2021-06-17 3-D posttroning and turning - 12+ h2+22 (x,h, 2) ostrang predefermined robot, 2 segments: m 3-dimensions, Jomen y-axis. Jomen 2-axs. (x, y) (D) (X, Z) rotate m rotate m X-Y plane leg spacing in her istation should be equal to starting position before. (Transform of translation/rotation) turning m Find positions (urt 0) for rotating around Center: place