

**Problem 1: Subset Sum, Dynamic Programming (25 points)**

You are given  $n$  items  $\{1, 2, \dots, n\}$ , where each item has a given positive weight  $w_i$ ,  $1 \leq i \leq n$ . You are also given an upper bound  $W$ . You would like to select a subset  $S$  of the items so that  $\sum_{i \in S} w_i \leq W$ , and, subject to this restriction,  $\sum_{i \in S} w_i \leq W$  is as large as possible. Give an  $O(nW)$  algorithm, justify correctness and running time.

**Answer:**

We are going to solve this with dynamic programming.

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## subset sum, dynamic programming - pseudocode

## given n items (each with increasing weight), and W upper bound
## compute the best set of items to put in the set S
## so that you get the highest weight thats still
## less than the max weight W

## 1. build look-up table M
## 2. work backwards from max weight to find
##    what items to put in the set S
##

## n: number of items
## w: array with weight of each item ; n total items
## W: max weight the sum can be
##

w = array of weights |
def subset_sum(n, W):
    ## initialize the look-up table
    for r = 0, ..., W
        M[0,r] = 0
    for j = 1, ..., n
        M[j,0] = 0

    for j = 1, ..., n
        for r = 0, ..., W
            if w[j] > r:
                M[j,r] = M[j-1, r] #if this item too heavy, cannot include;
                                   # therefore max sum is whatever it was
                                   # with the all items up to the last j
            M[j, r] = max( M[j-1, r],
                           w[j] + M[ j-1, W-w[j] ] ) #find max of these two
    return M[n,W] ## after table has been filled, we simply look it up
```

There are  $n \times W$  items in the lookup table. Therefore it takes  $O(nW)$  to fill up the table. It takes  $O(n)$  to follow the path backwards to get the answer. Therefore  $O(nW + n) = O(nW)$ .

**Problem 2: Balanced Tree, Dynamic Programming (25 points).**

Let  $T(V, E)$  be a directed acyclic graph with  $V = \{v_1, \dots, v_n\}$ .

Suppose that  $T$  is given in topologically sorted order, that is, if  $v_i$  is an ancestor of  $v_j$  then  $i < j$ .

Suppose further that each vertex  $v_i \in V$  has a given positive cost  $c(v_i) > 0$ . Define the weight of a vertex  $v_i \in V$  as the sum of the costs of all vertices that can be reached from  $v_i$  (equivalently belong to the subtree rooted at  $v_i$ ):  $weight(v_i) = \sum_{\substack{v_j \in V : \\ v_j \text{ is reachable from } v_i}} c(v_j)$

Say that  $T$  is balanced if and only if, for every vertex  $v_i \in V$ , if  $v_i$  has children  $u_1, \dots, u_k$ , then

$$weight(u_1) = weight(u_2) = \dots = weight(u_k)$$

Give a polynomial time algorithm that decides if a directed tree with costs on its vertices is balanced. Justify your answer and argue running time.

**Answer:**

**Problem 3: Max Independent Set, Dynamic Programming (25 points)**

(a) Consider a line graph on vertices  $\{1, \dots, n\}$  and edges  $\{1, 2\}, \{2, 3\}, \dots, \{(n-1), n\}$ . Each vertex has a positive weight  $w_i$ ,  $1 \leq i \leq n$ . Give an  $O(n)$  algorithm that outputs the weight of a maximum weight independent set of the line graph. You may give a simple description of the algorithm, and/or pseudocode. You should include a short argument of correctness and running time.

(b) Consider a cycle graph on vertices  $\{1, \dots, n\}$  and edges  $\{1, 2\}, \{2, 3\}, \dots, \{(n-1), n\}, \{n, 1\}$ . Each vertex has a positive weight  $w_i$ ,  $1 \leq i \leq n$ . Give an  $O(n)$  algorithm that outputs the weight of a maximum weight independent set of the cycle graph. You may give a simple description of the algorithm, and/or pseudocode. You should include a short argument of correctness and running time.

**Answer:**

Recall that a subset  $S$  of a graph  $G$  is an independent subset if there are no edges between any two elements in  $S$ .

**Part a**

Let MIS = max independent set. So say you have vertex  $v_i$ , then one of two scenarios exists: 1.  $v_i$  is IN the MIS of  $v_i$  and later, or 2.  $v_i$  is NOT in the MIS and thus the MIS is the MIS of vertices after  $v_i$ . If  $v_i$  is IN the MIS from  $v_i$  and later, then the MIS is the weight of  $v_i$ , plus the total weight of the MIS from  $v_{i+2}$  to  $v_n$ . Otherwise, then the MIS from  $v_i$  to  $v_n$  is the MIS from  $v_{i+1}$  to  $v_n$ . If you model the recurrence this way then the MIS from any  $v_i$  to  $v_n$  is:

$$MIS(v_i) = \text{MAX}\{MIS(v_{i+1}), w_i + MIS(v_{i+2})\}$$

This can be solved in linear time ( $O(n)$ ) because it's a line and that the subproblem for each subsequent vertex is smaller than the one before it.

**Part b**

This is the same problem as part a except that we have a cycle. Arbitrarily choose to cut the graph at any edge and now you have a line graph. Find MIS of this in the way as in **part a**. Running time is  $O(n)$  following the same logic.

**Problem 4: Longest Path, Dynamic Programming (25 points)**

Let  $G(V, E)$  be a directed acyclic graph, where  $V = \{v_1, \dots, v_n\}$ . The graph is presented in adjacency list representation, and with the property that  $v_i \rightarrow v_j \in E$  only if  $i < j$ . Give an  $O(|V| + |E|)$  algorithm that finds the length of the longest path (maximum number of edges) from  $v_1$  to  $v_n$ . If there is no path from  $v_1$  to  $v_n$  then your algorithm should output  $\infty$ .

Give a short justification of correctness and running time.

**Answer:**

This can be solved with dynamic programming. It is  $O(|V| + |E|)$  because you go thru all vertices in topological order and evaluate all edges once (all edges of each adjacent vertex in question).

```
## longest path, dynamic programming - pseudocode

## find length of longest path from v_1 to v_n
## in DAG G.
## assume G is topological sorted already
##

def longest_path_v1_vn(G, v_1, v_n):
    length_to_this_vertex = []
    for i in range(n):
        length_to_this_vertex.append( infinity) ## initialize all lengths to
                                                ## vertices from source
                                                ## to be infinity

    top_sorted_G = topological sort G ## O(|V| + |E|)

    ## loop thru edges in topologically sorted order
    for i in range(len(top_sorted_G)):
        for j in range(i, len(top_sorted_G)): # it's an edge of v_j comes later than v_i
                                                # in top_sorted_G
            ## add the weight of edge v_i -> v_j if it's going to increase greatest length to v_j so far
            if length_to_this_vertex[top_sorted_G[j]] <= length_to_this_vertex[top_sorted_G[i]] + weight(G, i,j):
                length_to_this_vertex[top_sorted_G[j]] = length_to_this_vertex[top_sorted_G[i]] + weight(G, i,j)

    return max( length_to_this_vertex ) #returns the LENGTH of the longest path
```