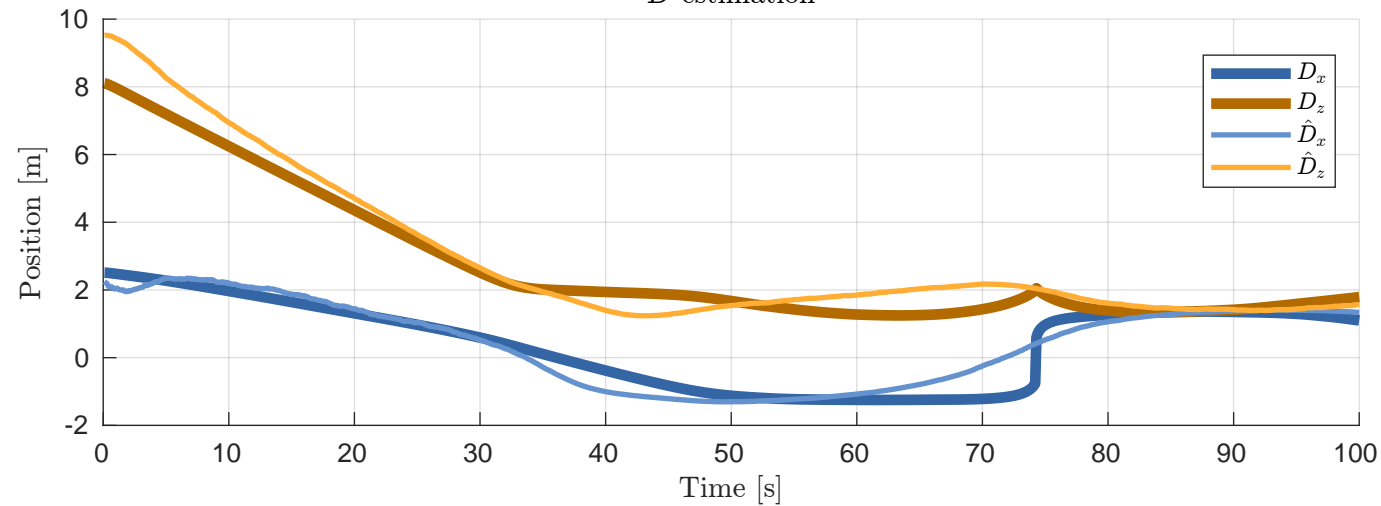


$\dot{D}$  estimation $\dot{D}$  estimation