

# DAPPER: Data Assimilation with Python: a Package for Experimental Research

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## Software

- [Review](#)
- [Repository](#)
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## Summary

Data assimilation (DA) is the science of optimally combining sparse data and computational models, both of which are typically large and varied. Based on classical statistics, signal processing, and control systems theory, and increasingly, machine learning, DA was primarily developed in weather, climate, and oceanographic forecasting but is presently used all across the geosciences and beyond. DAPPER is a set of templates for benchmarking the performance of DA methods.

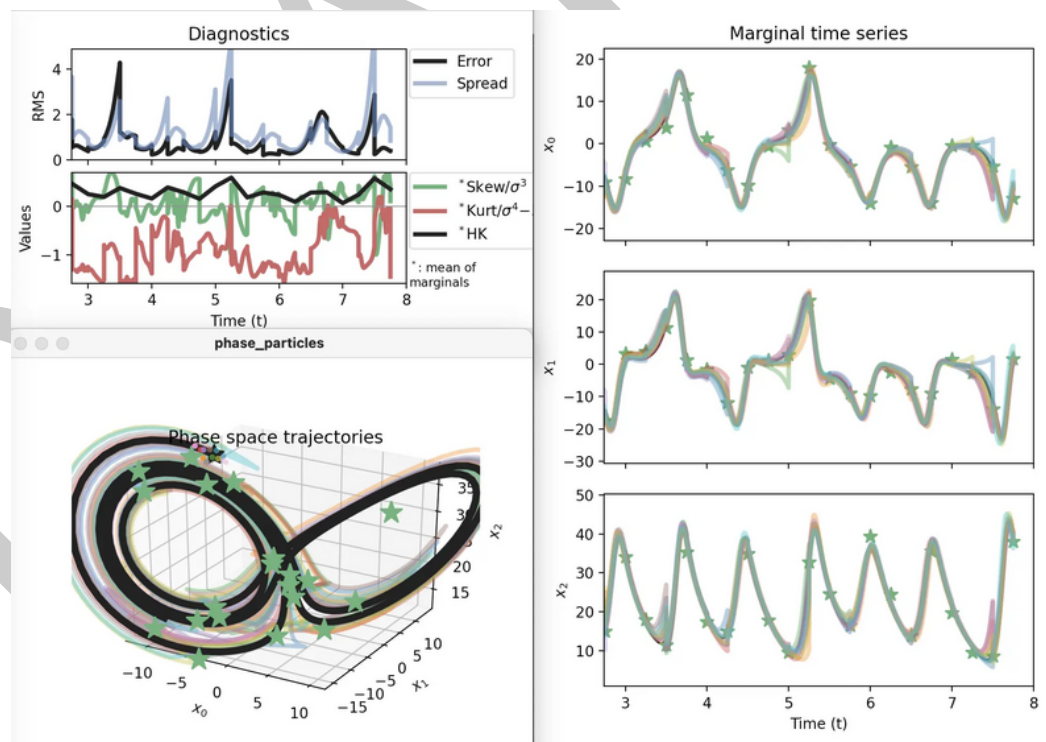


Figure 1: Screenshot from “liveplotting” in DAPPER

## Statement of need

DAPPER provides experimental support and guidance for new developments in DA by facilitating numerical investigations through a variety of typical test cases and statistics. It reproduces numerical benchmarks results reported in the literature and facilitates comparative studies, thus promoting the reliability and relevance of the results. DAPPER is open source, written in Python, and focuses on readability; this promotes the reproduction and dissemination of the underlying science, and makes it easy to adapt and extend.

## State of the field

The README contains a comprehensive list of related projects. Among projects aimed at research and teaching, DAPPER is probably the most mature, while it is small in size and complexity compared to those targeting real-world applications, such as [DART](#), [PDAF](#), [JEDI](#), and [OpenDA](#). The README also lists 5 publications (to date) that used DAPPER, and those results published in the literature that have been reproduced with DAPPER, of which we mention ([Anderson, 2010](#); [Asch et al., 2016](#); [Bocquet & Sakov, 2014](#)).

## Outlook

The intention is for DAPPER to continue benchmarking and illustrating the latest methods in DA and beyond. For example, at the time of writing, there are 26 open tickets in the repository's issue tracker. Most have been opened by the principal investigator, and are tagged with *enhancement*. These are not necessarily minor, and have mainly been filed under the v2 milestone.

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Bocquet, M., & Sakov, P. (2014). An iterative ensemble Kalman smoother. *Quarterly Journal of the Royal Meteorological Society*, 140(682), 1521–1535. <https://doi.org/10.1002/qj.2236>