction, etc</li><li>it enables parallelism, responsiveness, and efficiency.<ul style="list-style-type: none"><li><b>Def</b> - Parallelism - When multiple tasks are literally executed at the same time using multiple processing units (multiple cores for ex). Different than <b>interleaving</b>, when tasks just appear to run at the same time but actually take turns.</li></ul></li></ul>			