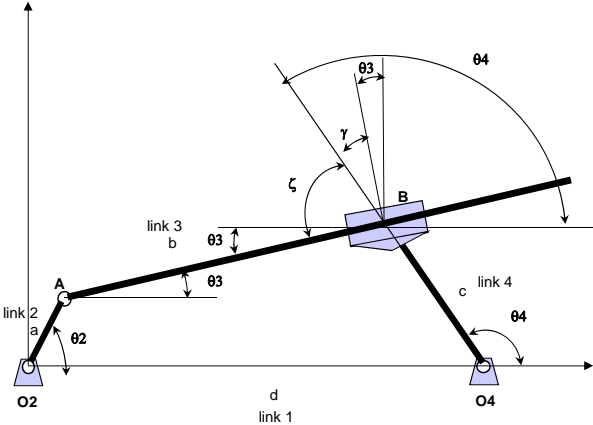


Inverted Slider Crank

a=	8	Link 2
c=	8	Link 4
d=	5	Link 1
$\theta_2 =$	150	
$\dot{\theta}_2 =$	0	
$\ddot{\theta}_2 =$	24	$\frac{1}{s}$
$\theta_2 =$	30	$\frac{1}{s^2}$
b=	9.71	-9.71
$\theta_4 =$	110.95	-148.02
$\theta_3 =$	20.95	-238.02
$\dot{\theta}_3 =$	12.46	17.46
$\dot{\theta}_4 =$	12.46	17.46
$\dot{b} =$	49.43	-49.43
$\ddot{\theta}_4 =$	129.38	-127.85
$\ddot{\theta}_3 =$	129.38	-127.85
$\ddot{b} =$	-2244.82	2244.82

$\zeta =$ 90
 $K1 =$ -4
 $K2 =$ 11.92820323
 $K3 =$ 8



	x comp	y comp	mag	angle	e _r		e _θ	
					i	j	i	j
rO4=	5.00	0.00	5.00	0.0	1.000	0.000	0.000	1.000
rA=	-6.93	4.00	8.00	150.0	-0.866	0.500	-0.500	-0.866
rBA=	9.07	3.47	9.71	20.9	0.934	0.358	-0.358	0.934
rBO4=	-2.86	7.47	8.00	110.9	-0.358	0.934	-0.934	-0.358
rB=	2.14	7.47	7.77	74.0	0.275	0.961	-0.961	0.275
vA=	-96.00	-166.28	192.00	-120.0	-0.500	-0.866	0.866	-0.500
vBA=	2.92	130.65	130.68	88.7	0.022	1.000	-1.000	0.022
vB=	-93.08	-35.63	99.67	-159.1	-0.934	-0.358	0.358	-0.934
aA=	3870.65	-2511.85	4614.25	-33.0	0.839	-0.544	0.544	0.839
aBA=	-4393.36	982.23	4501.82	167.4	-0.976	0.218	-0.218	-0.976
aB=	-522.71	-1529.62	1616.46	-108.9	-0.323	-0.946	0.946	-0.323
alt	x comp	y comp	mag	angle	i	j	i	j
rO4=	5.00	0.00	5.00	0.0	1.000	0.000	0.000	1.000
rA=	-6.93	4.00	8.00	150.0	-0.866	0.500	-0.500	-0.866
rBA=	5.14	-8.24	9.71	-58.0	0.530	-0.848	0.848	0.530
rBO4=	-6.79	-4.24	8.00	-148.0	-0.848	-0.530	0.530	-0.848
rB=	-1.79	-4.24	4.60	-112.9	-0.388	-0.921	0.921	-0.388
vA=	-96.00	-166.28	192.00	-120.0	-0.500	-0.866	0.866	-0.500
vBA=	169.95	47.82	176.55	15.7	0.963	0.271	-0.271	0.963
vB=	73.95	-118.45	139.64	-58.0	0.530	-0.848	0.848	0.530
aA=	3870.65	-2511.85	4614.25	-33.0	0.839	-0.544	0.544	0.839
aBA=	-2344.65	4670.28	5225.79	116.7	-0.449	0.894	-0.894	-0.449
aB=	1526.00	2158.43	2643.39	54.7	0.577	0.817	-0.817	0.577