Exercise no 03

for this exercise I have used the **xant robot** for this task , there are two method, first we train it by ourself using intial seed tand then see the performance , second we use pre-trained model , for this task I have used the pre-trained model to see the performance of the robot, the parameter I have used are **bestgS2.npy.** After that I have plot the graph , which show that intial performanc is zero but after training performance start to increase and at the end its show the good result .