
MAE 6258 HW11

```
%Randy Schur
%4/15/15
%Adapted from yield_failure.m
```

Problem 1

```
clc
clear
close all

c = [.1 1 10 100 1000 10000];
t_failure = zeros(6,8,10);
for times = 1:10
    for zetas = 1:length(c)
        % create linear system
        m = 5;
        % c = .1;
        wn = 1*2*pi; % natural frequency
        k = wn.^2*m;
        G = tf(1,[m c(zetas) k]);

        zeta = c(zetas)/(2*sqrt(m*k)) ; % damping ratio
        Tc = 1/(wn*zeta); % time constant of transients

        % create Gaussian white noise input
        dt = .01;
        N = 500000;
        t = linspace(0,(N-1)*dt,N);
        S0 = 1;

        u = randn(N,1)*sqrt(2*pi*S0/dt);

        % simulate system with input u, plot input vs. output
        y = lsim(G,u,t);
        ind = (t > 5*Tc); % trim transient response
        t = t(ind);
        t = t - t(1);
        N = length(t);
        u = u(ind);
        y = y(ind);

        % mean-square of output
        R_yy = xcorr(y,'unbiased');
        Ey2 = R_yy(N);
        Ey2a = mean(y.^2);
        Ey2_theory = pi/(c(zetas)*k);
```

```

for k_std = 1:8
% failure estimates
% k_std = 3; % # of standard deviations t
U = k_std*std(y); % std(y) = sqrt(Ey2a)

%calculate n_dot_plus(k*sigma_x)
[pks, locs] = findpeaks(y);
ind_fplus = (pks >= U);
pos_pks = find(ind_fplus>0);
n_dot_plus(k_std, times) = size(pos_pks,1)/t(end);
a_crosses = 0;
for count = 2:length(pos_pks)
    diff = pos_pks(count) - pos_pks(count-1);
    if diff > sqrt(Ey2a)*sqrt(6/pi)/(pi*zeta*U)
        a_crosses = a_crosses+1;
    end
end
n_dot_plus_a(k_std, times) = a_crosses/t(end);
if numel(pos_pks)>0
    t_failure(zetas, k_std, times) = t(pos_pks(1));
else
    t_failure(zetas, k_std, times) = t(end);
end

%theoretical values
n_dot_plus_theory(k_std, times) = 1*exp(-k_std^2/2);
sigma_x_sq = Ey2_theory;
K = 2*zeta*wn^3*sigma_x_sq/pi;
sigma_xdot_sq = pi*K/(2*zeta*wn^3)*((1+pi^2*zeta^2)/12);
sigma_l_sq = pi^3*zeta*K/(24*wn);

n_dot_plus_a_theory(k_std, times) = U*sqrt(sigma_l_sq)/(sqrt(2*pi)*sigma_x

end

end
figure(1)
for asdf=1:zetas
    subplot(2,3, asdf)
    plot(1:k_std, mean(n_dot_plus,2), 'ko', 1:k_std, n_dot_plus_theory(:,times)
    hold on
    plot(1:k_std, mean(n_dot_plus_a(:,times),2), 'mo', 1:k_std, n_dot_plus_a_t
    legend( 'x(t) crossings', 'theoretical value', 'a(t) crossings', 'theoreti
    str = strcat('\zeta', sprintf(' = %1.1d', zeta ));
    title(str)
    xlabel('k_std')
    ylabel('E[n dot plus] and E[n dot a plus]')
end
figure(2)
for i=1:6
    subplot(2,3,i)
    plot(1:k_std, t_failure(i,:,times))
    hold on
    str = strcat('\zeta', sprintf(' = %1.1d', zeta ));

```

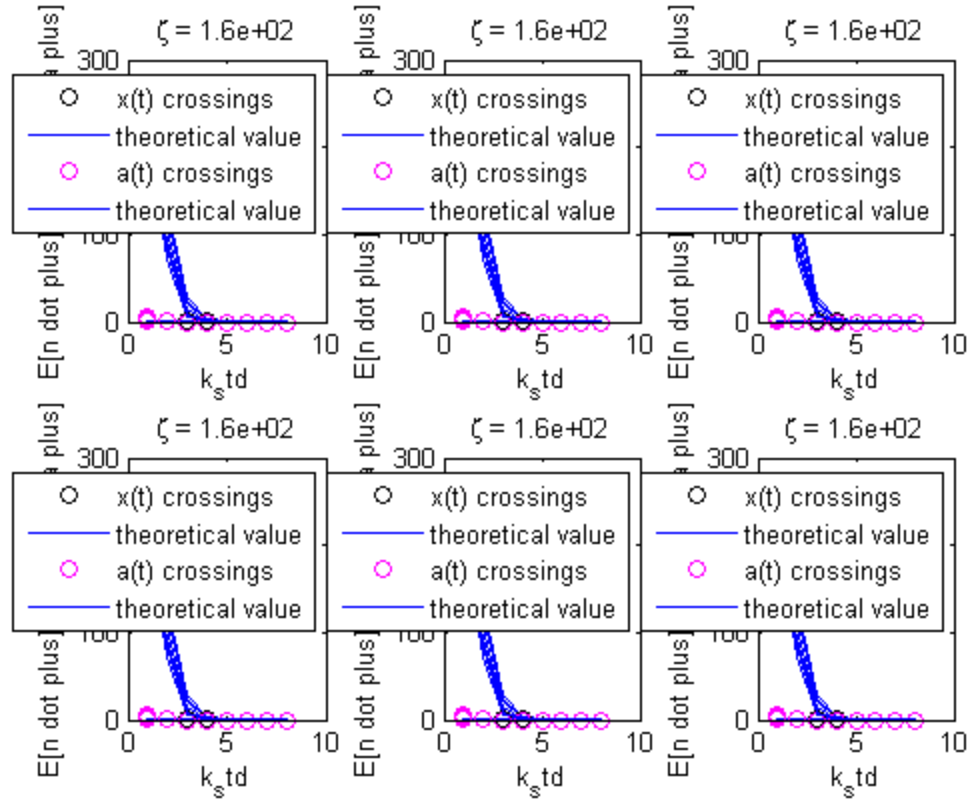
```

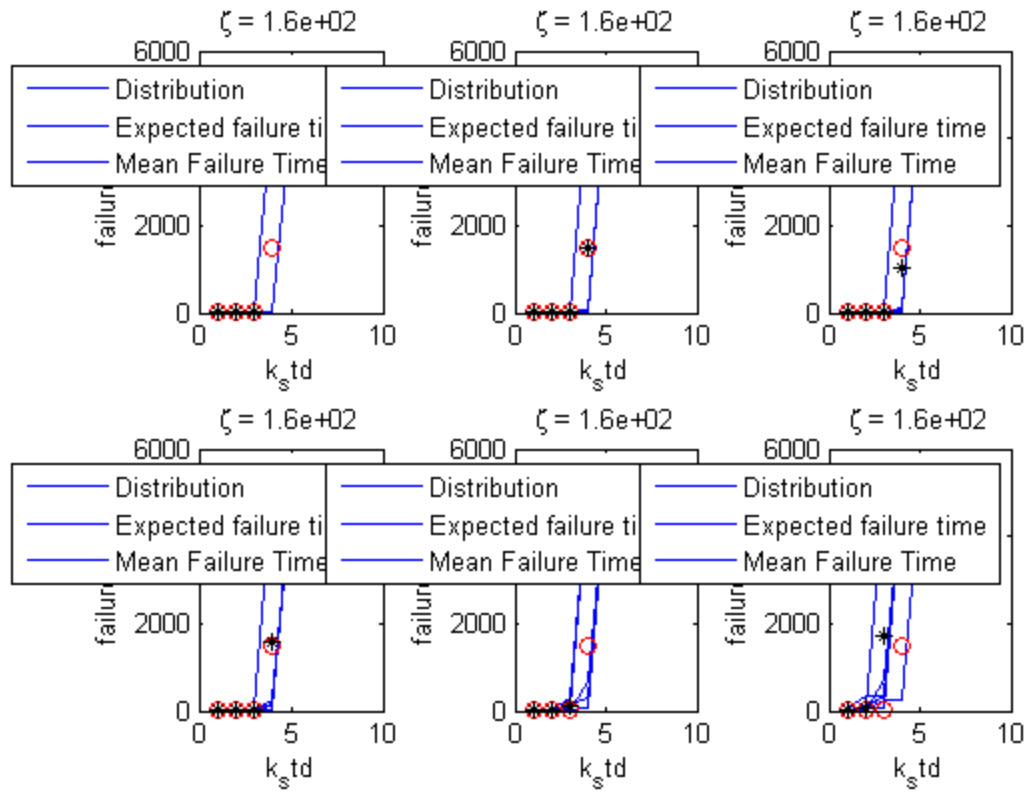
        title(str)
        xlabel('k_std')
        ylabel('failure time')
    end
end

%part b
figure(2)
E_tf = min(5000, 1/2.*exp((1:k_std).^2./2));

for i=1:6
    subplot(2,3,i)
    plot(1:k_std, E_tf, 'ro')
    hold on
    plot(1:k_std, mean(t_failure(i,:,:),3), 'k*')
    str = strcat('\zeta', sprintf(' = %1.1d', zeta ));
    title(str)
    xlabel('k_std')
    ylabel('failure time')
    legend('Distribution','Expected failure time', 'Mean Failure Time')
end

```





Published with MATLAB® R2013b