

PROB 2.2 | DETERMINE THE PATH OF POINT C USING  $15^\circ$  INCREMENTS OF ROTATION OF LINK 1. ( $O_A A = 1.0$ ,  $AB = 3.0$ ,  $O_B B = 1.5$ ,  $O_A O_B = 3.0$ ,  $AC = BC = 2.0$ )

GIVEN:

1. 4-BAR LINKAGE WITH A 3-NODE COUPLER LINK, SHOWN BELOW
2. DRIVE LINK GOING THROUGH  $15^\circ$  INCREMENTS OF ROTATION
3. THE INITIAL ANGLE OF THE DRIVE LINK WITH RESPECT TO THE POSITIVE HORIZONTAL IS  $60^\circ$
4.  $O_A A = 1.0$ ,  $AB = 3.0$ ,  $O_B B = 1.5$ ,  $O_A O_B = 3.0$ ,  $AC = BC = 2.0$

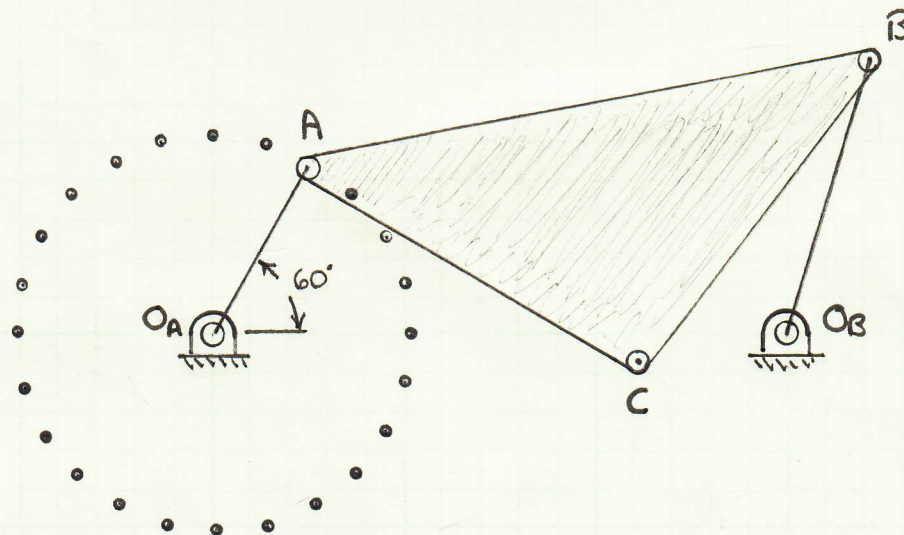
ASSUMPTIONS:

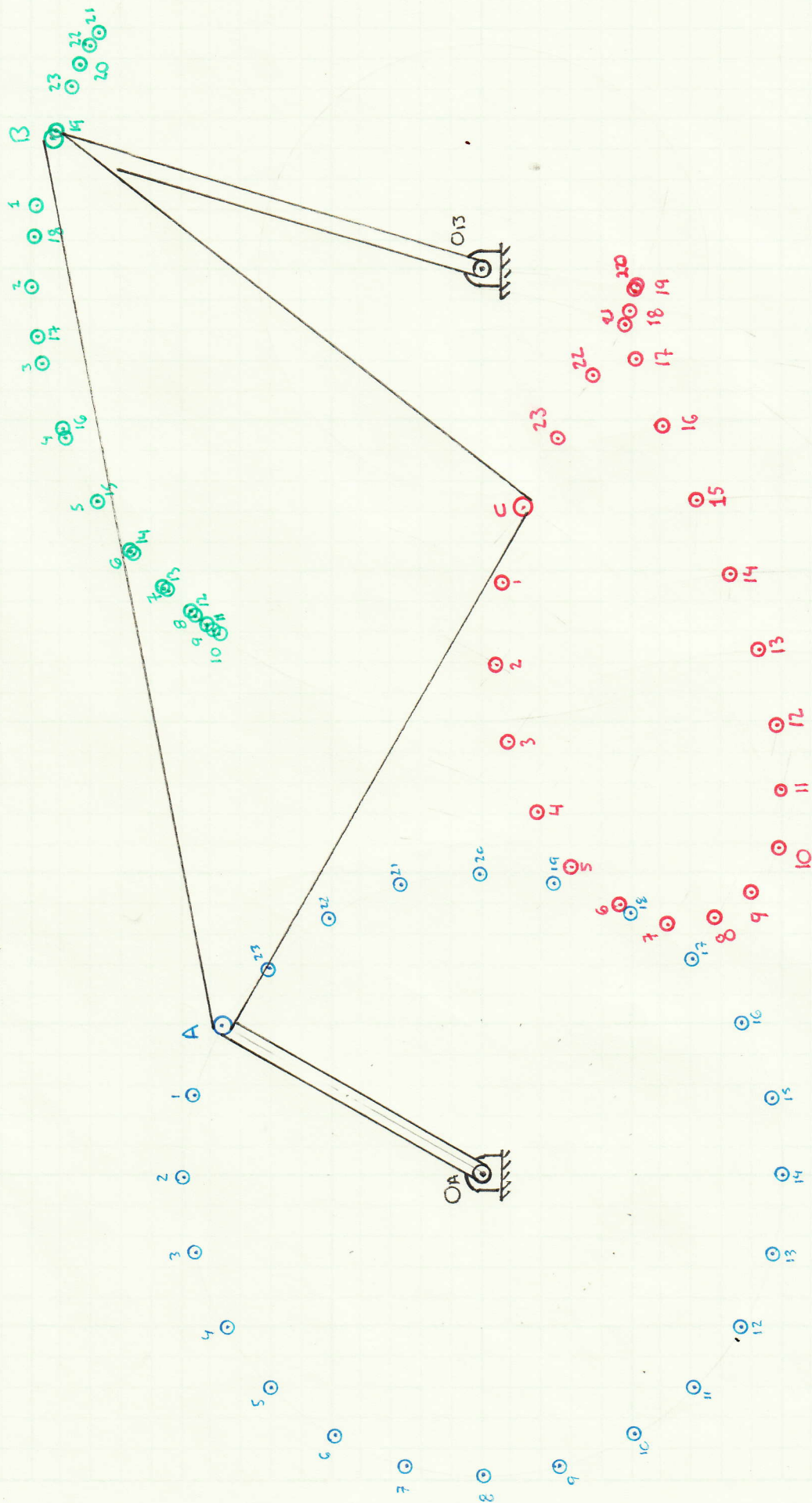
1. ALL LINKS ARE RIGID
2. THE MOTION OF ALL LINKS ARE PLANAR
3. ALL JOINTS ARE FRICTIONLESS
4. THE LINKS DO NOT INTERFERE WITH EACH OTHER DURING THE ROTATION.

FIND:

1. THE POSITION OF POINT C FOR EACH  $15^\circ$  ROTATION OF THE DRIVE LINK

FIGURE:





**SUMMARY:** THE LOCATION OF "A" IS NUMBERED IN BLUE, "B" IN GREEN, AND "C" IN RED SO THAT THE LOCATIONS OF "A" FOR CORRESPONDING POSITIONS OF "C" CAN EASILY BE SEEN. AS "A" ROTATES AT A CONSTANT RATE, INDICATED BY EQUAL CIRCUMFERENTIAL SPACING, POINTS "B" AND "C" SPEED UP AND SLOW DOWN, INDICATED BY THE UNEQUAL SPACING OF THE POINTS ON THE PATHS TAKEN BY "B" AND "C".