

# Machine Learning

## Linear Models

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# Linear Predictors and Affine Functions

Consider  $\mathcal{X} = \mathbb{R}^d$

**“Linear” (affine) functions:**

$$L_d = \{h_{\mathbf{w},b} : \mathbf{w} \in \mathbb{R}^d, b \in \mathbb{R}\}$$

where

$$h_{\mathbf{w},b}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle + b = \left( \sum_{i=1}^d w_i x_i \right) + b$$

**Note:**

- each member of  $L_d$  is a function  $\mathbf{x} \rightarrow \langle \mathbf{w}, \mathbf{x} \rangle + b$
- $b$ : *bias*

# Linear Models

Hypothesis class  $\mathcal{H}$ :  $\phi \circ L_d$ , where  $\phi : \mathbb{R} \rightarrow \mathcal{Y}$

- $h \in \mathcal{H}$  is  $h : \mathbb{R}^d \rightarrow \mathcal{Y}$

$\phi$  depends on the learning problem

## Example

- binary classification,  $\mathcal{Y} = \{-1, 1\} \Rightarrow \phi(z) = \text{sign}(z)$
- regression,  $\mathcal{Y} = \mathbb{R} \Rightarrow \phi(z) = z$

# Equivalent Notation

Given  $\mathbf{x} \in \mathcal{X}$ ,  $\mathbf{w} \in \mathbb{R}^d$ ,  $b \in \mathbb{R}$ , define:

- $\mathbf{w}' = (b, w_1, w_2, \dots, w_d) \in \mathbb{R}^{d+1}$
- $\mathbf{x}' = (1, x_1, x_2, \dots, x_d) \in \mathbb{R}^{d+1}$

Then:

$$h_{\mathbf{w},b}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle + b = \langle \mathbf{w}', \mathbf{x}' \rangle \quad (1)$$

$\Rightarrow$  we will consider bias term as part of  $\mathbf{w}$  and assume  $\mathbf{x} = (1, x_1, x_2, \dots, x_d)$  when needed, with  $h_{\mathbf{w}}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle$

# Linear Regression

$$\mathcal{X} = \mathbb{R}^d, \mathcal{Y} = \mathbb{R}$$

Hypothesis class:

$$\mathcal{H}_{reg} = L_d = \{\mathbf{x} \mapsto \langle \mathbf{w}, \mathbf{x} \rangle + b : \mathbf{w} \in \mathbb{R}^d, b \in \mathbb{R}\}$$

**Note:**  $h \in \mathcal{H}_{reg} : \mathbb{R}^d \rightarrow \mathbb{R}$

Commonly used loss function: *squared-loss*

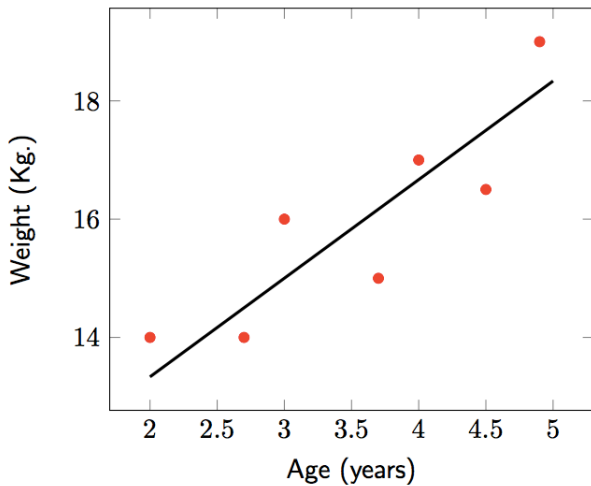
$$\ell(h, (\mathbf{x}, y)) \stackrel{\text{def}}{=} (h(\mathbf{x}) - y)^2$$

$\Rightarrow$  empirical risk function (training error): *Mean Squared Error*

$$L_S(h) = \frac{1}{m} \sum_{i=1}^m (h(\mathbf{x}_i) - y_i)^2$$

# Linear Regression - Example

$d = 1$



# Least Squares

How to find a ERM hypothesis? *Least Squares* algorithm

Best hypothesis:

$$\arg \min_{\mathbf{w}} L_S(h_{\mathbf{w}}) = \arg \min_{\mathbf{w}} \frac{1}{m} \sum_{i=1}^m (\langle \mathbf{w}, \mathbf{x}_i \rangle - y_i)^2$$

Equivalent formulation:  $\mathbf{w}$  minimizing *Residual Sum of Squares* (RSS), i.e.

$$\arg \min_{\mathbf{w}} \sum_{i=1}^m (\langle \mathbf{w}, \mathbf{x}_i \rangle - y_i)^2$$

## RSS: Matrix Form

Let

$$\mathbf{X} = \begin{bmatrix} \cdots & \mathbf{x}_1 & \cdots \\ \cdots & \mathbf{x}_2 & \cdots \\ \cdots & \vdots & \cdots \\ \cdots & \mathbf{x}_m & \cdots \end{bmatrix}$$

$\mathbf{X}$ : *design matrix*

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

$\Rightarrow$  we have that RSS is

$$\sum_{i=1}^m (\langle \mathbf{w}, \mathbf{x}_i \rangle - y_i)^2 = (\mathbf{y} - \mathbf{X}\mathbf{w})^T (\mathbf{y} - \mathbf{X}\mathbf{w})$$



Want to find  $\mathbf{w}$  that minimizes RSS (*=objective function*):

$$\arg \min_{\mathbf{w}} RSS(\mathbf{w}) = \arg \min_{\mathbf{w}} (\mathbf{y} - \mathbf{X}\mathbf{w})^T (\mathbf{y} - \mathbf{X}\mathbf{w})$$

How?

Compute gradient  $\frac{\partial RSS(\mathbf{w})}{\partial \mathbf{w}}$  of objective function w.r.t  $\mathbf{w}$  and compare it to 0.

$$\frac{\partial RSS(\mathbf{w})}{\partial \mathbf{w}} = -2\mathbf{X}^T (\mathbf{y} - \mathbf{X}\mathbf{w})$$

Then we need to find  $\mathbf{w}$  such that

$$-2\mathbf{X}^T (\mathbf{y} - \mathbf{X}\mathbf{w}) = 0$$

$$-2\mathbf{X}^T(\mathbf{y} - \mathbf{X}\mathbf{w}) = 0$$

is equivalent to

$$\mathbf{X}^T\mathbf{X}\mathbf{w} = \mathbf{X}^T\mathbf{y}$$

If  $\mathbf{X}^T\mathbf{X}$  is invertible  $\Rightarrow$  solution to ERM problem is:

$$\mathbf{w} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y}$$

# Complexity Considerations

We need to compute

$$(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Algorithm:

- 1 compute  $\mathbf{X}^T \mathbf{X}$ : product of  $(d+1) \times m$  matrix and  $m \times (d+1)$  matrix
- 2 compute  $(\mathbf{X}^T \mathbf{X})^{-1}$  inversion of  $(d+1) \times (d+1)$  matrix
- 3 compute  $(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T$ : product of  $(d+1) \times (d+1)$  matrix and  $(d+1) \times m$  matrix
- 4 compute  $(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$ : product of  $(d+1) \times m$  matrix and  $m \times 1$  matrix

Most expensive operation? Inversion!

$\Rightarrow$  done for  $(d+1) \times (d+1)$  matrix

## $\mathbf{X}^T \mathbf{X}$ not invertible?

How do we get  $\mathbf{w}$  such that

$$\mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

if  $\mathbf{X}^T \mathbf{X}$  is not invertible?

Let

$$\mathbf{A} = \mathbf{X}^T \mathbf{X}$$

Let  $\mathbf{A}^+$  be the *generalized inverse* of  $\mathbf{A}$ , i.e.:

$$\mathbf{A} \mathbf{A}^+ \mathbf{A} = \mathbf{A}$$

### Proposition

If  $\mathbf{A} = \mathbf{X}^T \mathbf{X}$  is not invertible, then  $\hat{\mathbf{w}} = \mathbf{A}^+ \mathbf{X}^T \mathbf{y}$  is a solution to  $\mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$ .

# Computing the Generalized Inverse of $\mathbf{A}$

Note  $\mathbf{A} = \mathbf{X}^T \mathbf{X}$  is symmetric  $\Rightarrow$  eigenvalue decomposition of  $\mathbf{A}$ :

$$\mathbf{A} = \mathbf{V} \mathbf{D} \mathbf{V}^T$$

with

- $\mathbf{D}$ : diagonal matrix (entries = eigenvalues of  $\mathbf{A}$ )
- $\mathbf{V}$ : orthonormal matrix ( $\mathbf{V}^T \mathbf{V} = \mathbf{I}_{d \times d}$ )

Define  $\mathbf{D}^+$  diagonal matrix such that:

$$\mathbf{D}_{i,i}^+ = \begin{cases} 0 & \text{if } \mathbf{D}_{i,i} = 0 \\ \frac{1}{\mathbf{D}_{i,i}} & \text{otherwise} \end{cases}$$

Let  $\mathbf{A}^+ = \mathbf{V}\mathbf{D}^+\mathbf{V}^T$

Then

$$\begin{aligned}\mathbf{A}\mathbf{A}^+\mathbf{A} &= \mathbf{V}\mathbf{D}\mathbf{V}^T\mathbf{V}\mathbf{D}^+\mathbf{V}^T\mathbf{V}\mathbf{D}\mathbf{V}^T \\ &= \mathbf{V}\mathbf{D}\mathbf{D}^+\mathbf{D}\mathbf{V}^T \\ &= \mathbf{V}\mathbf{D}\mathbf{V}^T \\ &= \mathbf{A}\end{aligned}$$

$\Rightarrow \mathbf{A}^+$  is a generalized inverse of  $\mathbf{A}$ .

**In practice:** the Moore-Penrose generalized inverse  $\mathbf{A}^\dagger$  of  $\mathbf{A}$  is used, since it can be efficiently computed from the Singular Value Decomposition of  $\mathbf{A}$ .