# **Anomaly Detection**

Latest Submission Grade 80% 1. Question 1
For which of the following problems would anomaly detection be a suitable algorithm?
1 / 1 point  ✓
Given a dataset of credit card transactions, identify unusual transactions to flag them as possibly fraudulent.
Correct
By modeling "normal" credit card transactions, you can then use anomaly detection to flag the unusuals ones which might be fraudulent.
Given an image of a face, determine whether or not it is the face of a particular famous individual.
Given data from credit card transactions, classify each transaction according to type of purchase (for example: food, transportation, clothing).
From a large set of primary care patient records, identify individuals who might have unusual health conditions.
Correct
Since you are just looking for unusual conditions instead of a particular disease, this is a good application of anomaly detection.
2. Question 2

Suppose you have trained an anomaly detection system that flags anomalies when p(x)p(x)p(x) is less than  $\varepsilon$ \varepsilon $\varepsilon$ , and you find on the cross-validation set that it has too many false negatives (failing to flag a lot of anomalies). What should you do?

1 / 1 point

0

Increase ε\varepsilonε

 $\circ$ 

Decrease ε\varepsilonε

Correct

By increasing ε\varepsilonε, you will flag more anomalies, as desired.

3. Question 3

Suppose you are developing an anomaly detection system to catch manufacturing defects in airplane engines. You model uses

 $p(x) = \prod_{j=1}^{j=1} np(xj;\mu j,\sigma j2).p(x) = prod_{j=1}^n p(x_j;\mu j,\sigma j2).p(x) = \prod_{j=1}^{j=1} np(xj;\mu j,\sigma j2).p(x) = \prod_{$ 

You have two features  $x1x_1x1 = vibration$  intensity, and  $x2x_2x2 = heat$  generated. Both  $x1x_1x1$  and  $x2x_2x2$  take on values between 0 and 1 (and are strictly greater than 0), and for most "normal" engines you expect that  $x1\approx x2x_1 \cdot x2x_1 \approx x2$ . One of the suspected anomalies is that a flawed engine may vibrate very intensely even without generating much heat (large  $x1x_1x1$ , small  $x2x_2x2$ ), even though the particular values of  $x1x_1x1$  and  $x2x_2x2$  may not fall outside their typical ranges of values. What additional feature  $x3x_3x3$  should you create to capture these types of anomalies:

## 1 / 1 point

Œ

 $x3=x1x2x_3 = \frac{x_1}{x_2}x3=x2x1$ 

O

 $x3=1x2x_3 = \frac{1}{x_2}x3=x21$ 

0

$$x3=x1+x2x\_3 = x\_1 + x\_2x3=x1+x2$$

0

$$x3=1x1x_3 = \frac{1}{x_1}x3=x11$$

#### Correct

This is correct, as it will take on large values for anomalous examples and smaller values for normal examples.

4.

Question 4

Which of the following are true? Check all that apply.



When choosing features for an anomaly detection system, it is a good idea to look for features that take on unusually large or small values for (mainly the) anomalous examples.

✓

If you have a large labeled training set with many positive examples and many negative examples, the anomaly detection algorithm will likely perform just as well as a supervised learning algorithm such as an SVM.

This should not be selected

Anomaly detection only models the negative examples, whereas an SVM learns to discriminate between positive and negative examples, so the SVM will perform better when you have many positive and negative examples.

✓

If you do not have any labeled data (or if all your data has label y=0y=0y=0), then is is still possible to learn p(x)p(x)p(x), but it may be harder to evaluate the system or choose a good value of  $\epsilon \cdot p(x)$ .

#### Correct

Only negative examples are used in training, but it is good to have some labeled data of both types for cross-validation.

If you are developing an anomaly detection system, there is no way to make use of labeled data to improve your system.

5. Question 5

You have a 1-D dataset  $\{x(1),...,x(m)\}\setminus\{x^{(1)}\}, \cdot x^{(m)}\setminus\{x(1),...,x(m)\}$  and you want to detect outliers in the dataset. You first plot the dataset and it looks like this:

Suppose you fit the gaussian distribution parameters  $\mu1$ \mu\_1 $\mu1$  and  $\sigma12$ \sigma\_1^2 $\sigma12$  to this dataset. Which of the following values for  $\mu1$ \mu\_1 $\mu1$  and  $\sigma12$ \sigma\_1^2 $\sigma12$  might you get?

### 1 / 1 point

**①** 

$$\mu 1 = -3, \sigma 12 = 4 \setminus mu_1 = -3, \setminus sigma_1^2 = 4\mu 1 = -3, \sigma 12 = 4$$

0

$$\mu 1 = -6, \sigma 12 = 4 \setminus mu_1 = -6, \setminus sigma_1^2 = 4\mu 1 = -6, \sigma 12 = 4$$

O

$$\mu 1 = -3, \sigma 12 = 2 \text{ mu}_1 = -3, \text{ sigma}_1^2 = 2\mu 1 = -3, \sigma 12 = 2$$

0

$$\mu 1 = -6, \sigma 12 = 2 \setminus mu_1 = -6, \cdot sigma_1^2 = 2\mu 1 = -6, \sigma 12 = 2$$

Correct

This is correct, as the data are centered around -3 and tail most of the points lie in [-5, -1].