# Achieving Optimal Blackjack Play Through Double Q-Learning COMP3106 Final Project

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# Outline

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# Background and Motivation

# Why Blackjack?

- Perfect blend of skill and probability
- Well-defined rules with complex decision spaces
- Real-world application potential
- Ideal for testing Al adaptation capabilities

#### Research Goals

- Develop optimal playing strategies using RL
- Test effectiveness of Double Q-Learning
- Compare performance against traditional strategies
- Integrate card counting for enhanced decision-making

## Related Prior Work

## Q-Learning Evolution

- Original Q-Learning (Watkins)
  - Value function approximation
  - State-action pair evaluation
  - Temporal difference learning
- Double Q-Learning (van Hasselt)
  - Addresses maximization bias
  - Dual estimator approach
  - Improved stability in stochastic environments

# **Industry Applications**

- FAIR's poker AI breakthrough (2017)
- Professional player defeat milestone
- Reinforcement learning in imperfect information games

## Basic Game Rules

#### **Card Values**

- 2-10: Face value
- Jack, Queen, King: 10
- Ace: 1 or 11 (flexible)

#### **Objective**

- Beat dealer's hand
- Get closest to 21
- Don't exceed 21 (bust)

#### **Player Actions**

- Hit: Request another card
- Stand: Keep current hand
- Split: Divide matching pairs
- Double Down: Double bet, one card

## Dealer Rules and Game Flow

#### **Dealer Constraints**

- Must hit on 16 or below
- Must stand on hard 17 or above
- Some casinos require hit on soft 17
- No splitting or doubling down

#### Game Resolution

- Player bust: Immediate loss
- Dealer bust: All standing players win
- Higher hand wins (if no busts)
- Equal hands: Push (tie)
- Natural blackjack pays 3:2

# Card Counting Fundamentals

# Hi-Lo System

- Low cards (2-6): +1
- Mid cards (7-9): 0
- High cards (10-A): -1

# Running Count vs True Count

- Running Count = Sum of card values seen
- True Count = Running Count ÷ Decks Remaining
- Positive count: Advantage to player
- Negative count: Advantage to dealer

# State Space Design

## **State Space Components:**

(player\_value, has\_usable\_ace, dealer\_upcard, count\_bucket, is\_pair, pair\_value

- player\_value  $\in$  [4,21]
- has\_usable\_ace ∈ 0,1
- dealer\_upcard  $\in$  [1,10]
- count\_bucket  $\in$  -1,0,1
- is\_pair  $\in 0,1$
- pair\_value ∈ [0,10]

# Action Space and Constraints

Action Space:  $A = \{0 \text{ (Stand)}, 1 \text{ (Hit)}, 2 \text{ (Split)}\}$ 

## Action Constraints

- Stand (0):
  - Always available
  - Ends player's turn
- Hit (1):
  - Available if not busted
  - Draws one card
- Split (2):
  - Requires matching pair
  - Maximum 3 splits
  - Each hand gets new card

# Q-Learning Implementation

# Core Update Equation

$$Q(s, a) \leftarrow Q(s, a) + \alpha[r(s) + \gamma \max_{a'} Q(s', a') - Q(s, a)]$$

#### Where:

- $\alpha$ : Learning rate
- $\gamma$ : Discount factor
- $\bullet$  r(s): Immediate reward
- s': Next state

# Dynamic Learning Rate

$$\alpha(s,a) = \max(\alpha_0 \cdot \delta^{N(s,a)}, \alpha_{\min})$$

- N(s, a): Visit count
- $\delta$ : Decay rate

# Double Q-Learning Implementation

#### **Dual Q-Tables**

- Maintains two Q-value estimators  $(Q_1, Q_2)$
- Reduces overestimation bias
- Randomly updates one table per step

#### **Update Function**

$$Q_1(s,a) \leftarrow Q_1(s,a) + \alpha [R + \gamma Q_2(s', \arg\max_{a'} Q_1(s',a')) - Q_1(s,a)]$$

#### Key Features:

- Action selection from Q<sub>1</sub>
- Value estimation from  $Q_2$
- Decorrelated maximum value estimation

## Reward Structure

$$R(p,d) = \begin{cases} -1.2b & \text{if } p > 21 \text{ (bust)} \\ 1.1b & \text{if } d > 21 \text{ (dealer bust)} \\ 1.5b & \text{if } p = 21 \text{ (natural)} \\ 1.1b & \text{if } p > d \text{ and } p \ge 20 \\ b & \text{if } p > d \\ -b & \text{if } p < d \\ 0 & \text{if } p = d \end{cases}$$

#### Where:

- p: Player's hand value
- d: Dealer's hand value
- b: Base reward unit



# **Epsilon-Greedy Exploration**

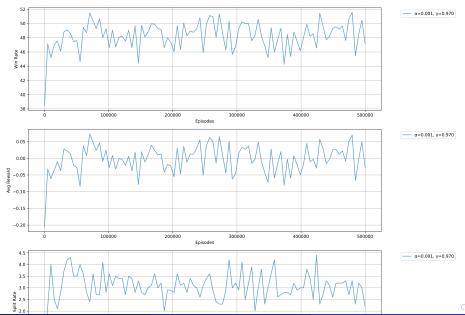
# Action Selection Probability

$$P(a|s) = egin{cases} 1 - \epsilon + rac{\epsilon}{|A|} & ext{if } a = rg \max_{a'} Q(s, a') \ rac{\epsilon}{|A|} & ext{otherwise} \end{cases}$$

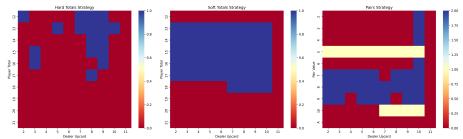
# Adaptive Exploration Rate

$$\epsilon = \max(\epsilon_{\min}, \epsilon \cdot egin{cases} \delta_{\epsilon} \cdot 1.1 & ext{if improving} \ \delta_{\epsilon} & ext{otherwise} \end{cases}$$

# Training Results



# Strategy Analysis



#### **Hard Totals**

- Stand on 17+
- Hit on 16- vs high cards
- Conservative vs dealer 2-6

#### Soft Totals

- Hit below soft 18
- Stand on soft 19+
- Strategic soft 18 play

# Limitations

# Performance Ceiling

- Win rate plateau at 48-50%
- Inherent house edge challenge
- Approaches theoretical maximum

# Strategic Gaps

- Suboptimal split rate (3.05%)
- Room for reward function refinement
- Casino simulation fidelity limitations

## **Future Directions**

#### **Technical Improvements**

- Enhanced split strategy training
- More sophisticated reward shaping
- Deeper card counting integration

# Real-World Applications

- Dealer rule variations
- Multi-deck adaptability
- Real-time decision support
- Training tool development