

# Analysis of Tensor Approximation for Compression-Domain Volume Visualization

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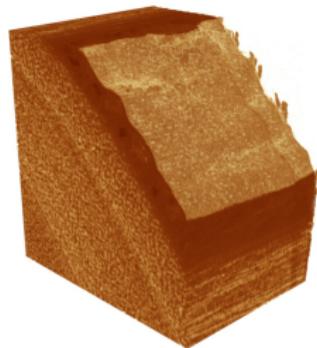
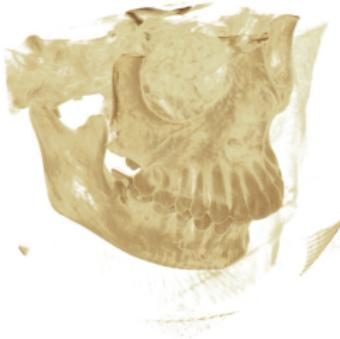
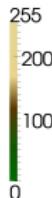
## Section 1

### **Background and Motivation**

# Context

- Large-scale interactive visualization: **complex** data over regular grids
  - Computer tomography, simulations, etc.
  - We tolerate (and encourage) approximations
- In volume rendering: data sets of size  $I^3$ , with  $I$  large (e.g. 2048).
  - Possible added dimension(s): features (RGB color, X-ray density), time, etc.
- Asymmetric pipeline:
  - Slow decomposition is acceptable (offline stage)
  - But **fast reconstruction** is critical (online stage)

# Example Volumes



# Tensor Approximation in Computer Graphics

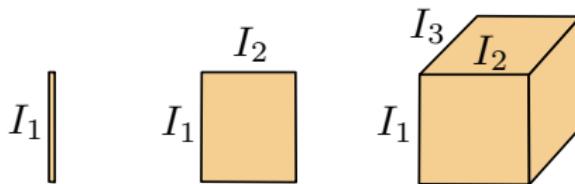
- **Texture synthesis** [VBP<sup>+</sup>05,CSS08,WXC<sup>+</sup>08]
- **Multiresolution rendering** [SIM<sup>+</sup>11,SMP13,BGG<sup>+</sup>14]
- **Micro-tomography compression** [BSP15, BP15]
- **Bidirectional texture functions**  
[WWS<sup>+</sup>05,WXC<sup>+</sup>08,RK09,TS12,Tsa15]
- **Bidirectional reflectance distribution functions** [RSK12]

## Section 2

# Introduction to Tensor Approximation

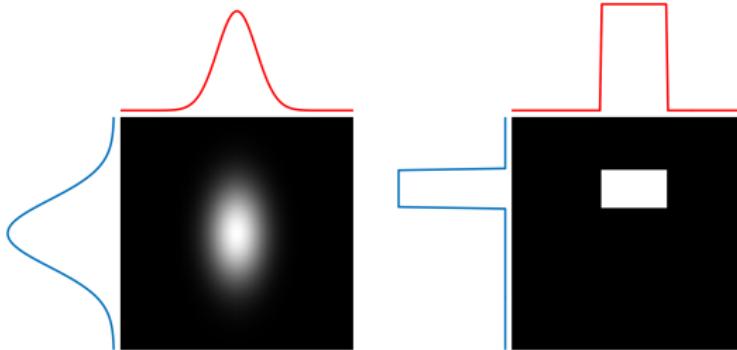
# What is a Tensor?

- For us, a *multidimensional array*:
  - A vector is a 1D tensor
  - A matrix is a 2D tensor
  - Etc...



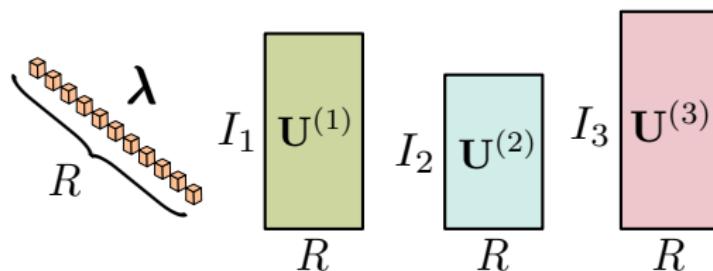
# In a Nutshell

- Let us express a tensor as a **sum of *simpler* terms**
- Main ingredient: **separable** (rank-1) components
- Example in 2D (outer product  $u \circ v$ )



# CP Decomposition

- One **factor matrix** per dimension
  - Coefficients in a **diagonal** form

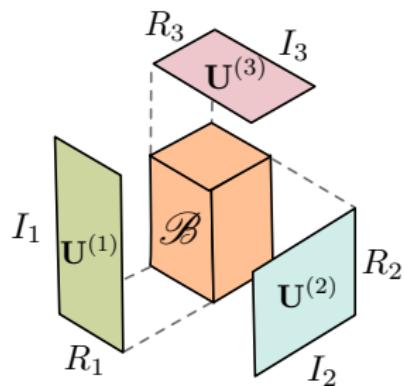


- Formula:

$$\mathcal{A} = \sum_{r=1}^R \lambda_r \cdot (u_r^{(1)} \circ_r^{(2)} \circ_r^{(3)})$$

# Tucker Decomposition

- Generalization of CP
- We can enforce orthonormality
- Here, most space is **used by the core**



# Tucker Decomposition

- Formula:

$$\mathcal{A} = \sum_{\substack{r_1=1, r_2=1, r_3=1 \\ r_1=R_1, r_2=R_2, r_3=R_3}} \mathcal{B}_{r_1 r_2 r_3} \cdot (u_{r_1}^{(1)} \circ u_{r_2}^{(2)} \circ u_{r_3}^{(3)})$$

- **Tensor-times-matrix** notation:  $\mathcal{B} \times_1 \mathbf{U}^{(1)} \times_2 \mathbf{U}^{(2)} \times_3 \mathbf{U}^{(3)}$
- **Distance preservation:**

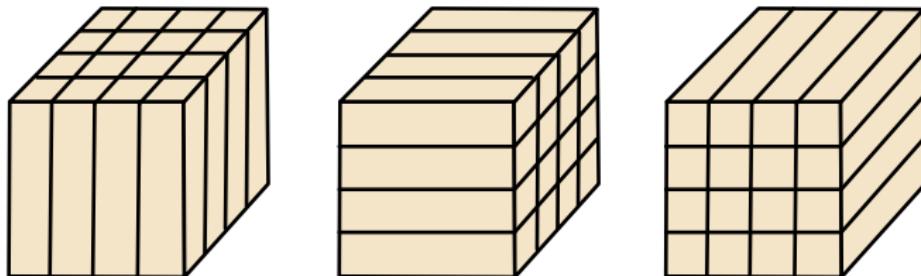
$$\left\{ \begin{array}{l} \mathcal{A}_1 \approx \mathcal{B}_1 \times_1 \mathbf{U}^{(1)} \times_2 \mathbf{U}^{(2)} \times_3 \mathbf{U}^{(3)} \\ \mathcal{A}_2 \approx \mathcal{B}_2 \times_1 \mathbf{U}^{(1)} \times_2 \mathbf{U}^{(2)} \times_3 \mathbf{U}^{(3)} \end{array} \right\} \Rightarrow \mathcal{B}_1 \approx \mathcal{B}_2$$

# Decomposition Algorithms

- CP: challenging problem → algorithms only work well *in practice*
- Tucker: there are error bounds
  - **Algorithm gives intuition** → let us look at it

# Fibers

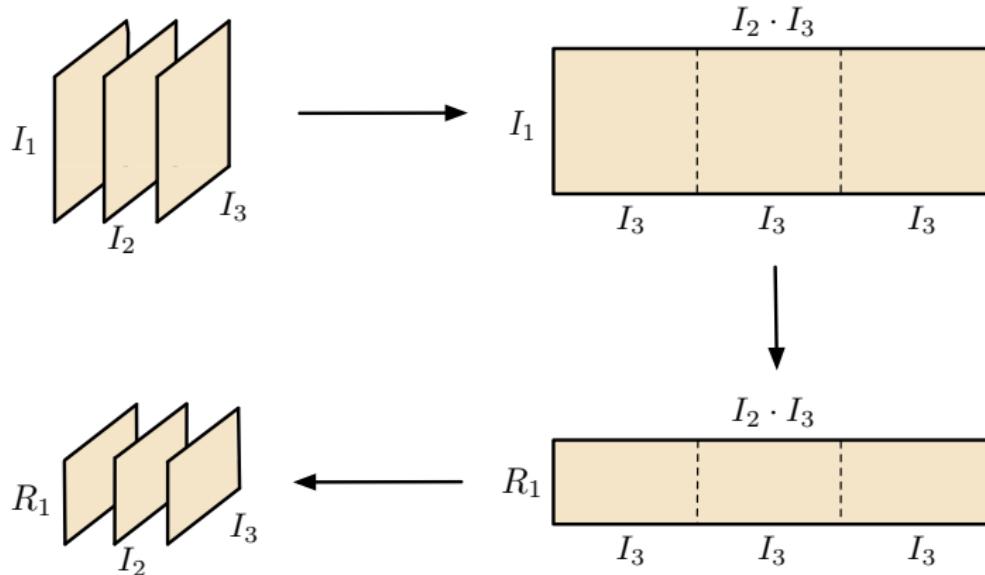
- In 3D: **columns, rows, tubes**



- Apply **principal component analysis (PCA)**

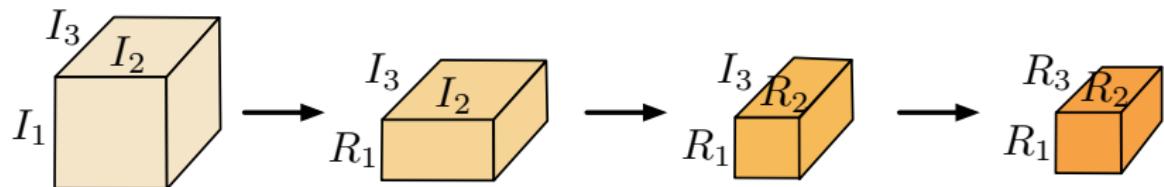
# Unfoldings

- We do PCA per fiber



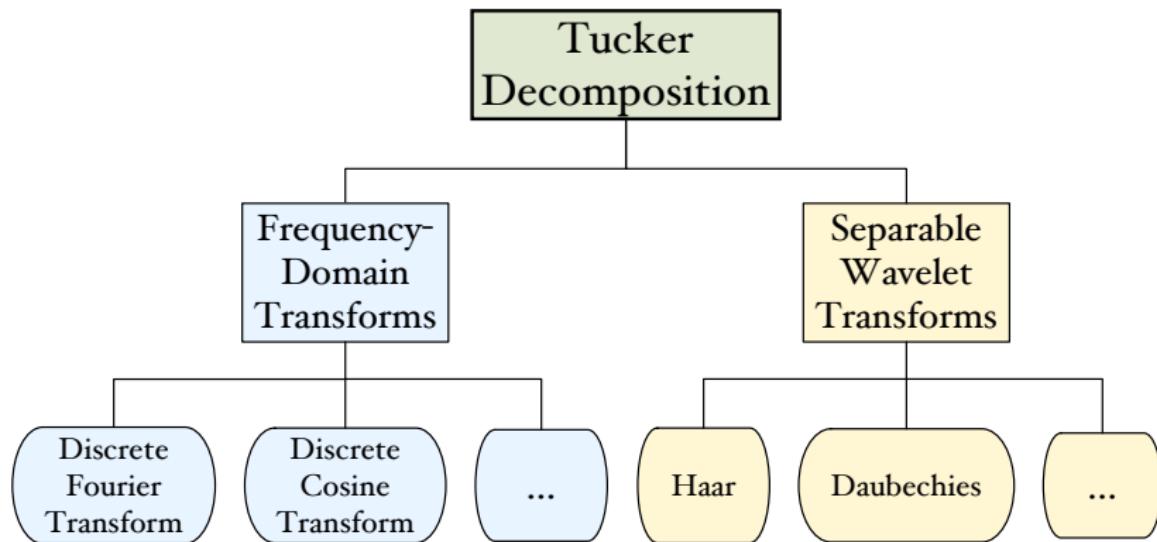
# Multilinear Transforms

- **Orthogonal basis** of  $R$  vectors
- Fibers are compressed one dimension at a time

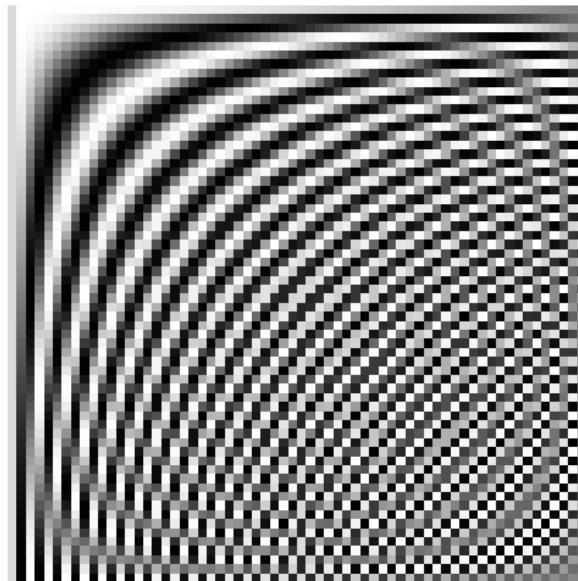


- This basis is precisely the matrices we want

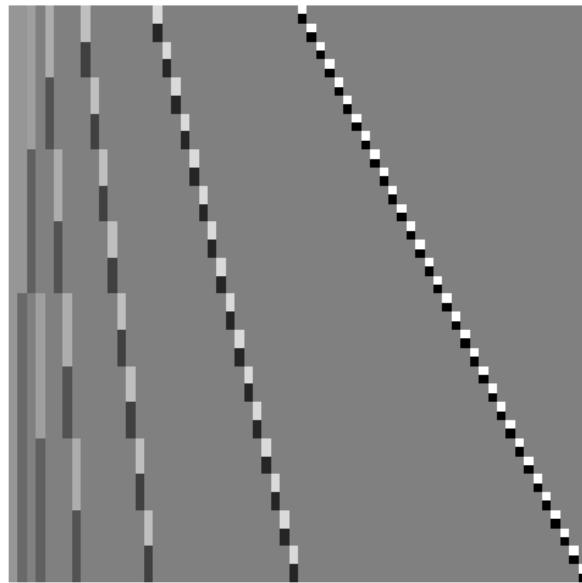
# In Context...



# Discrete Cosine Transform

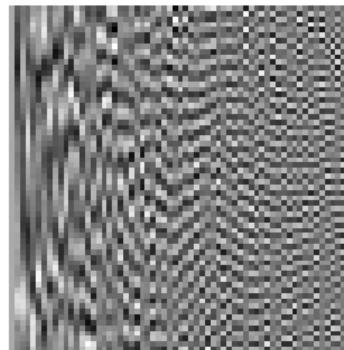
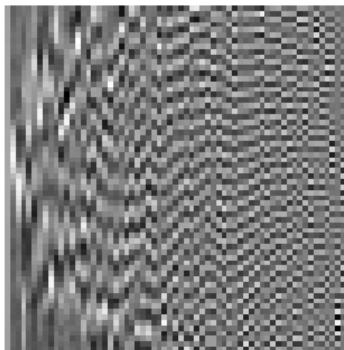
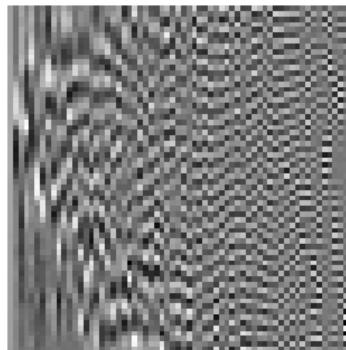


# Haar Wavelets



# Tucker Decomposition

- We leave it free → find **optimal** matrices

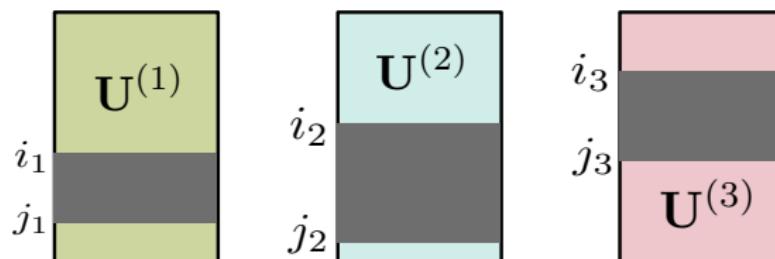


# Advantages of Tensor Approximation

- Optimal bases → **competitive compression** rates
  - Good for out-of-core solutions
  - Often, the compressed data fits **entirely in the GPU**
- For *many dimensions*, virtually **the only way to go**
- We can operate on the factor matrices:
  - Translation
  - Stretching
  - Projection
  - Convolution
  - Frequency-domain transforms
- Example: DCT on the factors + Reconstruction = Reconstruction + DCT on the result

# Spatial Selectivity

- To reconstruct the subregion  $[i_1, j_1] \times [i_2, j_2] \times [i_3, j_3]$ :

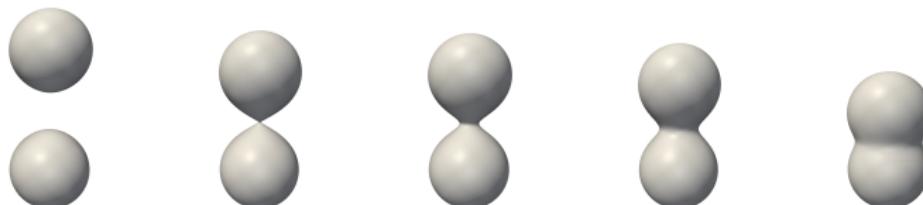


## Section 3

### Tensor-Based Compression

# Smooth Feature Compression

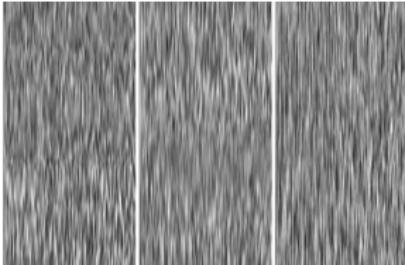
- At high compression rates, tensor approximation is good at **preserving visual features**
- One way to see it: **isosurfaces**
  - For example, spheres are isosurfaces of multivariate Gaussians (rank-1)



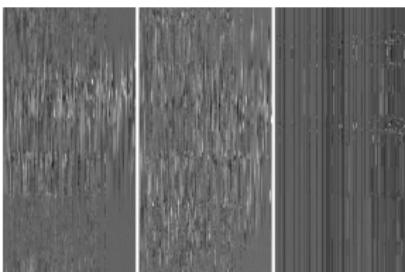
Metaballs: isosurfaces of a rank-1 function

# Example: CP

Lung

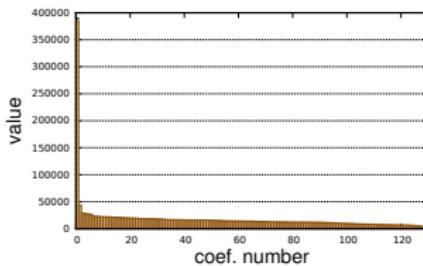
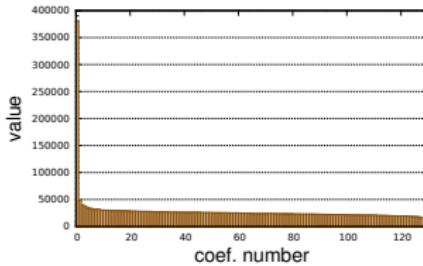


Video



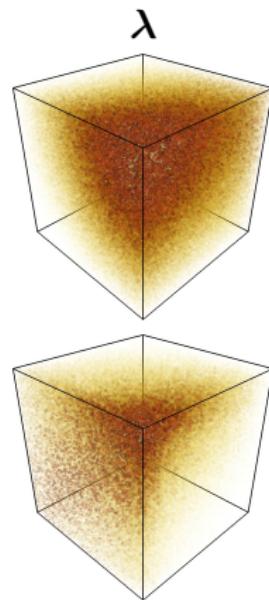
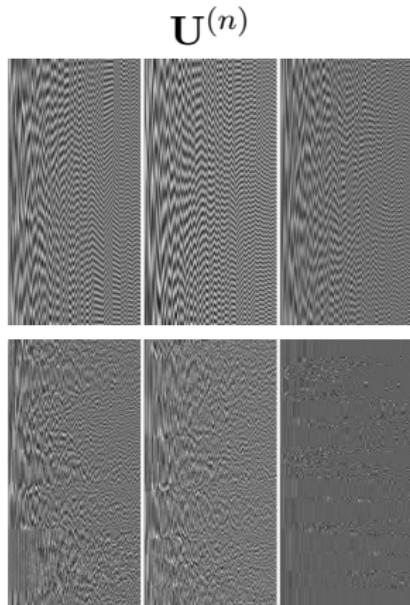
$\mathbf{U}^{(n)}$

$\lambda$



# Example: Tucker

Lung  
Video

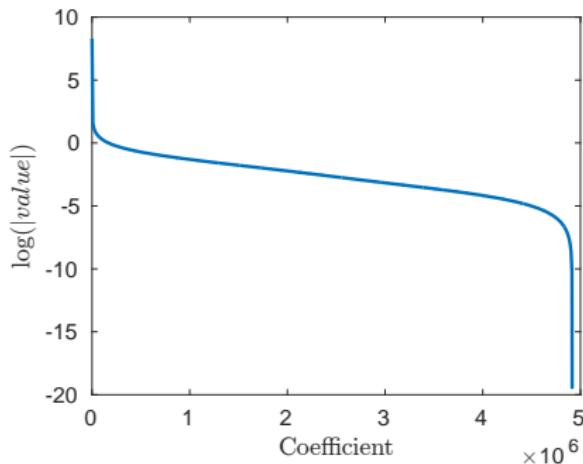


# Volume Compression

- Quantization [SMP13]
- Thresholding [BP15]
- Truncation [SMP13,BP15,BSP15]

# Quantization

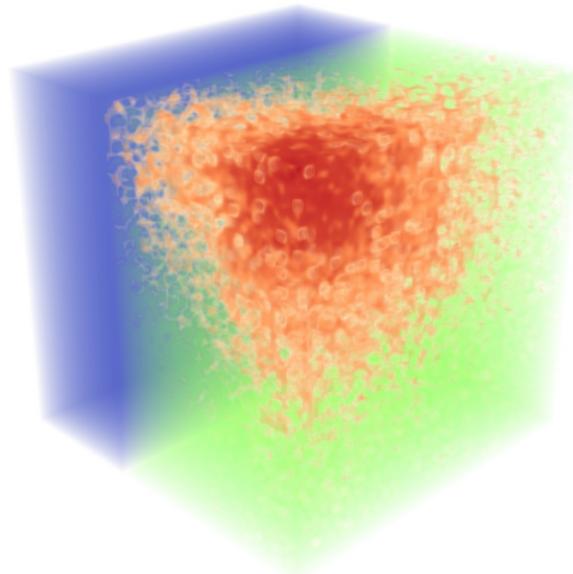
- Coefficients are roughly **logarithmic**:



- Logarithmic quantization** works best
  - E.g. 8 bits + 1 sign bit

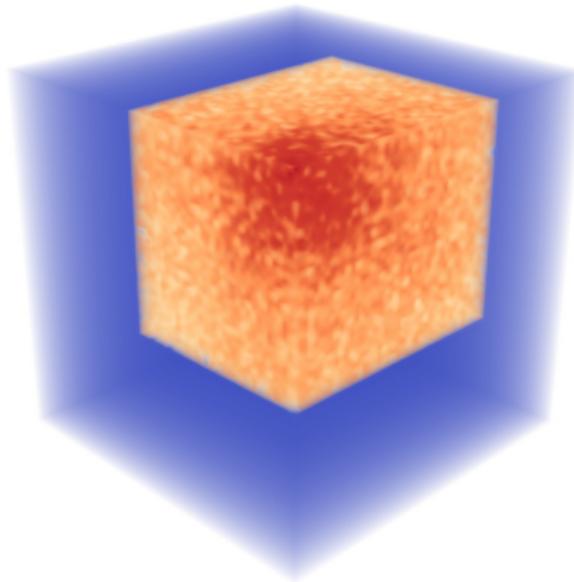
# Tucker Thresholding

- Make small elements 0
- Run-length + Entropy encoding



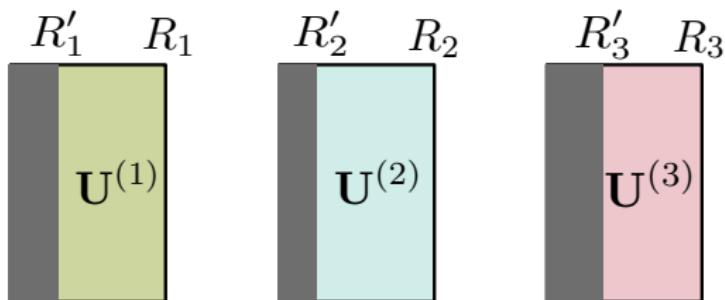
# Tucker Truncation

- During visualization, **reduce** ranks as needed
- Very fast to apply



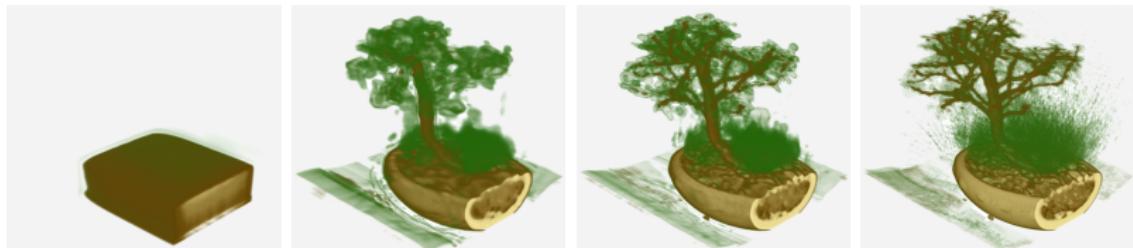
# Tucker Truncation

- Rank selection for interactive level-of-detail [SMP13]:  
Tucker core from  $\mathbb{R}^{R_1 \times R_2 \times R_3}$  to  $\mathbb{R}^{R'_1 \times R'_2 \times R'_3}$

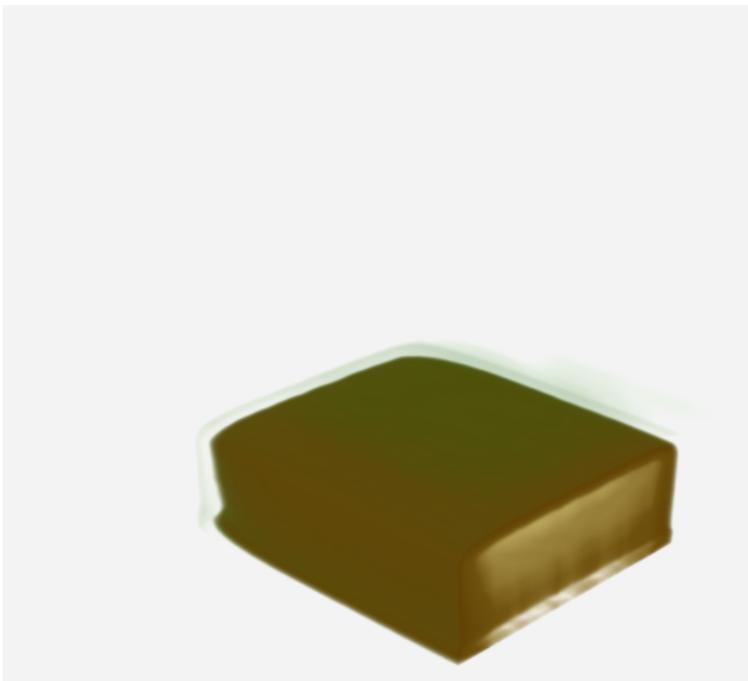


# Tucker Truncation

- **Different ranks select different features**
  - Example: bonsai ( $256^3$ ), from 1 to 256 Tucker ranks



# Tucker Truncation



# Tucker Truncation



# Tucker Truncation

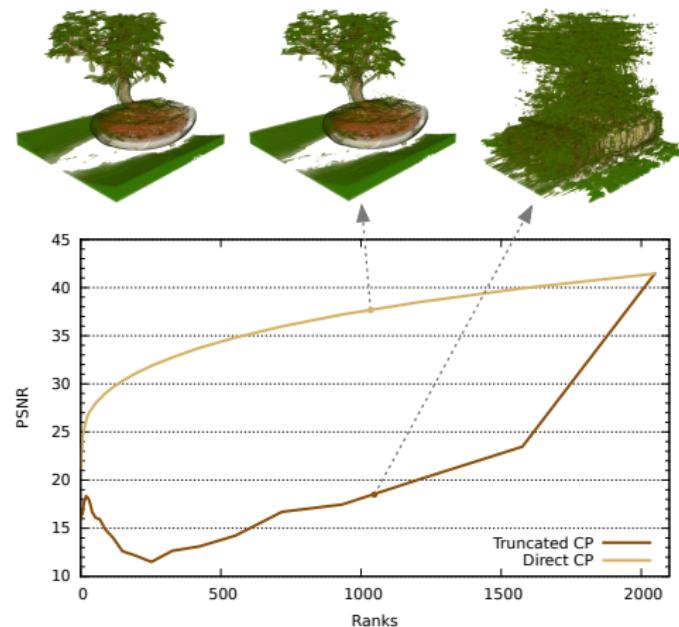


# Tucker Truncation



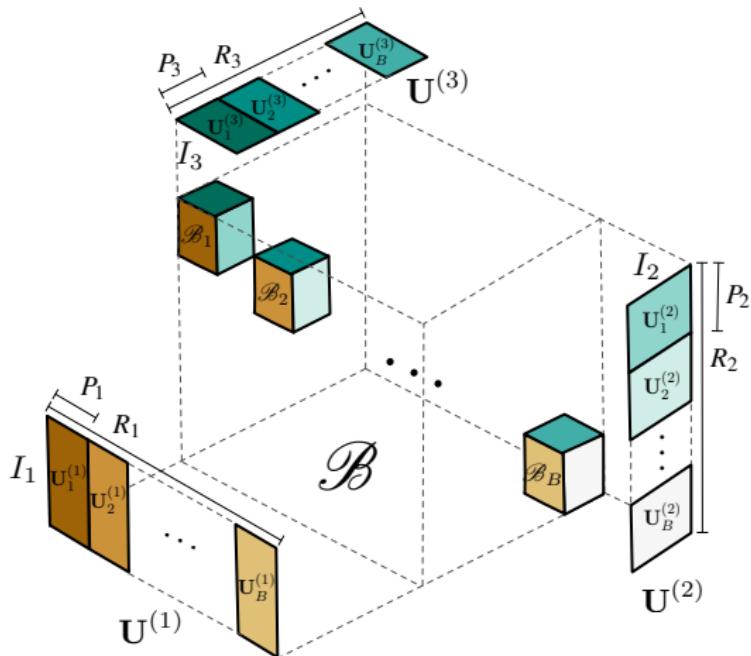
# CP Rank Truncation

- Truncation problems

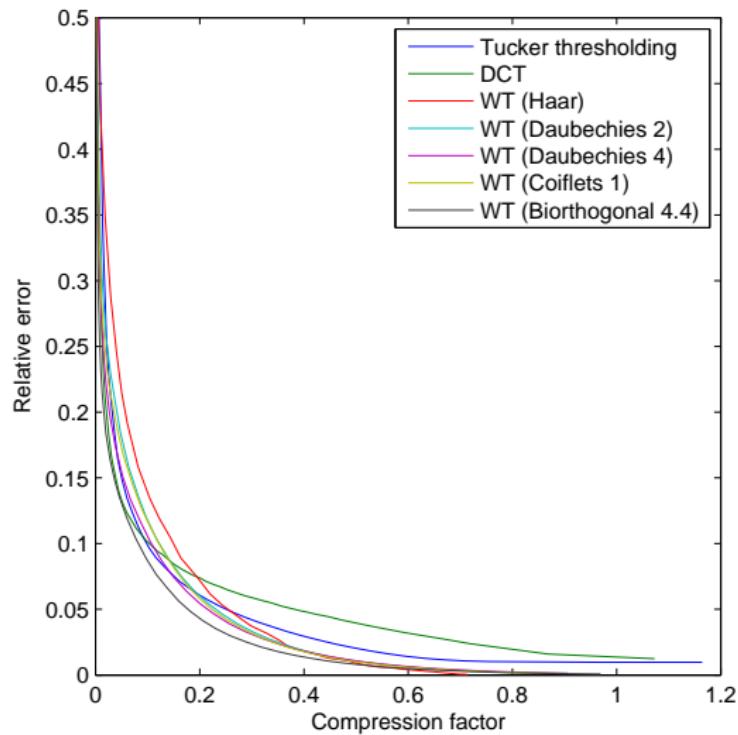


# One Solution

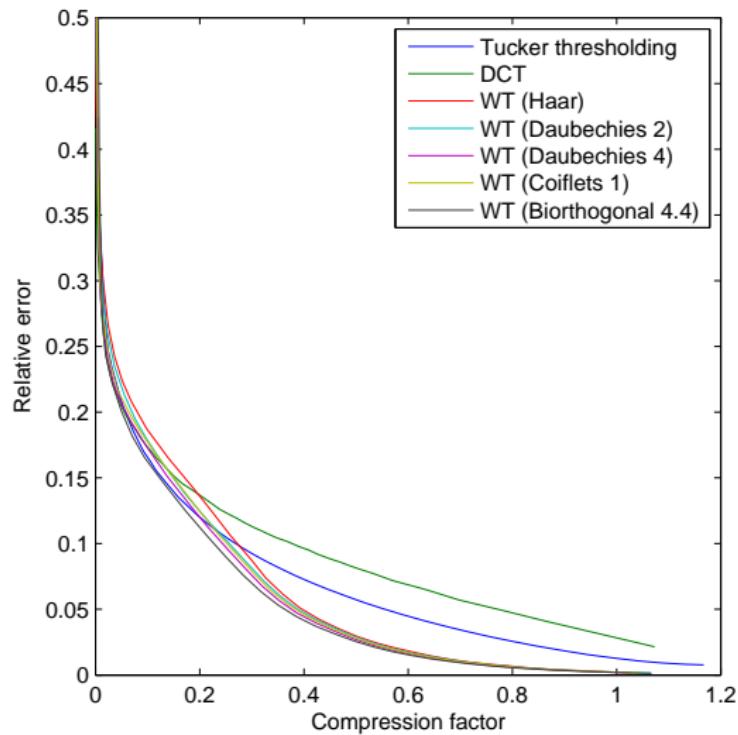
- Use incremental compression



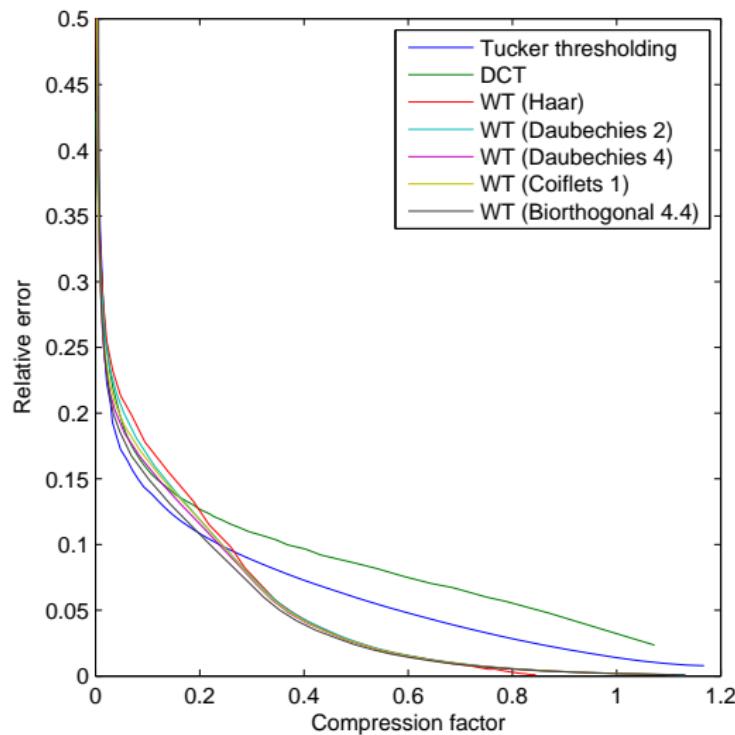
# Tucker vs. Wavelets (Bonsai)



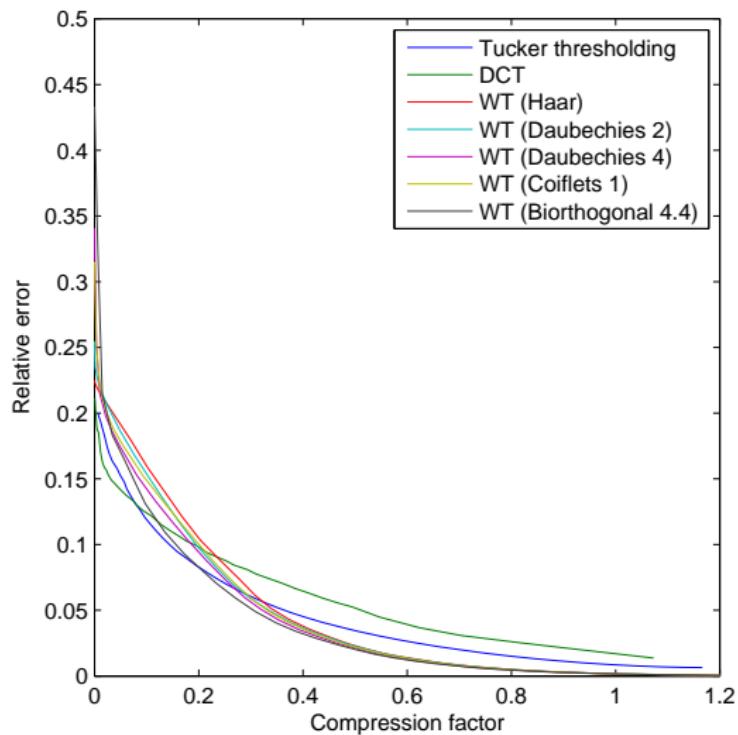
# Tucker vs. Wavelets (Foot)



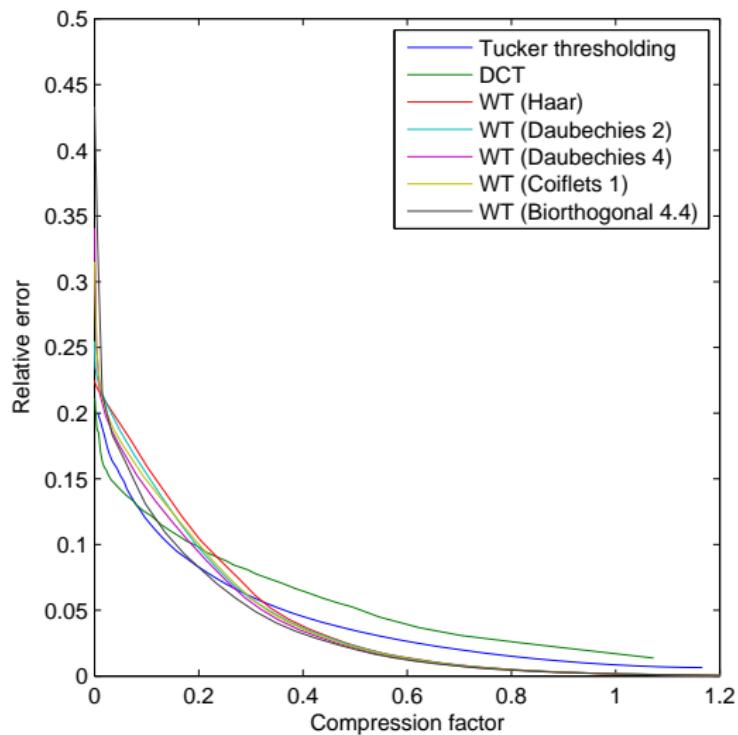
# Tucker vs. Wavelets (Skull)



# Tucker vs. Wavelets (Wood)



# Tucker vs. Wavelets (Wood)

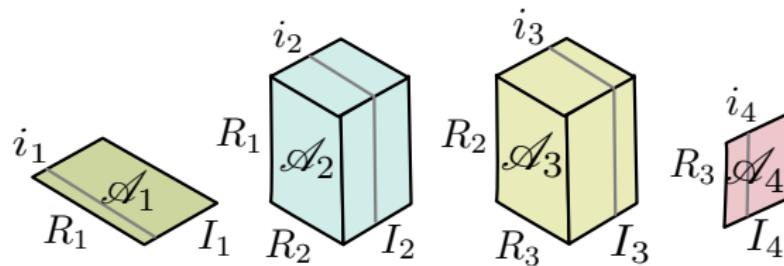


# Software and Methods

- C++: **vmmlib**
- MATLAB: Tensor Toolbox, Tensorlab
- Decomposition:
  - Up to  $2048^3$  is fine
  - After that, there are **incremental algorithms**
- Reconstruction:
  - Must be **fast**. We have also a CUDA implementation

# Future Work

- Tensor Train (TT): more recent model [Ose11]



- Even better suited for **many dimensions**
- Fast **random-access**

# Conclusions

- Tensor approximation **generalizes**:
  - **Frequency-based** transforms
  - Separable **wavelets**
- Good **compression quality**
- Good at **selecting features**
- Designed to overcome the **curse of dimensionality**
  - The more dimensions, the better the advantage

# Thank you!

- [VBP<sup>+</sup>05] D. Vlasic, M. Brand, H. Pfister, J. Popović: Face transfer with multilinear models.
- [WWS<sup>+</sup>05] H. Wang, Q. Wu, L. Shi, Y. Yu, N. Ahuja: Out-of-core tensor approximation of multi-dimensional matrices of visual data.
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- [WXC<sup>+</sup>08] Q. Wu, T. Xia, C. Chen, H.-Y. Lin, H. Wang, Y. Yu: Hierarchical tensor approximation of multidimensional visual data.
- [RK09] R. Ruiters, R. Klein: BTF compression via sparse tensor decomposition.
- [SIM<sup>+</sup>11] S. K. Suter, J. A. Iglesias Gutián, F. Marton, M. Agus, A. Elsener, C. Zollinofer, M. Gopi, E. Gobbetti, R. Pajarola: Interactive multiscale tensor reconstruction for multiresolution volume visualization.
- [Ose11] I. Oseledets: Tensor-train decomposition.
- [TS12] Y.-T. Tsai, Z.-C. Shih: K-clustered tensor approximation: a sparse multilinear model for real-time rendering.
- [RSK12] R. Ruiters, C. Schwartz, R. Klein: Data driven surface reflectance from sparse and irregular samples.
- [SMP13] S.K. Suter, M. Makhinya, R. Pajarola: TAMRESH: Tensor approximation multiresolution hierarchy for interactive volume visualization.
- [BGG<sup>+</sup>14] M. Balsa Rodríguez, E. Gobbetti, J. A. Iglesias Gutián, M. Makhinya, F. Marton, R. Pajarola, S. K. Suter: State-of-the-art in compressed GPU-based direct volume rendering.
- [Tsa15] Y.-T. Tsai: Multiway K-clustered tensor approximation: toward high-performance photorealistic data-driven rendering.
- [BP15] R. Ballester-Ripoll, R. Pajarola: Lossy volume compression using Tucker truncation and thresholding.



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