

Descriptive Complexity

Space-Based Complexity

Definition (class DSPACE): Let $T : \mathbb{N} \rightarrow \mathbb{N}$ be some function. A language L is in $\mathbf{DSPACE}(T(n))$ iff there is a Turing machine that uses $O(T(n))$ cells of the tape and decides L .

Definition (class NSPACE): Similarly defined using NDTM.

$$\mathbf{PSPACE} = \bigcup_{c \geq 1} \mathbf{DSPACE}(n^c)$$

Savitch' Theorem (1970):

$$\mathbf{PSPACE} = \bigcup_{c \geq 1} \mathbf{NSPACE}(n^c)$$

Similar Definitions:

- $\mathbf{DLOGSPACE}$, $\mathbf{NLOGSPACE}$





Polynomial Hierarchy

Definition (class PH): Languages in **PH** are those accepted, in polynomial time, by a NTDM can make “calls” to other similar machines.



The Complexity Zoo

Exponential classes

- **EXPTIME** = $\bigcup_{c \geq 1} \mathbf{DTIME}(2^{n^c})$
- **NEXPTIME** = $\bigcup_{c \geq 1} \mathbf{NTIME}(2^{n^c})$
- **EXPSPACE** = $\bigcup_{c \geq 1} \mathbf{DSpace}(2^{n^c})$

What do we know?

$$\mathbf{DLOGSPACE} \subseteq \mathbf{NLOGSPACE} \subseteq \mathbf{P} \subseteq \left\{ \begin{array}{c} \mathbf{NP} \\ \mathbf{coNP} \end{array} \right\} \subseteq \mathbf{PH} \subseteq \mathbf{PSPACE} \\ \subseteq \mathbf{EXPTIME} \subseteq \mathbf{NEXPTIME} \subseteq \mathbf{EXPSPACE}$$

Proper subsets?

- All we know is $\mathbf{NLOGSPACE} \subsetneq \mathbf{PSPACE} \subsetneq \mathbf{EXPSPACE}$, $\mathbf{P} \subsetneq \mathbf{EXPTIME}$, $\mathbf{NP} \subsetneq \mathbf{NEXPTIME}$

Logic vs. Complexity

Problem	Logical characterization	Complexity
GCD test	$\begin{aligned} &\exists p, q (p \cdot z = x \wedge q \cdot z = y) \\ &\vee \neg \exists z', p', q' (z' > z \wedge p' \cdot z' = x \wedge q' \cdot z' = y) \end{aligned}$	LOGSPACE
Graph Connectivity	$\forall x \forall y (x \neq y \rightarrow \mathbf{TC}(E)(x, y))$	P
Graph Hamiltonicity	$\exists L \exists S \left(\begin{array}{l} \text{linearOrder}(L) \\ \wedge \text{"}S \text{ is the successor relation of } L\text{"} \\ \wedge \forall x \exists y (L(x, y) \vee L(y, x)) \\ \wedge \forall x \forall y (S(x, y) \rightarrow E(x, y)) \end{array} \right)$	NP-complete

Logic vs. Complexity

Definition: A logic \mathcal{L} **captures** a complexity class \mathcal{K} if:

- The data complexity of \mathcal{L} is \mathcal{K} : that is, for every \mathcal{L} -sentence Φ , deciding if $\mathcal{A} \models \Phi$ for a *finite structure* \mathcal{A} is in \mathcal{K} .
- For every property \mathcal{P} that can be decided with complexity \mathcal{K} , there is a sentence $\Phi_{\mathcal{P}}$ of \mathcal{L} such that $\mathcal{A} \models \Phi_{\mathcal{P}}$ iff \mathcal{A} has the property \mathcal{P} , for every finite structure \mathcal{A} .

$\exists SO = NP$

Fagin's Theorem (1973): $\exists SO$ captures **NP**.

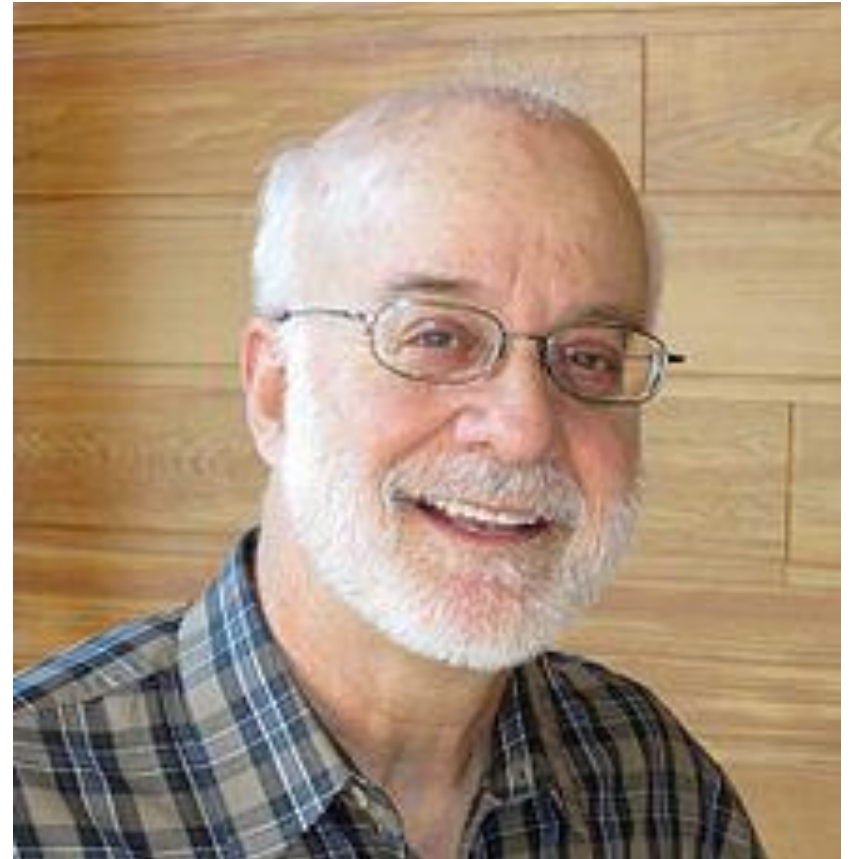
($\exists SO$ consists of SO sentences of the form $\exists X_1 \dots \exists X_n \varphi$ where φ is a FO formula with X_1, \dots, X_n)

To show a problem is in **NP**, it suffices to write a $\exists SO$ sentence capturing the desired property! (e.g., Graph Hamiltonicity)

Corollary: $\forall SO$ captures **coNP**.

Open problem: $\exists SO \neq \forall SO$ over finite structures?

($\exists SO \neq \forall SO \Rightarrow NP \neq coNP \Rightarrow P \neq NP$)



$\exists SO = NP$

Corollary (Cook-Levin Theorem): The satisfiability problem for propositional logic is **NP** - complete.

Proof: Let \mathcal{P} be a problem in **NP**. Then by Fagin's theorem, there is a $\exists SO$ sentence $\Phi \equiv \exists S_1 \dots \exists S_n \varphi$ such that $\mathcal{A} \models \Phi$ iff \mathcal{A} is in \mathcal{P} .

Now to check $\mathcal{A} \models \Phi$, we can construct a propositional formula from Φ :

- \mathcal{A} is finite! (with universe A)
- Replace $\exists x(\dots x \dots)$ with $\bigvee_{a \in A}(\dots a \dots)$
- Replace $\forall x(\dots x \dots)$ with $\bigwedge_{a \in A}(\dots a \dots)$
- Replace every $a \in S_i$ with a proposition " $a_in_S_i$ "
- Everything else can be evaluated to true or false on \mathcal{A}

$\exists SO = NP$

Proof idea:

- $\exists SO \subseteq NP$: Suppose $\Phi = \exists X_1 \dots \exists X_n \varphi$. Given \mathcal{A} , the NTDM first guesses S_1, \dots, S_n as the certificate and checks if $\varphi(S_1, \dots, S_n)$ holds, which can be done in polynomial time.
- $NP \subseteq \exists SO$: Yet another encoding of Turing machine, but more challenging!
 - NDTM now, and for arbitrarily long input
 - Solution: explicitly encode the tape as a SO relation L
 - Time and position are bounded by n^k so can be encoded as a k -tuple!



A Logic for P ?



$NP = \exists SO, coNP = \forall SO, P = ?$

Gurevich's Conjecture: There is no logic that captures P .

- If true, then $P \neq NP$!

Some logics do capture P on
ordered structures

$FO(LFP) = P$ on ordered structures

Immerman-Vardi Theorem (1982): $FO(LFP) + <$ captures P .

$FO(LFP)$ extends FO with an **lfp** operator

- For every monotone operator F , the sequence $\emptyset, F(\emptyset), F^2(\emptyset), \dots$ stabilizes at the least fixed point, denoted by **lfp**(F)
- E.g., if $F(S) = \{x \mid \forall y (E(y, x) \rightarrow y \in S)\}$, then $\forall u. [\mathbf{lfp} F](u)$ says a graph is acyclic

$<$ is a linear order of the structure

More results for ordered structures

$FO(PFP) + <$ captures **PSPACE**

- Partial fixed point: $\mathbf{pfp} F \triangleq \begin{cases} F^\infty(\emptyset) & \text{if the sequence stabilizes} \\ \emptyset & \text{otherwise} \end{cases}$

$FO(TC) + <$ captures **NLOGSPACE**

- Transitive closure (TC) is a special LFP

$FO(DTC) + <$ captures **LOGSPACE**

- Deterministic transitive closure (e.g., TC applied on the successor relation)

$SO + <$ captures **PH**