











1 *hp*3D: A Scalable MPI/OpenMP *hp*-Adaptive Finite 2 Element Software Library for Complex Multiphysics 3 Applications

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9 Summary

10 The *hp*3D finite element (FE) library is a tool for computational modeling of engineering
11 applications. The library provides a framework for discretization of three-dimensional¹ multi-
12 physics problems described by systems of partial differential equations. *hp*3D can be compiled
13 in real or complex mode to accommodate the need for real- or complex-valued physics vari-
14 ables, respectively. The library is written entirely in Fortran; user applications interfacing
15 with the library are also written in Fortran. The *hp*3D software can be installed and runs
16 efficiently on various CPU-based compute architectures, from laptops and single workstations
17 to state-of-the-art supercomputers.

18 Statement of need

19 *hp*3D combines a list of unique features and algorithms setting it apart from other publicly
20 available finite element libraries. The software supports hybrid meshes combining elements of
21 “all shapes:” hexahedra, tetrahedra, prisms, and pyramids. The internal Geometric Modeling
22 Package (GMP) provides support for *exact geometry* elements and *isoparametric* elements.
23 Exact geometry elements directly use the parametrizations provided by GMP resulting in
24 computations with no geometry error; isoparametric elements approximate the geometry maps
25 with polynomials spanning the element space of shape functions. *hp*3D’s shape functions
26 package provides compatible discretization of energy spaces forming the $H^1 - H(\text{curl}) -$
27 $H(\text{div}) - L^2$ exact sequence ([Demkowicz, 2023](#); [Fuentes et al., 2015](#)). Additionally, the *hp*3D
28 FE code sets itself apart from other advanced FE libraries (e.g., MFEM ([Anderson et al.,](#)
29 [2021](#)) or deal.II ([Bangerth et al., 2007](#))) by supporting *hp-adaptive* solutions with *anisotropic*
30 *refinements* in both element size h and polynomial order p . Such *hp-adaptive* methods are
31 the most efficient way to converge to difficult solutions, e.g., resolving solutions with boundary
32 layers, adapting toward geometric singularities, etc. ([Chakraborty et al., 2023](#)). *hp*3D features
33 a number of unique algorithms, including *constrained approximation* routines for assembling
34 elements with hanging nodes ([Demkowicz et al., 1989](#); [Oden et al., 1989](#); [Rachowicz et al.,](#)
35 [1989](#)), and *projection-based interpolation* for computation of nodal constraints ([Demkowicz,](#)
36 [2008](#)). Besides discretization with the standard Bubnov-Galerkin FE method, the *hp*3D library
37 also supports discretization with the discontinuous Petrov-Galerkin (DPG) method ([Demkowicz](#)
38 [& Gopalakrishnan, 2017](#)). The *hp*3D software leverages hybrid MPI/OpenMP parallelism to
39 run efficiently on large-scale computing facilities ([Badger et al., 2023](#); [Henneking, 2021](#)).

¹The *hp*2D FE library for two-dimensional problems is conceptually equivalent to *hp*3D but has not yet been released publicly.

Dependencies

hp3D interfaces with several well-established third-party libraries: for mesh partitioning (ParMETIS (Karypis & Kumar, 1998), PT-Scotch (Chevalier & Pellegrini, 2008)), for dynamic load balancing (Zoltan (Devine et al., 2002)), for linear solvers (MUMPS (Amestoy et al., 2001), PETSc (Balay et al., 2020)), and for I/O (pHDF5 (The HDF Group, 1997)). We note that all of these dependencies can be directly installed via PETSc. Additionally, the geometry mesh and the solution can be exported to VTK and visualized with ParaView (Ahrens et al., 2005).

Examples of applications

Some examples of 3D applications that have been implemented in *hp3D* include modeling of acoustic wave propagation in the human head (Gatto, 2012), modeling of electromagnetic waves with thermal effects in the human head (Kim, 2013), electromagnetic and acoustic scattering and high-frequency beams (Petrides, 2019; Petrides & Demkowicz, 2021), modeling of insulators in high-energy density electric motors (thermo-viscoelasticity) (Fuentes et al., 2017), and modeling of optical amplifiers (nonlinear Maxwell equations coupled with the heat equation) (Henneking et al., 2022, 2021; Nagaraj et al., 2019).

Further reading

Instructions on installing and using the code are available in the *hp3D* user manual (Henneking & Demkowicz, 2022). *hp3D*'s underlying algorithms are described in various published articles and books. Many parts of the current version of the *hp3D* software are based on the algorithms described in the two-volume *hp* book series (Demkowicz, 2006; Demkowicz et al., 2007) on the former 2D and 3D versions of the code (which were not published as open-source libraries). A third *hp* book volume detailing the additions and modifications of the newest version, including its MPI/OpenMP parallel algorithms, will be published soon (Henneking et al., 2023). The orientation-embedded shape functions package is described in (Fuentes et al., 2015). Details on the FE methodology and conforming discretization of exact-sequence elements are given in (Demkowicz, 2023).

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