

Exercise no 1

in this exercise ,when I used the the different environment the value of the command also change , value of the (env.observation_space.high) ,(env.observation_space.low) and discrete value comeout different , in my case the value for the CartPole-v0 ,MounttainCar-v0 and MsPacman-v0 value of the different parameter is given below

CartPole-v0

for Cartpole_v0 value of the discrete is (2)which show that it has two output, physically it has two motors

2-value of Box is (4) which show the input value, two value for position and two value for velocity .

Pendulum-v0

it give the box value (3) which show its dimesion in space is three