



# Vulnerability Prevention - Checked C

Holistic Software Security

Aravind Machiry



# Safe C Dialects

- Add new types/features to unsafe languages: C/C++.
- Developers can write/convert the existing code by using these new features.
- Small burden to developers but low performance penalty.

## Checked C

- Safe-dialect of C:
  - Fast and backward compatible
  - `_Ptr<type>`
  - `_Array_ptr<type>:count(expr)`
  - `_Nt_array_ptr<type>:count(expr)`

## Writing Checked C Code

```
unsigned dlen;  
int *darr;  
int sarr[10];  
char *r = "hello";
```

```
unsigned dlen;  
_Array_ptr<int> darr: count(dlen);  
int sarr _Checked[10];  
_Nt_array_ptr<char> r: count(6) =  
"hello";
```

## Minimizes Runtime Checks

```
unsigned dlen;  
_Array_ptr<int> darr: count(dlen);  
int sarr[10] _Checked;  
_Nt_array_ptr<char> r : count(6) = "hello";
```

```
if (dlen > 4) {  
    s = dlen - 4;  
    ...darr[s];  
}
```

Runtime check `if (s < dlen)` is optimized out.

# Minimizes Runtime Checks

```
unsigned dlen;  
_Array_ptr<int> darr: count(dlen);  
int sarr[10] _Checked;  
_Nt_array_ptr<char> r : count(6) = "hello";
```

```
if (dlen > 4) {  
    s = dlen - 4;  
    ...darr[s];  
}  
If (q < dlen) {  
    ....darr[q]...  
} else { err("dynamic check failed");}
```

## Can We Easily Convert C to Checked C?

# Refactoring the FreeBSD Kernel with Checked C

Junhan Duan,\* Yudi Yang,\* Jie Zhou, and John Criswell  
Department of Computer Science  
University of Rochester

**It took two undergraduate students approximately three months to refactor the system calls, the network packet (mbuf) utility routines, and parts of the IP and UDP processing code. Our experiments show that using Checked C incurred no performance or code size overheads.**

***Index Terms***—memory safety, safe C, FreeBSD

## Automated Conversion of C to Checked C

- Infer Checked C types for pointers
  - Type Inference
- Infer bounds for array pointers
  - Relationships among program variables
- Rewrite the code with Checked C types



## Inferring Checked C types

- Type Inference
  - Standard Type Inference does not work

# Conversion Example

```
int main(int argc, char **argv) {
```

```
    int *b, *c;
```

```
    struct f ob[5];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[51];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

```
    char *s = a;
```

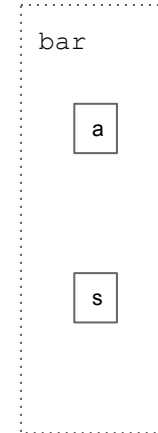
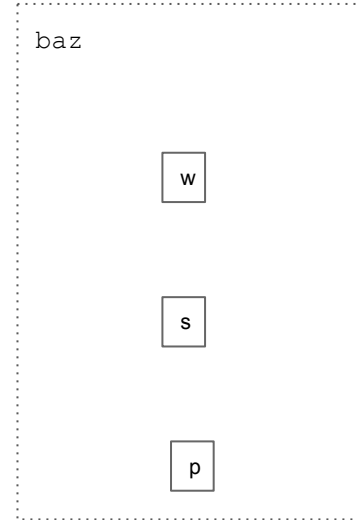
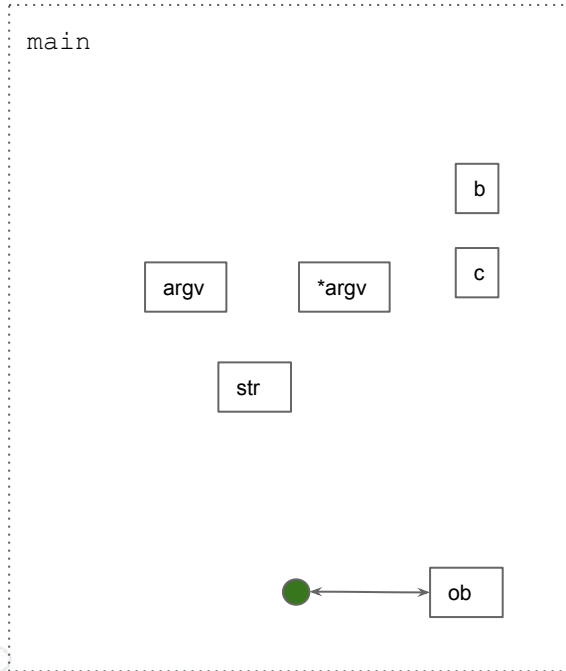
```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

WILD <: `_Nt_array_ptr` <: `_Array_ptr` <: `_Ptr`

## Constraint Graph



# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[5];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

```
    char *s = a;
```

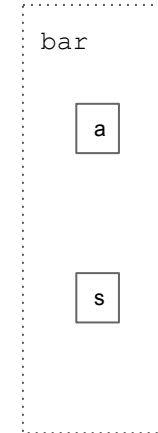
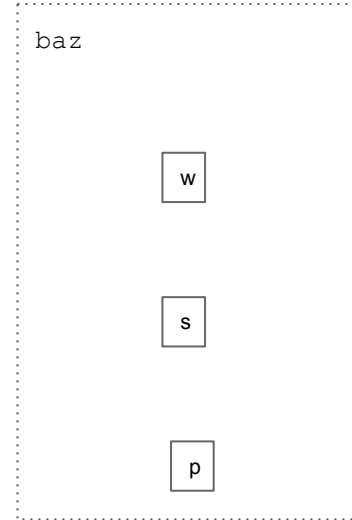
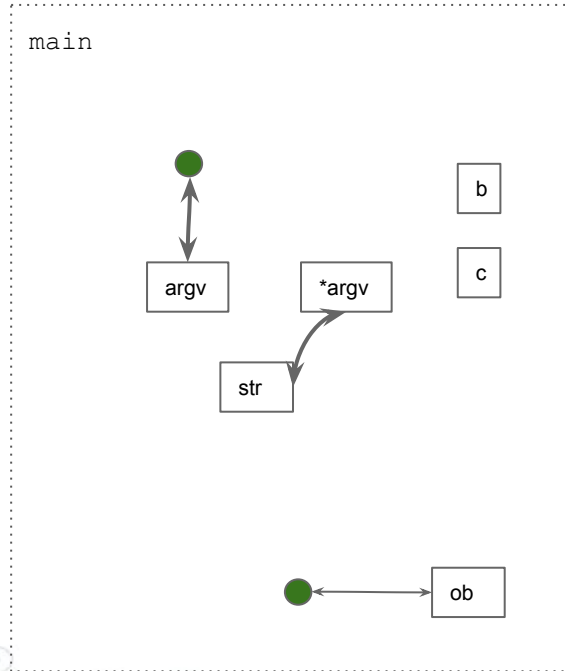
```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

WILD <: `_Nt_array_ptr` <: `_Array_ptr` <: `_Ptr`

## Constraint Graph



# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[51];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

```
    char *s = a;
```

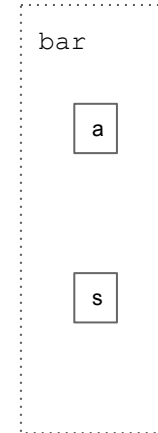
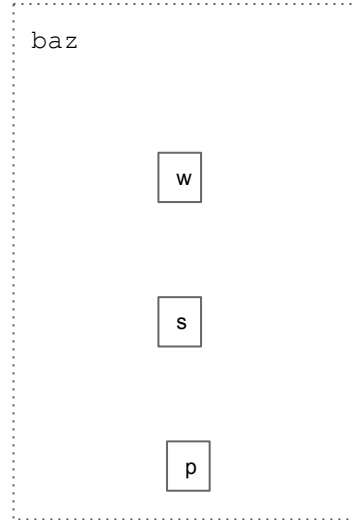
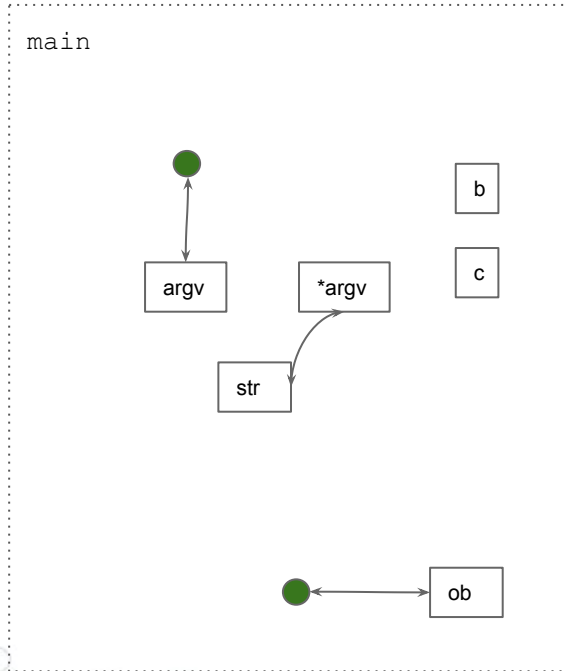
```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

WILD <: `_Nt_array_ptr` <: `_Array_ptr` <: `_Ptr`

## Constraint Graph





# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[5];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

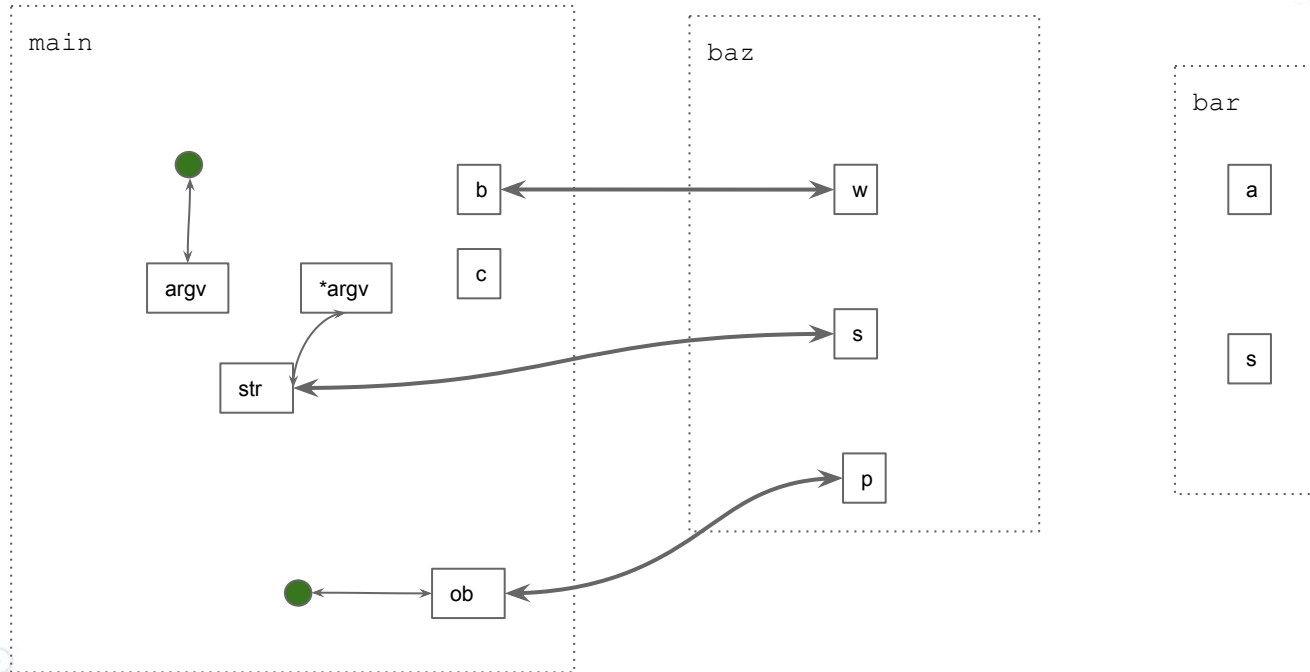
```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

# Constraint Graph



# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[51];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

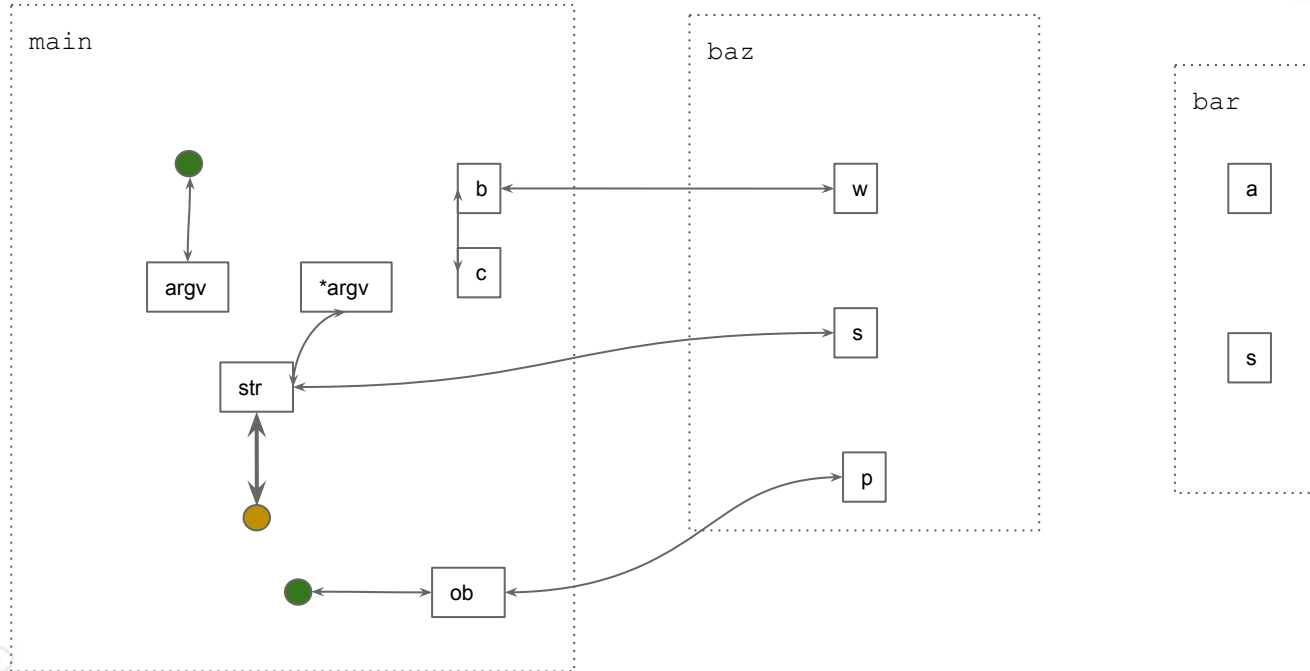
```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

## Constraint Graph



# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[5];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

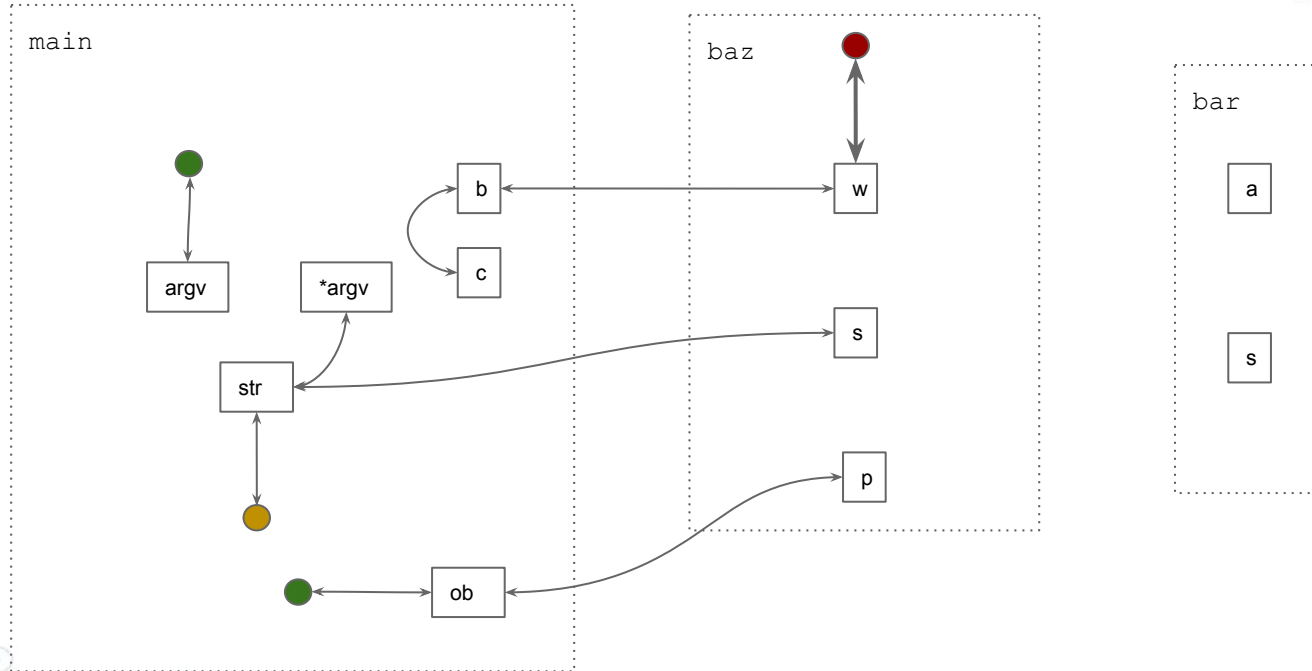
```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

## Constraint Graph



# Conversion Example

```
int main(int argc, char**argv) {
```

```
    int *b, *c;
```

```
    struct f ob[51];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, struct f *p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

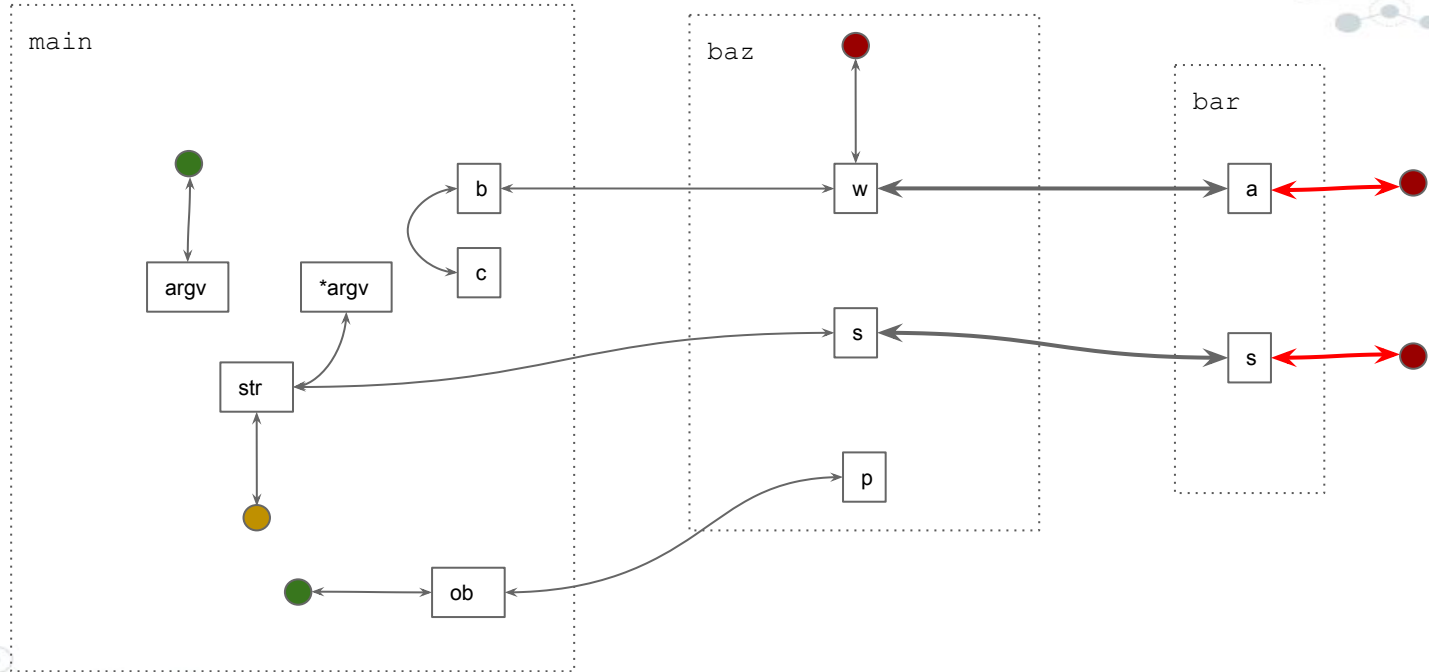
```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

## Constraint Graph



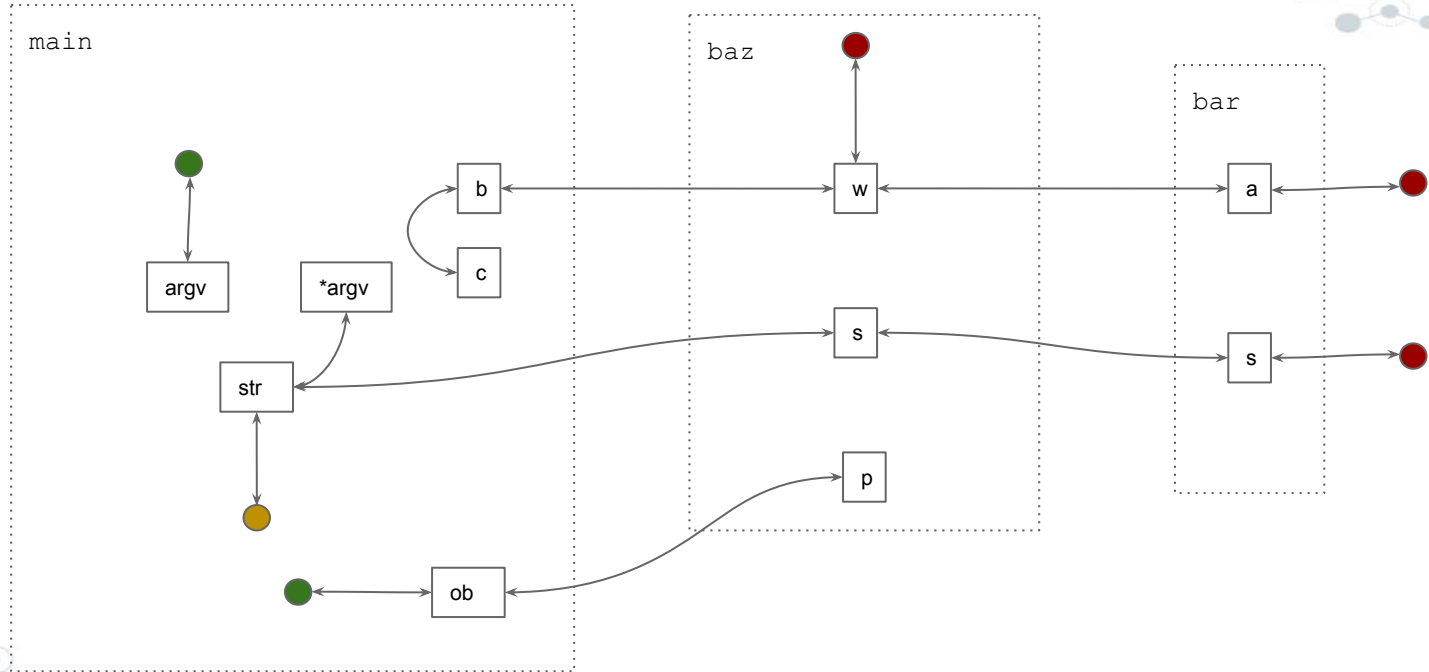


## Constraint Solving

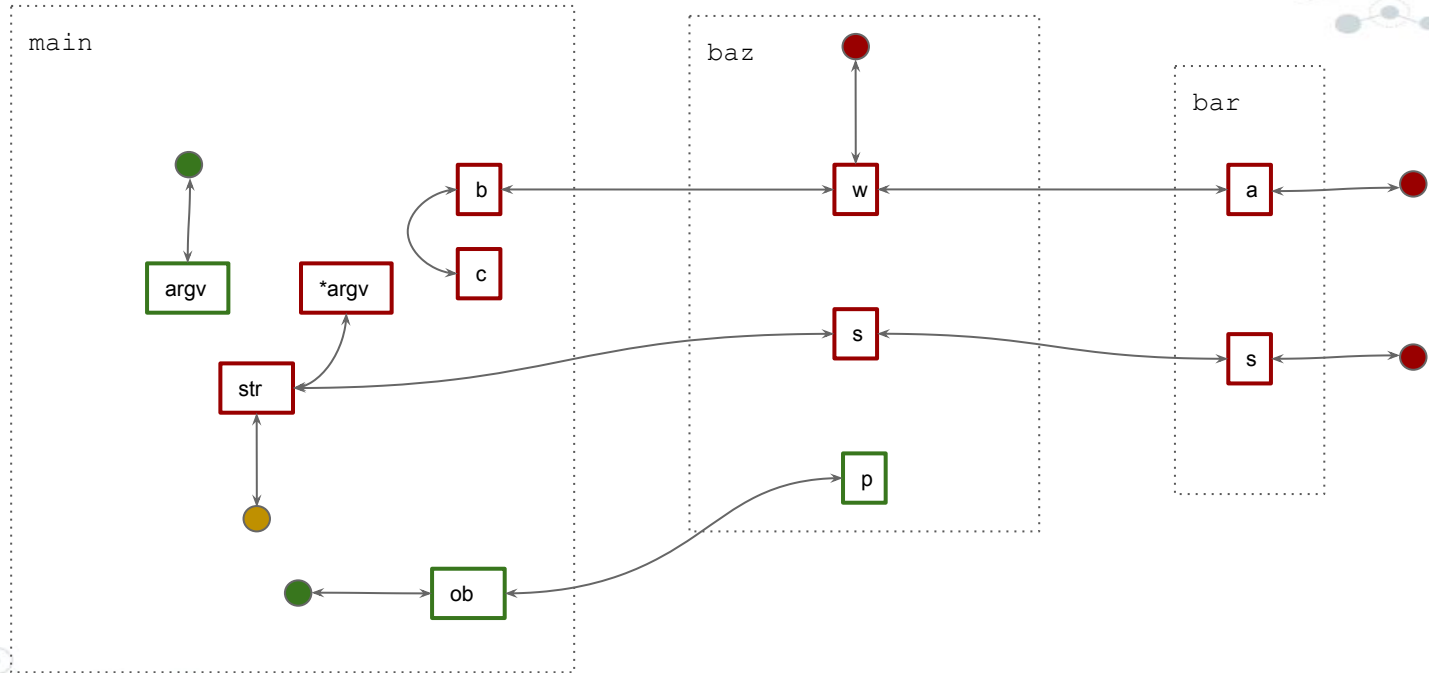
- Propagate Checked C types along the edges
- Join based on the type lattice

WILD <: \_Nt\_array\_ptr <: \_Array\_ptr <: \_Ptr

## Constraint Graph



## Constraint Graph Solution



# Conversion with unification

```
int main(int argc, __Array_ptr<char *> argv) {
```

```
    int *b, *c;
```

```
    struct f ob __Checked[5];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, __Array_ptr<struct f> p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

## Unification Based Inference

- Simple and easy
- Imprecise
  - WILD pointers
  - Unnecessarily specific types

# Conversion with unification

```
int main(int argc, _Array_ptr< char *> argv) {
```

```
    int *b, *c;
```

```
    struct f ob_Checked[5];
```

```
    char *str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, char *s, _Array_ptr<struct f> p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

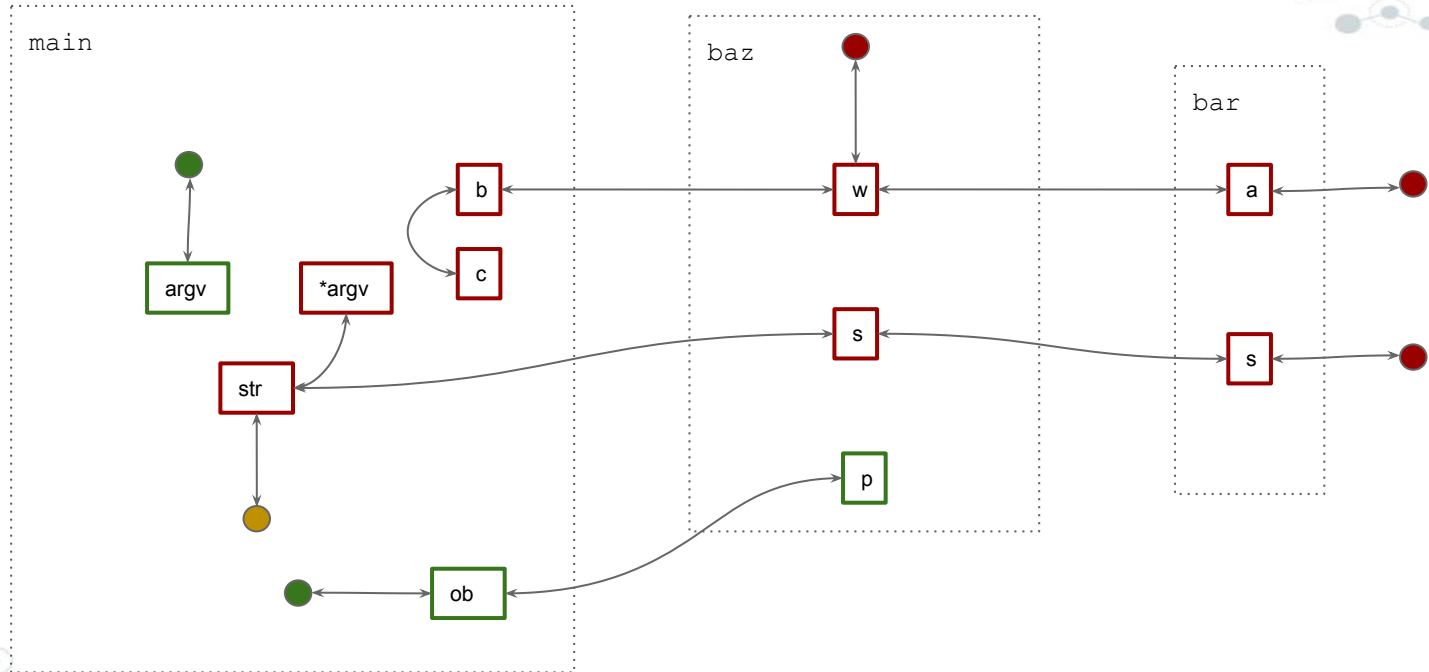
```
    char *s = a;
```

```
    baz(a, s, NULL);
```

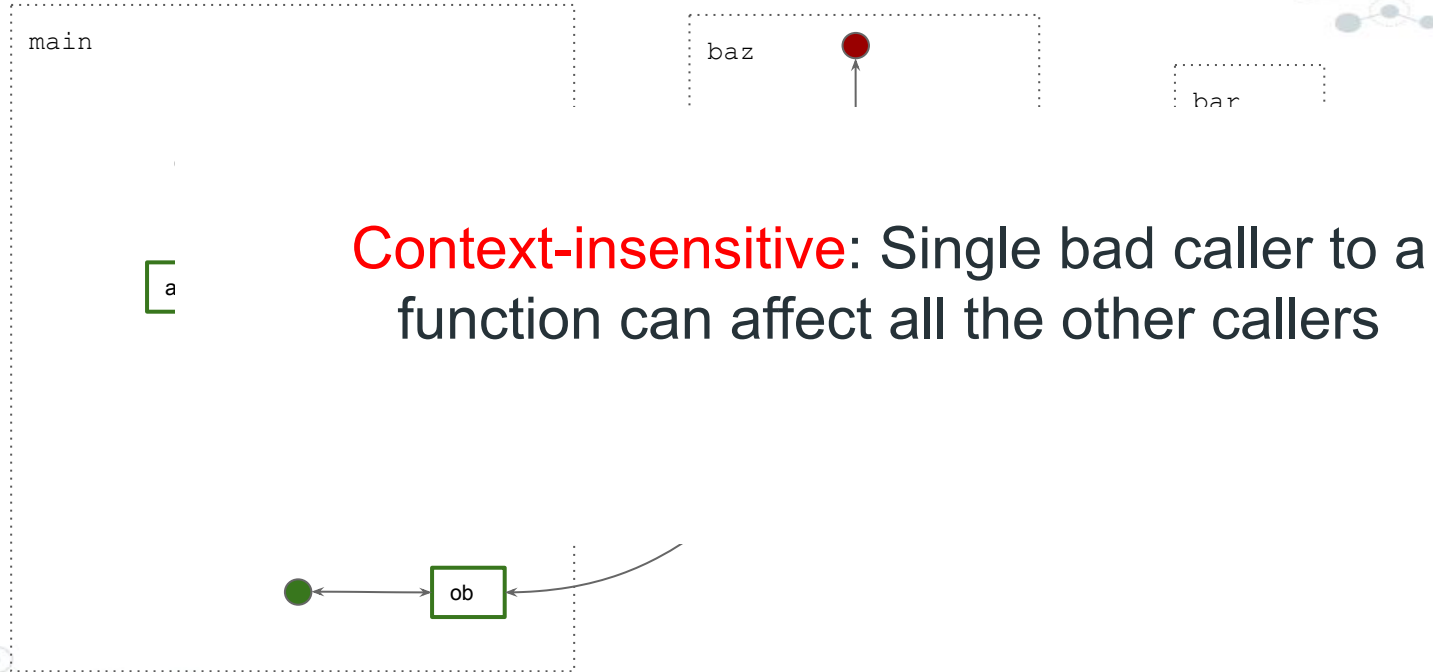
```
    return 0;
```

```
}
```

## Constraint Graph Solution



## Constraint Graph Solution







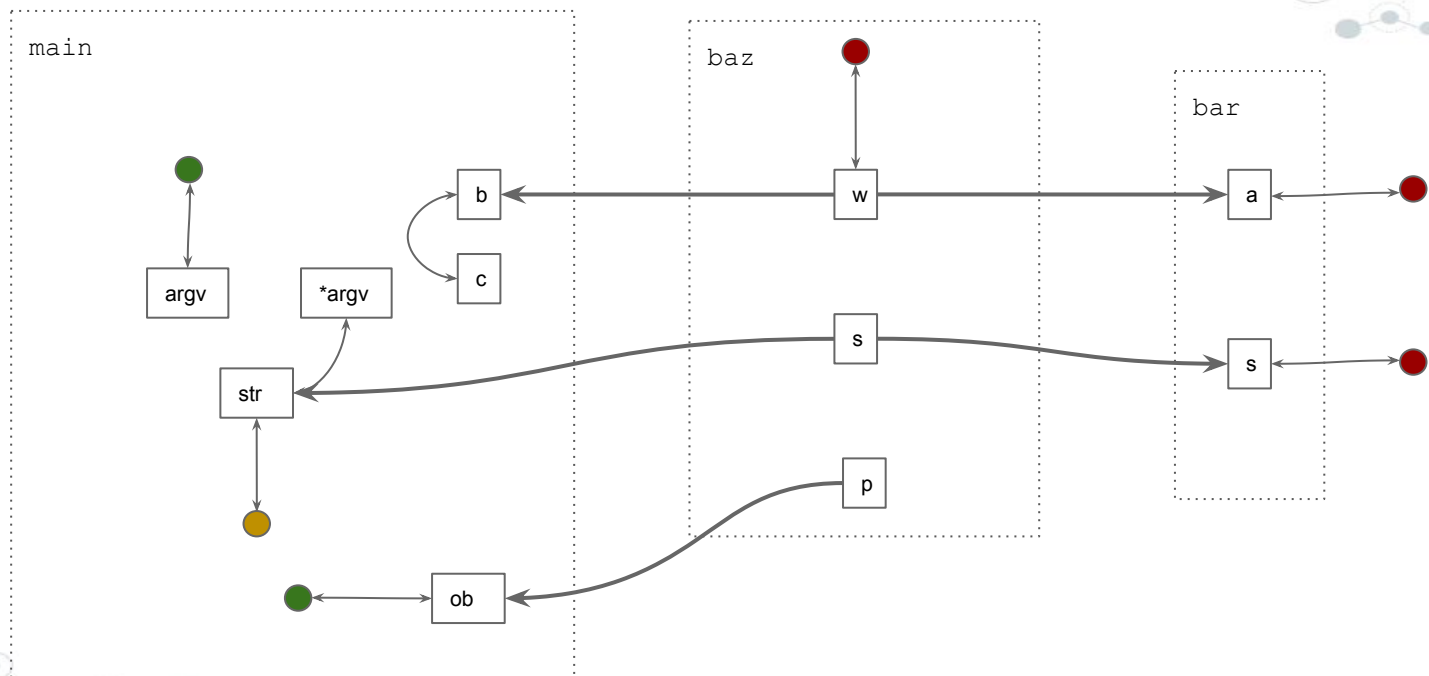
*Let us make the flow-directional  
across caller-callee boundaries  
- **Function Subtyping***

## Function Subtyping

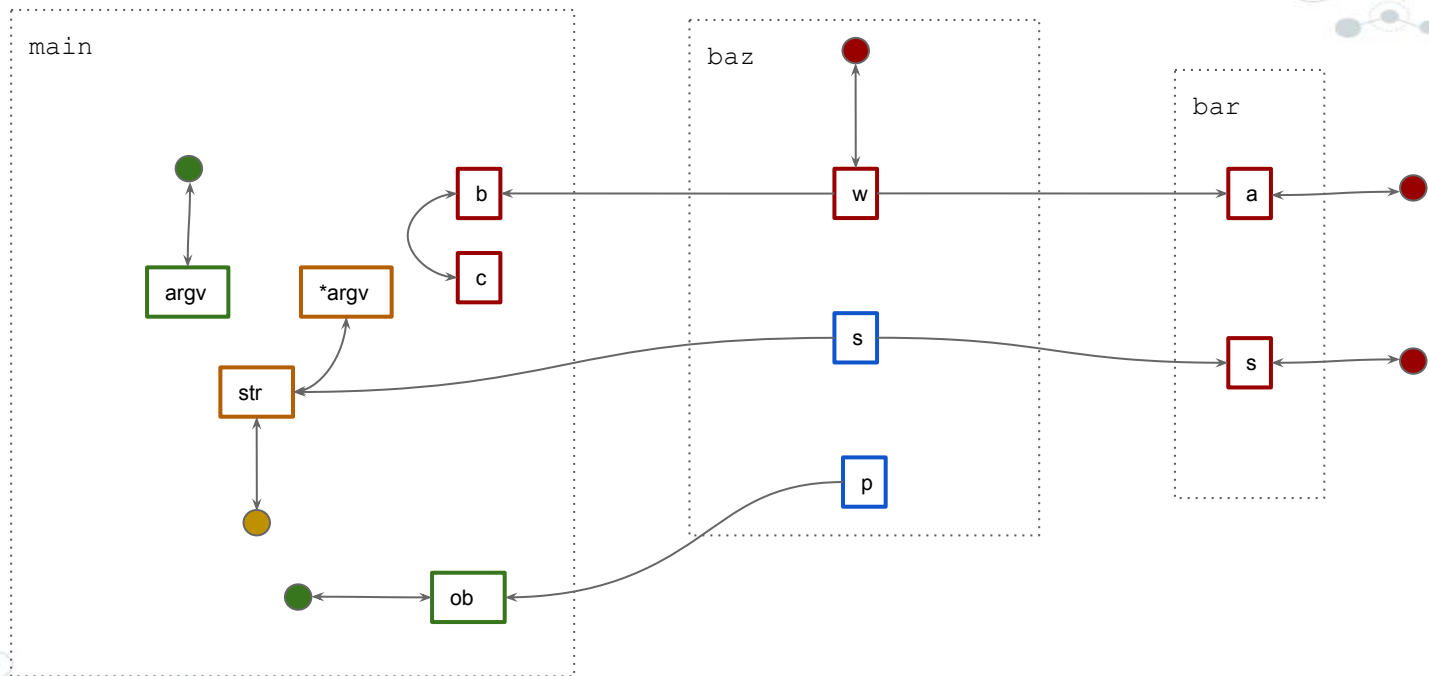
---

- Covariant: Argument type should be a subtype of corresponding parameter type
- [Reverse of above] Contra-variant: Return type should be a subtype of the type to which we assign

# Constraint Graph - Directional Caller-Callee Edges



## Constraint Graph Solution - Directional Caller-Callee Edges



# Conversion with Directional Caller-Callee Edges

```
int main(int argc, _Array_ptr< Nt_array_ptr<char>>
argv) {
```

```
    int *b, *c;
```

```
    struct f ob_Checked[5];
```

```
    Nt_array_ptr<char> str = argv[0];
```

```
    b = &global;
```

```
    baz(b, str, ob);
```

```
    c = b;
```

```
    printf("%d", strlen(str));
```

```
    return 0;
```

```
int *efunc();
```

```
int global;
```

```
int baz(int *w, Ptr<char> s, Ptr<struct f> p) {
```

```
    ...
```

```
    w = (int*)0xdeadbeef;
```

```
    *s = p->ch;
```

```
    return 0;
```

```
}
```

```
int bar() {
```

```
    int *a = efunc();
```

```
    char *s = a;
```

```
    baz(a, s, NULL);
```

```
    return 0;
```

```
}
```

## Function Subtyping

A decorative network diagram in the top right corner of the slide. It consists of numerous small circles (nodes) connected by thin lines (edges). Some nodes are highlighted with a thicker border or a different fill color, and the overall structure is a complex, interconnected web.

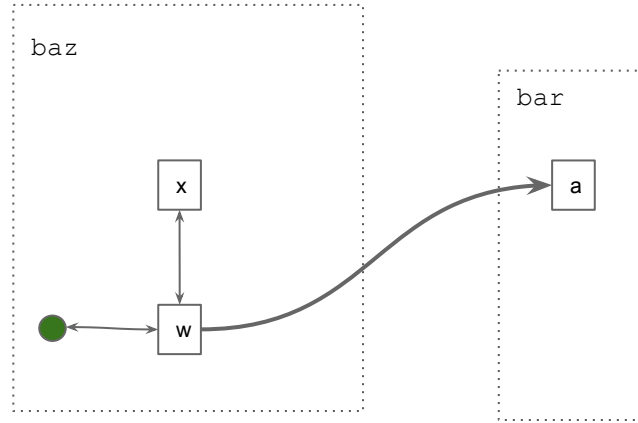
- Works for argument and parameter types
- Does not work for return types

# Valid Return Type : Example

```
void baz() {  
  
    int *x = NULL;  
  
    int *w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

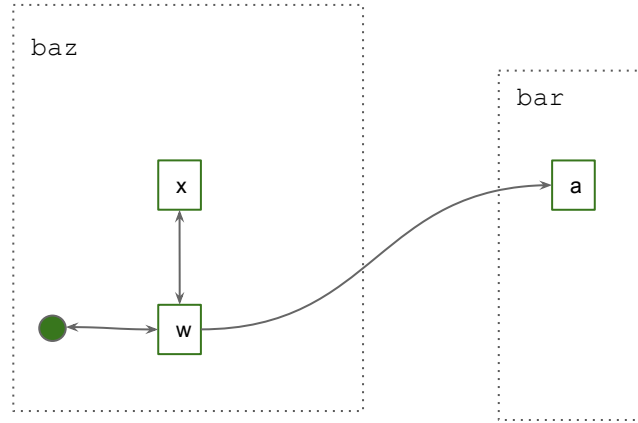
```
int *bar() {  
  
    int *a = malloc(5*sizeof(int));  
  
    return a;  
  
}
```

## Constraint Graph - Valid Return Type





## Constraint Graph Solution - Valid Return Type



## Conversion: Valid Return Type

```
void baz() {  
    _Array_ptr<int> x = NULL;  
  
    _Array_ptr<int> w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

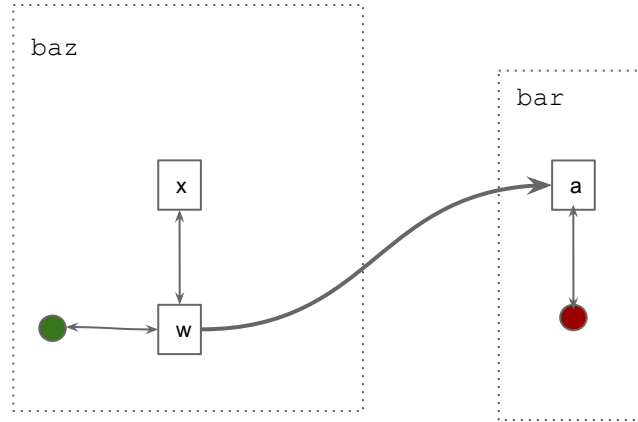
```
_Array_ptr<int> bar() {  
  
    int *a = malloc(5*sizeof(int));  
  
    return a;  
  
}
```

## Wrong Return Type : Example

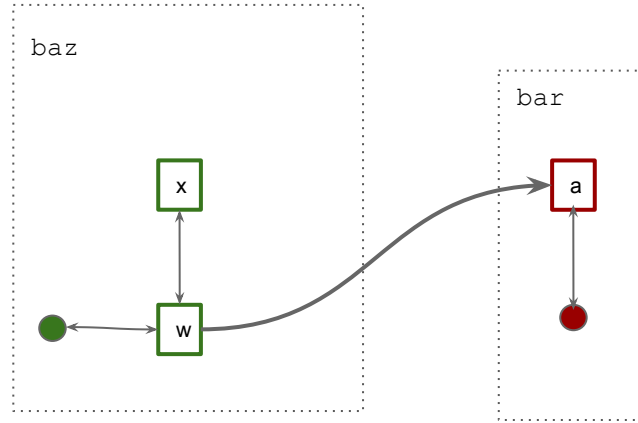
```
void baz() {  
  
    int *x = NULL;  
  
    int *w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

```
int *bar() {  
  
    int *a = (int *)0xdeadbeef;  
  
    return a;  
  
}
```

## Constraint Graph - Wrong Return Type



## Constraint Graph - Wrong Return Type



# Conversion : Imprecise Return Type

```
void baz() {  
    _Array_ptr<int> x = NULL;  
  
    _Array_ptr<int> w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

```
int *bar() {  
  
    int *a = (int *)0xdeadbeef;  
  
    return a;  
  
}
```

## Conversion : Imprecise Return Type

```
void baz() {
```

```
    _Array_ptr<int> x = NULL;
```

```
    _Array_ptr<int> w = bar();
```

```
    ...
```

```
    x = w;
```

```
    ...
```

```
    w[0] = 0;
```

```
}
```

```
int *bar() {
```

```
    int *a = (int *)0xdeadbeef;
```

```
    return a;
```

```
}
```

**This is wrong!** We are using WILD pointer as a Checked type i.e., **\_Array\_ptr**

## Function Subtyping : Return Type

- If the return type is a Checked Type :
  - Return type should be subtype of its callers
    - Regular Contra-Variant



# Valid Return Type : Example

```
void baz() {  
  
    int *x = NULL;  
  
    int *w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

```
int *bar() {  
  
    int *a = malloc(5*sizeof(int));  
  
    return a;  
  
}
```

## Function Subtyping : Return Type

- If the return type is a Checked Type :
  - Return type should be subtype of its callers
    - Regular Contra-Variant
- If the return type is **WILD**:
  - Then all the callers should use it as **WILD**
    - Reverse of Contra-Variant

## Wrong Return Type : Example

```
void baz() {  
  
    int *x = NULL;  
  
    int *w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

```
int *bar() {  
  
    int *a = (int *)0xdeadbeef;  
  
    return a;  
  
}
```

## Chicken And Egg Problem

- The direction of propagation depends on the inferred type of the pointer
- To infer types we need to perform propagation

## Split Types

- For each pointer, Create two type variables: (O, P)
  - O: Indicates whether the type is Checked or Wild
    - O : [C|W]
  - P: Indicates the Checked pointer type
    - P : [Ptr | Arr | NtArr]

**WILD** <: Checked

**\_Nt\_array\_ptr** <: **\_Array\_ptr** <: **\_Ptr**

## Constraint Graph

- P edges are introduced according to regular subtyping rules
- O edges follow regular subtyping rules except for return where the direction will be reversed

## Constraints Solving

- Solve O graph and P graph independently
- Merge solutions: For all pointers whose O variable is Checked, fetch the corresponding solution for P variable as the final type

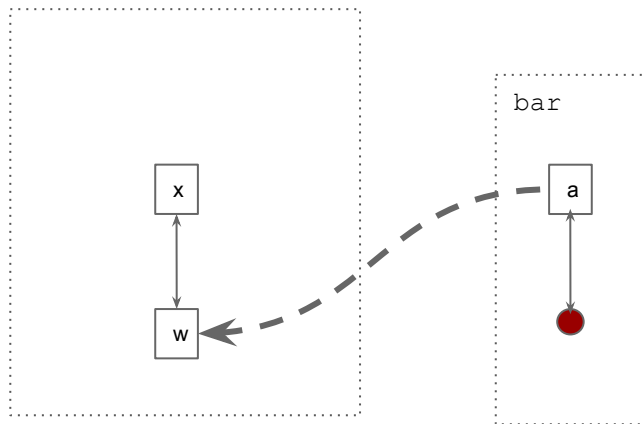
## Return Type : Example

```
void baz() {  
  
    int *x = NULL;  
  
    int *w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

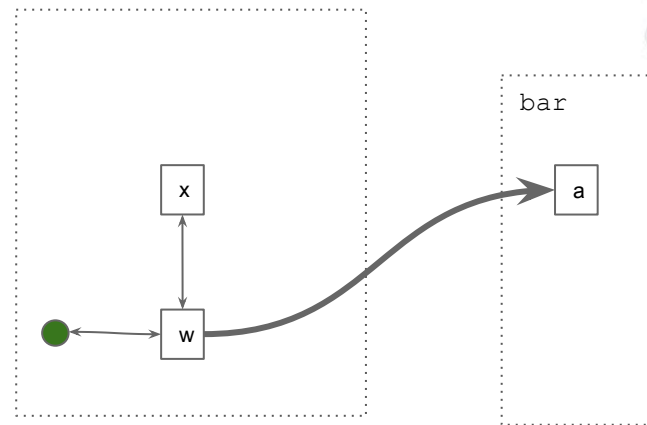
```
int *bar() {  
  
    int *a = (int *)0xdeadbeef;  
  
    return a;  
  
}
```



# Constraint Graph - (O, P) Graphs

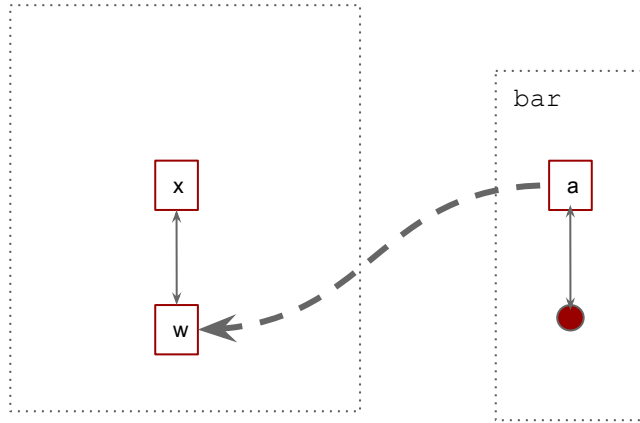


O Graph

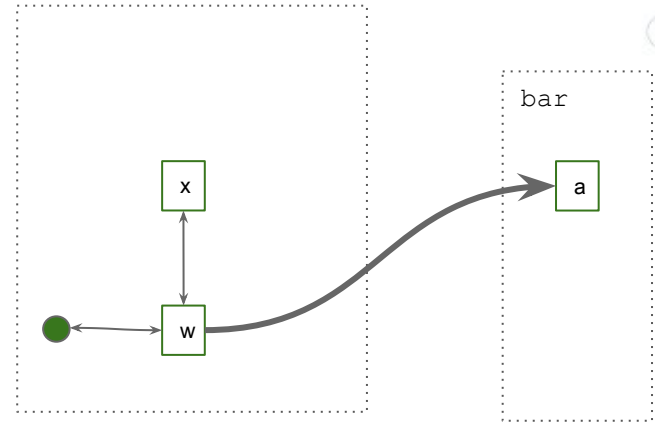


P Graph

## Constraint Graph - (O, P) Solution

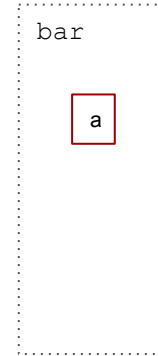
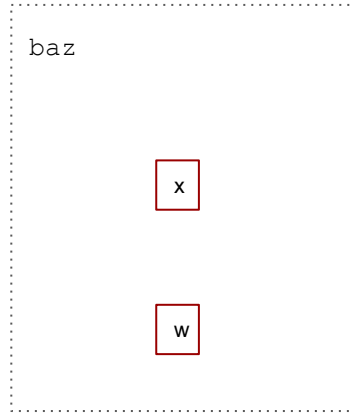


O Graph



P Graph

## Constraint Graph - Merged Solution



# Correctly Converted Return Type

```
void baz() {  
  
    int *x = NULL;  
  
    int *w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

```
int *bar() {  
  
    int *a = (int *)0xdeadbeef;  
  
    return a;  
  
}
```

## Conversion: Valid Return Type

```
void baz() {  
    _Array_ptr<int> x = NULL;  
  
    _Array_ptr<int> w = bar();  
  
    ...  
  
    x = w;  
  
    ...  
  
    w[0] = 0;  
  
}
```

```
_Array_ptr<int> bar() {  
  
    int *a = malloc(5*sizeof(int));  
  
    return a;  
  
}
```

# Inferring Array Bounds : Primer

// Static sized array

```
int arr_Checked[10]; // Bounds of arr are (arr, arr + 10 * sizeof(int))
```

// Dynamically allocated array

```
_Array_ptr<int> v : count(n) = malloc(n*sizeof(int)); // Bounds of v are (v, v + n*sizeof(int))
```

// Constant array

```
_Nt_array_ptr<const char> s : byte_count(6) = "hello"; // Bounds of s are (s, s + 6)
```

```
struct hash_table {
```

```
    unsigned buckets;
```

```
    unsigned idx;
```

```
    // Bounds of entries are (entries, entries + buckets * sizeof(struct hash *))
```

```
    _Array_ptr<_Ptr<struct hash>> entries : count(buckets);
```

```
}
```

## Array Bounds Inference

1. Infer Checked types
1. Insert seed bounds:
  - a. malloc, built-in annotations, control-dependencies
1. Propagate the bounds information

# Array Bounds Inference

```
struct foo {  
  
    int *y;  
  
    int l;  
  
};
```

```
void bar(int *x, int c) {  
  
    struct foo f = { x, c };  
  
    memset(x, 1, c);  
  
    x[0] = 0;  
  
}
```



# Array Bounds Inference : Type Inference

```
struct foo {  
  
    _Array_ptr<int> y;  
  
    int l;  
  
};
```

```
void bar(_Array_ptr<int> x, int c) {  
  
    struct foo f = { x, c };  
  
    memset(x, 1, c);  
  
    x[0] = 0;  
  
}
```

# Array Bounds Inference : Seed Bounds

```
struct foo {  
  
    _Array_ptr<int> y;  
  
    int l;  
  
};
```

```
void bar(_Array_ptr<int> x, int c) {  
  
    struct foo f = { x, c };  
  
    memset(x, 1, c); // bounds of x are byte_bound(c)  
  
    x[0] = 0;  
  
}
```

# Array Bounds Inference : Propagate Bounds

```
struct foo {  
  
    _Array_ptr<int> y;  
  
    int l;  
  
};
```

```
void bar(_Array_ptr<int> x, byte_count(c), int c) {  
  
    struct foo f = { x, c };  
  
    memset(x, 1, c);  
  
    x[0] = 0;  
  
}
```

# Array Bounds Inference : Propagate Bounds

```
struct foo {
```

```
    _Array_ptr<int> y;
```

```
    int l;
```

```
};
```

```
void bar(_Array_ptr<int> x, byte_count(c), int c) {
```

```
    struct foo f = { x, c };
```

```
    memset(x, 1, c);
```

```
    x[0] = 0;
```

```
}
```

# Array Bounds Inference : Propagate Bounds

```
struct foo {
```

```
    _Array_ptr<int> y : byte_count(1);
```

```
    int l;
```

```
};
```

```
void bar(_Array_ptr<int> x, byte_count(c), int c) {
```

```
    struct foo f = { x, c };
```

```
    memset(x, 1, c);
```

```
    x[0] = 0;
```

```
}
```

## Need For Interactivity

- Handling explicit but safe casting

## Need For Interactivity

- Handling explicit but safe casting

```
struct vsf_sysutil_dir* vsf_sysutil_opendir(const char* p_dirname) {  
  
    return (struct vsf_sysutil_dir*) opendir(p_dirname);  
  
}
```

## Need For Interactivity

- Handling explicit but safe casting
  - Example: 90 additional pointers can be converted to checked types with a 1 bit (yes/no) input from user



## Preliminary Evaluation : Dataset

Program	Category	Size	Total Pointers (Tot)
vsftpd	FTP Server	17K	2,020
anagram	Pointer Benchmarks	352	72
ft		115	209
ks		609	79
yacr2		2,915	109
<b>Total</b>		<b>22K</b>	<b>2,486</b>

# Preliminary Evaluation : Conversion

Program	Total Pointers (Tot)	Regular Pointers PTR	Array Pointers					Unconverted (WILD) (% over Tot)	Directly UnConverted (% over Tot)
			ARR	NTARR	Constant Size	Need Bounds (nb)	Inferred Bounds (% over nb)		
vsftpd	2,020	1,114	23	35	39	19	7 (36.84%)	848 (41.98%)	<b>189 (9.35%)</b>
anagram	72	23	21	2	15	7	1 (14.29%)	26 (36.11%)	<b>8 (11.11%)</b>
ft	209	115	8	0	6	2	0 (0%)	86 (41.15%)	<b>5 (2.39%)</b>
ks	79	15	8	5	11	4	0 (0%)	48 (63.16%)	<b>1 (1.32%)</b>
yacr2	109	12	82	0	77	5	2 (40%)	15 (13.76%)	<b>4 (3.67%)</b>
Total	2,486	1,279	142	42	148	37	10 (27.03)	1,023 (41.15%)	207 (8.33%)

## Rewriting Challenges

A decorative network diagram in the top right corner of the slide. It consists of numerous circular nodes of varying sizes, some of which are highlighted with a double outline. These nodes are interconnected by a web of thin, light gray lines, creating a complex, organic structure that resembles a molecular or neural network.

- Rewriting C code is hard
  - Typedefs
  - Preprocessor directives

# Infeasibility of Automated Conversion

```
int resize_buf(char **buf, unsigned *sz) {  
    char *newbuf = NULL;  
    unsigned news = round_up(*sz, 64);  
    newbuf = realloc(buf, news);  
    *buf = newbuf;  
    *sz = news;  
    return newbuf != NULL;  
}
```



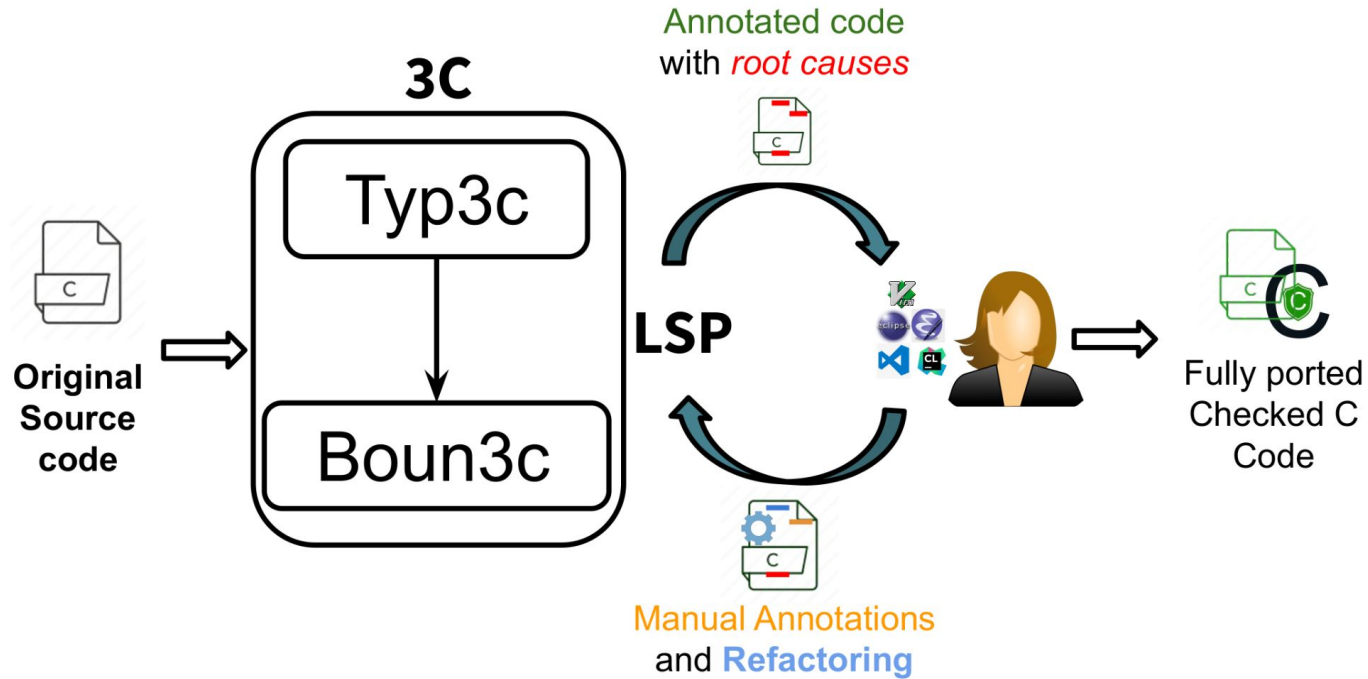
```
typedef struct {  
    array_ptr<char> buf : count(sz);  
    unsigned sz;  
} SIZEBUF;
```

```
int resize_buf(ptr<SIZEBUF> buf) _Checked {  
    unsigned news = round_up(buf->sz, 64);  
    array_ptr<char> newbuf : count(news) = NULL;  
    newbuf = realloc<char>(buf->buf, news);  
    buf->buf = newbuf;  
    buf->sz = news;  
    return newbuf != NULL;  
}
```

*// Refactor all callers of resize\_buf to  
// use the new caller.*



## 3C : Interactive Conversion to Checked C





# Status

- C to Checked C (3C) : well-maintained open source project  
<https://github.com/correctcomputation/checkedc-clang>
- Supported by Microsoft.