

# Depth-First Search

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Adapted from the CLRS book slides

# DEPTH-FIRST SEARCH

**Input:**  $G = (V, E)$ , directed or undirected. No source vertex given.

**Output:**

- 2 *timesteps* on each vertex:

- $v.d = \text{discovery time}$
- $v.f = \text{finish time}$

These will be useful for other algorithms later on.

- $v.\pi$  is  $v$ 's predecessor in the *depth-first forest* of  $\geq 1$  *depth-first trees*.  
If  $u = v.\pi$ , then  $(u, v)$  is a *tree edge*.

# DEPTH-FIRST SEARCH (continued)

Methodically explores *every* edge.

- Start over from different vertices as necessary.

As soon as a vertex is discovered, explore from it.

- Unlike BFS, which puts a vertex on a queue so that it's explored from later.

As DFS progresses, every vertex has a ***color***:

- WHITE = undiscovered
- GRAY = discovered, but not finished (not done exploring from it)
- BLACK = finished (have found everything reachable from it)

Discovery and finish times:

- Unique integers from 1 to  $2|V|$ .
- For all  $v$ ,  $v.d < v.f$ .

In other words,  $1 \leq v.d < v.f \leq 2|V|$ .

# PSEUDOCODE

Global search starts a local search on each vertex to explore entire graph.

$\text{DFS}(G)$

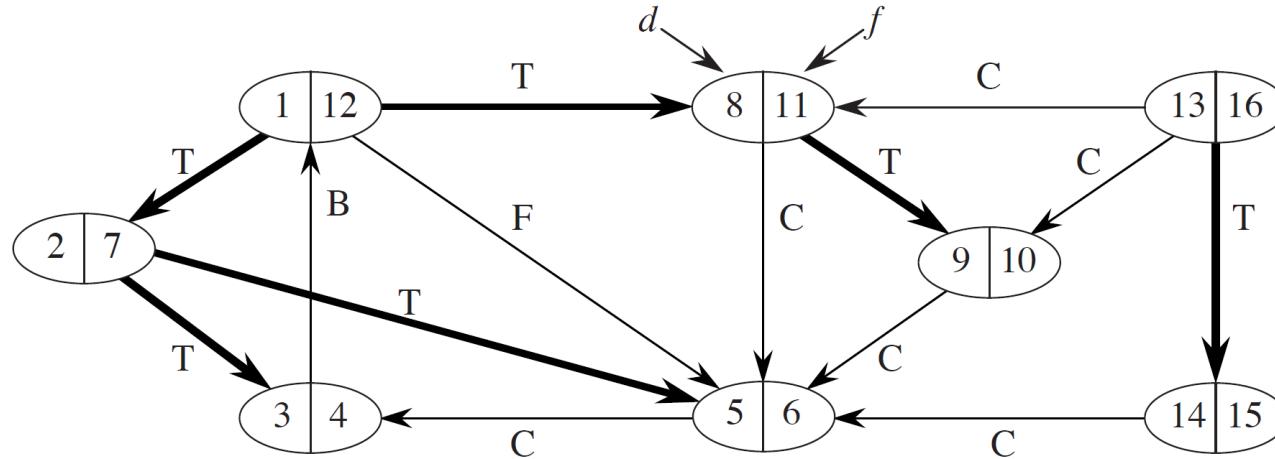
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1  for each vertex  $u \in G.V$ 
2       $u.\text{color} = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4       $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.\text{color} == \text{WHITE}$ 
7           $\text{DFS-VISIT}(G, u)$ 
```

# PSEUDOCODE (continued)

DFS-VISIT( $G, u$ )

```
1  time = time + 1          // white vertex  $u$  has just been discovered
2   $u.d$  = time
3   $u.color$  = GRAY
4  for each vertex  $v$  in  $G.Adj[u]$  // explore each edge  $(u, v)$ 
5    if  $v.color == \text{WHITE}$ 
6       $v.\pi$  =  $u$ 
7      DFS-VISIT( $G, v$ )
8  time = time + 1
9   $u.f$  = time
10  $u.color$  = BLACK           // blacken  $u$ ; it is finished
```

# EXAMPLE



$$\text{Time} = \Theta(V + E).$$

- Similar to BFS analysis.
- $\Theta$ , not just  $O$ , since guaranteed to examine every vertex and edge.

Each depth-first tree is made of edges  $(u, v)$  such that  $u$  is gray and  $v$  is white when  $(u, v)$  is explored.



## CLASSIFICATION OF EDGES

- ***Tree edge:*** in the depth-first forest. Found by exploring  $(u, v)$ .
- ***Back edge:***  $(u, v)$ , where  $u$  is a descendant of  $v$ .
- ***Forward edge:***  $(u, v)$ , where  $v$  is a descendant of  $u$ , but not a tree edge.
- ***Cross edge:*** any other edge. Can go between vertices in same depth-first tree or in different depth-first trees.

In an undirected graph, there may be some ambiguity since  $(u, v)$  and  $(v, u)$  are the same edge. Classify by the first type above that matches.

## THEOREM (PARENTHESIS THEOREM)

For all  $u, v$ , exactly one of the following holds:

1.  $u.d < u.f < v.d < v.f$  or  $v.d < v.f < u.d < u.f$  (i.e., the intervals  $[u.d, u.f]$  and  $[v.d, v.f]$  are disjoint) and neither of  $u$  and  $v$  is a descendant of the other.
2.  $u.d < v.d < v.f < u.f$  and  $v$  is a descendant of  $u$ . ( $v$  is discovered after and finished before  $u$ .)
3.  $v.d < u.d < u.f < v.f$  and  $u$  is a descendant of  $v$ . ( $u$  is discovered after and finished before  $v$ .)

So  $u.d < v.d < u.f < v.f$  ( $v$  is both discovered and finished after  $u$ ) *cannot* happen.