

EE270

Large scale matrix computation, optimization and learning

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Randomized Linear Algebra
Lecture 6: Johnson Lindenstrauss Lemma and
Applications

JL - Lemma

Dimension Reduction

- ▶ map a high dimensional vector to low dimensions such that certain properties are preserved
- ▶ examples so far:
- ▶ Approximate Matrix Multiplication $\underbrace{AS^T}_{S^{(1)}} \underbrace{SB}_{S^{(2)}} \approx AB$ where S is random
- ▶ Freivalds Algorithm $ABr - Mr$ where r is random
- ▶ Trace estimation $r^T Mr \approx \text{tr}(M)$ where r is random

$$\text{Diag} \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix}$$

Dimension Reduction

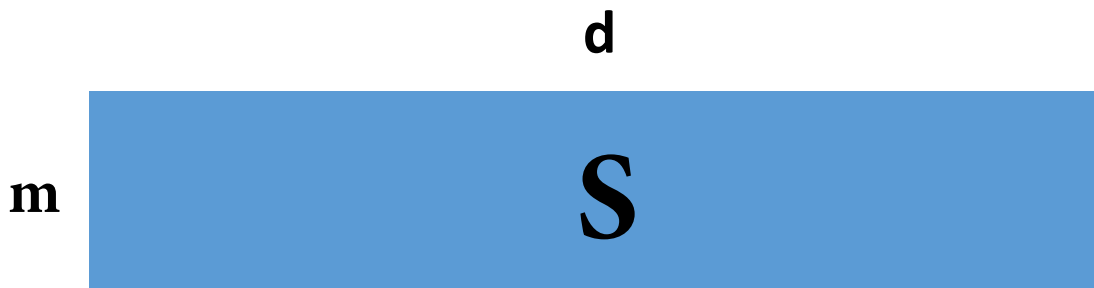
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$$n_{\text{samples}} \quad x_i^T$$

- ▶ Generic dimension reduction problem
- ▶ Given vectors $x_1, \dots, x_n \in \mathbb{R}^d$, compress the data points into low dimensional representation $y_1, \dots, y_n \in \mathbb{R}^m$ where $m \ll d$
- ▶ another instance is Principal Component Analysis

Randomized Dimension Reduction

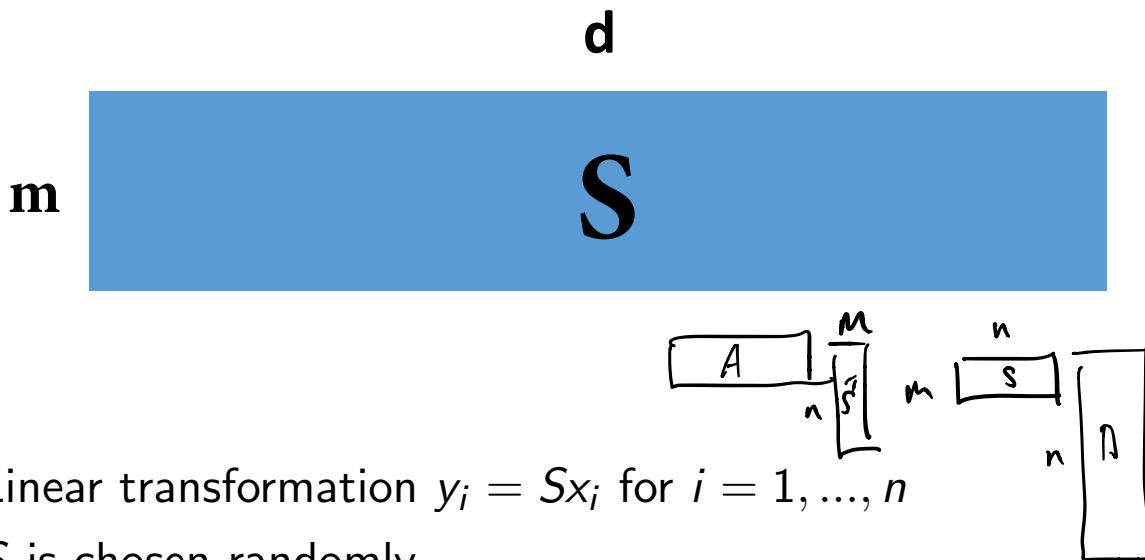
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- ▶ Linear transformation $y_i = Sx_i$ for $i = 1, \dots, n$
 - ▶ S is chosen randomly
- $O(md)$

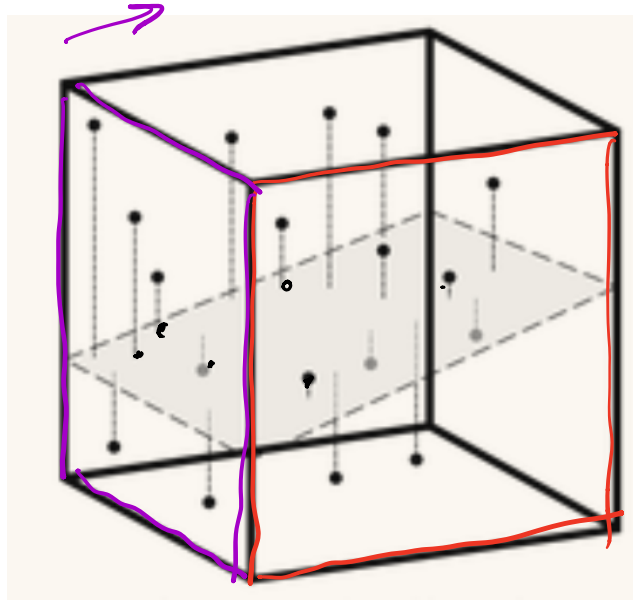
Randomized Dimension Reduction

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- ▶ Linear transformation $y_i = Sx_i$ for $i = 1, \dots, n$
- ▶ S is chosen randomly
- ▶ Approximate Matrix Multiplication: $AS^T SB \approx AB$
where S is random matrix

Geometry of Random Projections $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$



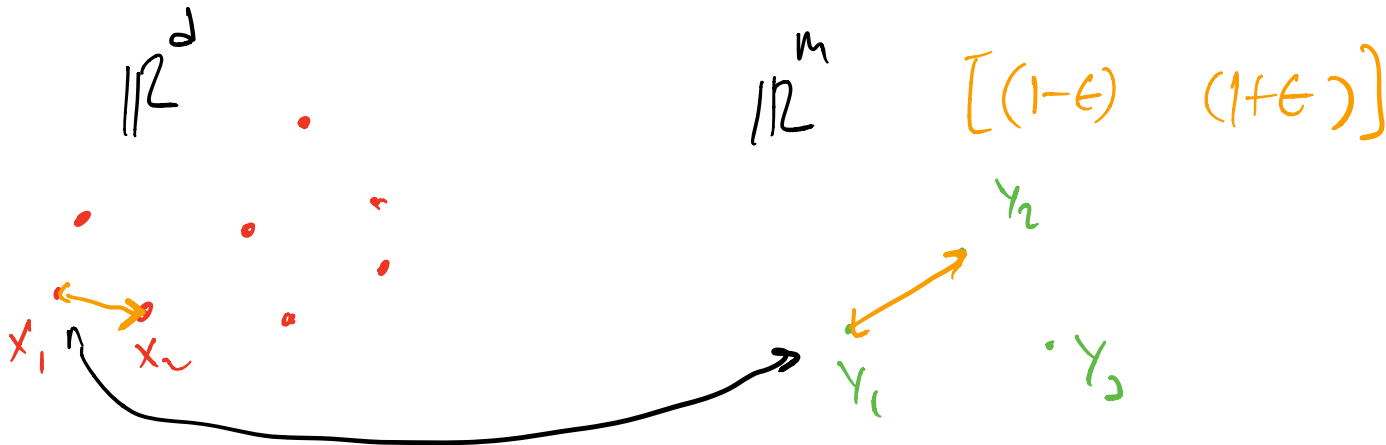
Johnson Lindenstrauss Lemma

$$\gamma_i = \mathcal{S}(x_i) = Sx_i$$

- Let $\epsilon \in (0, \frac{1}{2})$. Given any set of points $\{x_1, \dots, x_n\}$ in \mathbb{R}^d , there exists a map $S : \mathbb{R}^d \rightarrow \mathbb{R}^m$ with $m = \frac{9 \log(n)}{\epsilon^2 - \epsilon^3}$ such that

$$1 - \epsilon \leq \frac{\|Sx_i - Sx_j\|_2^2}{\|x_i - x_j\|_2^2} \leq 1 + \epsilon$$

$$(1 - \epsilon) \cdot \|x_i - x_j\|_2^2 \leq \|\gamma_i - \gamma_j\|_2^2 \leq (1 + \epsilon) \cdot \|x_i - x_j\|_2^2$$



Johnson Lindenstrauss Lemma

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- ▶ Note that the target dimension m is **independent of the original dimension d** , and depends **only on the number of points n** and the accuracy parameter.

Johnson Lindenstrauss Lemma $1 - \epsilon \leq \left\| \frac{S(x_i - x_j)}{\|x_i - x_j\|_2} \right\|_2^2 \leq 1 + \epsilon$

- ▶ Let $\epsilon \in (0, \frac{1}{2})$. Given any set of points $\{x_1, \dots, x_n\}$ in \mathbb{R}^d , there exists a map $S : \mathbb{R}^d \rightarrow \mathbb{R}^m$ with $m = \frac{9 \log(n)}{\epsilon^2 - \epsilon^3}$ such that



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- ▶ Note that the target dimension m is **independent of the original dimension d** , and depends **only on the number of points n** and the accuracy parameter.

- ▶ more surprises: picking an $m \times d$ random matrix $S = \frac{1}{\sqrt{m}} G$ with $G_{ij} \sim N(0, 1)$ standard normal works with high probability!

Sx

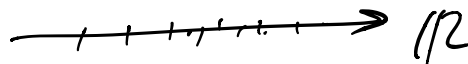
Johnson Lindenstrauss (JL) Lemma

- ▶ Define $u_{ij} \triangleq \frac{x_i - x_j}{\|x_i - x_j\|_2}$.
- ▶ note that $\|u_{ij}\|_2 = 1$
- ▶ JL Lemma:
$$\mathbb{P}[\|Su_{ij}\|_2^2 \in (1 \pm \epsilon) \text{ for all } i, j \in \{1, \dots, n\}] \geq 1 - \delta$$

where $\delta \in (0, 1)$ for large enough m

Warm-up: Geometry of Concentration of Measure on the Sphere

$$S = \boxed{}$$

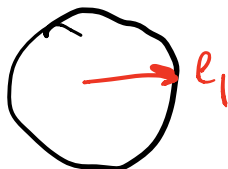
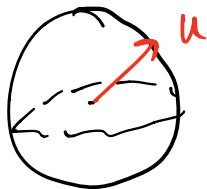


- ▶ Suppose $m = 1$, i.e., we project to dimension one
- ▶ S is a uniformly random row vector on the sphere, i.e.,
 $S = \frac{g^T}{\|g\|_2}$ where $g \sim N(0, I)$
- ▶ For any fixed unit norm vector u , how large is the product Su ?
- ▶ Su is distributed identically to $Se_1 = S_1 = \frac{g_1}{\|g\|_2}$ where e_1 is the first ordinary basis vector

$$g \stackrel{(d)}{=} Rg$$

$$Su = \frac{g^T u}{\|g\|_2} \stackrel{(d)}{=} \frac{g^T R u}{\|g\|_2}$$

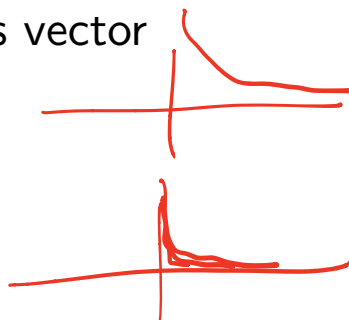
$$Se_1 = S_1 = \frac{g_1}{\|g\|_2} = \frac{g_1}{\sqrt{\sum g_i^2}}$$



identical
dist

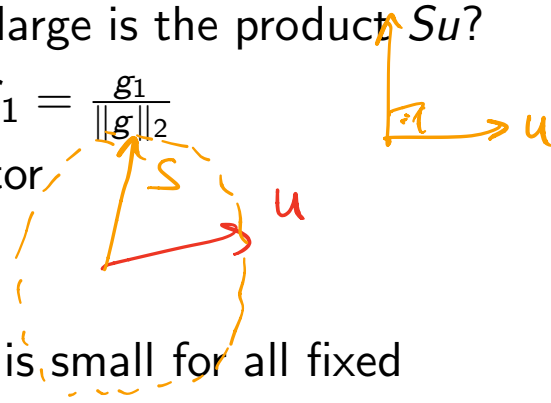
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where e_1 is the first ordinary basis vector
- ▶ **Lemma:** $\mathbb{P}[|S_1| \geq t] \leq 2e^{-\frac{dt^2}{2}}$.



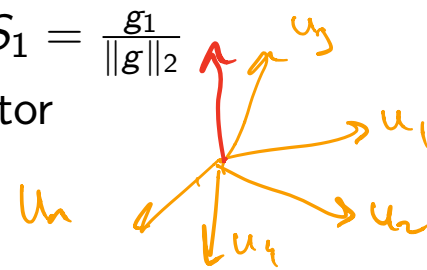
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- ▶ **Lemma:** $\mathbb{P}[|S_1| \geq t] \leq 2e^{-\frac{dt^2}{2}}$.
- ▶ The inner product $Su = \left(\frac{g}{\|g\|_2}\right)^T \frac{u}{\|u\|_2}$ is small for all fixed directions $\frac{u}{\|u\|_2}$, implying near-orthogonality



Warm-up: Geometry of Concentration of Measure on the Sphere

- ▶ Suppose $m = 1$, i.e., we project to dimension one
- ▶ S is a uniformly random row vector on the sphere, i.e., $S = \frac{g^T}{\|g\|_2}$ where $g \sim N(0, I)$ $n \leq e^{\frac{d\epsilon^2}{2}}$
- ▶ For any fixed unit norm vector u , how large is the product Su ?
- ▶ Su is distributed identically to $Se_1 = S_1 = \frac{g_1}{\|g\|_2}$ where e_1 is the first ordinary basis vector
- ▶ **Lemma:** $\mathbb{P}[|S_1| \geq t] \leq 2e^{-\frac{dt^2}{2}}$ $\log(2n) < \frac{d\epsilon^2}{2}$
- ▶ The inner product $Su = \left(\frac{g}{\|g\|_2}\right)^T \frac{u}{\|u\|_2}$ is small for all fixed directions $\frac{u}{\|u\|_2}$, implying near-orthogonality
- ▶ For n fixed vectors u_1, \dots, u_n , we can apply union bound



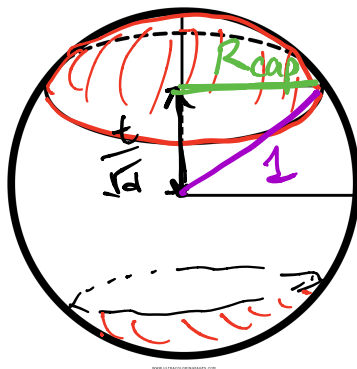
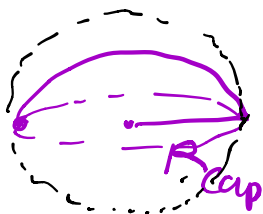
$\max_{i=1, \dots, n} x_i \geq t$
 \Downarrow
 $\exists i \text{ s.t. } x_i \geq t$

$$\mathbb{P}\left[\max_{i=1, \dots, n} |Su_i| \geq t\right] \leq \sum_{i=1}^n 2e^{-\frac{dt^2}{2}} = 2ne^{-\frac{dt^2}{2}} = e^{-\frac{dt^2}{2} + \log(2n)}$$

$\leq \mathbb{P}\left[\bigcup_{i=1, \dots, n} \{|Su_i| \geq t\}\right] \leq \sum \mathbb{P}[|Su_i| \geq t]$

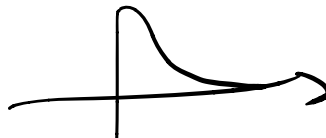
Concentration of Measure for Uniform Distribution on the Sphere

- ▶ **Lemma (rephrased):** $\mathbb{P} \left[\left| \frac{g_1}{\|g\|_2} \right| \geq \frac{t}{\sqrt{d}} \right] \leq 2e^{-\frac{t^2}{2}}.$
- ▶ Note that $\frac{g}{\|g\|_2}$ is distributed uniformly on the unit sphere



Surface area of sphere $\propto R^{d-1}$

- ▶ Pythagorean theorem: $\frac{t^2}{d} + R_{\text{cap}}^2 = 1$ implies $R_{\text{cap}} = \sqrt{1 - \frac{t^2}{d}}$
 - ▶ $\mathbb{P} \left[\left| \frac{g_1}{\|g\|_2} \right| \geq \frac{t}{\sqrt{d}} \right] \leq \frac{\text{area of the spherical cap}}{\text{area of the sphere}} \leq \frac{\left(\sqrt{1 - \frac{t^2}{d}} \right)^{d-1}}{1}$
 - ▶ using the fact $(1 - \frac{x}{n})^n \leq e^{-x}$ we get
- $$\mathbb{P} \left[\left| \frac{g_1}{\|g\|_2} \right| \geq \frac{t}{\sqrt{d}} \right] \leq 2e^{-\frac{t^2}{2}}.$$



Proof of JL Lemma

- ▶ We need to show $\|Su_{ij}\|_2^2$ is concentrated around 1
- ▶ **Lemma** Let $S = \frac{1}{\sqrt{m}}G \in \mathbb{R}^{m \times n}$ where $G_{ij} \sim N(0, 1)$ and u be any fixed vector. Then

$$\mathbb{E}\|Su\|_2^2 = \|u\|_2^2$$

- ▶ implies that the distance between two points is preserved in expectation

▶ **Proof:**

$$\begin{aligned} \mathbb{E} \left[\begin{array}{c} \overbrace{G_{(u),1} \dots G_{(u),n}} \\ \cancel{G_{(u),1} \dots G_{(u),n}} \end{array} \right] & \mathbb{E} \left\| \frac{1}{\sqrt{m}} G u \right\|_2^2 = \mathbb{E} \frac{1}{m} u^T G G^T u \\ &= \mathbb{E} \frac{1}{m} u^T \sum_{k=1}^m G_{(k)} G_{(k)}^T u \\ &= \frac{1}{m} u^T \sum_{k=1}^m \underbrace{\mathbb{E} G_{(k)} G_{(k)}^T}_{I} u \\ &= \frac{1}{m} u^T m I u = u^T u \end{aligned}$$

Proof of JL Lemma

- ▶ Set $S = \frac{1}{\sqrt{m}} G$ where $G \in \mathbb{R}^{m \times d}$ and $G_{ij} \sim N(0, 1)$
- ▶ Consider the probability that $\|Su\|_2^2$ deviates from 1, i.e., projected vectors are stretched more than their expectation

we first show that $\mathbb{P} [\|Su\|_2^2 \geq (1 + \epsilon)\|u\|_2^2] \leq e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}}$

$$\mathbb{P}\left(\frac{1}{m} \|Gu\|_2^2 > (1 + \epsilon)\right) = \mathbb{P}\left(\frac{1}{m} \sum_{i=1}^m (G_{(i)}^T u)^2 > 1 + \epsilon\right)$$

$$z_i \triangleq \sum_{j=1}^d G_{ij} u_j$$

$N(0, 1)$ Gaussian distributed

$$\mathbb{E} z_i = \mathbb{E} \sum_{j=1}^d G_{ij} u_j$$

$$= \sum (\mathbb{E} G_{ij}) u_j$$

$$= 0$$

$$= \mathbb{P}\left(\frac{1}{m} \sum_{i=1}^m \left(\underbrace{\sum_{j=1}^d G_{ij} u_j}_{z_i}\right)^2 > 1 + \epsilon\right)$$

$$= \mathbb{P}\left(\frac{1}{m} \sum_{i=1}^m z_i^2 > 1 + \epsilon\right)$$

$$\text{Var}(z_i) = \sum_j \underbrace{\text{Var}(G_{ij} u_j)}_{N(0, u_j^2)} = \sum_{j=1}^d u_j^2 = 1$$

Proof of JL Lemma

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$$\mathbb{P} \left[\frac{\lambda}{m} \sum_{i=1}^m z_i^2 > (1+\epsilon) \cdot \lambda \right] = \mathbb{P} \left[e^{\frac{\lambda}{m} \sum_{i=1}^m z_i^2 - (1+\epsilon) \cdot \lambda} > e \right]$$

Apply Markov's Inequality

$$\leq \frac{\mathbb{E} e^{\frac{\lambda}{m} \sum_{i=1}^m z_i^2}}{e^{(1+\epsilon) \cdot \lambda}}$$

$$= \mathbb{E} \prod_{i=1}^m e^{\lambda \cdot z_i^2} \cdot e^{-(1+\epsilon) \cdot \lambda m}$$

$\lambda \leftarrow \lambda \cdot m$

$$= \prod_{i=1}^m \mathbb{E} [e^{\lambda z_i^2}] \cdot e^{-(1+\epsilon) \cdot \lambda m}$$

Moment Generating Function
of $z_i^2 \cdot \lambda$

Proof of JL Lemma

$$\int e^{\lambda \cdot z} \cdot p(z) dz = \sqrt{\frac{1}{1-2\lambda}}$$

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- ▶ $\mathbb{P} [\|Su_{ij}\|_2^2 \geq (1 + \epsilon)\|u_{ij}\|_2^2] \leq \sum_{i,j} e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}} = n^2 e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}}$

pick $\lambda = \frac{\epsilon}{2(1+\epsilon)}$

$$\leq \left(\frac{1}{1-2\lambda} \right)^{m/2} e^{-(1+\epsilon) \cdot \lambda m} \leq e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}}$$

$$\lambda^* = \frac{\epsilon}{2(1+\epsilon)}$$

Proof of JL Lemma

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- ▶ $\mathbb{P} [\|Su_{ij}\|_2^2 \geq (1 + \epsilon)\|u_{ij}\|_2^2] \leq \sum_{i,j} \overset{\text{union bound}}{\downarrow} e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}} = n^2 e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}}$

Set error probability = $\frac{1}{2} = n^2 e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}} + \log(n^2)$

- ▶ $m = \frac{9 \log n}{\epsilon^2 - \epsilon^3}$

Proof of JL Lemma

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Set error probability = $\frac{1}{2} = n^2 e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}}$

- ▶ $m = \frac{9 \log n}{\epsilon^2 - \epsilon^3}$

for smaller error probability $0.01 = n^2 e^{-(\epsilon^2 - \epsilon^3)\frac{m}{4}}$

- ▶ $m = \frac{\text{constant} \times \log n}{\epsilon^2 - \epsilon^3}$

True ‘projections’: random subspaces also work

- ▶ Pick $S_{(i)}$ uniformly random on the unit sphere
- ▶ Pick $S_{(i+1)}$ uniformly random on the unit sphere and $\perp S_{(i)}, \dots S_{(1)}$
- ▶ S is a projection matrix, which projects onto a uniformly random subspace

$$\mathbb{P} \left\{ \left| \|Su\|_2 - \sqrt{\frac{m}{d}} \right| > t \right\} \leq 2e^{-\frac{t^2 d}{2}}$$

- ▶ Applying union bound for all points $i, j = 1, \dots, d$ gives a similar result
- ▶ Random i.i.d. S matrices are easier to generate and approximately orthogonal: $\mathbb{E} S^T S = I$

Computationally cheaper random matrices

- ▶ Gaussian $S_{ij} = \frac{1}{\sqrt{m}} N(0, 1)$
- ▶ Rademacher

$$S_{ij} = \begin{cases} +\frac{1}{\sqrt{m}} & \text{with probability } \frac{1}{2} \\ -\frac{1}{\sqrt{m}} & \text{with probability } \frac{1}{2} \end{cases} \quad (1)$$

- ▶ Bernoulli-Rademacher

$$S_{ij} = \begin{cases} +\frac{\sqrt{3}}{\sqrt{m}} & \text{with probability } \frac{1}{6} \\ 0 & \text{with probability } \frac{2}{3} \\ -\frac{\sqrt{3}}{\sqrt{m}} & \text{with probability } \frac{1}{6} \end{cases} \quad (2)$$

- ▶ other sparse matrices (e.g. one non-zero per column)
- ▶ Fourier transform based matrices

Optimality of the JL Embedding

- ▶ Let $\epsilon \in (0, \frac{1}{2})$. Given any set of points $\{x_1, \dots, x_n\}$ in \mathbb{R}^d , there exists a map $S : \mathbb{R}^n \rightarrow \mathbb{R}^m$ with $m = \frac{9 \log(n)}{\epsilon^2 - \epsilon^3}$ such that

$$1 - \epsilon \leq \frac{\|Sx_i - Sx_j\|_2^2}{\|x_i - x_j\|_2^2} \leq 1 + \epsilon \quad (\star)$$

- ▶ Can we embed to a **smaller dimension**?
- ▶ maybe using a **nonlinear** embedding?

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▶ **No**

Johnson-Lindenstrauss Embedding is optimal

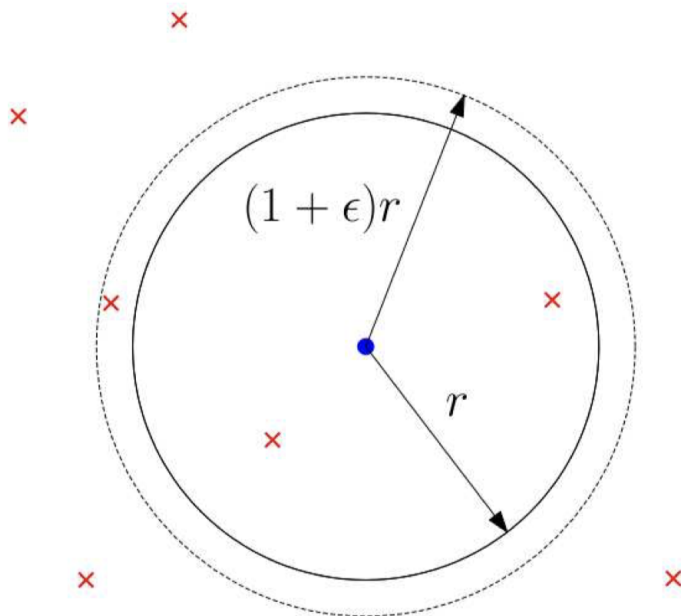
- ▶ There exists a set of n points $\{x_1, \dots, x_n\}$ such that any linear/nonlinear embedding satisfying (\star) must have $m \geq O(\frac{\log n}{\epsilon^2})$.

Applications of JL Embeddings

- ▶ General idea: run algorithms on $Sx_1, \dots, Sx_n \in \mathbb{R}^m$ instead of x_1, \dots, x_n
- ▶ Examples:
 - ▶ approximate nearest neighbor search
 - ▶ estimating norms and frequency moments
 - ▶ regression
 - ▶ classification
 - ▶ randomized matrix operations (matrix multiplication, decomposition etc)
 - ▶ optimization
 - ▶ ...

Approximate Nearest Neighbors

- ▶ Given a point set $P = \{x_1, \dots, x_n\} \in \mathbb{R}^d$
- ▶ and a query point $q \in \mathbb{R}^d$
- ▶ Find an ϵ -approximate nearest neighbor to q from P



Estimating p-norms

- ▶ Streaming data

$$x_{t+1} = x_t + \delta_t$$

- ▶ Estimate $\|x\|_2$
- ▶ second moment

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- ▶ **linear sketch**

Generate S randomly such that $\mathbb{E}S^T S = I$

Let $y_t = Sx_t$

$$y_t = Sx_t + S\delta_t$$

- ▶ $\|Sy\|_2^2 \approx \|Sx\|_2^2$

Estimating p-norms

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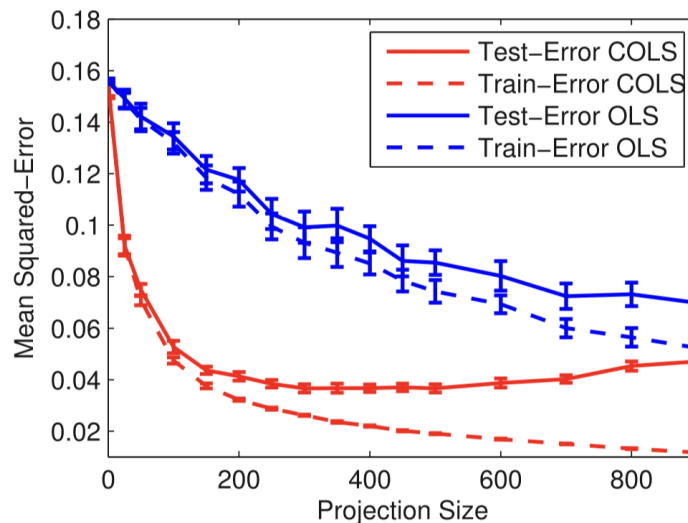
- ▶ Can also be extended to $\|x\|_p$

Music similarity prediction

- ▶ Predict the similarity score $\in [0, 1]$ between 30 second tracks
- ▶ Frequency based features from each 200ms segment results in 10^6 features
- ▶ OLS: randomly pick m features
- ▶ COLS: apply random projection to dimension m

Fard et al. Compressed Least-Squares Regression on Sparse Spaces, 2012

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Random Projection for Approximate Matrix Multiplication

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- ▶ need to characterize $\|Sx\|_2^2 - \|x\|_2^2$ for vectors x
- ▶ **Definition:** (ϵ, δ, p) JL moment property

$$\mathbb{E} \left| \|Sx\|_2^2 - 1 \right|^p \leq \epsilon^p \delta$$

for any unit norm x where $p \geq 2$

Random Projection for Approximate Matrix Multiplication

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Approximating inner products

► Lemma

$$\mathbb{E} \left| \|Sx\|_2^2 - 1 \right|^p \leq \epsilon^p \delta$$

for any unit norm x implies that

$$\mathbb{E} \left| x^T S^T S y - x^T y \right|^p \leq 3\epsilon^p \delta$$

since

$$x^T y = \frac{1}{2} (\|x\|_2^2 + \|y\|_2^2 - \|x - y\|_2^2)$$

$$x^T S^T S y = \frac{1}{2} (\|Sx\|_2^2 + \|Sy\|_2^2 - \|S(x - y)\|_2^2)$$

Random Projection for Approximate Matrix Multiplication

► Let $C = AS^T SB$

$$\begin{aligned}\mathbb{P}[\|AB - C\|_F > 3\epsilon\|A\|_F\|B\|_F] &= [\|AB - C\|_F^p > (3\epsilon)^p\|A\|_F^p\|B\|_F^p] \\ &\leq \frac{\mathbb{E}\|AB - C\|_F^p}{(3\epsilon\|A\|_F\|B\|_F)^p}\end{aligned}$$

► Let $a_i = A_{(i)}$ and $b_i = B_{(i)}$

$$\|AB - C\|_F^2 = \sum_{ij} \left| (Sa_i)^T (Sb_j) - a_i^T b_j \right|^2$$

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- ▶ we can normalize $\frac{a_i}{\|a_i\|_2}$, $\frac{b_i}{\|b_i\|_2}$ and apply JL moment property to get

$$\mathbb{P}[\|AB - C\|_F > 3\epsilon\|A\|_F\|B\|_F] \leq \delta$$

Final error bound for random projection

- ▶ Let the approximate product of AB be $C = AS^T SB$

$$\mathbb{P} [\|AB - C\|_F > 3\epsilon \|A\|_F \|B\|_F] \leq \delta$$

- ▶ Follows from JL Moment property
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- ▶ $S \in \mathbb{R}^{m \times n} \sim \frac{1}{\sqrt{m}} \times \text{Fast JL Transform with } m = \frac{c_3}{\epsilon} \log \frac{1}{\delta}$
- ▶ Sparse JL and Fast JL are more efficient
- ▶ advantages: doesn't require any knowledge about matrices A and B (**oblivious**)
- ▶ optimal sampling probabilities depend on the column/row norms of A and B

Questions?