

Discretization of the fractional Laplacian using finite element methods and a posteriori error estimation

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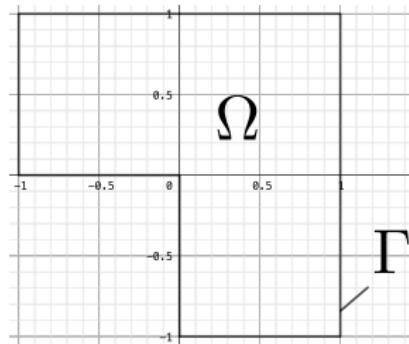
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 - Error estimation
 - Numerical results
- Application to a fractional Laplacian problem
 - The spectral fractional Laplacian
 - How to compute the solution numerically ?
 - A posteriori error estimation
- Challenges

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A finite element method

Example of elliptic PDE



Let $\gamma \in \mathbb{R}^{+,*}$ and $f \in L^2(\Omega)$. We are looking for u (with sufficient regularity) such that

$$\begin{aligned} u - \gamma \Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \Gamma, \end{aligned}$$

where $\Delta u(x_1, x_2) := (\partial_{x_1}^2 + \partial_{x_2}^2)u$.

A finite element method

Example of elliptic PDE

Instead of looking at the strong formulation: find u satisfying

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Example of elliptic PDE

Instead of looking at the strong formulation: find u satisfying

$$\begin{aligned} u - \gamma \Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \Gamma, \end{aligned}$$

we consider the **weak formulation**: find a function u in $H_0^1(\Omega)$ such that

$$\int_{\Omega} uv + \gamma \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} fv \quad \forall v \in H_0^1(\Omega),$$

where $H_0^1(\Omega)$ is the Sobolev space of functions v in $L^2(\Omega)$ vanishing on Γ and with $\partial_x v$ and $\partial_y v$ in $L^2(\Omega)$.

A finite element method

Discretization

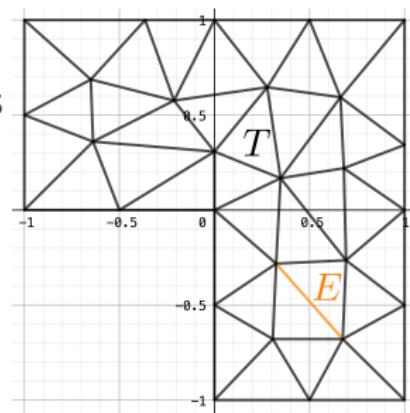
Goal: Compute a numerical approximation to u , solution to

$$\int_{\Omega} uv + \gamma \int_{\Omega} \nabla u \cdot \nabla v = \int_{\Omega} fv \quad \forall v \in H_0^1(\Omega).$$

A finite element method

Discretization

Let $\mathcal{T} = \{T\}$ be a mesh on Ω , of edges $\mathcal{E} = \{E\}$.

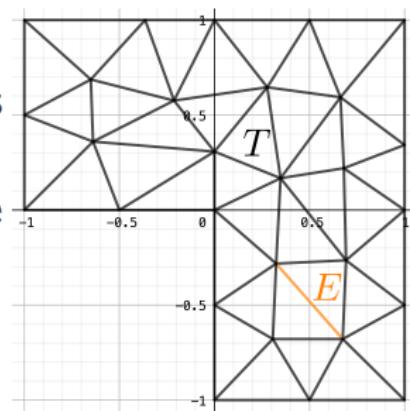


A finite element method

Discretization

Let $\mathcal{T} = \{T\}$ be a mesh on Ω , of edges $\mathcal{E} = \{E\}$.

We consider $V^1 \subset H_0^1(\Omega)$ the space of continuous piecewise linear polynomial functions over \mathcal{T} , vanishing on Γ .

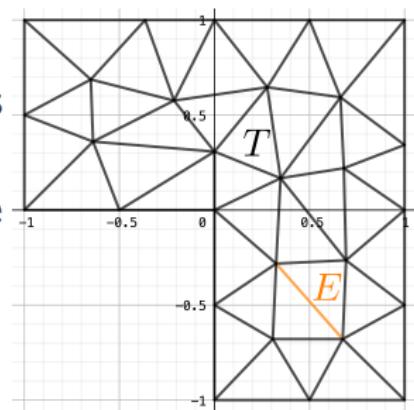


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Let $u_1 \in V^1$ be the solution to

$$\int_{\Omega} u_1 v_1 + \gamma \int_{\Omega} \nabla u_1 \cdot \nabla v_1 = \int_{\Omega} f v_1 \quad \forall v_1 \in V^1.$$

A finite element method

Discretization

Original problem:

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Linear Lagrange finite element discretization:

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We take $u_1 \approx u$.

A finite element method

Discretization

Let's try it out!

A finite element method

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We take $\gamma = 1$, $f = 1$ and solve

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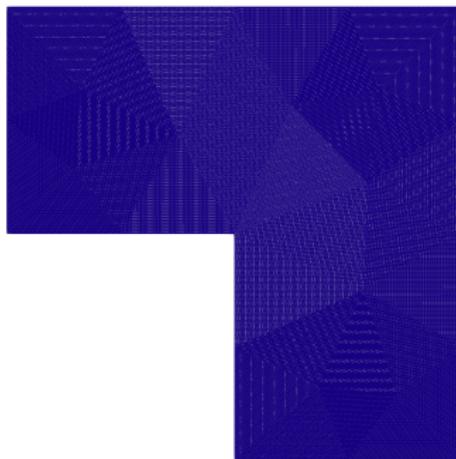
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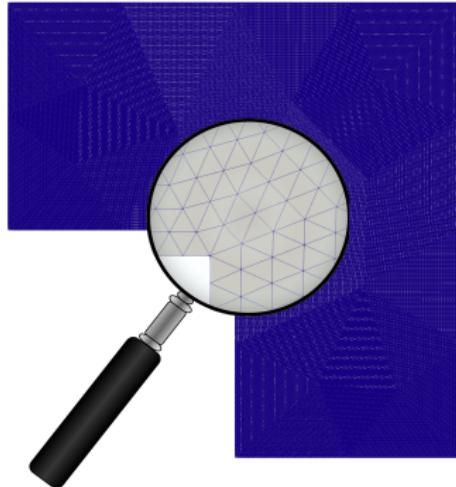
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(Linear system dimension: 66049.)

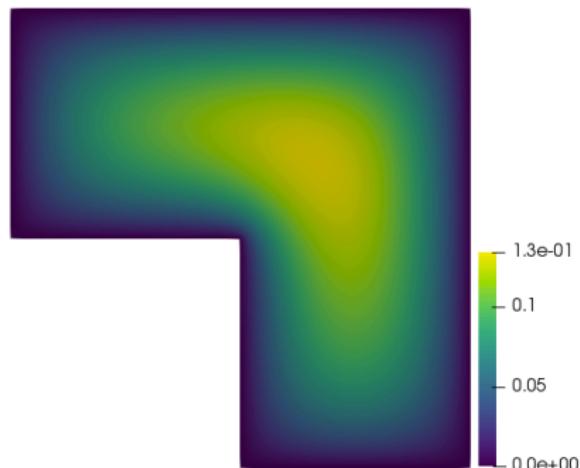
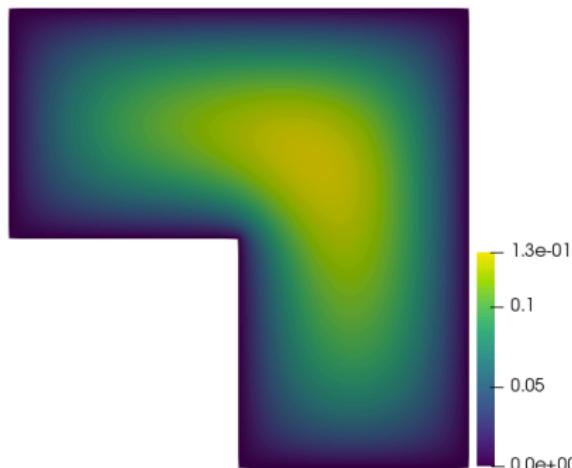


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Error estimation

A priori error estimation

What can we say about the discretization error ?

Error estimation

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We quantify the error $e := u - u_1$ using the energy norm

$$\|e\|_\gamma := \left(\int_{\Omega} e^2 + \gamma \int_{\Omega} \nabla e \cdot \nabla e \right)^{1/2}.$$

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A priori error estimation

Let Ω be an open subset of \mathbb{R}^2 of polygonal boundary and let $\{\mathcal{T}_h\}_{h>0}$ be a shape-regular family of conformal meshes of Ω . Then,

$$\lim_{h \rightarrow 0} \|e\|_\gamma = 0.$$

Moreover, if $u \in H^2(\Omega)$ there exists c_γ such that

$$\|e\|_\gamma \leq c_\gamma h |u|_{H^2}.$$

$H^2(\Omega) := \{v \in L^2(\Omega), \partial^\alpha v \in L^2(\Omega), \alpha \in \mathbb{N}^2, |\alpha| \leq 2\}$ is an Hilbert space on which

we define the semi-norm, $|u|_{H^2}^2 := \|\partial_{xx}^2 u\|_{L^2}^2 + \|\partial_{yy}^2 u\|_{L^2}^2 + \|\partial_{xy}^2 u\|_{L^2}^2$.

Error estimation

A priori error estimation

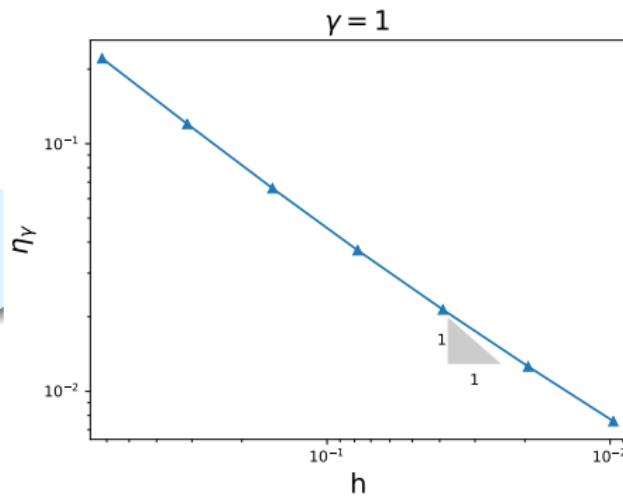
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A priori error estimation

$$\|e\|_\gamma \leq c_\gamma h^{\textcolor{red}{1}} |u|_{H^2}.$$

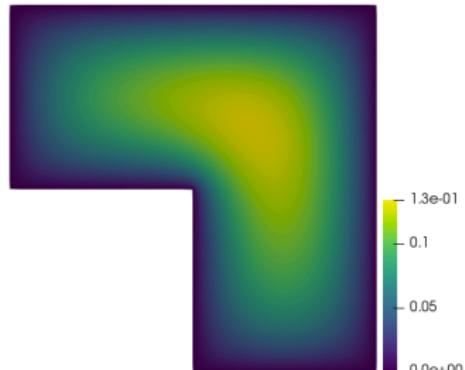


Error estimation

What happened ?

A priori error estimation

$$\|e\|_{\gamma} \leq c_{\gamma} h |u|_{H^2}.$$



Error estimation

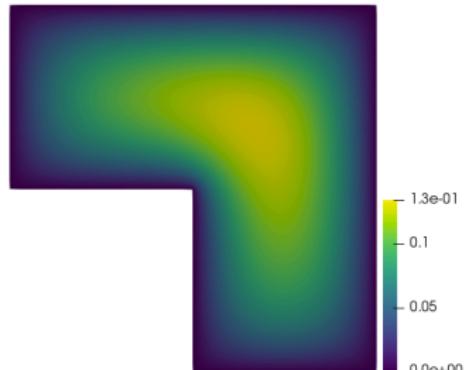
What happened ?

A priori error estimation

$$\|e\|_{\gamma} \leq c_{\gamma} h |u|_{H^2}.$$

The solution u does not belong to $H^2(\Omega)$!

∇u admits a singularity in the reentrant corner of Ω [Grisvard, 1986].



Error estimation

A posteriori error estimation

- How to deal with solutions having local features ?

Error estimation

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Error estimation

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A priori error estimation	A posteriori error estimation
$\ e\ _\gamma \leq \tilde{C}(u)$ $\tilde{C}(u)$ is unknown.	$\ e\ _\gamma \approx \eta$ η is known.

Error estimation

A posteriori error estimation

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- computable from problem data (f , boundary conditions data...) and u_1 only,

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- **cheap** to compute, ideally much less expensive than computing u_1 .

Error estimation

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Let $e := u - u_1$, we can show that e is solution to the local problem:

$$\int_T ev_T + \gamma \int_T \nabla e \cdot \nabla v_T = \int_T r_{\gamma,T} v_T + \sum_{E \in \partial T} \int_E J_{\gamma,E} v_T \quad \forall v_T \in H_0^1(T),$$

with $r_{\gamma,T} := (f - u_1 + \gamma \Delta u_1)|_T$ and $J_{\gamma,E} := \gamma \left[\frac{\partial u_1}{\partial n} \right]_E$.

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For a cell T in \mathcal{T} , we define $e_T^{\text{bw}} \in V^{\text{bw}}(T)$ the solution to

$$\int_T e_T^{\text{bw}} v_T + \gamma \int_T \nabla e_T^{\text{bw}} \cdot \nabla v_T = \int_T r_{\gamma,T} v_T + \sum_{E \in \partial T} \int_E J_{\gamma,E} v_T \quad \forall v_T \in V^{\text{bw}}(T),$$

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The local Bank-Weiser a posteriori error estimator [Bank, Weiser, 1985] is defined by:

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Error estimation

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and the global estimator by:

$$\eta_{\text{bw}}^2 := \sum_{T \in \mathcal{T}} \eta_T^2.$$

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- computable from data and u_1 only: ✓

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- efficient ($c\eta_{bw} \leq \|e\|_{\gamma}$): ✓ [Bank, Weiser, 1985],
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- cheap: ✓ [Bordas, B., Chouly, Hale, Lozinski, 2020].

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Numerical results

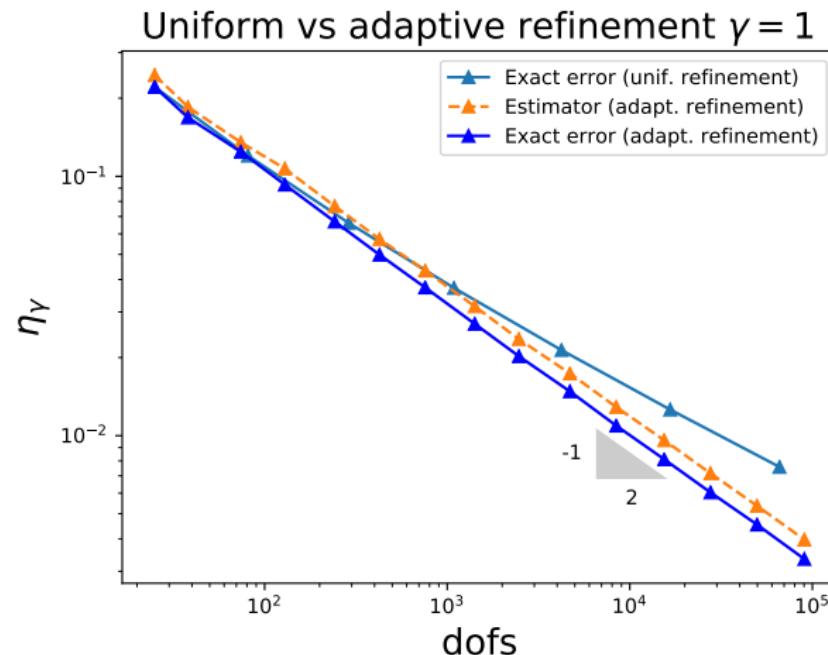
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7. go back to 2. replacing l by $l + 1$.

Numerical results

Let's try it out!

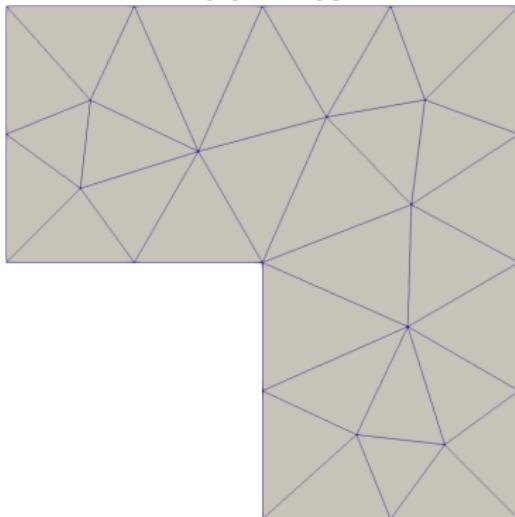


Numerical results

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Uniform refinement:

Initial mesh

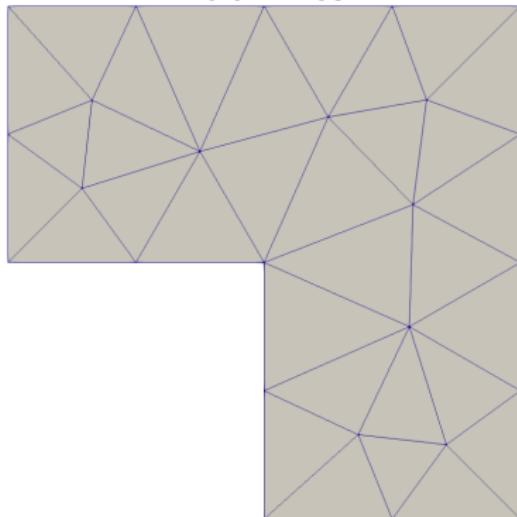


Exact error ≈ 0.2210

Linear system dim. = 25

Adaptive refinement:

Initial mesh



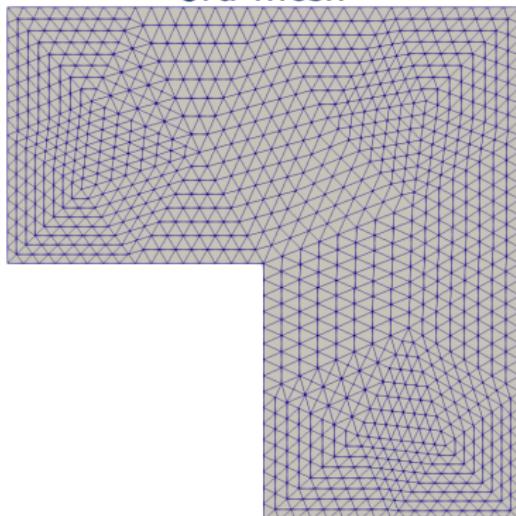
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Numerical results

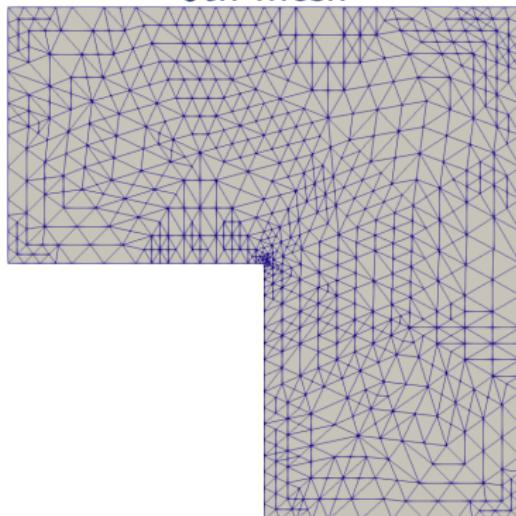
Let's try it out!

Uniform refinement:
3rd mesh



Exact error ≈ 0.0371
Linear system dim. = 1089

Adaptive refinement:
6th mesh

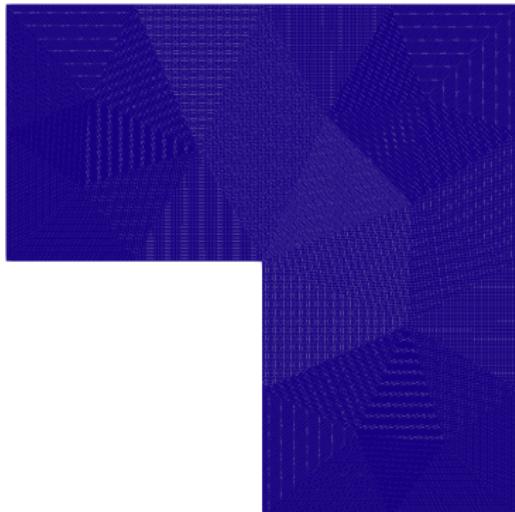


Exact error ≈ 0.0372
Linear system dim. = 757

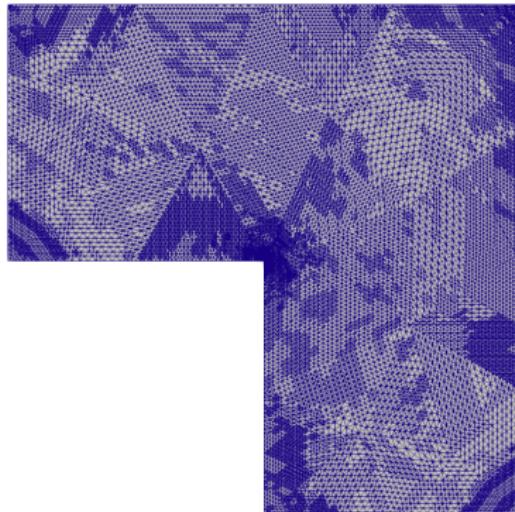
Numerical results

Let's try it out!

Uniform refinement:
6th mesh



Adaptive refinement:
11th mesh



Exact error ≈ 0.0076

Linear system dim. = 66049

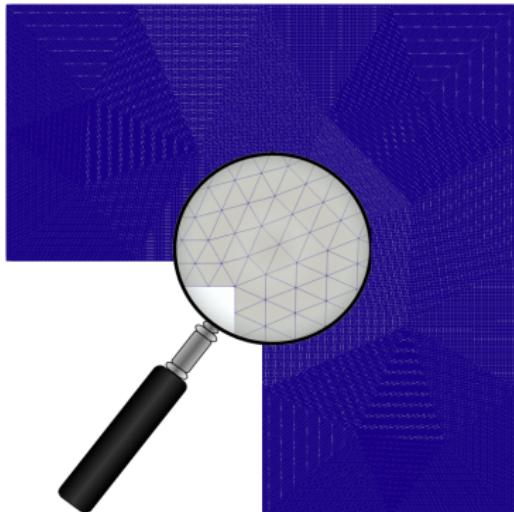
Exact error ≈ 0.0081

Linear system dim. = 15429

Numerical results

Let's try it out!

Uniform refinement:
6th mesh



Exact error ≈ 0.0076
Linear system dim. = 66049

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Application to a fractional Laplacian problem

The spectral fractional Laplacian

Let $\alpha \in (0, 2)$ and $f \in L^2(\Omega)$, we are looking for $u \in L^2(\Omega)$ (with sufficient regularity) such that

$$\begin{aligned}(-\Delta)^{\alpha/2} u &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \Gamma.\end{aligned}$$

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How is the function u defined ?

Let \mathcal{L} be the Laplace-Dirichlet operator on Ω such that $\mathcal{L}w = f$ if w is the solution of

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We consider the weak formulation: w in $H_0^1(\Omega)$ is solution to

$$\int_{\Omega} \nabla w \cdot \nabla v = \int_{\Omega} fv \quad \forall v \in H_0^1(\Omega).$$

Application to a fractional Laplacian problem

The spectral fractional Laplacian

The eigenfunctions $\{\psi_j\}_{j=1}^{\infty}$ of \mathcal{L} form a basis of $L^2(\Omega)$.

$$f = \sum_{j=1}^{\infty} f_j \psi_j,$$

with $f_j := \int_{\Omega} f \psi_j$ for $j = 1, \dots, \infty$.

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with $f_j := \int_{\Omega} f \psi_j$ for $j = 1, \dots, \infty$.

If $\{\lambda_j\}_{j=1}^{\infty}$ are the corresponding eigenvalues, we define the solution u as follow:

$$u = (-\Delta)^{-\alpha/2} f = \mathcal{L}^{-\alpha/2} f := \sum_{j=1}^{\infty} \lambda_j^{-\alpha/2} f_j \psi_j.$$

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Application to a fractional Laplacian problem

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There are many ways to compute a numerical approximation to the solution u e.g.

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Some tweaks lead to

$$s^{\theta-1} = c_\theta \int_0^{+\infty} t^{\theta-1}(s+t)^{-1} dt \quad \forall s > 0 \text{ and } \forall \theta \in (0, 1),$$

with $c_\theta = \frac{\sin(\pi\theta)}{\pi}$.

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with $c_\theta = \frac{\sin(\pi\theta)}{\pi}$.

Then, for $\theta - 1 = -\alpha/2 \in (-1, 0)$ and $s = \lambda_j$, $j \in \llbracket 1, +\infty \rrbracket$,

$$\lambda_j^{-\alpha/2} = c_\alpha \int_0^{+\infty} t^{-\alpha/2}(\lambda_j + t)^{-1} dt.$$

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$$\mathcal{L}^{-\alpha/2} f = c_\alpha \int_0^{+\infty} t^{-\alpha/2} (\mathcal{L} + t \operatorname{Id})^{-1} f \, dt,$$

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$$\mathcal{L}^{-\alpha/2} f = c_\alpha \int_0^{+\infty} t^{-\alpha/2} (\mathcal{L} + t \operatorname{Id})^{-1} f \, dt,$$

and with a nice change of variable,

$$\mathcal{L}^{-\alpha/2} f = c_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} \left(\operatorname{Id} + e^{2y} \mathcal{L} \right)^{-1} f \, dy \quad \text{for } \alpha \in (0, 2).$$

with $c_\alpha := \frac{2 \sin(\pi \alpha / 2)}{\pi}$.

How to compute the solution numerically ?

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$$u = \mathcal{L}^{-\alpha/2} f = c_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} (\text{Id} + e^{2y} \mathcal{L})^{-1} f \, dy \quad \text{for } \alpha \in (0, 2).$$

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Let us denote $u_y := (\text{Id} + e^{2y} \mathcal{L})^{-1} f$. This function is solution to the following problem (in weak formulation)

$$\int_{\Omega} u_y v + e^{2y} \int_{\Omega} \nabla u_y \cdot \nabla v = \int_{\Omega} f v \quad \forall v \in H_0^1(\Omega).$$

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$$\int_{\Omega} u_y v + e^{2y} \int_{\Omega} \nabla u_y \cdot \nabla v = \int_{\Omega} f v \quad \forall v \in H_0^1(\Omega).$$

We want to discretize the above integral into a finite sum involving computable terms.

How to compute the solution numerically ?

Euler's reflection formula

$$c_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} u_y \, dy = u \approx u_1^N := c_\alpha \sum_{l=-N}^N \omega_l e^{\alpha y_l} u_{y_l,1}.$$

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1. Using FEM, we discretize the function u_y into $u_{y,1}$ solution to

$$\int_{\Omega} u_{y,1} v_{y,1} + e^{2y} \int_{\Omega} \nabla u_{y,1} \cdot \nabla v_{y,1} = \int_{\Omega} f v_{y,1} \quad \forall v_{y,1} \in V^1.$$

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2. We discretize the integral using a simple rectangle quadrature rule of weights $\omega_l = \frac{1}{\sqrt{N}}$ and points $y_l = \frac{l}{\sqrt{N}}$ for any $l \in [-N, \dots, N]$, where N is a user chosen parameter.

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A posteriori error estimation

Euler's reflection formula

We would like to quantify the approximation error:

$$\|e\|_{L^2} := \|u - u_1^N\|_{L^2} := \left\| c_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} u_y dy - \frac{c_\alpha}{\sqrt{N}} \sum_{l=-N}^N e^{\alpha y_l} u_{y_l,1} \right\|_{L^2}.$$

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To do so, we introduce

$$u_1 := c_\alpha \int_{-\infty}^{+\infty} e^{\alpha y} u_{y,1} dy.$$

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We have,

$$\begin{aligned} \|u - u_1^N\|_{L^2} &= \|u - u_1 + u_1 - u_1^N\|_{L^2} \\ &\leqslant \underbrace{\|u - u_1\|_{L^2}}_{\text{FE error}} + \underbrace{\|u_1 - u_1^N\|_{L^2}}_{\text{quadrature error}}. \end{aligned}$$

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Finite element error

We want to quantify the finite element error $\|u - u_1\|_{L^2}$.

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Finite element error

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Idea: We already know an estimator for the error $u_y - u_{y,1}$.
Can we use it to estimate $u - u_1$?

A posteriori error estimation

Finite element error

For a fixed y in \mathbb{R} and for a cell T of the mesh, we compute $e_{y,T}^{\text{bw}} \in V^{\text{bw}}(T)$ the solution to

$$\int_T e_{y,T}^{\text{bw}} v_T + e^{2y} \int_T \nabla e_{y,T}^{\text{bw}} \cdot \nabla v_T = \int_T r_{y,T} v_T + \sum_{E \in \partial T} \int_E J_{y,E} v_T \quad \forall v_T \in V^{\text{bw}}(T).$$

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$$\|u - u_1\|_{L^2} \approx \eta_{\text{bw}}?$$

Numerical results

Let's try it out!

Adaptive refinement algorithm:

1. fix a tolerance ε , pick an initial (coarse) mesh \mathcal{T}_j ($j = 0$) and pick a very fine quadrature rule $\{y_l\}_{l=-N}^N$ (take N large),

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 - ▶ for each cell T of \mathcal{T}_j , solve the BW equation on T to compute $e_{y_l,T}^{\text{bw},j}$,
3. sum the functions $u_{y_l,1}^j$ into the quadrature rule to get u_1^j ,
4. for each cell T of \mathcal{T}_j :
 - ▶ sum (over l) the functions $e_{y_l,T}^{\text{bw},j}$ into the quadrature rule to get $e_T^{\text{bw},j}$,

Numerical results

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Adaptive refinement algorithm:

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9. go back to 2. replacing j by $j + 1$.

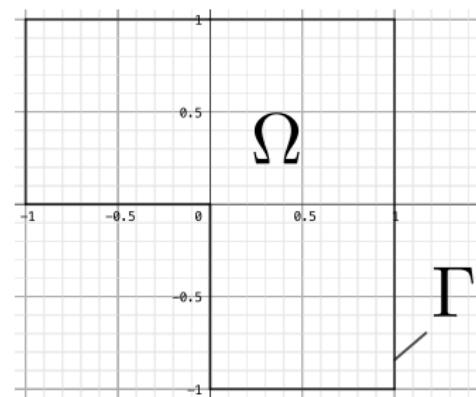
Numerical results

Let's try it out!

Taking $f = 1$, we solve

$$\begin{aligned}(-\Delta)^{\alpha/2}u &= f \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \Gamma.\end{aligned}$$

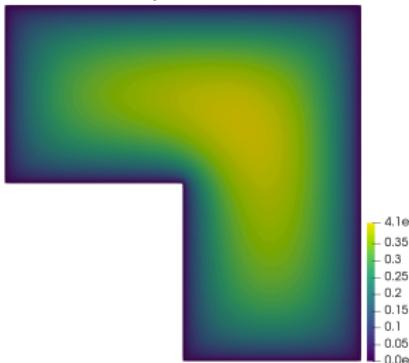
using finite elements and Euler's reflection formula and we estimate the error using the Bank-Weiser estimator.



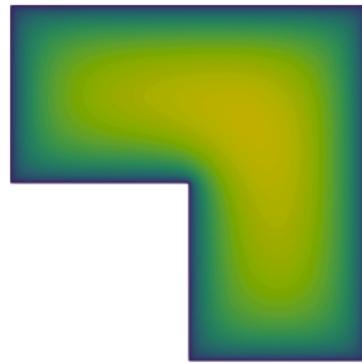
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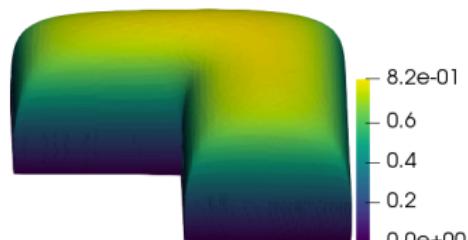
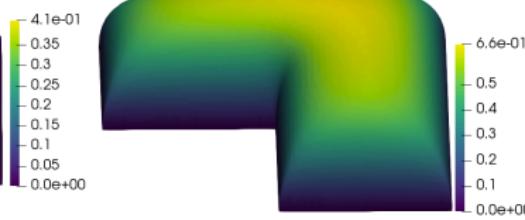
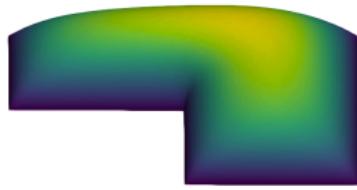
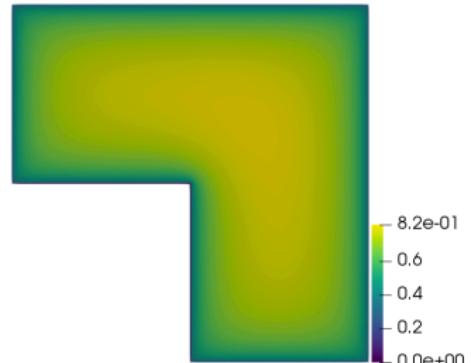
$$\alpha/2 = 0.5$$



$$\alpha/2 = 0.25$$

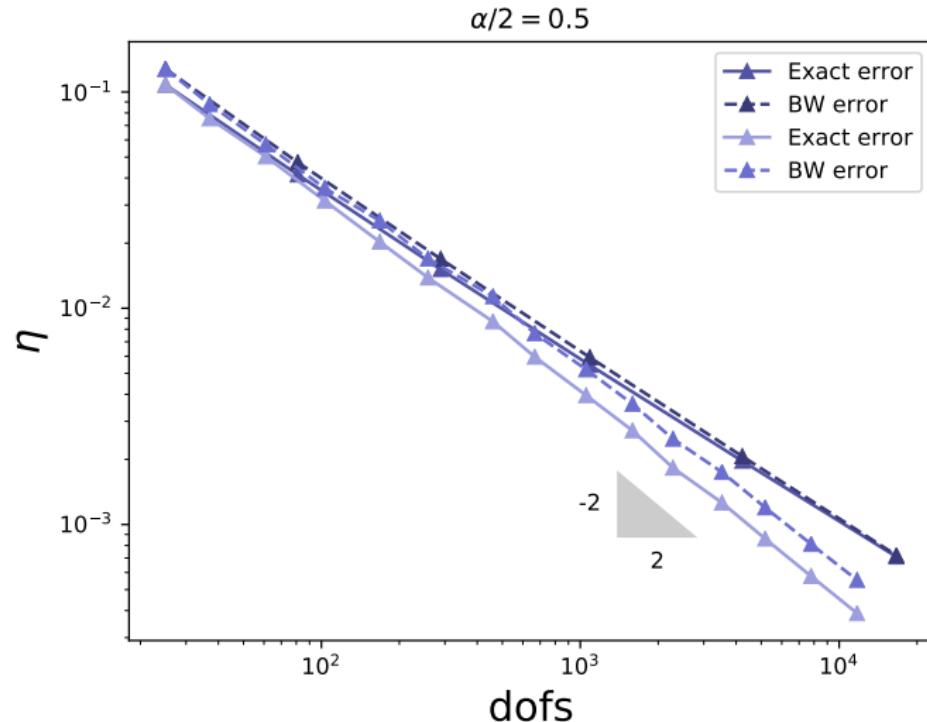


$$\alpha/2 = 0.125$$



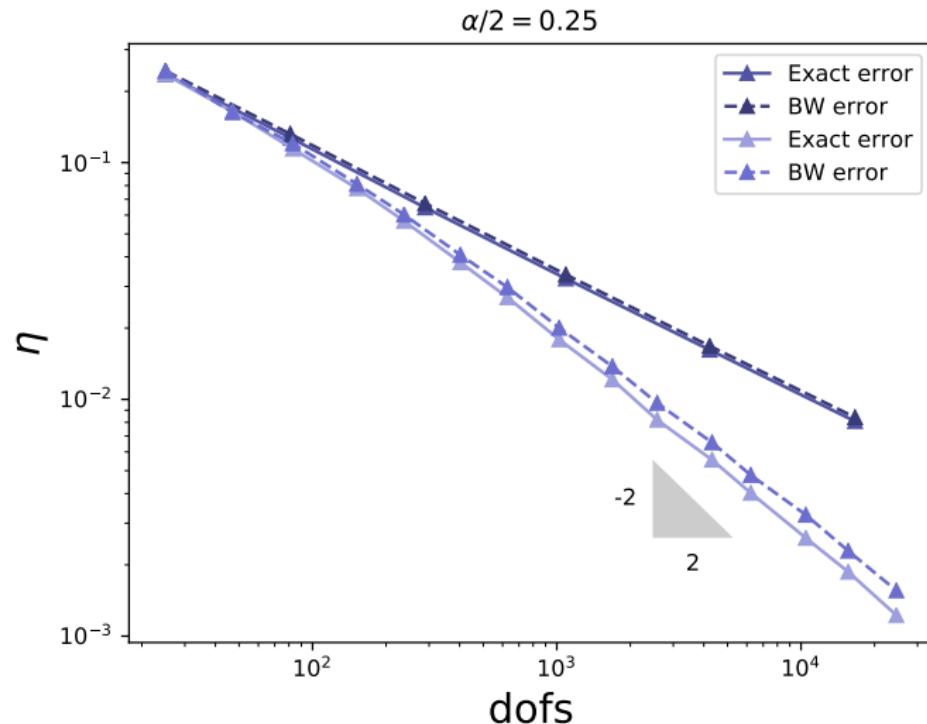
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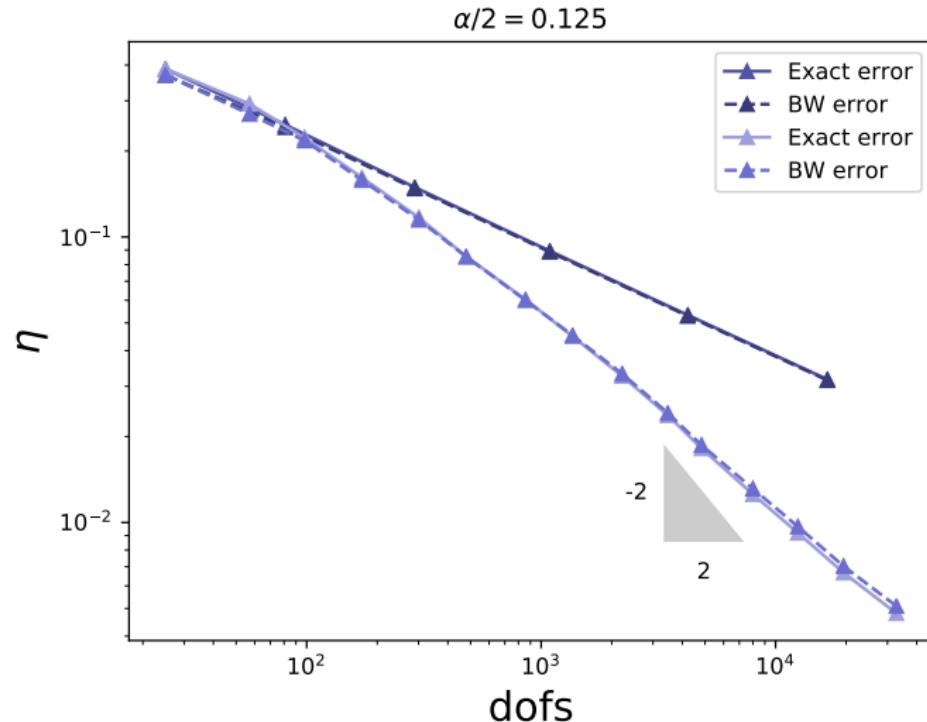
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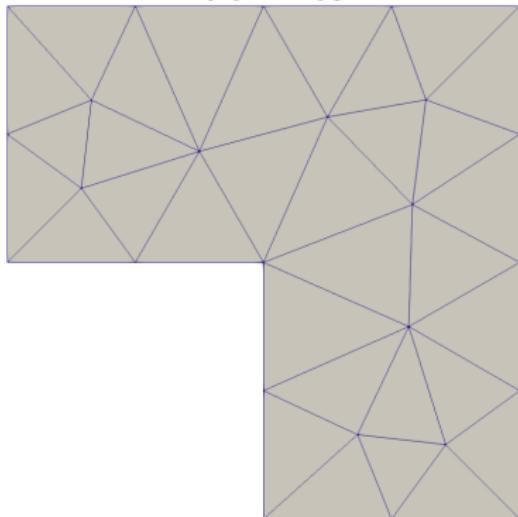
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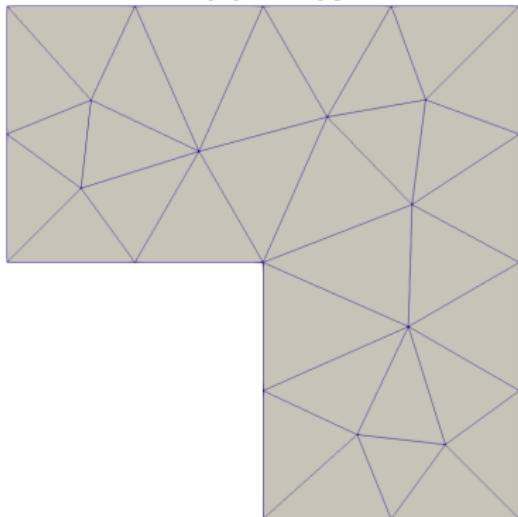
Uniform refinement:

Initial mesh



Adaptive refinement:

Initial mesh



Exact error ≈ 0.1079

Linear system dim. = 25

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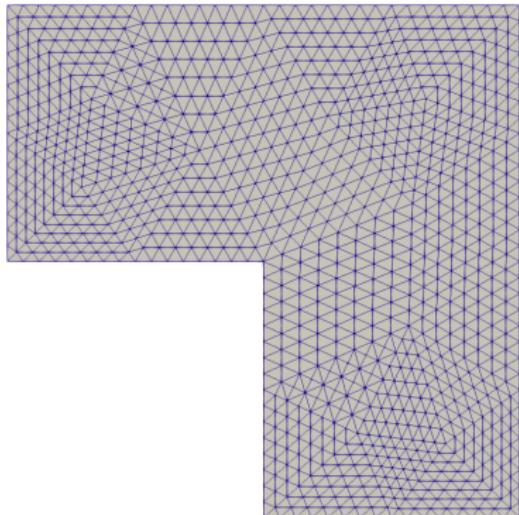
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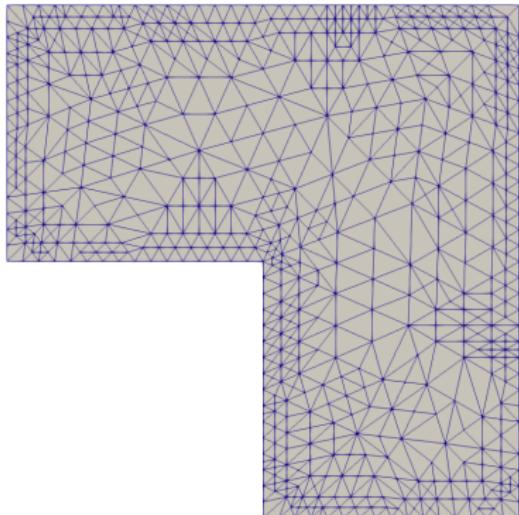
$$\alpha/2 = 0.5$$

Uniform refinement:
3rd mesh



Exact error ≈ 0.0055
Linear system dim. = 1089

Adaptive refinement:
7th mesh



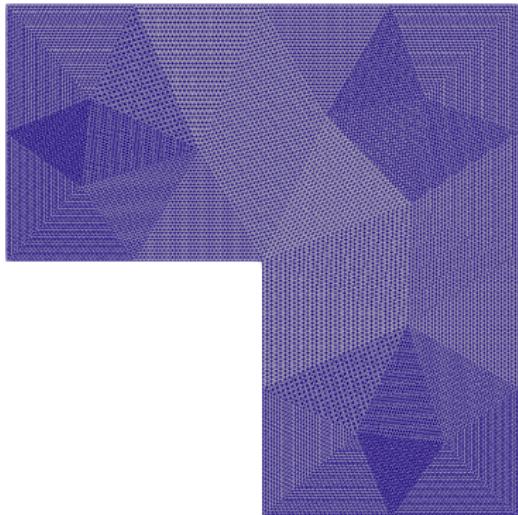
Exact error ≈ 0.0060
Linear system dim. = 667

Numerical results

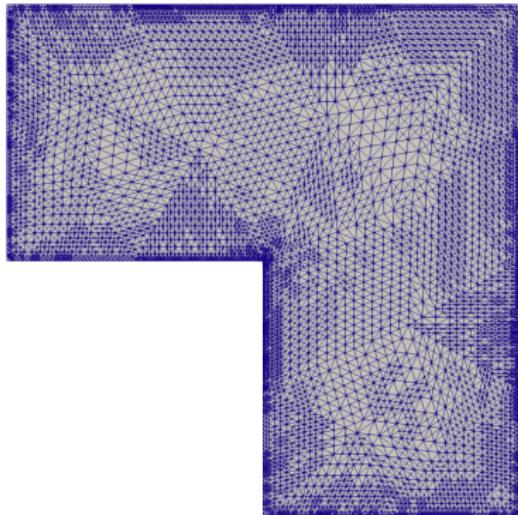
Let's try it out!

$$\alpha/2 = 0.5$$

Uniform refinement:
5th mesh



Adaptive refinement:
13th mesh



Exact error ≈ 0.0007

Linear system dim. = 16641

Exact error ≈ 0.0006

Linear system dim. = 7791

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- Challenges

Challenges

- Computational science/engineering:

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- Become famous and get a permanent job.

Thank you for your attention!