

CAMs

- ☐ Roller
- ☐ Flat Faced

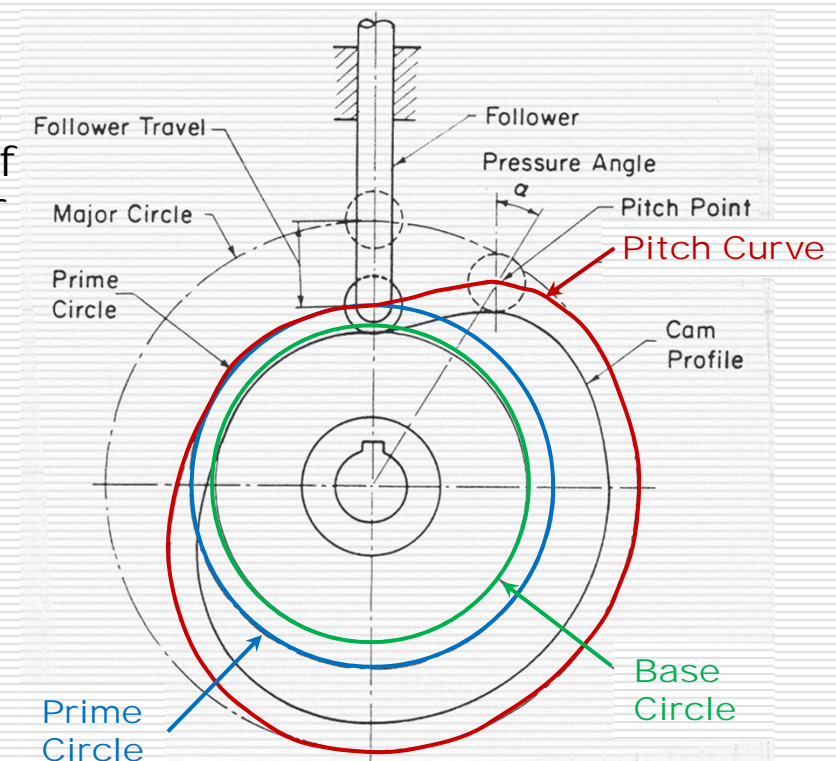
CAM Sizing Is Based On Radius Of Curvature and Pressure Angle

□ Prime Circle

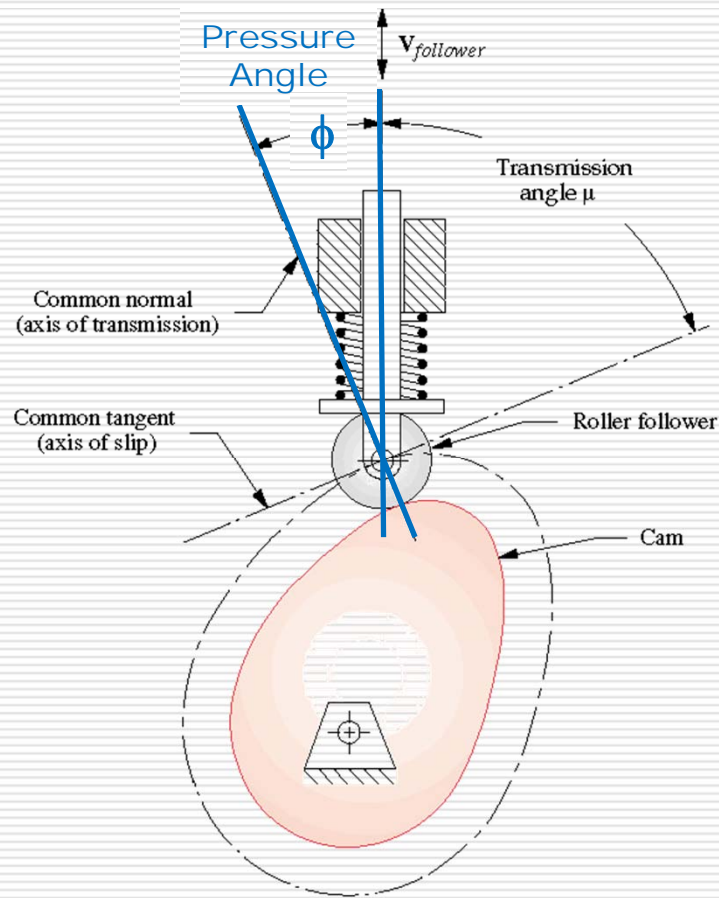
- **ROLLER** or RADIUSSED Followers
- Smallest circle which can be drawn tangent to the locus of the centerline of the follower
- **Pitch Curve** - locus of the centerline of the follower
- CAMs with roller followers are defined with respect to the pitch curve

□ Base Circle radius

- **FLAT FACED** Followers
- Smallest circle which can be drawn tangent to the physical CAM Surface



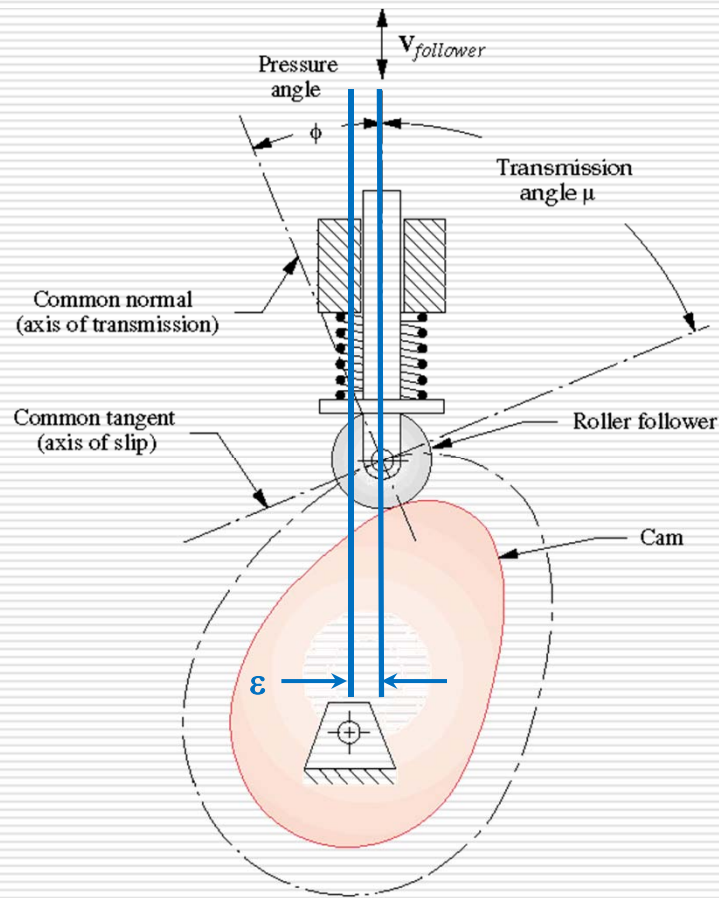
Roller Follower: PRESSURE ANGLE



PRESSURE ANGLE ϕ : Angle between the direction of motion (velocity) of the follower and the direction of the Axis of Transmission (Common Normal)

- Only valid for single DoF systems
- Extremes
 - $\phi=90^\circ$ no follower motion
 - $\phi=0^\circ$ all transmission force goes into motion of the follower
- Rule of Thumb
 - Translating Followers $0^\circ \leq \phi \leq 30^\circ$
 - Oscillating Followers $0^\circ \leq \phi \leq 35^\circ$

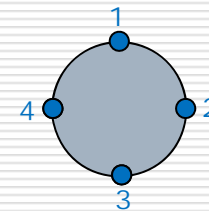
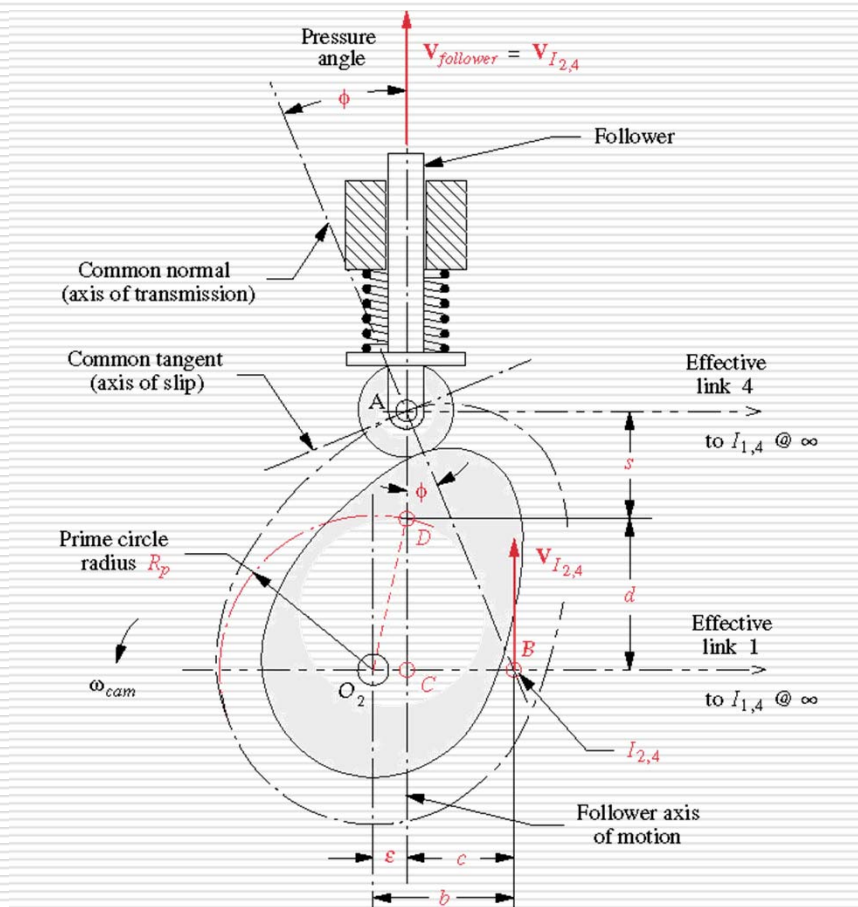
Roller Follower: ECCENTRICITY



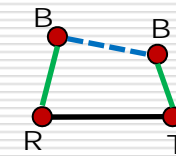
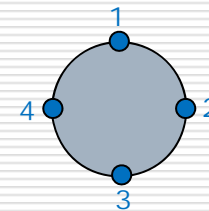
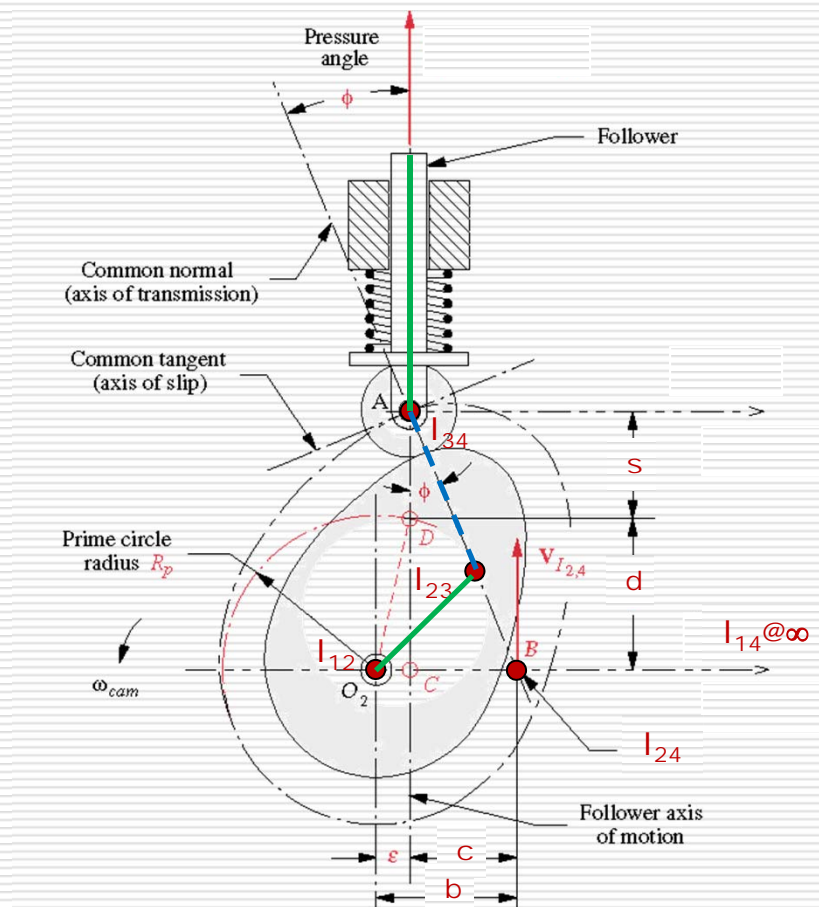
ECCENTRICITY ϵ : Perpendicular distance between the follower's axis of motion and the center of the CAM

- Aligned Followers, $\epsilon=0$
- For a positive ω
 - **POSITIVE ϵ** , the PRESSURE ANGLE will be decreased on the RISE, but increase on the FALL
 - **NEGATIVE ϵ** , the opposite occurs

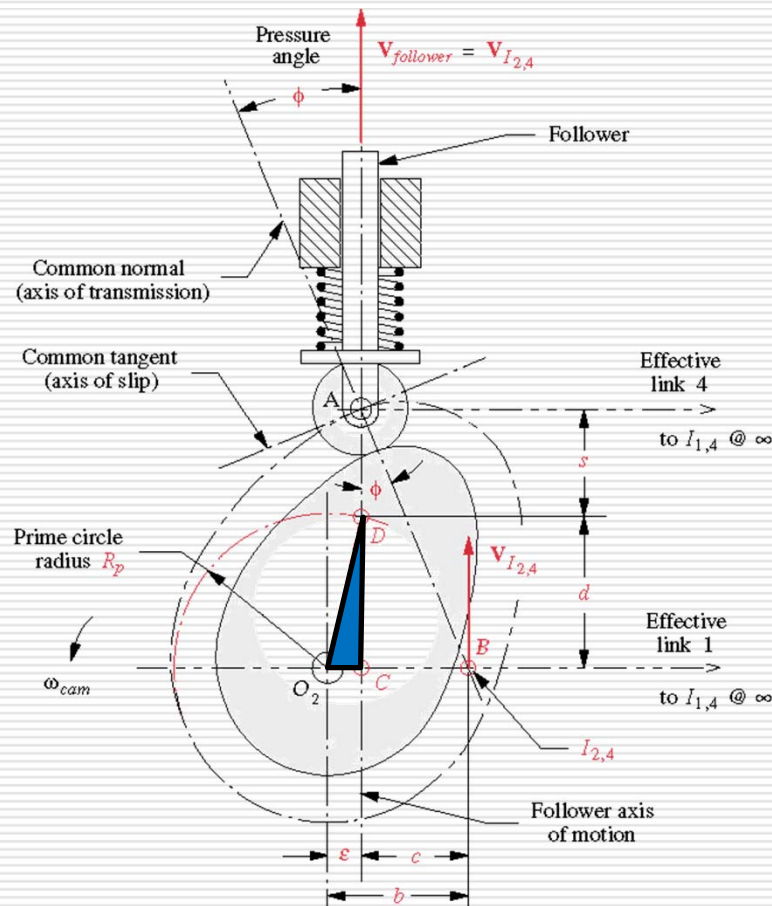
Roller Follower Instant Center



Roller Follower Instant Center Linkage Isomer

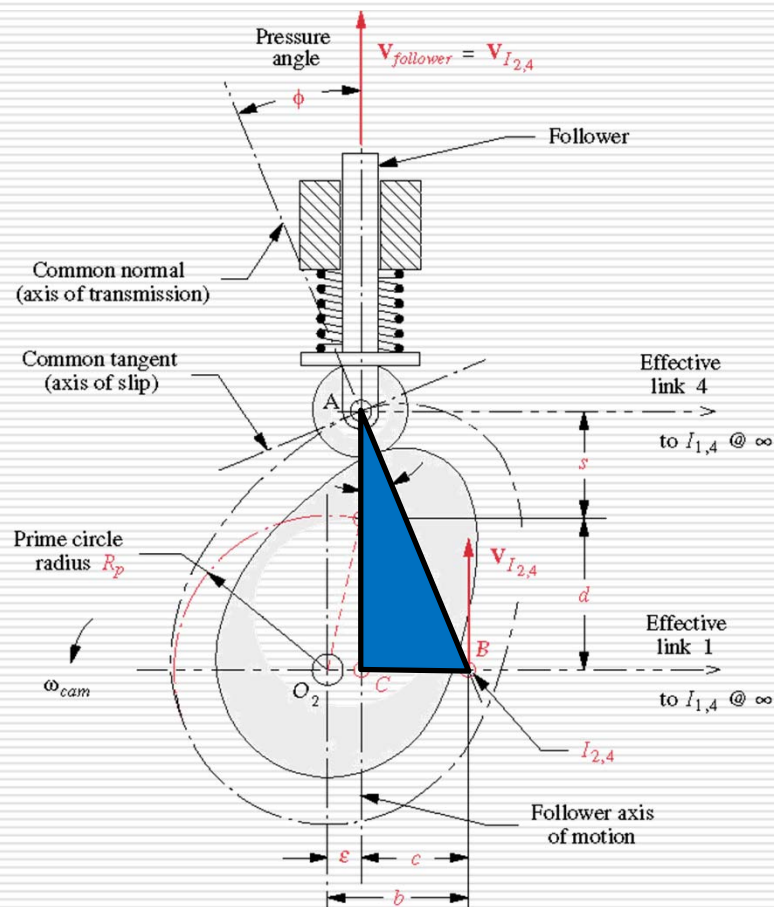


Roller Follower Instant Center Finding $d(R_p, \epsilon)$



$$d = \sqrt{R_p^2 - \epsilon^2}$$

Roller Follower Instant Center Determining ϕ



$$\phi = \tan^{-1} \left(\frac{s' - \epsilon}{s + \sqrt{R_p^2 - \epsilon^2}} \right)$$

As R_p is increased, ϕ will be reduced

- For a positive ω
 - POSITIVE ϵ** , the PRESSURE ANGLE ϕ will be decreased on the RISE, but increase on the FALL
 - NEGATIVE ϵ** , the opposite occurs

Radius of Curvature Calculation

$$\rho_{pitch} = \frac{\left[(R_p + s)^2 + s'^2 \right]^{3/2}}{(R_p + s)^2 + 2 \cdot s'^2 - s'' \cdot (R_p + s)}$$

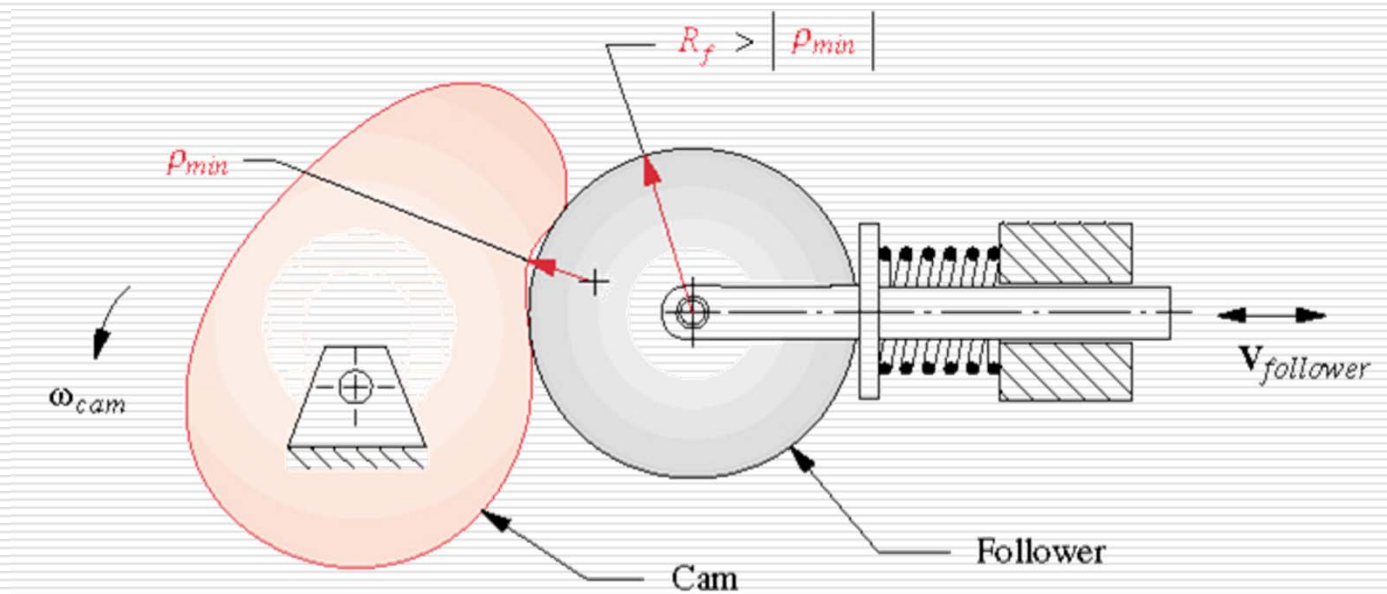
≡ Radius of Curvature of the **Pitch Curve**

Rule of Thumb

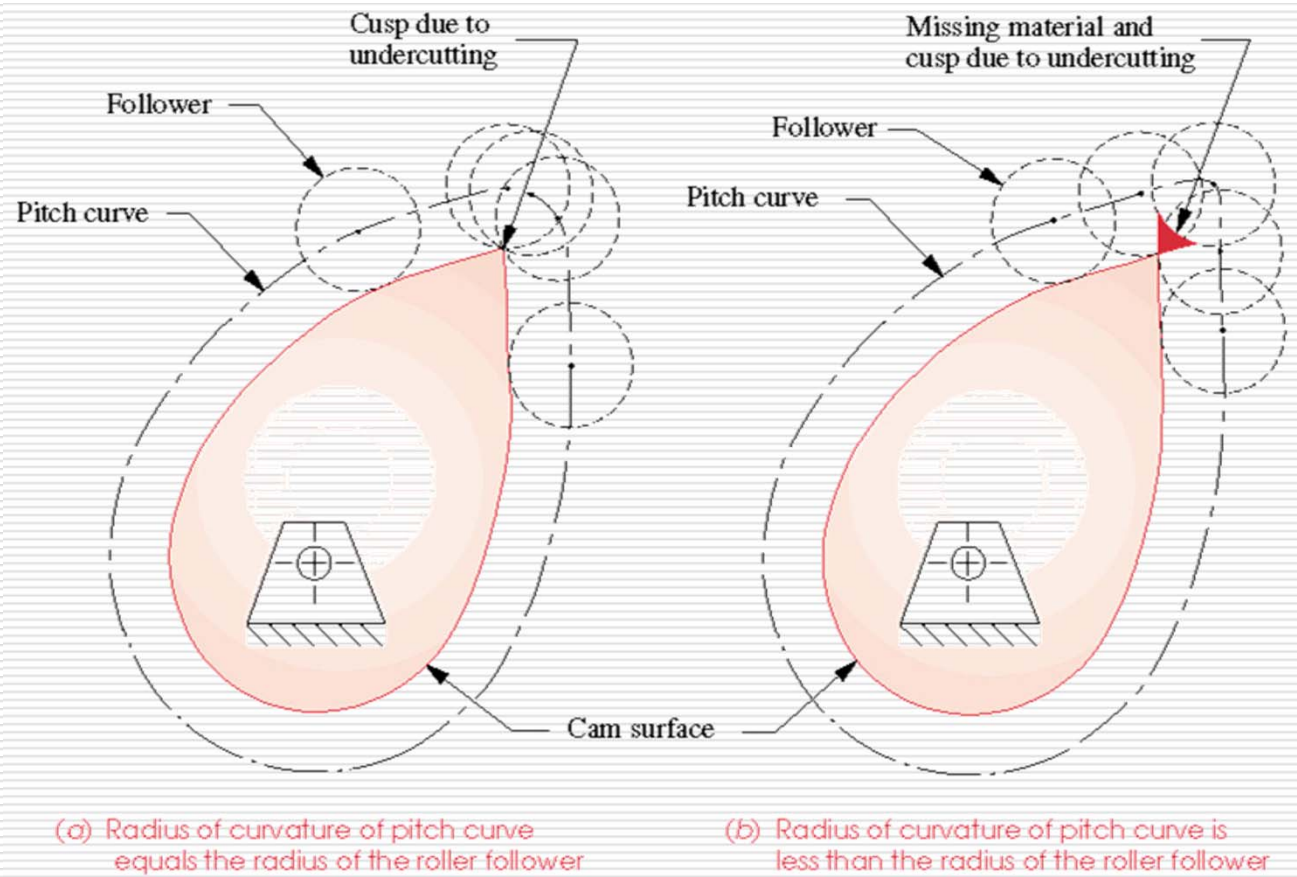
$$|\rho_{\min}| \gg R_f$$

ρ At Least 2 to 3 Times R_f

Too Large a Follower



Undercutting

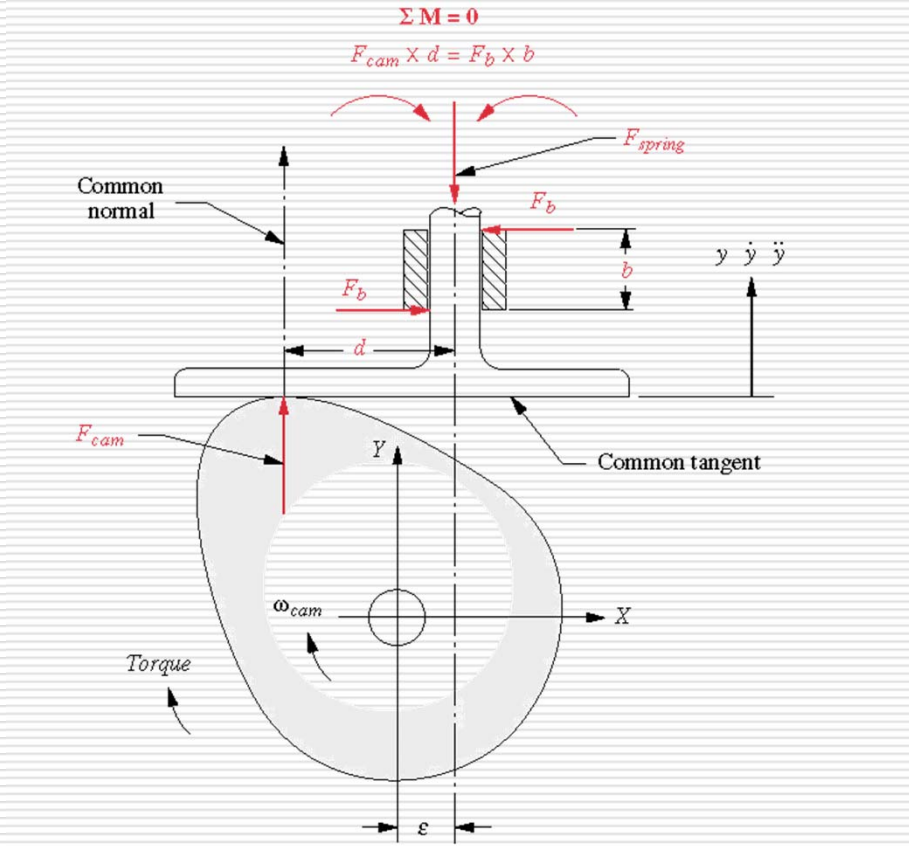


X Y Coordinates

$$x = \cos \lambda \cdot \sqrt{(d + s)^2 + \varepsilon^2}$$

$$y = \sin \lambda \cdot \sqrt{(d + s)^2 + \varepsilon^2}$$

$$\lambda = (2\pi - \theta) - \tan^{-1} \left(\frac{\varepsilon}{d + s} \right)$$

[illegible]

Determining the Shape of the Cam

