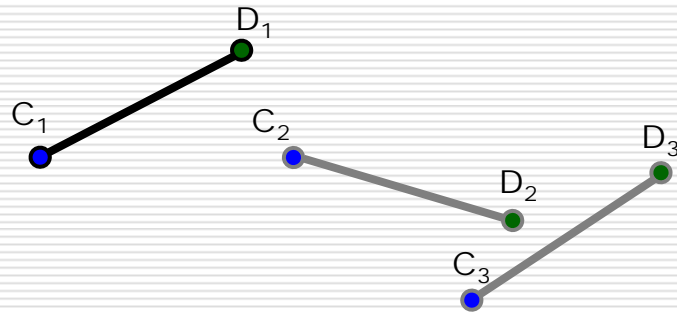


Three Position Graphical Linkage Synthesis

- Three Position
- Three Position with Alternate Moving Pivots
- Three Position with Specified Fixed Pivots

Three Position Synthesis

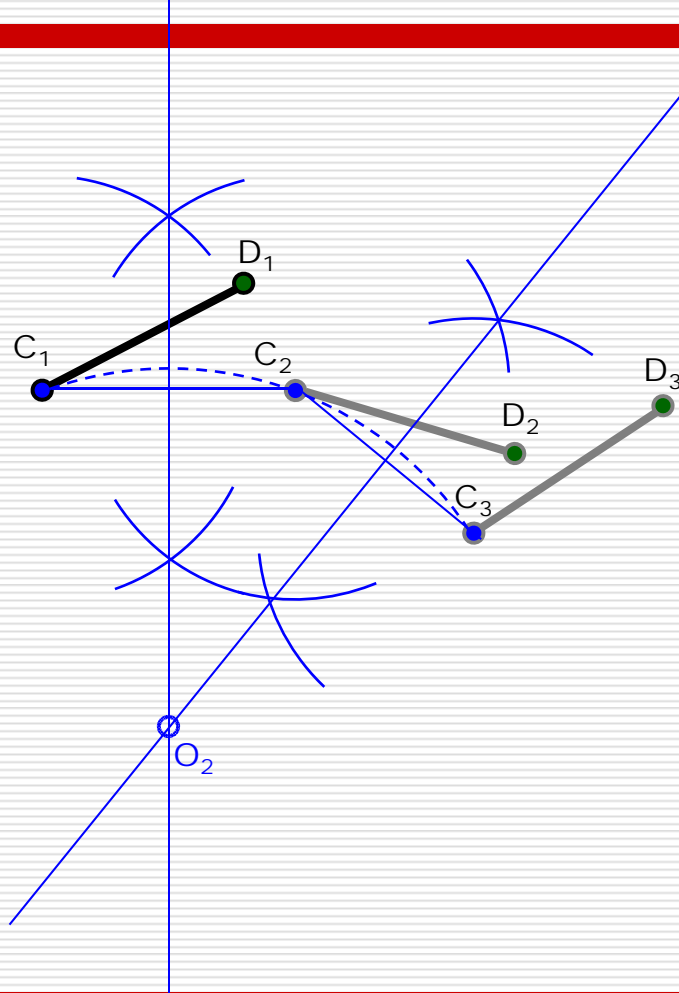
Coupler CD has three desired positions



$C_1D_1, C_2D_2, \text{ \& } C_3D_3$

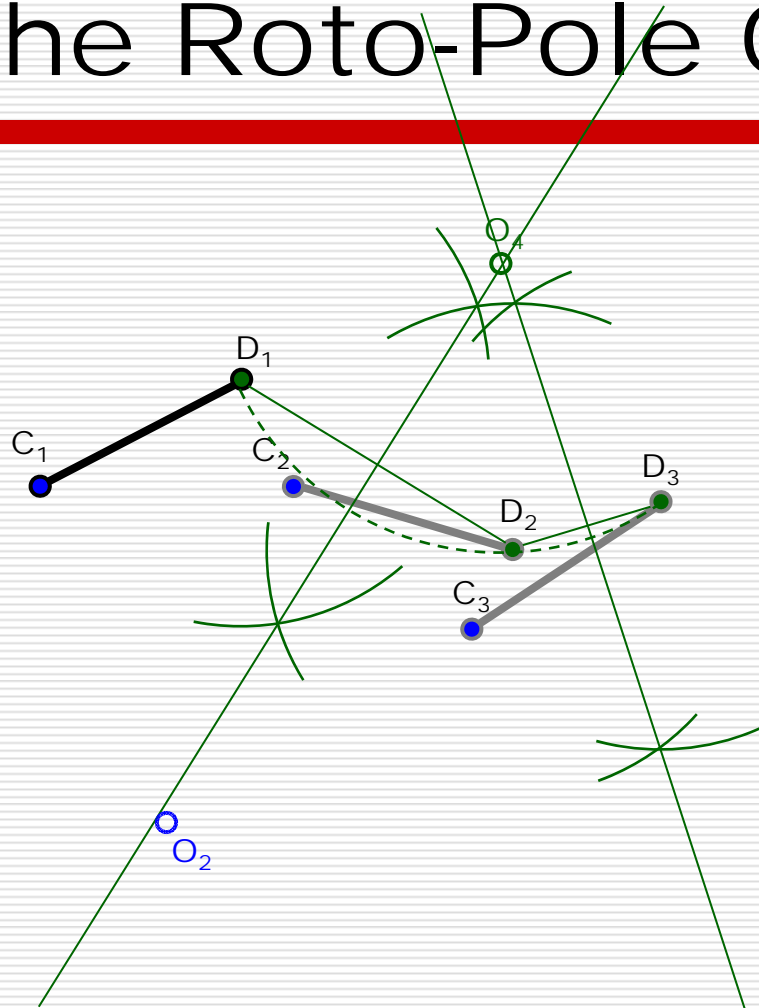
A four bar mechanism needs to be designed to generate this movement

Determining The Location of the Roto-Pole O_2



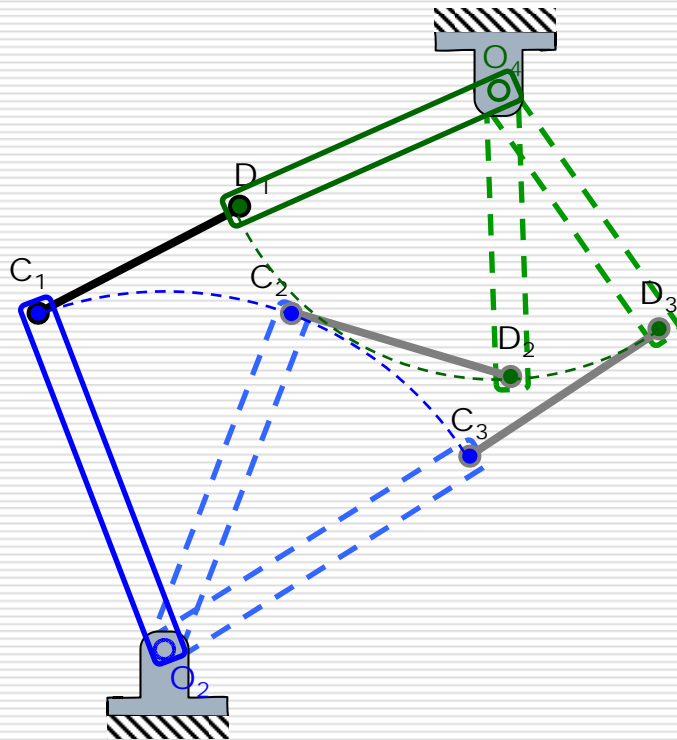
1. Draw Coupler CD in the three desired positions
 - a. C_1D_1 , C_2D_2 , & C_3D_3
2. Draw Construction Lines
 - a. C_1C_2 , C_2C_3
3. Construct Perpendicular Bisectors
 - a. C_1C_2
 - b. C_2C_3
4. At the intersection of the Two Perpendicular Bisectors is the Location of the Roto-Pole O_2

Determining The Location of the Roto-Pole O_4



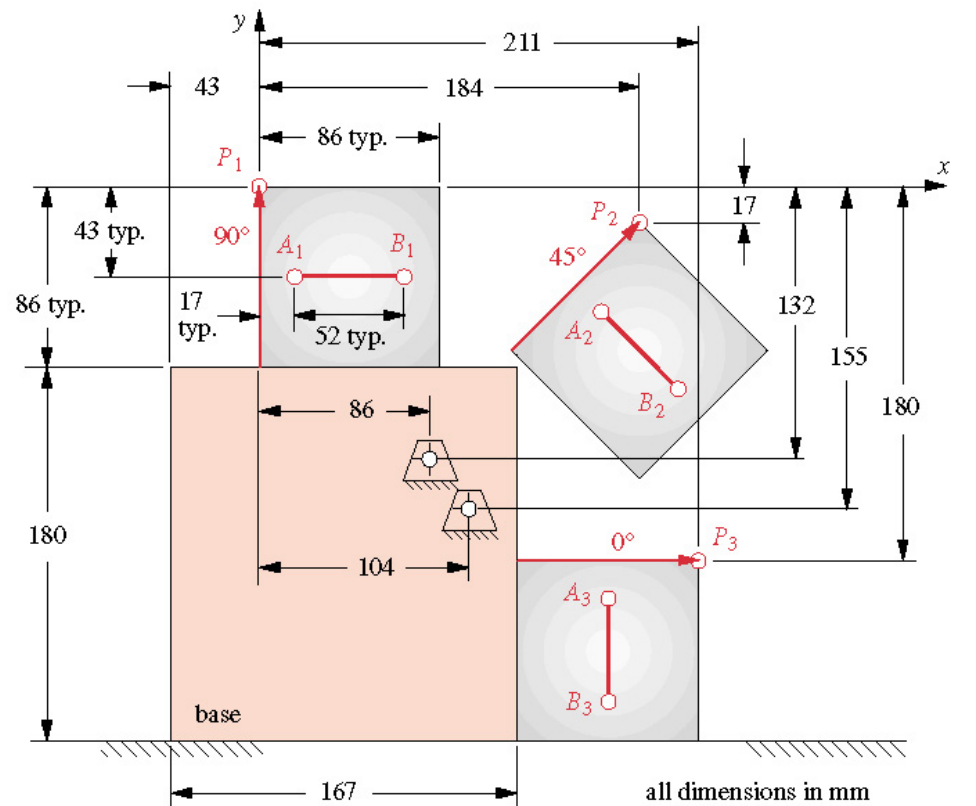
1. Draw Coupler CD in the three desired positions
 - a. C_1D_1 , C_2D_2 , & C_3D_3
2. Draw Construction Lines
 - a. D_1D_2 , D_2D_3
3. Construct Perpendicular Bisectors
 - a. D_1D_2
 - b. D_2D_3
4. At the intersection of the Two Perpendicular Bisectors is the Location of the Roto-Pole O_4

Final 4 Bar Synthesis

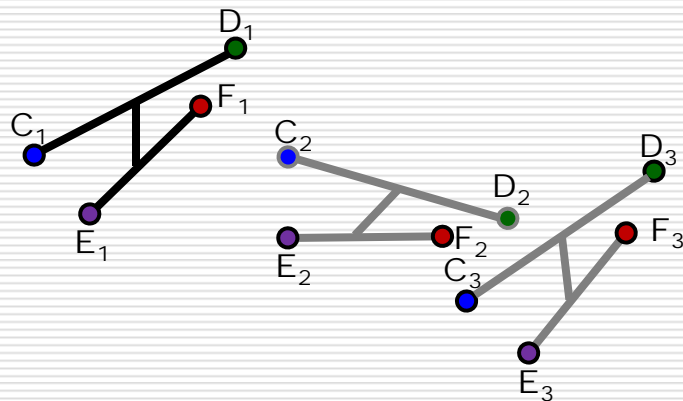


1. O_2 and O_4 are the ground points
2. Draw Link O_2C
3. Draw Link O_4D
4. May want to consider a drive dyad

Example

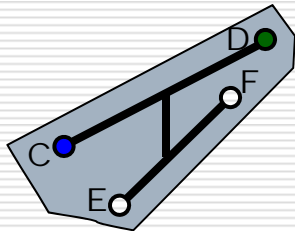


Three Position Synthesis with ALTERNATE PIVOTS

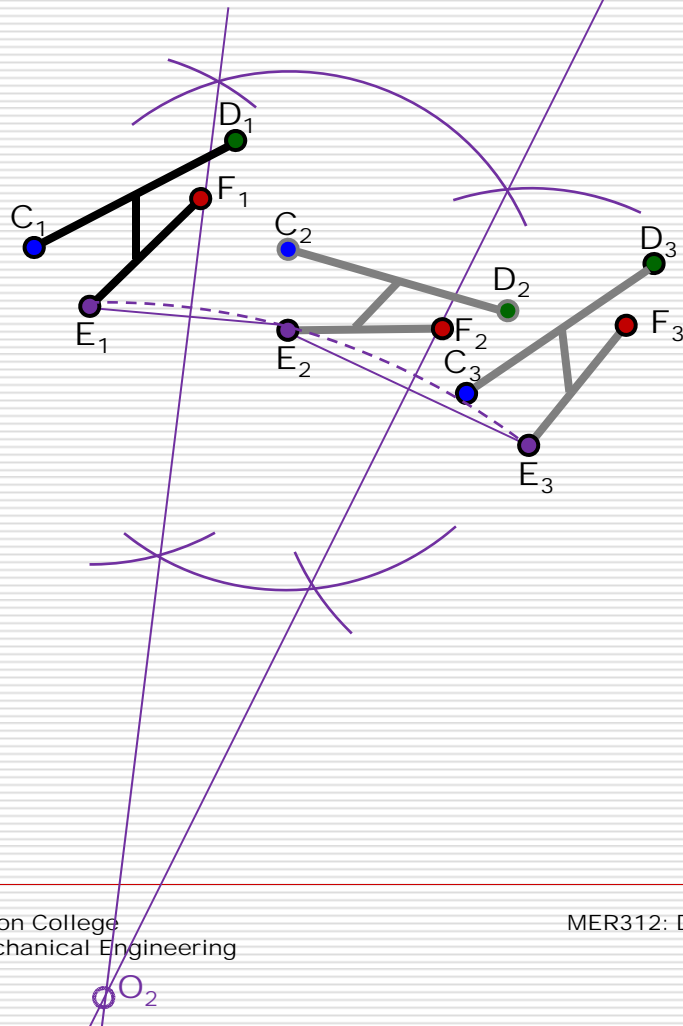


The situation may come up that the mechanism synthesized does not meet the design requirements. It is still required that C_1D_1 , C_2D_2 , & C_3D_3 have the three positions specified.

The ALTERNATE PIVOTS E_1F_1 , E_2F_2 , & E_3F_3 are now considered.

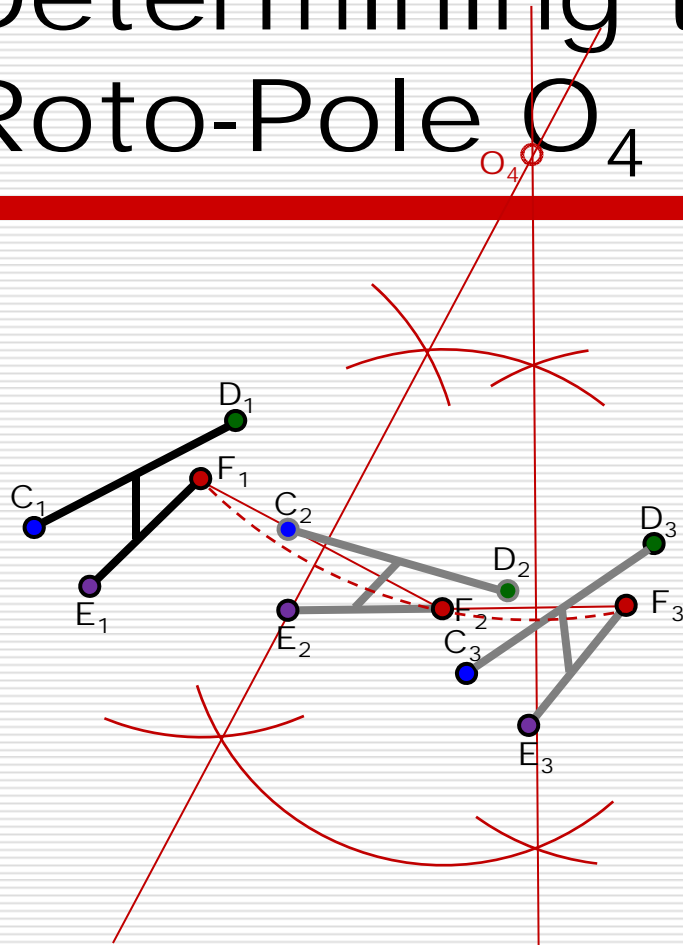


Determining the Location of Roto-Pole O_2



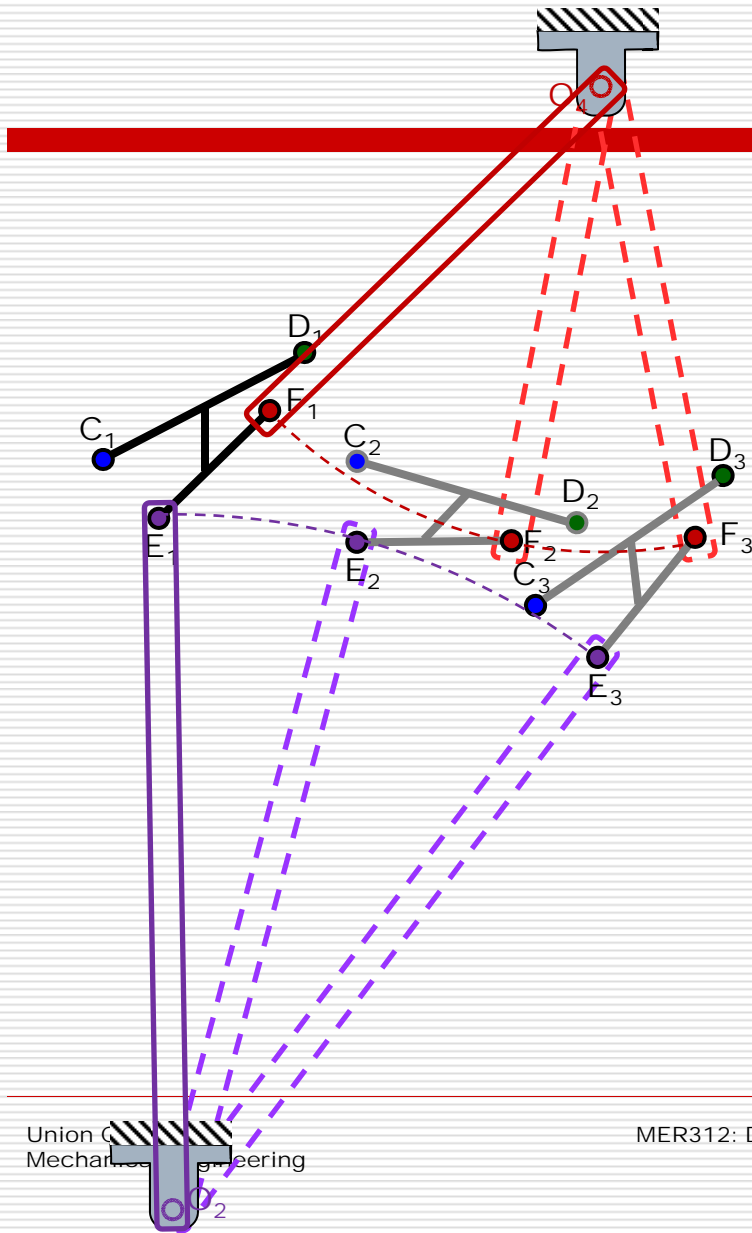
1. Draw Coupler EF in the three desired positions
 - a. E_1F_1 , E_2F_2 , & E_3F_3
2. Draw Construction Lines
 - a. E_1E_2 , E_2E_3
3. Construct Perpendicular Bisectors
 - a. E_1E_2
 - b. E_2E_3
4. At the intersection of the Two Perpendicular Bisectors is the Location of the Roto-Pole O_2

Determining the Location of Roto-Pole O_4



1. Draw Coupler EF in the three desired positions
 - a. E_1F_1 , E_2F_2 , & E_3F_3
2. Draw Construction Lines
 - a. F_1F_2 , F_2F_3
3. Construct Perpendicular Bisectors
 - a. F_1F_2
 - b. F_2F_3
4. At the intersection of the Two Perpendicular Bisectors is the Location of the Roto-Pole O_4

Final 4 Bar Synthesis



1. O_2 and O_4 are the ground points
2. Draw Link O_2E
3. Draw Link O_4F
4. May want to consider a drive dyad

Example

