Problem 1

a)

Our model is: $y_t = \alpha y_{t-1} + e_t + \theta e_{t-1}$. Using the lag operator:

$$y_t (1 - \alpha L) = e_t (1 + \theta L) \Rightarrow$$

$$y_t = \frac{(1 + \theta L)}{(1 - \alpha L)} e_t$$

$$= e_t (1 + \theta L) \sum_{j=0}^{\infty} (\alpha L)^j \Rightarrow$$

$$= e_t \left(\sum_{j=0}^{\infty} (\alpha L)^j + \sum_{j=0}^{\infty} \theta (\alpha L)^{j+1} \right)$$

By rearranging terms and collecting the terms with the same L^{j} we find:

$$\psi_j = \begin{cases} 1 & j = 0\\ \alpha^{j-1} (\alpha + \theta) & j \ge 1 \end{cases}$$

b)

Recall that we can write y_t as:

$$y_t = \sum_{j=0}^{\infty} \psi_j e_{t-j}$$

Since e_t are independent from each other:

$$\operatorname{var}(y_t) = \operatorname{var}(e_t) \sum_{j=0}^{\infty} \psi_j^2$$

Now,

$$\sum_{j=0}^{\infty} \psi_j^2 = 1 + (\alpha + \theta)^2 \sum_{j=1}^{\infty} \alpha^{2(j-1)}$$
$$= 1 + \frac{(\alpha + \theta)^2}{1 - \alpha^2}$$

Let, $var(e_t) = \sigma^2$, then:

$$\operatorname{var}(y_t) = \left(1 + \frac{(\alpha + \theta)^2}{1 - \alpha^2}\right) \sigma^2$$

We now calculate the first five autocovariances:

$$\gamma(1) = \mathbb{E}\left[y_t y_{t-1}\right]$$

$$= \mathbb{E}\left[\sum_{j=0}^{\infty} \psi_j e_{t-j} \sum_{k=0}^{\infty} \psi_k e_{t-1-k}\right]$$

$$= \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \psi_j \psi_k \mathbb{E}\left[e_{t-j} e_{t-1-k}\right]$$

$$= \sum_{j=1}^{\infty} \psi_j \psi_{j-1} \sigma^2$$

$$= \sigma^2 \left[(\alpha + \theta) + (\alpha + \theta)^2 \sum_{j=2}^{\infty} \alpha^{j-1} \alpha^{j-2}\right]$$

$$= \sigma^2 \left[(\alpha + \theta) + \frac{(\alpha + \theta)^2}{\alpha^3} \sum_{j=2}^{\infty} \alpha^{2j}\right]$$

$$= \sigma^2 (\alpha + \theta) \left[1 + \frac{\alpha (\alpha + \theta)}{1 - \alpha^2}\right]$$

Now to find $\gamma(k)$ for $k \geq 2$ note that:

$$y_t y_{t-k} = \alpha y_{t-1} y_{t-k} + e_t y_{t-k} + \theta e_{t-1} y_{t-k} \Rightarrow$$
$$\gamma(k) = \mathbb{E} [y_t y_{t-k}]$$
$$= \alpha \gamma(k-1)$$

So we have the following:

$$\gamma\left(k\right) = \alpha^{k-1}\sigma^{2}\left(\alpha + \theta\right)\left[1 + \frac{\alpha\left(\alpha + \theta\right)}{1 - \alpha^{2}}\right]$$

for $k \geq 1$. Writing this explicitly for the first 5 k:

$$\gamma(1) = \sigma^{2}(\alpha + \theta) \left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^{2}} \right]$$

$$\gamma(2) = \alpha\sigma^{2}(\alpha + \theta) \left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^{2}} \right]$$

$$\gamma(3) = \alpha^{2}\sigma^{2}(\alpha + \theta) \left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^{2}} \right]$$

$$\gamma(4) = \alpha^{3}\sigma^{2}(\alpha + \theta) \left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^{2}} \right]$$

$$\gamma(5) = \alpha^{4}\sigma^{2}(\alpha + \theta) \left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^{2}} \right]$$

 $\mathbf{c})$

I report the first 5 ψ_i below:

$$\psi_0 = 1$$

$$\psi_1 = 1.3$$

$$\psi_2 = 0.65$$

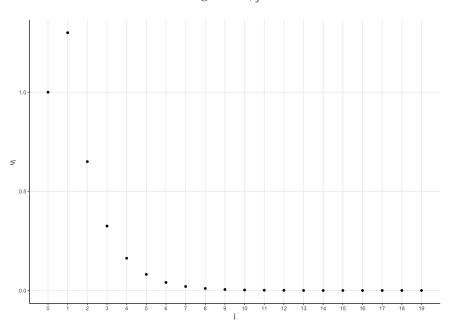
$$\psi_3 = 0.325$$

$$\psi_4 = 0.1625$$

$$\psi_5 = 0.08125$$

And here is the plot with the first 20 coefficients:

Figure 1: ψ_i



d)

 y_t and \tilde{y}_t will be observationally equivalent if they have the same autocovariances function. Recall the expressions we found in part a) for the y_t process:

$$\gamma(0) = \left(1 + \frac{(\alpha + \theta)^2}{1 - \alpha^2}\right)\sigma^2$$
$$\gamma(k) = \alpha^{k-1}\sigma^2(\alpha + \theta)\left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^2}\right]$$

Rewriting for the $\tilde{y_t}$ process:

$$\tilde{\gamma}(0) = \left(1 + \frac{\left(\alpha + \tilde{\theta}\right)^2}{1 - \alpha^2}\right)\tilde{\sigma}^2$$

$$\tilde{\gamma}(k) = \alpha^{k-1}\tilde{\sigma}^2\left(\alpha + \tilde{\theta}\right)\left[1 + \frac{\alpha\left(\alpha + \tilde{\theta}\right)}{1 - \alpha^2}\right]$$

We first set $\gamma(0) = \tilde{\gamma}(0)$ and isolate $\tilde{\sigma}^2$:

$$\tilde{\sigma}^2 = \left(1 + \frac{(\alpha + \theta)^2}{1 - \alpha^2}\right) \frac{\sigma^2}{\left(1 + \frac{(\alpha + \tilde{\theta})^2}{1 - \alpha^2}\right)} \tag{1}$$

Now, set $\tilde{\gamma}(k) = \gamma(k)$ for $k \geq 1$:

$$\sigma^{2}\left(\alpha+\theta\right)\left[1+\frac{\alpha\left(\alpha+\theta\right)}{1-\alpha^{2}}\right]=\tilde{\sigma}^{2}\left(\alpha+\tilde{\theta}\right)\left[1+\frac{\alpha\left(\alpha+\tilde{\theta}\right)}{1-\alpha^{2}}\right]$$

Substituting $\tilde{\sigma}^2$ in the expression above and simplifying:

$$(\alpha + \theta) \frac{\left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^2}\right]}{\left(1 + \frac{(\alpha + \theta)^2}{1 - \alpha^2}\right)} \left(1 + \frac{\left(\alpha + \tilde{\theta}\right)^2}{1 - \alpha^2}\right) = \left(\alpha + \tilde{\theta}\right) \left[1 + \frac{\alpha\left(\alpha + \tilde{\theta}\right)}{1 - \alpha^2}\right]$$

Define the following:

$$\kappa = (\alpha + \theta) \frac{\left[1 + \frac{\alpha(\alpha + \theta)}{1 - \alpha^2}\right]}{\left(1 + \frac{(\alpha + \theta)^2}{1 - \alpha^2}\right)}$$
$$x = \left(\alpha + \tilde{\theta}\right)$$

Substituting these in the above expression:

$$\kappa \left(1 + \frac{x^2}{1 - \alpha^2} \right) = x \left[1 + \frac{\alpha x}{1 - \alpha^2} \right] \Rightarrow$$
$$x^2 (\alpha - \kappa) + x \left(1 - \alpha^2 \right) - \kappa \left(1 - \alpha^2 \right) = 0$$

This is a quadratic equation in x. The solutions are:

$$x_1 = \alpha + \frac{1}{\theta} \Rightarrow \tilde{\theta_1} = \frac{1}{\theta}$$

 $x_2 = \alpha + \theta \Rightarrow \tilde{\theta_2} = \theta$

The second solution is the trivial one. So we focus on the first one to find $\tilde{\sigma}^2$. Substituting $\tilde{\theta} = \frac{1}{\theta}$ in Equation (1) we find:

$$\tilde{\sigma}^2 = \sigma^2 \frac{1 - \alpha^2 + (\alpha + \theta)^2}{1 - \alpha^2 + (\alpha + \frac{1}{\theta})^2}$$

To sum up, choosing $\tilde{\theta} = \frac{1}{\theta}$ and $\tilde{\sigma}^2 = \sigma^2 \frac{1 - \alpha^2 + (\alpha + \theta)^2}{1 - \alpha^2 + (\alpha + \frac{1}{\theta})^2}$ will make \tilde{y}_t observationally equivalent to y_t .

e)

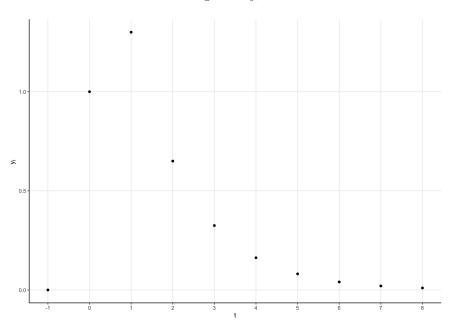
I am assuming I have to compare the results I obtained here with the ψ_j I calculated on part c. As expected they are the same. I report the values of y for the first five instants of time:

$$y_1 = 1$$

 $y_2 = 1.3$
 $y_3 = 0.65$
 $y_4 = 0.325$
 $y_5 = 0.1625$
 $y_6 = 0.08125$

And the plot of y_t

Figure 2: y_t



An easy way to see why y_t should match ψ_j is considering the moving average representation of this process:

$$y_t = \sum_{j=0}^{\infty} \psi_j e_{t-j}$$

Since:

$$e_t = \begin{cases} 1 & t = 0 \\ 0 & \text{otherwise} \end{cases}$$

we have:

$$y_0 = \psi_0 e_0 = \psi_0$$

$$y_1 = \psi_0 e_1 + \psi_1 e_0 = \psi_1$$

$$y_2 = \psi_0 e_2 + \psi_1 e_1 + \psi_2 e_0 = \psi_2$$

The way we generated y_t is a way of obtaining the impulse response function for this model.

Problem 2

Let $y_{1,t} = \alpha_1 y_{1,t-1} + e_{1,t}$ and $y_{2,t} = \alpha_2 y_{2,t-1} + e_{2,t}$. In what follows, I will assume that $e_{2,t} \perp e_{2,t}$ and $e_{i,t} \sim (0, \sigma_i^2)$.

Using the lag operator we can write:

$$y_{1,t} (1 - \alpha_1 L) = e_{1,t}$$

Multiplying both sides by $1 - \alpha_2 L$:

$$y_{1,t} (1 - \alpha_1 L) (1 - \alpha_2 L) = e_{1,t} (1 - \alpha_2 L)$$

Similarly for $y_{2,t}$:

$$y_{2,t} (1 - \alpha_2 L) (1 - \alpha_1 L) = e_{2,t} (1 - \alpha_1 L)$$

Summing both equations:

$$(1 - \alpha_2 L) (1 - \alpha_1 L) (y_{1,t} + y_{2,t}) = e_{1,t} (1 - \alpha_2 L) + e_{2,t} (1 - \alpha_1 L)$$

Let $x_t = y_{1,t} + y_{2,t}$, then:

$$x_t - L(\alpha_1 + \alpha_2) x_t + \alpha_1 \alpha_2 L^2 x_t = e_{1,t} - \alpha_2 e_{1,t-1} + e_{2,t} - \alpha_1 e_{2,t-1} \Rightarrow x_t - (\alpha_1 + \alpha_2) x_{t-1} + \alpha_1 \alpha_2 x_{t-2} = e_{1,t} - \alpha_2 e_{1,t-1} + e_{2,t} - \alpha_1 e_{2,t-1}$$

You can see that the left-hand side of the last equation is an AR(2) process with parameters $\alpha_1 + \alpha_2$ and $-\alpha_1\alpha_2$. Now we need to show that the right hand side has the same covariance structure of an MA(1) process. So let $w_t = e_{1,t} - \alpha_2 e_{1,t-1} + e_{2,t} - \alpha_1 e_{2,t-1}$, then:

$$\gamma_w(j) = \begin{cases} \left(1 - \alpha_2^2\right) \sigma_1^2 + \left(1 - \alpha_1^2\right) \sigma_2^2 & , j = 0\\ -\alpha_2 \sigma_1^2 - \alpha_1 \sigma_2^2 & , j = 1\\ 0 & , j \ge 2 \end{cases}$$

Which has the same covariance structure as an MA(1). Recall that if $z_t = e_t + \theta e_{t-1}$ with $e_t \sim (0, \sigma^2)$, then:

$$\gamma_{z}(j) = \begin{cases} \left(1 + \theta^{2}\right) \sigma^{2} &, j = 0\\ \theta \sigma^{2} &, j = 1\\ 0 &, j \geq 2 \end{cases}$$

In order to express θ , σ as a function of $\alpha_1, \alpha_2, \sigma_1, \sigma_2$ we impose:

$$\gamma_w (0) = \gamma_z (0)$$
$$\gamma_w (1) = \gamma_z (1)$$

Dividing the last two equations and rearranging give us a quadratic equation in θ :

$$\theta^2 \left[\alpha_2 \sigma_1^2 + \alpha_1 \sigma_2^2 \right] + \theta \left[\left(1 - \alpha_2^2 \right) \sigma_1^2 + \left(1 - \alpha_1^2 \right) \sigma_2^2 \right] + \alpha_2 \sigma_1^2 + \alpha_1 \sigma_2^2 = 0$$

Solving for θ

$$\theta = \frac{-\left(1 - \alpha_{2}^{2}\right)\sigma_{1}^{2} - \left(1 - \alpha_{1}^{2}\right)\sigma_{2}^{2} \pm \sqrt{\left[\left(1 - \alpha_{2}^{2}\right)\sigma_{1}^{2} + \left(1 - \alpha_{1}^{2}\right)\sigma_{2}^{2}\right]^{2} - 4\left[\alpha_{2}\sigma_{1}^{2} + \alpha_{1}\sigma_{2}^{2}\right]^{2}}}{2\left(\alpha_{2}\sigma_{1}^{2} + \alpha_{1}\sigma_{2}^{2}\right)}$$

Recall that:

$$\sigma^2 = \frac{-\alpha_2 \sigma_1^2 - \alpha_1 \sigma_2^2}{\theta}$$

Note that the numerator of the expression we found for both solutions for θ is always negative. So the sign of θ will be determined by the sign of $\alpha_2\sigma_1^2 + \alpha_1\sigma_2^2$. In both possible cases $\alpha_2\sigma_1^2 + \alpha_1\sigma_2^2 > 0$ and $\alpha_2\sigma_1^2 + \alpha_1\sigma_2^2 < 0$, $\sigma^2 > 0$ so both solutions satisfy this condition.

Another condition we should impose is $|\theta| \leq 1$ for invertibility. This will give the criteria to select the appropriate solution for θ .

Problem 3

i)

We estimate the model $y_t = \alpha_1 y_{t-1} + \alpha_2 y_{t-2} + \alpha_3 y_{t-3} + \alpha_4 y_{t-4} + e_t$ where y_t is the quarterly growth rate for GDP. The model was estimated by OLS and the estimates are shown below:

$$\hat{\alpha_1} = 0.35157$$
 $\hat{\alpha_2} = 0.25944$
 $\hat{\alpha_3} = 0.03455$
 $\hat{\alpha_4} = 0.15831$

We can represent this AR(4) process as an AR(1) 4-vector process: $Y_t = AY_{t-1} + E_t$ where:

$$Y_{t} = \begin{bmatrix} y_{t} \\ y_{t-1} \\ y_{t-2} \\ y_{t-3} \end{bmatrix}$$

$$A = \begin{bmatrix} \alpha_{1} & \alpha_{2} & \alpha_{3} & \alpha_{4} \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$E_{t} = \begin{bmatrix} e_{t} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

The h step ahead forecast for Y_{t+h} is given by:

$$\hat{Y_{t+h}} = A^h Y_t$$

and the forecast errors are given by:

$$\sum_{j=0}^{h-1} A^j E_{t+h-j}$$

and the mean squared error for $\hat{Y_{t+h}}$ is:

$$\mathbb{E}\left[\left(\sum_{j=0}^{h-1} A^{j} E_{t+h-j}\right) \left(\sum_{j=0}^{h-1} A^{j} E_{t+h-j}\right)'\right] = \mathbb{E}\left[\left(\sum_{j=0}^{h-1} A^{j} E_{t+h-j}\right) \left(\sum_{j=0}^{h-1} (A')^{j} E'_{t+h-j}\right)\right]$$

$$= \left(\sum_{j=0}^{h-1} A^{j} \mathbb{E}\left[E_{t+h-j} E'_{t+h-j}\right] (A')^{j}\right)$$

$$= \sigma^{2} \left(\sum_{j=0}^{h-1} A^{j} (A')^{j}\right)$$

where I assumed $e_t \sim (0, \sigma^2)$.

We estimated σ^2 using the variance of the residuals:

$$\hat{\sigma^2} = 6.247812 \cdot 10^{-5}$$

The forecast and the 95% prediction interval are shown in the following table:

Table 1: Forecasts

\overline{h}	\hat{Y}_{t+h}	IC inf	IC sup
1	0.47%	-1.08%	2.02%
2	0.45%	-1.26%	2.16%

ii)

In order to generate the 1 and 2 step ahead forecast for this model, I fixed the initial date in every estimation sample to 1961-Q1 and increase the end date by 1 quarter in each of the 16 estimation samples.

The following two pictures show the results of our 1 and 2 step ahead forecast together with the 95% confidence interval. As you can see both the 1 and 2 step ahead predictions could not forecast the 2020Q1 and Q2 downturn, since they are outside the 95% confidence interval.

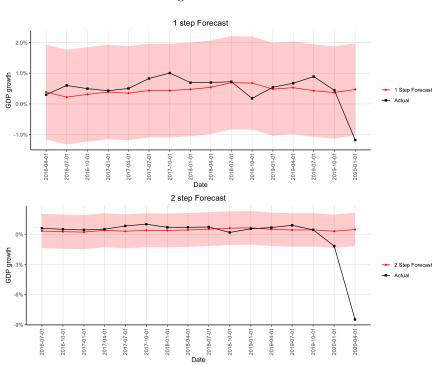


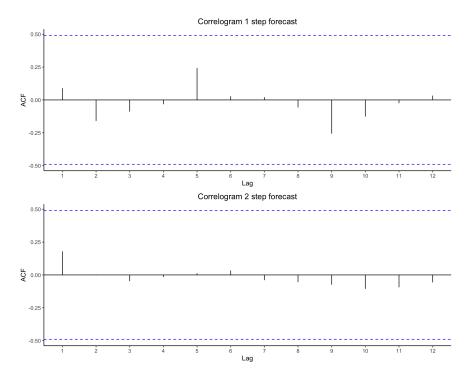
Figure 3: Forecasts

iii)

The correlogram for both errors are shown in the following pictures. The dashed lines are the 2 standard error deviations from 0.

As you can see, both appear to be white noise since we don't have any significant coefficient.

Figure 4: Forecasts



iv)

We compare the predictability of the AR(4) model (Model A) with the predictability of an AR(5) model (Model B).

Let $\hat{e_t}^A$ and $\hat{e_t}^B$ be the forecast errors of model A and B respectively. The two-sided test statistic S is given by:

$$S = \frac{\sqrt{P}\bar{d}}{\mathrm{Avar}(\bar{d})}$$

where P = 16 in our case and

$$\bar{d} = \frac{1}{P} \sum_{t=1}^{P} \left(\hat{e_t}^B\right)^2 - \left(\hat{e_t}^A\right)^2$$

Under the null (equal predictability) $S \xrightarrow{d} \mathcal{N}(0,1)$. I estimate Avar (\bar{d}) using the following:

$$\hat{\operatorname{Avar}}(\bar{d}) = \hat{\gamma_d}(0) + 2\sum_{j=1}^{\tau} \hat{\gamma_d}(j)$$

I used two different estimates: one using only the short run variance $\hat{\gamma_d}(0)$ and another one including one lag : $\hat{\gamma_d}(0) + 2\hat{\gamma_d}(1)$

The results from both were pretty close and gave a p-value of 0.55, so we failed to reject the null with a 5% significance level.