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Outline

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Introduction

Overall Plan

From a large data set we try to separate a signal from a specific type of noise.

- Signal := *stop squark* event
- Noise := top quark background event
- Use SOM and Back-prop as filters



Purpose

- Search for the *stop squark*, predicted by SUSY
- Guided by Dr. Paul Padley of Bonner Lab
- Simulated data generated by PYTHIA

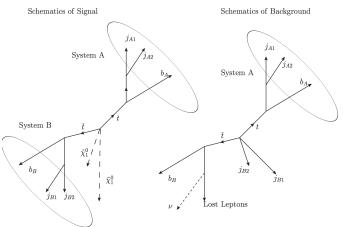
Aim

Improve on the results in the paper by Dutta et al. [1], working in parallel with Onkur Sen, who is attacking the same problem using boosted decision trees.





What is a *stop squark* Event?







Classification Basics

From the simulated data, with the help of Onkur's code, we were able to create:

- a length 24 vector of raw data for each signal or background event
- a length 8 vector of derived variables from the raw data [1]

Previously attempted strategy:

• Thresholds on derived variables as outlined in Dutta et al. [1]





Back-Propagation Filter Settings

ARCHITECTURE		
Topology	$(8 + 1_{Bias}) - (30 + 1_{Bias}) - 2_{output}$	
Transfer Function	tanh with slope $b = 1$	
LEARNING PARAMETERS		
Initial weights	$w \sim U[-0.1, 0.1]$	
Learning rate, $\gamma(t)$	$\gamma(t) = 0.01(1 - 0.0001)^t$	
Momentum, α	$\alpha = 0.3$	
Epoch size	K = 1	
Stopping criteria	learning step $> 100,000$	
Error measure (Err)	RMSE	
Monitoring frequency (m)	1,000 Learning Steps	
INPUT/OUTPUT SCALING		
Input Scaling	(-0.9,0.9)	
Output Scaling	(-0.9,0.9)	
PERFORMANCE EVALUATION		
Accuracy measure (Acc_X)	Significance = $\frac{S}{\sqrt{B}}$	



Self-Organizing Map Filter

ARCHITECTURE		
Topology	10 x 10	
LEARNING PARAMETERS		
Initial weights	$w \sim U[-0.1, 0.1]$	
Learning rate, $\gamma(t)$	$\gamma(t) = 0.3(1 - 0.00001)^t$	
Neighborhood, $\sigma(t)$	$\sigma(t) = 1.5 + 3.5 (1 - 0.00001)^t$	
Epoch size	K = 1	
Stopping criteria	learning step $> 100,000$	
Monitoring frequency (m)	1,000 Learning Steps	
INPUT/OUTPUT SCALING		
Input Scaling	Angles in Degrees, Otherwise None	
Output Scaling	None	
PERFORMANCE EVALUATION		
Accuracy measure (Acc_X)	Significance = $\frac{S}{\sqrt{B}}$	



Significance: A Filter Comparison Metric

 A measure of discovery confidence based on a certain number of high energy particle collisions

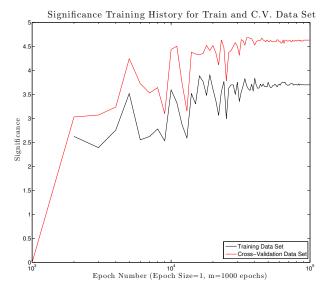
$$significance = \frac{N_{\text{Signal}}}{\sqrt{N_{\text{Background}}}}$$

 N_{Signal} := number of signal events that come through the filter $N_{\text{Background}}$:= number of noise events that come through the filter

- Used commonly in physics
- Every significance measure in the Results Section is based on a standard number of collisions



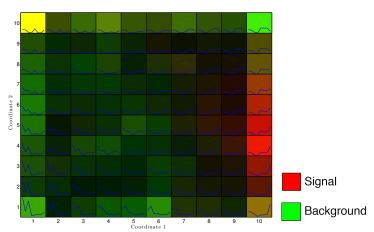
Back-Propagation Results for Derived Variables





SOM for Derived Variables

SOM Signal and Noise Density plots with weights

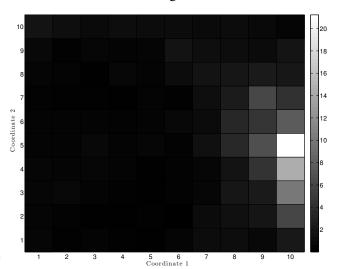






SOM for Derived Variables

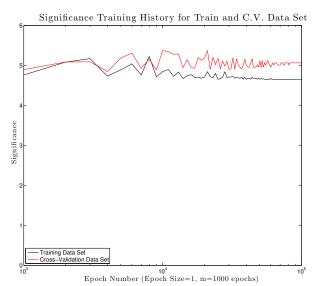
SOM Normalized Signal to Noise Ratios







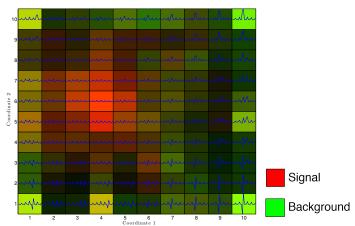
SOM followed by BP for Derived Variables





SOM on Raw Data

SOM Signal and Noise Density plots with weights

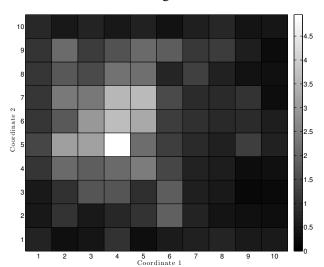






SOM on Raw Data

SOM Normalized Signal to Noise Ratios







Significance Analysis

Метнор	TEST SET SIGNIFICANCE
Thresholding [1]	1.93σ
No Filter	2.62σ
Back-Propagation	3.79σ
Self-Organizing Map for Derived Variables	3.69σ
Self-Organizing Map and Back-Propagation	4.36σ
Self-Organizing Map for Raw Data	2.62σ





Analysis

- Back-Propagation and the SOM using the 8 derived variables produced interesting results
- The SOM using 24 raw variables did not
- The two-stage SOM and BP process was slightly superior to either method alone
- We suspect the success of the 8 derived variables is due to the jet angle invariance of these parameters



Next Steps

- Determine a method of aligning the 24 non-derived variables
- Further Experimentation with Training Parameters
- Run a second SOM on the SOM cells with high signal to noise ratios



References

[1] Dutta, B.; Kamon, T.; Kolev, N.; Sinha, K.; Wang, K. *High Energy Physics - Phenomenology* **2012**,

