EXAMPLE SOLUTION
MER311: ADVANCED MECHANDOS

Example 2 PG 1cFG RBB FE LECTURE 3

EXAMPLE 2 CONSIDER THE ASSEMBLAGE OF THE TRUSS ELEMENTS SHOWN. DETERMINE THE NOOAL PORCES, NOOAL DESAMOEMENTS,

#### GIVEN:

1. THREE ELEMENT STRUCTURE

- TWO OF THE ELEMENTS ARE IN PARALLEL

- THE THIRD ELEMENT IS IN SENTES WITH THE PORMULL ELEMENTS

2. THE STOPPHESSES OF THE ELEMENTS ARE: k1 = 50 %, k2 = 30 1/1, k3 = 30 1/2 in

3. THE PARALLE PLEMENTS ARE ATTACHED TO THE WALL

3. AN EXTERMAL LOAD OF 40 10 IS APPLIED TO THE STALLTURE

## Assemptions:

1. ALL ELEMENTS ARE TRUSS EZEMENTS; TWO FORCE MEMBERS

2. ALL SUPPORTING STRUCTURES HAVE REGID

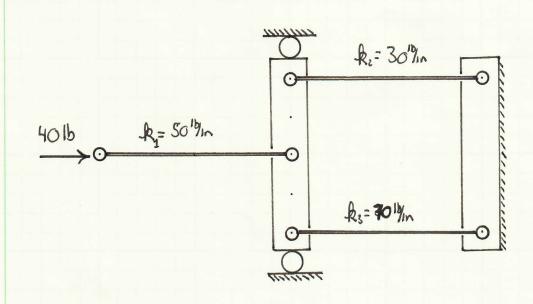
3. ALL FORCES AND DISPURCEMENTS ARE IN THE HORIZONIAL DIRECTION.

## FIND:

1. NODAL FUNCES

2. NODAL DISPLACEMENTS

### FIGURE:



(a)

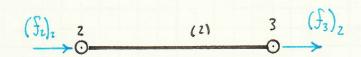
EXAMPLE SOLUTION

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Example 2 PG ZGFG RBB PE LECTURE 3

SOUTION:

FIRST THE STRUCTURE IS BROCKEN DOWN INTO EXEMENTS.



$$(\mathcal{S}_1)_1 \xrightarrow{1} (\mathcal{S}_2)_1$$

$$(f_2)_3 \stackrel{?}{\bigcirc} \qquad (3) \qquad \stackrel{\checkmark}{\bigcirc} \qquad (f_4)_3$$

CALCULATING THE STIFFNESS MATRICES FOR EACH ELEMENT

## ELEMENT 1

$$\begin{cases}
(\beta_1)_1 \\
(\beta_2)_1
\end{cases} = \begin{bmatrix}
k_1 & -k_1 \\
-k_1 & k_1
\end{bmatrix} \begin{cases}
(u_1)_1 \\
(u_2)_1
\end{cases} = \begin{bmatrix}
k_1 & -k_1 \\
-k_1 & k_2
\end{bmatrix} \begin{cases}
u_1 \\
u_2
\end{cases}$$

$$\begin{cases} (f_2)_2 \\ (f_3)_2 \end{cases} = \begin{bmatrix} k_1 & -k_2 \\ -k_2 & k_2 \end{bmatrix} \begin{cases} (u_2)_2 \\ (u_3)_2 \end{cases} = \begin{bmatrix} k_1 & -k_2 \\ -k_1 & k_2 \end{bmatrix} \begin{cases} u_2 \\ u_3 \end{cases}$$

3

KNOWING THAT FROM INTERMAL EQUILIDATION CONSIDERATIONS

(4)

$$F_{z} = (f_{z})_{1} + (f_{z})_{3} + (f_{z})_{3} = 0$$

(3)

$$F_3 = (f_3)_2$$

**(1)** 

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EXAMPLE 2 PO-30F6 RBB FE LEAUNE 3

THE GLOBAL STIFFHESS MATRIX IS CONSTRUCTED BY FIRST EXPANDING (1)-(3)

$$(f_2)_2 = k_2 \cdot U_2 - k_2 \cdot U_3$$

$$(f_3)_2 = -k_2 \cdot U_2 + k_2 \cdot U_3$$

$$(f_3)_2 = -k_2 \cdot U_2 + k_3 \cdot U_3$$

$$(3 \to (f_2)_3 = k_3 \cdot ll_2 - k_3 \cdot ll_4$$

$$(f_4)_5 = -k_3 \cdot ll_2 + k_3 \cdot ll_4$$
(3)

(8)-(13) ARE NOW SUBSTITUTED INTO (4)-(7)

$$F_{1} = (f_{1})_{1} = k_{1} \cdot u_{1} - k_{1} \cdot u_{2} = 401b$$

$$F_{2} = (f_{2})_{1} + (f_{2})_{2} + (f_{2})_{3} = 0$$

$$= -k_{1} \cdot u_{1} + k_{1} \cdot u_{2} + k_{2} \cdot u_{2} - k_{2} \cdot u_{3} + k_{2} \cdot u_{4} = 0$$

$$= -k_{1} \cdot u_{1} + (k_{1} + k_{2} + k_{3}) \cdot u_{2} - k_{3} \cdot u_{3} - k_{3} \cdot u_{4} = 0$$

$$= -k_{1} \cdot u_{1} + (k_{1} + k_{2} + k_{3}) \cdot u_{2} - k_{3} \cdot u_{3} - k_{3} \cdot u_{4} = 0$$
(5)

$$f_3 = (f_3)_2 = -k_2 \cdot U_2 + k_2 \cdot U_3$$
   
 $f_4 = (f_4)_3 = -k_3 \cdot U_2 + k_3 \cdot U_4$    
17

(14) - (17) CAN NOW BE WRITTEN IN MATRIX FORM

From the problem statement and figure it is seen that  $U_3 = U_4 = O$ . These results can now be entened that (19)

Example Solution MER311: Advanced Mechanics EXAMPLE 2 PG 4 OF G RBB FE LECRIE 3

$$\begin{pmatrix}
401b \\
01b
\end{pmatrix} = \begin{pmatrix}
k_1 & -k_2 & 0 & 0 \\
-k_1 & (k_3 + k_2 + k_3) & -k_2 & -k_3 \\
0 & -k_2 & k_2 & 0 \\
0 & -k_3 & 0 & k_3
\end{pmatrix} \begin{pmatrix}
u_1 \\
u_2 \\
0 \\
0
\end{pmatrix}$$

(19) NOW HAS TO BE PARTITIONED. STARTING BY TAKING OCT THE ROOMS ASSOCIATED WITH THE KNOWN PERCES

$$\begin{cases}
401b \\
01b
\end{cases} = 
\begin{bmatrix}
k_1 - k_1 & 0 & 0 \\
- k_1 & (k_1 + k_2 + k_3) & -k_2 - k_3
\end{bmatrix}
\begin{cases}
u_1 \\
u_2 \\
0
\end{cases}$$

THIS CAN FURTHER BE REDUCED

$$\begin{cases}
401b + (6)(c) + (6)(c) \\
01b + (k_2)(6) + k_3(6)
\end{cases} = \begin{cases}
401b \\
01b
\end{cases} = \begin{bmatrix}
k_1 & -k_1 \\
-k_1 & (k_1 + k_2 + k_3)
\end{bmatrix} \begin{cases} U_1 \\
U_2 \end{cases}$$

$$(26)$$

ONCE THE TOP TWO ROWS ARE REMOTED FROM (19) THE REMAINDING COMPONENTS OF THE MATRIX HAVE KNOWN DISPLACEMENTS AND UNKNOWN PORCES

$$\begin{cases}
F_3 \\
F_4
\end{cases} = \begin{bmatrix}
0 & -k_2 & k_2 & 6 \\
0 & -k_3 & 0 & k_3
\end{bmatrix} \begin{pmatrix} u_1 \\ u_2 \\ 0 \\
0 \end{pmatrix}$$
(21)

TO FIND F3 & F4, U1 & U2 MUST FIRST BE SOLVED FOR. FROM (20) U1 & U2 ARE FOUND BY THE INVENSE OF THE STIFFUESS MATRIX

$$\begin{bmatrix}
k_1 & -k_1 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
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k_1 & -k_2 \\
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k_1 & -k_2 \\
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\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
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k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
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\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
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\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
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\end{bmatrix} = \begin{bmatrix}
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\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
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\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4 & (k_1 + k_2 + k_3)
\end{bmatrix} = \begin{bmatrix}
k_1 & -k_2 \\
-k_4$$

EXAMPLE SCLUTION
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Example 2 PGS of G RBPS PE LECTURE 3

SCBSTITUTING THE RESCUTS IN (22) INTO (21), THE UNKNOWN FORCES CON NOW BE SOLVED.

$$\begin{cases}
F_{3} \\
F_{4}
\end{cases} = 
\begin{bmatrix}
0 & -k_{2} & k_{1} & 0 \\
0 & -k_{3} & 0 & k_{3}
\end{bmatrix}
\begin{cases}
\frac{1.2 \text{ in}}{0.4 \text{ in}}
\end{cases}$$

$$= \begin{bmatrix} 0 & -36 \frac{10}{10} & 36 \frac{10}{10} & 0 \\ 0 & -70 \frac{10}{10} & 0 & 76 \frac{10}{10} \end{bmatrix} \begin{bmatrix} 1.2 \text{ in} \\ 0.4 \text{ in} \\ 0 \\ 0 \end{bmatrix} = \begin{cases} -12 \frac{10}{10} \\ -28 \frac{10}{10} \end{cases}$$

THE MAKRIX CALCULATIONS WERE MADE USING THE MIND MATRIX INTENSION FUNCTION AND THE MMOUT MATRIX MOUTIFULATION FUNCTION IN EXCELL. THE EXCEL CALCULATIONS ARE FOUND ON THE NEXT PAGE.

# SUMMARY:

THIS EXAMPLE ILLUSTRATION THE CONSTRUCTION OF THE GLOBAL STIFFNESS MATRIX FOR A PARAMET SYSTEM OF ELEMENTS AND HOW THE MATRIX IS PARTITIONED TO SOLVE FOR THE UNKNOWN FORCES AND DISPLACEMENTS.

EXAMPLE SCILTICK
MERS11: ADVANCED MECHANICS

EXAMPLE 2 PGG OF G RBB FE LECTURE 3

MER311: Advanced Mechanics, Lecture 03, Example 02

$$\begin{bmatrix}
40 \\
0
\end{bmatrix} = \begin{bmatrix}
50 \\
-50
\end{bmatrix} = \begin{bmatrix}
150 \\
150
\end{bmatrix} = \begin{bmatrix}
12 \\
0.4
\end{bmatrix}$$

$$\begin{bmatrix}
12 \\
0.4
\end{bmatrix} = \begin{bmatrix}
0 \\
0 \\
-70
\end{bmatrix} = \begin{bmatrix}
1.2 \\
0.4
\end{bmatrix}$$

$$= \left\{ \begin{array}{c} -12 \\ -28 \end{array} \right\}$$