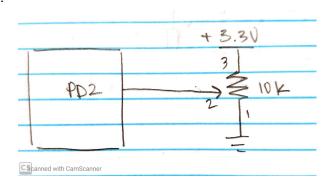
1.



2.

Name	Value	Type	
<b>₽</b> Data	0x000000A7	uint	
→ PlotImage	<cannot evaluate=""></cannot>	uchar	
Data	167	uint	
<ul> <li>OutDectime</li> </ul>	3576	uint	
	129	uint	1

3.

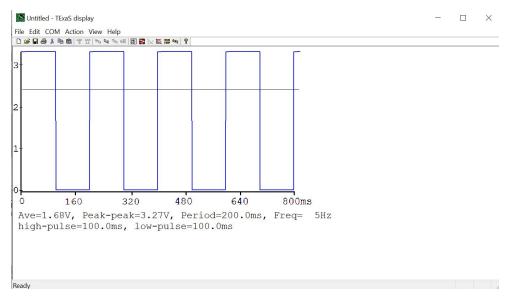
Position (0.01 cm)	ADC Sample	Analog Input
10	67	0.02
40	570	0.471
80	1594	1.244
120	2554	2.131
140	3092	2.516

## 4. ADC.c (part c)

```
15 poid ADC_Init(void) {
16
      SYSCTL_RCGCADC_R |= 0x1;
17
      SYSCTL_RCGCGPIO_R |= 0x8;
18
      while ((SYSCTL PRGPIO R & 0x8) != 0x8) {};
     GPIO_PORTD_DIR_R &= ~0x4;
19
     GPIO_PORTD_AFSEL_R |= 0x4;
GPIO_PORTD_DEN_R &= ~0x4;
20
21
22
     GPIO PORTD AMSEL R |= 0x4;
     ADC0_PC_R &= ~0xF;
ADC0_PC_R |= 0x1;
23
24
25
     ADCO_SSPRI_R = 0x0123;
26
    ADCO_ACTSS_R &= ~0x8;
    ADCO_EMUX_R &= ~0xF000;
ADCO_SSMUX3_R &= ~0xF;
27
28
29
     ADCO_SSMUX3_R += 0x5;
     ADCO_SSCTL3_R = 0x6;
30
31
      ADC0_IM_R &= ~0x8;
32
     ADCO_ACTSS_R |= 0x8;
33 }
34
35 //-----ADC_In-----
36 // Busy-wait Analog to digital conversion
37 // Input: none
38
    // Output: 12-bit result of ADC conversion
39 // measures from PD2, analog channel 5
40 □ uint32_t ADC_In(void) {
     uint32_t result;
ADC0_PSSI_R = 0x8;
41
42
    while((ADCO_RIS_R & 0x8) == 0){};
43
     result = ADC0_SSFIF03_R & 0xFFF;
ADC0_ISC_R = 0x8;
44
45
46
     return result;
47
    }
```

Lab8.c (part e,f,g,h)

```
46 //Part e
47 // your function to convert ADC sample to distance (0.01cm)
48 - uint32 t Convert (uint32 t input) {
49
     return 173*input/4096+12;
50
     1
51
52 //Part F
53 @ void SysTick_Init(void) [
54
      NVIC ST CTRL R - 0;
55
      NVIC ST RELOAD R - 8000000;
      NVIC ST CURRENT R - 0;
56
57
     NVIC ST CTRL R - 7;
58 -1
59 //Part G
60 uint32_t ADCMail; // 0 to 4095
61 uint32 t ADCStatus; // 1 means new data
62 - void SysTick Handler (void) [
63
     GPIO PORTF DATA R ^- 0x02; // toggle PF1
64
      ADCMail = Convert(ADC_In()); // Sample ADC
65
      ADCStatus - 1;
                         // Synchronize with other threads
66
    1
67
68
    //Part H
69
    uint32_t Sample;
70
71 = int main(void)[
72
     TExas_Init();
73
      ST7735_InitR(INITR_REDTAB);
74
     PortF_Init();
75
      ADC Init();
76
      SysTick_Init();
77
78 - while(1)[
79 白
       if (ADCStatus -- 1) (
80
          Sample - ADCMail;
81
          ADCStatus - 0;
         LCD OutFix (Sample);
82
83
         ST7735 OutString(" cm");
84
         ST7735_SetCursor(0,0);
85
  -1
86
        1
87
BB
89
```



## 6. Average accuracy (with units in cm) = 0.020 cm

True position	Measured Position	Error
x <sub>ti</sub>	x <sub>mi</sub>	$x_{ti}$ - $x_{mi}$
0.3 cm	0.27 cm	0.030 cm
0.5 cm	0.48 cm	0.020 cm
1 cm	1.00 cm	0 cm
1.3 cm	1.32 cm	-0.020 cm
1.5 cm	1.53 cm	-0.030 cm