REUBEN S MATHEW

MASTERS STUDENT,

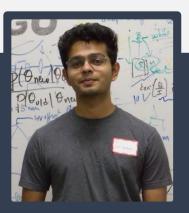
ADVANCED OPTICAL TECHNOLOGIES

EDUCATION

- Friedrich-Alexander University, Erlangen
- 2024-Present
 - Masters in Advanced Optical Technologies.
 - Max Planck School of Photonics.
- NATIONAL INSTITUTE OF TECHNOLOGY, CALICUT, INDIA
- 2020-2024
 - Bachelor of Technology in Engineering Physics.
 - CGPA 8.53/10.

PROJECT EXPERIENCE

- FINAL YEAR PROJECT AT NATIONAL INSTITUTE OF TECHNOLOGY, CALICUT (NIT, Calicut) (Link)
- AUGUST 2023-May 2024
 - Analysis of microplastics using incoherent broadband cavity enhanced absorption spectroscopy
 - Under guidance of Dr. MK Ravi Varma, Professor and Head, Dept. of Physics, NIT Calicut.
 - Literature survey completed, and initiated experimental phase at the Applied Optics and Instrumentation laboratory at the Dept. of Physics, NIT Calicut.
- SUMMER INTERNSHIP AT CALIFORNIA INSTITUE OF TECHNOLOGY (Link)
- MAY 2023-JULY 2023
 - Improvement of laser locking stabilization with digital controllers
 - Mentored by Dr. Rana Adhikari, Professor of Physics, Caltech and Radhika Bhatt, graduate student, Caltech.
 - Worked at the LIGO 40m laboratory.
 - Gained hands-on experience in control theory, laser locking and digital controllers (on the Moku platform) and related Python programming, collaborated with grad students, scientists and postdocs.
- SUMMER INTERNSHIP AT INDIAN INSTITUTE OF SPACE SCIENCE AND TECHNOLOGY (IIST) (Link)
- MAY 2022-JUNE 2022
 - Design and realization of a rotation stage for characterization of optical gyroscopes
 - Under guidance of Dr. Dinesh Naik, Assistant Professor, IIST.
 - Worked at the Applied and Adaptive Optics Lab and Small Spacecraft Systems and Payload Centre (SSPACE) at IIST.
 - Experience gained in working with laser, optical fibers, interferometers and related components and in the design and machining of related parts.
 - Presented a paper on the above project at optics symposium, COPaQ'22 at IIT Roorkee.
- MINI PROJECT: DESIGN AND REALISATION OF QUADRUPED ROBOT (LINK)
- AUGUST 2021



rbnsmathew@gmail.com rbnsmathew.github.io Erlangen, Germany

- A robot with four legs, capable of moving forward and backwards under static stability, made with 3D printed parts powered by servo motors and controlled with micro controllers.
- 3D modelling Autodesk Inventor.
- Movement and gait simulation MATLAB and Simulink.
- Hardware and code Raspberry Pi Pico running Python.

Courses Taken

Quantum Mechanics Classical Mechanics General Theory of Relativity

Optics Condensed Matter Physics Physics of Climate

Digital/Analogue Electronics Computational Physics Nuclear Physics

Statistical Physics Complex Analysis Laser Physics

Thermodynamics Critical Phenomena Solid State Physics
Electromagnetics Waveguides Machine Learning

Achievements and Attributes

- Scholarship from Max Planck School of Photonics.
- Recipient of the Caltech Summer Undergraduate Research Fellowship (SURF), 2023.
- Secretary of Bhauthiki, the physics association at NIT Calicut, awarded the best performing club for the year 2022-2023.
- Internal Affairs Secretary, Audio-Visual Club at NIT Calicut.
- GATE Physics 2022 All India Rank 514.
- GRE general score Quantitative 168/170, Verbal 158/170, Analytical Writing 4.0/6.0.
- IELTS Academic score 8.5/9.
- Head boy and Vice-Captain in high school.
- Plays guitar, participated and won prizes in Western Solo, Group Songs.
- Represented school at inter school basketball tournaments.

Skills

- Laboratory experience
 - Lasers, interferometers, nonlinear crystals, fiber optics and related optical components.
 - Waveguides, measuring instruments and related electromagnetic components.
 - Precision measurement equipment like oscilloscopes, multimeters, frequency response analyzers and VSWR meters and FPGA based controllers.
- Software and coding
 - Advanced Python coding and basic coding in Java, C, HTML and MATLAB scripting. Capable of picking up on object-oriented languages easily.
 - Experience in working with Inventor, MATLAB, Simulink, Mathematica, Blender and Linux systems.
 - Design of hardware and coding for micro controllers and peripherals on Raspberry Pi and Arduino.
- Mechanical design and problem solving related to physics and robotics.
- Handling power tools like drills, cutters, grinders, circular saws, angle grinders, used for basic woodworking.

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