Machine Learning

in 2018... Deep Learning!

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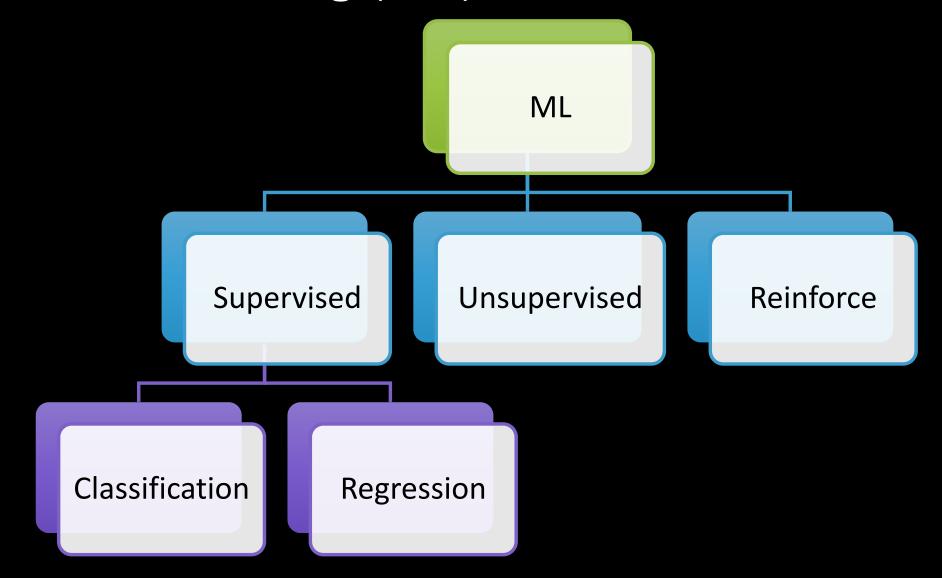


ALF

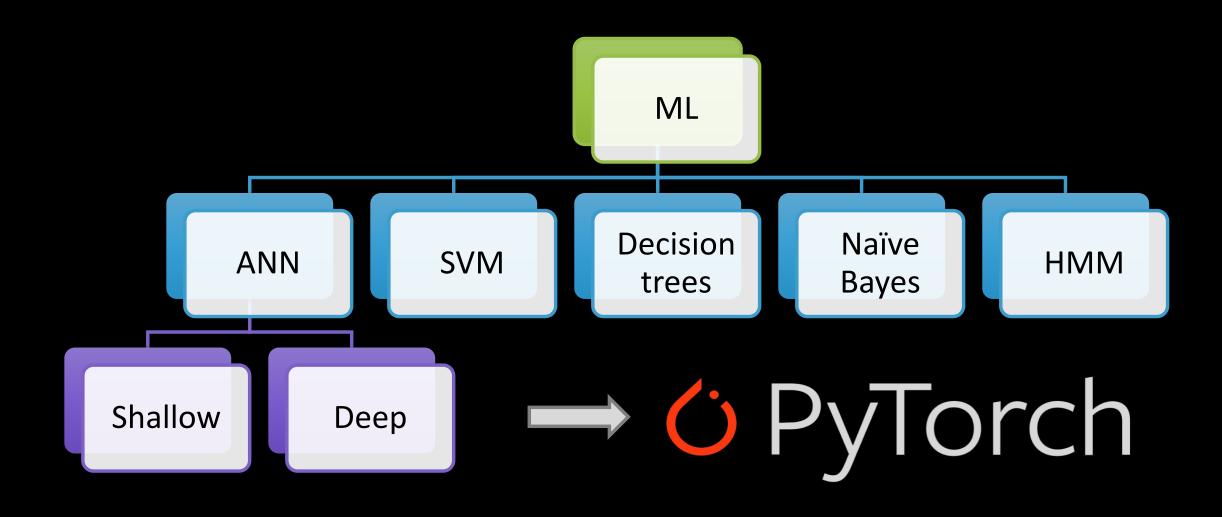
Taxonomy of ML

Learning paradigms and algorithms

Machine Learning (ML)

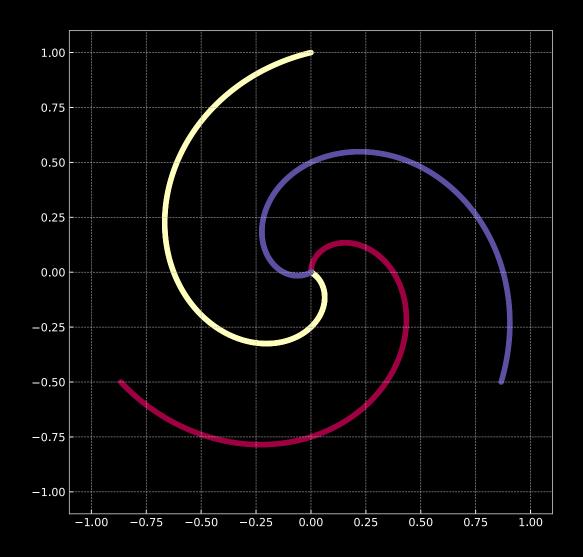


ML algorithms



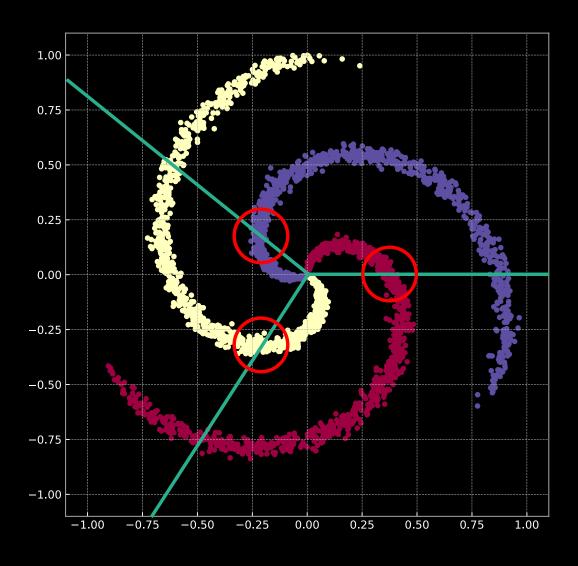
ANN – supervised learning

Classification

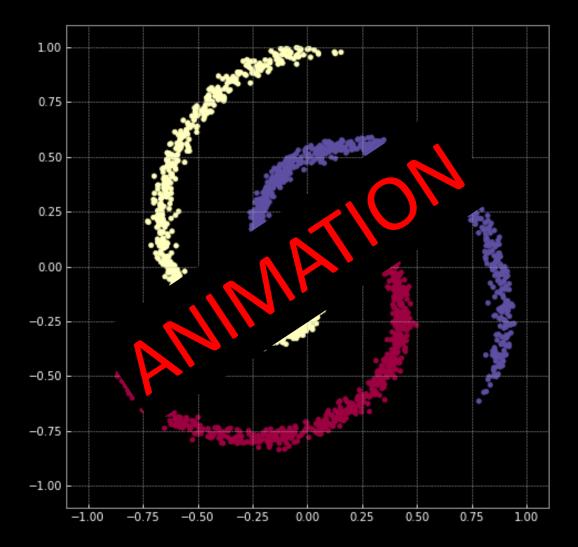


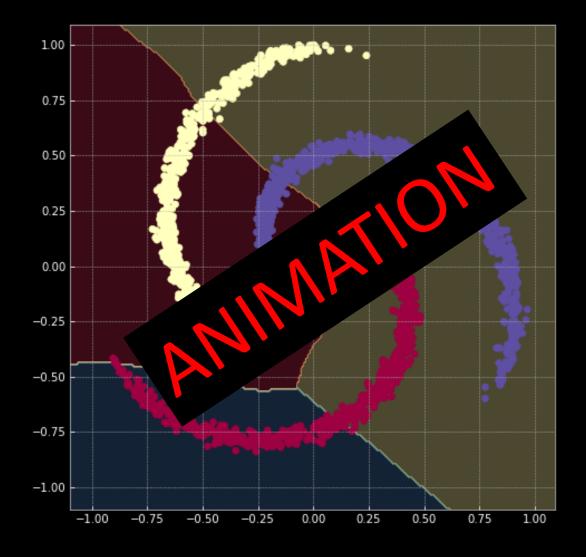
$$X_c(t) = t \begin{pmatrix} \sin\left(\frac{2\pi}{C}\left(2t + c - 1\right)\right) \\ \cos\left(\frac{2\pi}{C}\left(2t + c - 1\right)\right) \end{pmatrix}$$

$$0 \le t \le 1, \quad c = 1, \dots, C$$



$$X_c(t) = t \begin{pmatrix} \sin\left(\frac{2\pi}{C}\left(2t + c - 1\right)\right) \\ \cos\left(\frac{2\pi}{C}\left(2t + c - 1\right)\right) \\ + \mathcal{N}(0, \sigma^2) \end{pmatrix}$$





Training data

$$X = \begin{bmatrix} \frac{2}{2} \\ \frac{2}{2} \\ \frac{2}{2} \end{bmatrix}$$

$$Y = \begin{bmatrix} \frac{2}{2} \\ \frac{2}{2} \\ \frac{2}{2} \end{bmatrix}$$

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$$x^{(i)} \in \mathbb{R}^n$$
, $n=2$ $y^{(i)} \in \mathbb{R}^q$, $C=3$ $m: \# samples in data set$

$$(y^{(i)}) \in \mathbb{R}^{G}$$
, $C = 3$

$$c_i \in \{1,...,G\} \subseteq \mathbb{N}^+$$

Neural network (inference)

$$\hat{\boldsymbol{y}} \in \mathbb{R}^{C=3}$$

$$\boldsymbol{h} = f(\boldsymbol{W_h}\boldsymbol{x} + \boldsymbol{b_h})$$

$$\hat{\boldsymbol{y}} = g(\boldsymbol{W_y}\boldsymbol{h} + \boldsymbol{b_y})$$

$$\boldsymbol{b_h} \in \mathbb{R}^d$$

$$\boldsymbol{b_y} \in \mathbb{R}^C \times d$$

$$\boldsymbol{b_y} \in \mathbb{R}^C$$

$$\boldsymbol{h} \in \mathbb{R}^{d=100}$$

$$f(\cdot), g(\cdot) : \text{ReLU}(\cdot) \doteq (\cdot)^+, \sigma(\cdot), \text{tanh}(\cdot), \text{softmax}(\cdot)$$

$$\hat{\boldsymbol{y}} = \hat{\boldsymbol{y}}(\boldsymbol{x}), \quad \hat{\boldsymbol{y}} : \mathbb{R}^n \to \mathbb{R}^C, \quad \boldsymbol{x} \mapsto \hat{\boldsymbol{y}}$$

$$\hat{\boldsymbol{y}} \in \mathbb{R}^{n=2}$$

$$\hat{\boldsymbol{y}} : \mathbb{R}^n \to \mathbb{R}^d \to \mathbb{R}^C, \quad d \gg n, C$$

Neural network (training I)

 $h = f(W_h x + b_h)$ $\hat{y} = g(W_y h + b_y)$

logits: output of final layer

$$\operatorname{softmax}(\boldsymbol{l})[c] \doteq \frac{\exp(\boldsymbol{l}[c])}{\sum_{j=1}^{C} \exp(\boldsymbol{l}[j])} \in (0,1)$$

$$\mathcal{L}(\hat{m{Y}}, m{c}) \doteq \frac{1}{m} \sum_{i=1}^{m} \ell(\hat{m{y}}^{(i)}, c^{(i)}), \quad \ell(\hat{m{y}}, c) \doteq -\log(\hat{m{y}}[c]) \leftarrow \frac{\text{cross entropy / negative log-likelihood}}{m}$$

$$\frac{2}{3}\left(\frac{2}{3}\right) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0$$

Neural network (training II)

$$\mathbf{h} = f(\mathbf{W_h}\mathbf{x} + \mathbf{b_h})$$

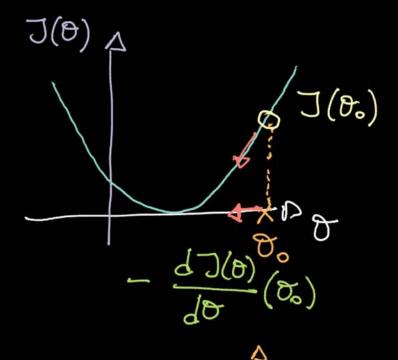
 $\hat{\mathbf{y}} = g(\mathbf{W_y}\mathbf{h} + \mathbf{b_y})$

$$\Theta \equiv \{W_h, \boldsymbol{b}_h, W_y, \boldsymbol{b}_y\}$$

$$J(\Theta) \equiv \mathcal{L}(\hat{Y}(\Theta), \underline{c}) \in \mathbb{R}^{+}$$

$$\frac{\partial J(\Theta)}{\partial W_y} = \frac{\partial J(\Theta)}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial W_y}$$

$$\frac{\partial J(\Theta)}{\partial W_h} = \frac{\partial J(\Theta)}{\partial \hat{g}} \frac{\partial \hat{g}}{\partial h} \frac{\partial \hat{h}}{\partial w_h}$$



Back propagation

aradiant descent

Gradient computation example

x = torch.tensor([[1, 2], [3, 4]], requires_grad=True)

y = x - 2

z = y * y * 3

out = z.mean()

$$2 = 3y^2 = 3(x-2)^2 \qquad \frac{1}{2} = \frac{1$$