EE270 Large scale matrix computation, optimization and learning

Instructor: Mert Pilanci

Stanford University

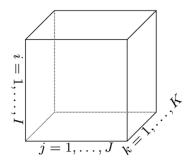
Thursday, Jan 26 2020

Randomized Linear Algebra Lecture 4: Approximate Tensor Products, Randomized Verification and Concentration Inequalities

Tensors and tensor multiplication

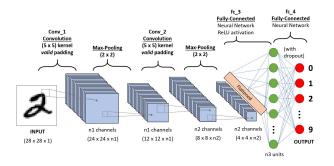
- A tensor is a multidimensional array
- Order of a tensor: number of dimensions, also known as modes
- ▶ An element (i, j, k) of a third-order tensor X is denoted by $X_{i,j,k}$
- ► (Frobenious) norm of a tensor

$$||X||_F = \sqrt{\sum_{i_1=1}^{l_1} \sum_{i_2=1}^{l_2} ... \sum_{i_N=1}^{l_N} |X_{i_1 i_2 ... i_N}|^2}$$



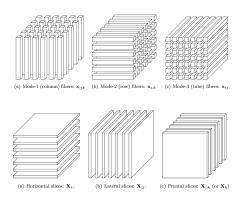
Tensors and tensor multiplication

 Deep Neural Network weights and activations are typically tensors



Tensors and tensor multiplication

- ► Fibers are the higher-order analogue of matrix rows and columns. Defined by fixing every index but one
- Slices are two-dimensional sections of a tensor, defined by fixing all but two indices



Tensor n-Mode Product

▶ n-mode (matrix) product of a tensor $A \in \mathbb{R}^{d_1 \times d_2 \times \cdots \times d_N}$ with a matrix $B \in \mathbb{R}^{p \times d_n}$ is elementwise

$$(A \times_n B)_{i_1,\dots,i_{n-1},i_{n+1}\dots i_N} = \sum_{i_n=1}^{d_n} A_{i_1 i_2 \dots i_n \dots d_N} B_{j i_n}$$

each mode-n fiber of A is multiplied by the matrix B

Approximate Tensor Multiplication

Algorithm 1 Approximate Tensor n-Mode Product via Sampling Input: An $d_1 \times \cdots \times d_n \times \cdots \times d_N$ dimensional tensor A and an $p \times d_n$ dimensional tensor B, an integer m and probabilities $\{p_k\}_{k=1}^{d_n}$ Output: Tensors CR such that $CR \approx AB$

- 1: **for** t = 1 to m **do**
- 2: Pick $i_t \in \{1,...,d_n\}$ with probability $\mathbb{P}[i_t = k] = p_k$ in i.i.d. with replacement
- 3: Set $C^{(t)} = \frac{1}{\sqrt{mp_{i_t}}} A_{:,i_t,:}$ and $R_{(t)} = \frac{1}{\sqrt{mp_{i_t}}} B_{:,i_t,:}$
- 4: end for
- ▶ We can multiply *CR* using the classical algorithm
- ► Complexity $O(d_1 \cdots d_{n-1} m d_{n+1} \cdots d_N p)$

Approximate Tensor Multiplication: Mean and variance

$$M_{\vec{i}\vec{j}} \triangleq (A \times_n B)_{i_1, \dots, i_{n-1} j i_{n+1} \dots i_N} = \sum_{i_n=1}^{d_n} A_{i_1 i_2 \dots i_n \dots i_N} B_{j i_n}$$

$$\hat{M}_{\vec{i}\vec{j}} \triangleq \sum_{i_n=1}^m \frac{1}{p_{i_n}} A_{i_1 i_2 \cdots i_n \cdots i_N} B_{j i_n}$$

- Mean and variance of the matrix multiplication estimator
 Lemma
- $\blacktriangleright \mathbb{E}\left[\hat{M}_{\vec{i}\vec{j}}\right] = M_{\vec{i}\vec{j}}$
- ▶ Var $\left[\hat{M}_{\vec{i}\vec{j}}\right] = \frac{1}{m} \sum_{i_n=1}^{d_n} \frac{1}{p_{i_n}} A_{i_1 i_2 \cdots i_n \cdots i_N}^2 B_{ji_n}^2 \frac{1}{m} (M_{\vec{i}\vec{j}})^2$

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- lacksquare minimize $_{p}\,\mathbb{E}\|\hat{M}-M\|_{F}^{2}=\sum_{ec{i}ec{j}}\mathbf{Var}\left[\hat{M}_{ec{i}ec{j}}
 ight]$

Approximate Multiplication for Tensors

$$\hat{M}_{\vec{i}\vec{j}} \triangleq \sum_{i_n=1}^m \frac{1}{\rho_{i_n}} A_{i_1 i_2 \cdots i_n \cdots i_N} B_{j i_n}$$

Importance sampling distribution

$$p_{k} = \frac{\|A_{:\cdots k\cdots:}\|_{F} \|B_{:k}\|_{F}}{\sum_{k} \|A_{:\cdots k\cdots:}\|_{F} \|B_{:k}\|_{F}}$$

Verifying Matrix Multiplication

- ▶ Given three $n \times n$ matrices A, B, M
- verify whether

$$AB = M$$

Naive method: $O(n^3)$

Randomized Algorithm for Verifying Matrix Multiplication

- ► Sample a random vector $r = [r_1, ..., r_n]^T$
- ► Compute ABr by first computing Br and then A(Br)
- ► Compute *Mr*
- ▶ If $A(Br) \neq Mr$, then $AB \neq M$
- ightharpoonup Otherwise, return AB = M

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- Complexity: three matrix-vector multiplications $O(n^2)$ Freivalds' Algorithm (1977)

Failure Probability

- ▶ Let $r = [r_1, ..., r_n]^T$ be i.i.d. +1, -1 each with probability $\frac{1}{2}$
- ▶ Lemma $\mathbb{P}[ABr = Mr] \leq ?$

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Multiple trials

- $ightharpoonup r=[r_1,...,r_n]^T$ be i.i.d. 0,1 each with probability $\frac{1}{2}$ also works
- ➤ To improve the error probability, we run the algorithm independently k times with

$$r_1,...,r_k \in \mathbb{R}^n$$
 i.i.d.

- If we ever find an r_k such that $ABr_k \neq Mr$
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- If we ever find an r_k such that $ABr_k \neq Mr$
- lacktriangle then the algorithm correctly returns $AB \neq M$
- If we always find ABr = Mr, then the error probability is at most $\frac{1}{2^k}$
- For k = 25 we have error probability $\leq 10^{-9}$.

Concentration bounds: Tighter success probability

- In AMM size of the sample is $m=\frac{1}{\delta\epsilon^2}$. dependence on the failure probability δ is not ideal we can do better
- recall Markov's Inequality For Z > 0 and t > 0

$$\mathbb{P}\left[Z>a\right]\leq\frac{\mathbb{E}Z}{a}$$

► Chebyshev's inequality Let X be a random variable with expectation $\mathbb{E}[X]$ and variance $\mathbf{Var}[X]$

$$\mathbb{P}\left[|X - \mathbb{E}[X]| \ge t\right] \le \frac{\mathsf{Var}(\mathsf{X})}{t^2}.$$

Concentration of independent sums

- Chernoff Bound¹
- Let $X_1,...,X_m$ be independent random variables $\in [0,1]$ and let $\mu=\mathbb{E} X_1$

$$\mathbb{P}\left[\left|\frac{1}{m}\sum_{i=1}^{m}X_{i}-\mu\right|>t\mu\right]\leq 2e^{-m\frac{t^{2}\mu}{3}}$$

¹There are other versions of the Chernoff bound which have better constants

Application 1: Monte Carlo Approximations

- ightharpoonup Estimating π
- Sample $z_1, ..., z_m$ i.i.d. uniform in $[0, 1]^2$
- ▶ Let $Z_i = 1$ if $||z_i||_2 \le 1$ and 0 otherwise
- $\blacktriangleright \mathbb{P}[Z_i=1]=\tfrac{\pi}{4}$

Application 1: Monte Carlo Approximations

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- ▶ Let $Z_i = 1$ if $||z_i||_2 \le 1$ and 0 otherwise
- $\triangleright \mathbb{P}[Z_i=1]=\tfrac{\pi}{4}$
- ► Applying Chernoff bound we get

$$\left|\frac{1}{m}\sum_{i=1}^{m}Z_{i}-\frac{\pi}{4}\right|\leq\epsilon\frac{\pi}{4}$$

with probability at least $1-2e^{-m\epsilon^2\frac{\pi}{12}}$

we can pick $m \geq \frac{12}{\pi\epsilon^2}\log\frac{2}{\delta}$ and obtain an estimate $\hat{\pi}$ such that $(1-\epsilon)\pi \leq \hat{\pi} \leq (1+\epsilon)\pi$ with probability at least $1-\delta$ the range $[(1-\epsilon)\pi, (1+\epsilon)\pi]$ is a confidence interval

Application 2: Amplifying Probability of Success

- Suppose we have a randomized algorithm which produces an ϵ approximation $|\hat{x} x^*| \le \epsilon$ with probability at least 0.9
- Repeat the algorithm m times independently
- Take median of m outputs

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- Suppose we have a randomized algorithm which produces an ϵ approximation $|\hat{x} x^*| \le \epsilon$ with probability at least 0.9
- ▶ Repeat the algorithm *m* times independently
- ► Take median of *m* outputs
- ▶ Let $X_i = 1$ if the *i*-th trial is **good**, i.e., $|\hat{x}_i x^*| \le \epsilon$
- Median of the m outputs is also **good**, i.e., $|\text{Median}(\hat{x}_i) x^*| \le \epsilon$ if **at least half** of the X_i 's are one
- ► Chernoff Bound implies that $\left|\frac{1}{m}\sum_{i=1}^{m}X_i 0.9\right| \le 0.9t$ with probability $1 e^{-t^20.9m/3}$. Pick t = 0.4/0.9
- Median is an ϵ approximation with probability at least $1-e^{-0.059m}$
 - e.g., for m = 200, failure probability is $\leq 7 \times 10^{-6}$.

- Chernoff bound implies that majority of estimators are good
- The definition of median does not extend to the matrix case in a simple way
- ► Recall AMM final probability bound For any $\delta > 0$, set $m = \frac{1}{\delta \epsilon^2}$ to obtain

$$\mathbb{P}\left[\|AB - CR\|_F > \epsilon \|A\|_F \|B\|_F\right] \le \delta$$

- ▶ suppose $||A||_F = ||B||_F = 1$ and let $\epsilon = 0.1$, $\delta = 0.9$
- Repeat independently and obtain $C_1R_1, ..., C_tR_t$ in t independent trials

$$||AB - C_iR_i||_F < 0.1$$
 with probability 0.9 for each i

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- ► Compute $\rho_i \triangleq |\{j \mid j \neq i, \|C_iR_i C_jR_j\|_F \leq 0.2\}|$
- \triangleright ρ_i is the number of *neighbors*
- ▶ Output $C_k R_k$ such that $\rho_k > \frac{t}{2}$
- ▶ **Lemma:** $||AB C_k R_k||_F \le 0.3$ with probability at least $1 e^{-0.059m}$.

Median Trick for Matrices

- Proof:
- ▶ triangle inequality: $||X + Y||_F \le ||X||_F + ||Y||_F$ and
- reverse triangle inequality: $||X + Y||_F \ge ||X||_F ||Y||_F$ for matrices $X, Y \in \mathbb{R}^{n \times p}$.
- ▶ These inequalities imply $\|C_iR_i C_jR_j\|_F \le \|C_iR_i AB\|_F + \|C_jR_j AB\|_F + \|C_iR_i C_jR_j\|_F \ge \|C_iR_i AB\|_F \|C_jR_j AB\|_F$

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- ▶ If C_iR_i is \mathbf{good} , $\|AB C_iR_i\|_F \le 0.1$ then it is close to at least half of the other C_jR_j 's $\rho_i \triangleq |\{j \mid j \neq i, \ \|C_iR_i C_jR_j\|_F \le 0.2\}| \ge \frac{t}{2}$ by triangle inequality

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- ► These inequalities imply $\|C_iR_i C_jR_j\|_F \le \|C_iR_i AB\|_F + \|C_jR_j AB\|_F$ $\|C_iR_i - C_jR_j\|_F \ge \|C_iR_i - AB\|_F - \|C_iR_j - AB\|_F$
- If C_iR_i is \mathbf{good} , $||AB C_iR_i||_F \le 0.1$ then it is close to at least half of the other C_jR_j 's $\rho_i \triangleq |\{j \mid j \neq i, \ \|C_iR_i C_jR_j\|_F \le 0.2\}| \ge \frac{t}{2}$ by triangle inequality
- ▶ If C_iR_i is **bad**, i.e., $||AB C_iR_i||_F > 0.3$ then $||C_iR_i C_jR_j||_F \ge 0.2$ by triangle inequality and $\rho_i \le \frac{t}{2}$

Questions?