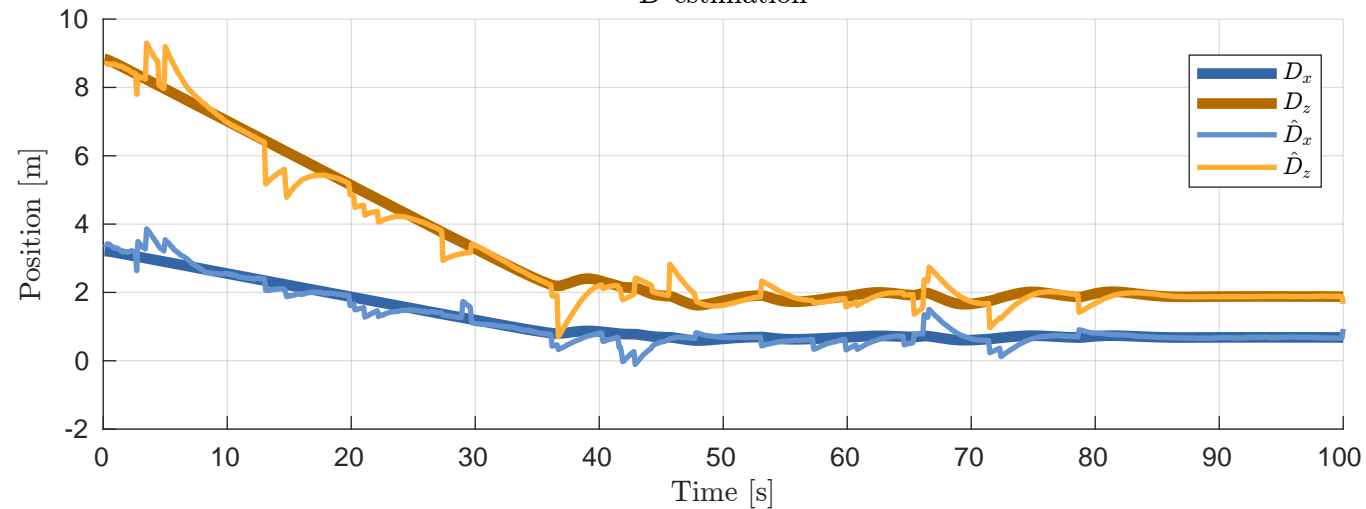


D estimation \dot{D} estimation