

Retiring the third law of black hole thermodynamics

Ryan Unger

Department of Mathematics, Princeton University

Edinburgh analysis seminar
February 2023

joint work with Christoph Kehle (ETH Zürich)

Classical thermodynamics

Law	Thermodynamics

Classical thermodynamics

Law	Thermodynamics
Zeroth	T constant throughout body in thermal equilibrium

Classical thermodynamics

Law	Thermodynamics
Zeroth	T constant throughout body in thermal equilibrium
First	$dE = TdS + \text{work terms } (PdV)$

Classical thermodynamics

Law	Thermodynamics
Zeroth	T constant throughout body in thermal equilibrium
First	$dE = TdS + \text{work terms } (PdV)$
Second	$dS \geq 0$ in any process

Classical thermodynamics

Law	Thermodynamics
Zeroth	T constant throughout body in thermal equilibrium
First	$dE = TdS + \text{work terms } (PdV)$
Second	$dS \geq 0$ in any process
Third	Impossible to achieve $T = 0$ in finite time

Black hole thermodynamics

Commun. math. Phys. 31, 161–170 (1973)
© by Springer-Verlag 1973

The Four Laws of Black Hole Mechanics

J. M. Bardeen*

Department of Physics, Yale University, New Haven, Connecticut, USA

B. Carter and S. W. Hawking

Institute of Astronomy, University of Cambridge, England

Received January 24, 1973

Black hole thermodynamics is a proposed close mathematical **analogy** between black hole dynamics and classical thermodynamics.

Black hole thermodynamics

Commun. math. Phys. 31, 161–170 (1973)
© by Springer-Verlag 1973

The Four Laws of Black Hole Mechanics

J. M. Bardeen*

Department of Physics, Yale University, New Haven, Connecticut, USA

B. Carter and S. W. Hawking

Institute of Astronomy, University of Cambridge, England

Received January 24, 1973

Black hole thermodynamics is a proposed close mathematical **analogy** between black hole dynamics and classical thermodynamics.

- ▶ What is a black hole?
- ▶ What is the analogue of temperature T ?
- ▶ What is the analogue of entropy S ?

Crash course on black holes: Spacetimes and Einstein's equations

The setting is Einstein's theory of general relativity. A **spacetime** consists of a 4-manifold \mathcal{M}^{3+1} and a Lorentzian metric g satisfying the **Einstein field equations**

$$\text{Ric}(g) - \frac{1}{2}R(g)g = 2T. \quad (\text{EFE})$$

Crash course on black holes: Spacetimes and Einstein's equations

The setting is Einstein's theory of general relativity. A **spacetime** consists of a 4-manifold \mathcal{M}^{3+1} and a Lorentzian metric g satisfying the **Einstein field equations**

$$\text{Ric}(g) - \frac{1}{2}R(g)g = 2T. \quad (\text{EFE})$$

Example: Minkowski space. $\mathcal{M}^{3+1} = \mathbb{R}_{t,x,y,z}^{3+1}$ and

$$g = -dt^2 + dx^2 + dy^2 + dz^2$$

This metric describes the geometry of special relativity with speed of light $c = 1$.

Crash course on black holes: Spacetimes and Einstein's equations

The setting is Einstein's theory of general relativity. A **spacetime** consists of a 4-manifold \mathcal{M}^{3+1} and a Lorentzian metric g satisfying the **Einstein field equations**

$$\text{Ric}(g) - \frac{1}{2}R(g)g = 2T. \quad (\text{EFE})$$

Example: Minkowski space. $\mathcal{M}^{3+1} = \mathbb{R}_{t,x,y,z}^{3+1}$ and

$$g = -dt^2 + dx^2 + dy^2 + dz^2$$

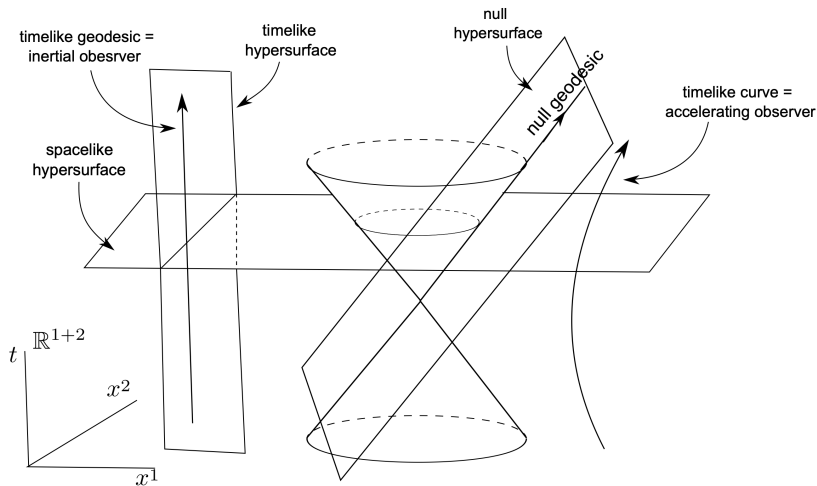
This metric describes the geometry of special relativity with speed of light $c = 1$.

Given a vector $v \in T_p\mathcal{M}$:

- ▶ $g(v, v) < 0$, v is *timelike*
- ▶ $g(v, v) = 0$, v is *null*
- ▶ $g(v, v) > 0$, v is *spacelike*

Curves with null or timelike tangent vector let us define **causality** on a spacetime.

Crash course on black holes: Geometry of Minkowski space



Crash course on black holes: What is a black hole?

Asymptotic flatness: g approaches the Minkowski metric “at infinity.”

Crash course on black holes: What is a black hole?

Asymptotic flatness: g approaches the Minkowski metric “at infinity.”

An asymptotically flat spacetime is said to contain a **black hole region**

$$\mathcal{BH} \subset \mathcal{M}$$

if observers and signals originating in \mathcal{BH} cannot reach infinity.

Crash course on black holes: What is a black hole?

Asymptotic flatness: g approaches the Minkowski metric “at infinity.”

An asymptotically flat spacetime is said to contain a **black hole region**

$$\mathcal{BH} \subset \mathcal{M}$$

if observers and signals originating in \mathcal{BH} cannot reach infinity.

The **event horizon** of the black hole is its topological boundary

$$\mathcal{H}^+ := \partial(\mathcal{BH}).$$

Crash course on black holes: What is a black hole?

Asymptotic flatness: g approaches the Minkowski metric “at infinity.”

An asymptotically flat spacetime is said to contain a **black hole region**

$$\mathcal{BH} \subset \mathcal{M}$$

if observers and signals originating in \mathcal{BH} cannot reach infinity.

The **event horizon** of the black hole is its topological boundary

$$\mathcal{H}^+ := \partial(\mathcal{BH}).$$

The event horizon \mathcal{H}^+ is a **null hypersurface**: it is ruled by geodesics with null tangent vectors.

Crash course on black holes: What is a black hole?

Asymptotic flatness: g approaches the Minkowski metric “at infinity.”

An asymptotically flat spacetime is said to contain a **black hole region**

$$\mathcal{BH} \subset \mathcal{M}$$

if observers and signals originating in \mathcal{BH} cannot reach infinity.

The **event horizon** of the black hole is its topological boundary

$$\mathcal{H}^+ := \partial(\mathcal{BH}).$$

The event horizon \mathcal{H}^+ is a **null hypersurface**: it is ruled by geodesics with null tangent vectors.

Examples to come shortly!

Crash course on black holes: Teleology



The black hole region \mathcal{BH} and event horizon \mathcal{H}^+ of a spacetime are **teleological** notions—they can't be known to exist, much less be located, *without knowing the entire future of the spacetime*.

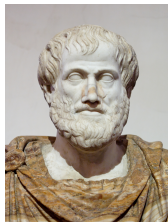
Crash course on black holes: Teleology



The black hole region \mathcal{BH} and event horizon \mathcal{H}^+ of a spacetime are **teleological** notions—they can't be known to exist, much less be located, *without knowing the entire future of the spacetime*.

The event horizon \mathcal{H}^+ is not a singular object.

Crash course on black holes: Teleology



The black hole region \mathcal{BH} and event horizon \mathcal{H}^+ of a spacetime are **teleological** notions—they can't be known to exist, much less be located, *without knowing the entire future of the spacetime*.

The event horizon \mathcal{H}^+ is not a singular object.

The formation, dynamics, and stability of black holes can be rigorously studied using the tools of Lorentzian geometry and hyperbolic PDE.

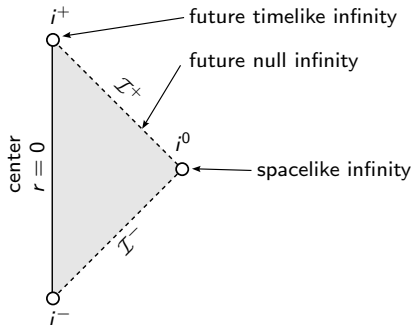
Crash course on black holes: Penrose diagrams

Penrose diagrams: A $(1 + 1)$ -dimensional diagrammatic representation of spacetimes. This is particularly useful for visualizing causality.

Crash course on black holes: Penrose diagrams

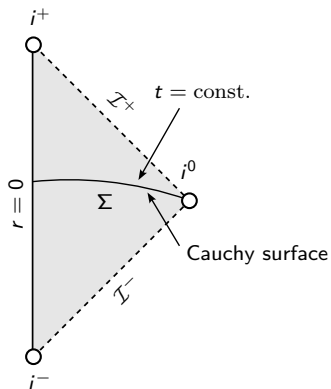
Penrose diagrams: A $(1 + 1)$ -dimensional diagrammatic representation of spacetimes. This is particularly useful for visualizing causality.

- ▶ 45 degree lines correspond to null hypersurfaces in $(3 + 1)$ dimensions
- ▶ steeper than 45: timelike
- ▶ shallower than 45: spacelike

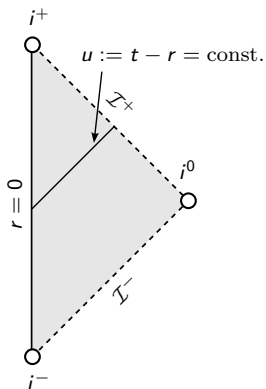


Penrose diagram of Minkowski space

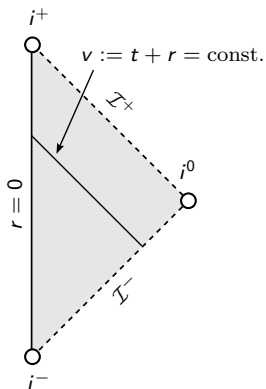
Crash course on black holes: Minkowski space



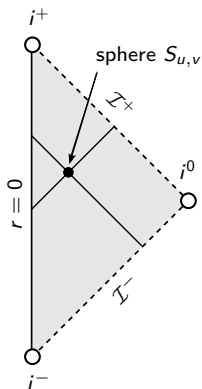
Crash course on black holes: Minkowski space



Crash course on black holes: Minkowski space



Crash course on black holes: Minkowski space



Crash course on black holes: The Schwarzschild solution

- Mass $M > 0$

$$g_M = - \left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2)$$

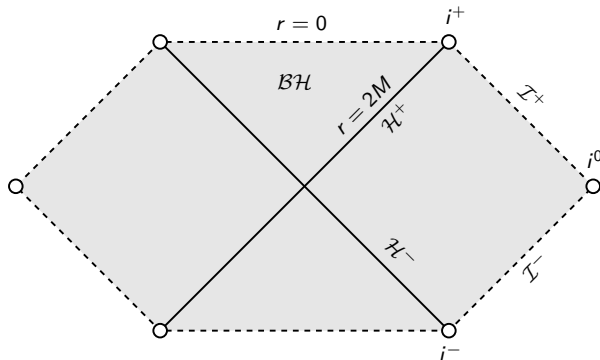
- Solves the **Einstein vacuum** equations
- Describes a static, nonrotating black hole

Crash course on black holes: The Schwarzschild solution

- Mass $M > 0$

$$g_M = - \left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2)$$

- Solves the **Einstein vacuum** equations
- Describes a static, nonrotating black hole

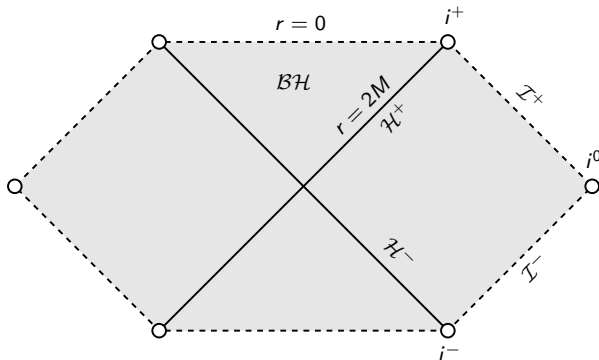


Crash course on black holes: The Schwarzschild solution

- Mass $M > 0$

$$g_M = - \left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2)$$

- Solves the **Einstein vacuum** equations
- Describes a static, nonrotating black hole



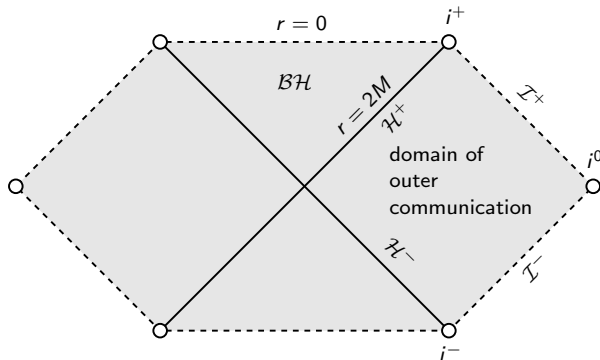
As $M \rightarrow 0$, recover the Minkowski metric.

Crash course on black holes: The Schwarzschild solution

- Mass $M > 0$

$$g_M = - \left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2)$$

- Solves the **Einstein vacuum** equations
- Describes a static, nonrotating black hole



As $M \rightarrow 0$, recover the Minkowski metric.

Crash course on black holes: Reissner–Nordström

- Mass $M > 0$ and charge $0 \leq |e| \leq M$

$$g_{M,e} = - \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right) dt^2 + \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

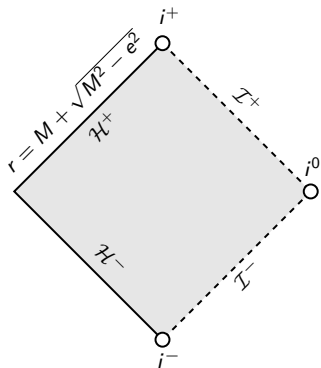
- Solves the **Einstein-Maxwell** equations
- Describes a static, charged, nonrotating black hole

Crash course on black holes: Reissner–Nordström

- Mass $M > 0$ and charge $0 \leq |e| \leq M$

$$g_{M,e} = - \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right) dt^2 + \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

- Solves the **Einstein-Maxwell** equations
- Describes a static, charged, nonrotating black hole



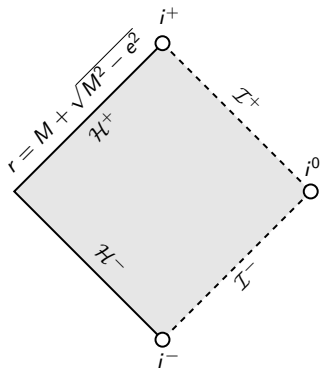
Subextremal $|e| < M$

Crash course on black holes: Reissner–Nordström

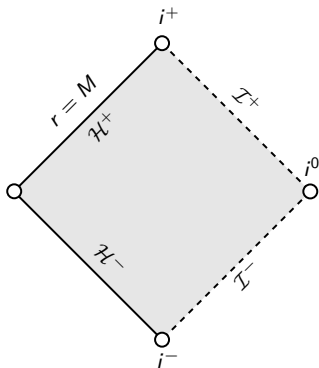
- Mass $M > 0$ and charge $0 \leq |e| \leq M$

$$g_{M,e} = - \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right) dt^2 + \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

- Solves the **Einstein-Maxwell** equations
- Describes a static, charged, nonrotating black hole



Subextremal $|e| < M$



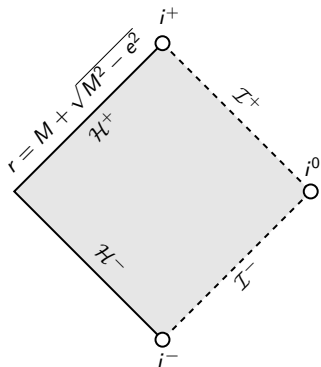
Extremal $|e| = M$

Crash course on black holes: Reissner–Nordström

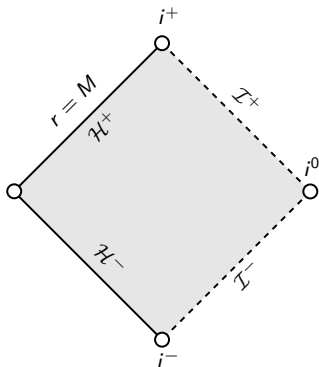
- Mass $M > 0$ and charge $0 \leq |e| \leq M$

$$g_{M,e} = - \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right) dt^2 + \left(1 - \frac{2M}{r} + \frac{e^2}{r^2} \right)^{-1} dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\phi^2)$$

- Solves the **Einstein-Maxwell** equations
- Describes a static, charged, nonrotating black hole



Subextremal $|e| < M$



Extremal $|e| = M$

Superextremal $|e| > M$ does not contain a black hole!

Crash course on black holes: Surface gravity and extremality

- Associated to a horizon is a function $\kappa \geq 0$, called the **surface gravity**

Crash course on black holes: Surface gravity and extremality

- ▶ Associated to a horizon is a function $\kappa \geq 0$, called the **surface gravity**
- ▶ Physically, κ measures the force required to hold a test mass “at the horizon” “from infinity”

Crash course on black holes: Surface gravity and extremality

- ▶ Associated to a horizon is a function $\kappa \geq 0$, called the **surface gravity**
- ▶ Physically, κ measures the force required to hold a test mass “at the horizon” “from infinity”
- ▶ It is also related to the celebrated **(local) redshift effect**

Crash course on black holes: Surface gravity and extremality

- ▶ Associated to a horizon is a function $\kappa \geq 0$, called the **surface gravity**
- ▶ Physically, κ measures the force required to hold a test mass “at the horizon” “from infinity”
- ▶ It is also related to the celebrated **(local) redshift effect**
- ▶ For Reissner–Nordström,

$$\kappa(g_{M,e}) = \frac{\sqrt{M^2 - e^2}}{(M + \sqrt{M^2 - e^2})^2}$$

Crash course on black holes: Surface gravity and extremality

- ▶ Associated to a horizon is a function $\kappa \geq 0$, called the **surface gravity**
- ▶ Physically, κ measures the force required to hold a test mass “at the horizon” “from infinity”
- ▶ It is also related to the celebrated **(local) redshift effect**
- ▶ For Reissner–Nordström,

$$\kappa(g_{M,e}) = \frac{\sqrt{M^2 - e^2}}{(M + \sqrt{M^2 - e^2})^2}$$

- ▶ **Subextremal horizon:** $\kappa > 0$
- ▶ **Extremal horizon:** $\kappa \equiv 0$

Black hole thermodynamics

Law	Classical thermodynamics	Black holes

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	surface gravity $\kappa \not\rightarrow 0$ in finite advanced time

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	surface gravity $\kappa \not\rightarrow 0$ in finite advanced time

- Proposed by Bardeen–Carter–Hawking '73

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	surface gravity $\kappa \not\rightarrow 0$ in finite advanced time

- Proposed by Bardeen–Carter–Hawking '73
- Hawking radiation—interpret $\kappa \propto T$

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	surface gravity $\kappa \not\rightarrow 0$ in finite advanced time

- ▶ Proposed by Bardeen–Carter–Hawking '73
- ▶ Hawking radiation—interpret $\kappa \propto T$
- ▶ Bekenstein entropy—interpret $A \propto S$

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	surface gravity $\kappa \not\rightarrow 0$ in finite advanced time

- ▶ Proposed by Bardeen–Carter–Hawking '73
- ▶ Hawking radiation—interpret $\kappa \propto T$
- ▶ Bekenstein entropy—interpret $A \propto S$
- ▶ These identifications are further justified once quantum effects are considered, but are **formal analogies** in classical GR.

Black hole thermodynamics

Law	Classical thermodynamics	Black holes
Zeroth	T constant in equilibrium	surface gravity κ constant on stationary horizon
First	$dE = TdS + \dots$	$dM = \kappa dA + \dots$
Second	$dS \geq 0$	$dA \geq 0$
Third	$T \not\rightarrow 0$ in finite process	surface gravity $\kappa \not\rightarrow 0$ in finite advanced time

- ▶ Proposed by Bardeen–Carter–Hawking '73
- ▶ Hawking radiation—interpret $\kappa \propto T$
- ▶ Bekenstein entropy—interpret $A \propto S$
- ▶ These identifications are further justified once quantum effects are considered, but are **formal analogies** in classical GR.
- ▶ Laws 0, 1, and 2 proved by Hawking, Carter, Bardeen–Carter–Hawking, Wald, ...

Retiring the third law

Original formulation of Bardeen–Carter–Hawking:

Extending the analogy even further one would postulate:

The Third Law

It is impossible by any procedure, no matter how idealized, to reduce κ to zero by a finite sequence of operations.

Retiring the third law

Conjecture (The third law, BCH '73, Israel '86).

*A subextremal black hole cannot become extremal in finite time by any continuous process, no matter how idealized, in which the spacetime and matter fields remain *regular* and obey the *weak energy condition*.*

Retiring the third law

Conjecture (The third law, BCH '73, Israel '86).

A subextremal black hole cannot become extremal in finite time by any continuous process, no matter how idealized, in which the spacetime and matter fields remain regular and obey the weak energy condition.

Theorem (Kehle–U. '22).

Subextremal black holes can become extremal in finite time, evolving from regular initial data. In particular, the “third law of black hole thermodynamics” is false.

Retiring the third law

Conjecture (The third law, BCH '73, Israel '86).

*A subextremal black hole cannot become extremal in finite time by any continuous process, no matter how idealized, in which the spacetime and matter fields remain **regular** and obey the **weak energy condition**.*

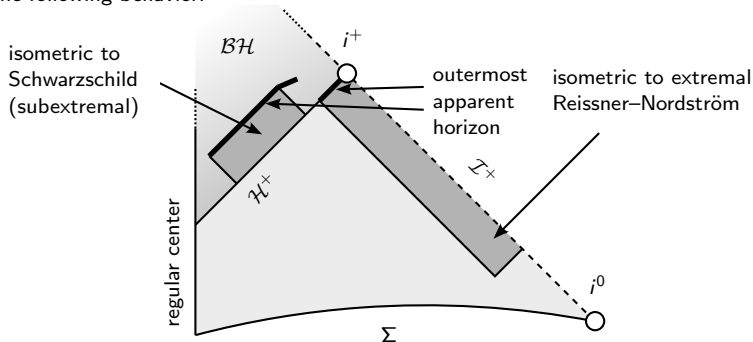
Theorem (Kehle–U. '22).

Subextremal black holes can become extremal in finite time, evolving from regular initial data. In particular, the “third law of black hole thermodynamics” is false.

More precisely, there exist **regular** solutions of the Einstein–Maxwell-charged scalar field system (which satisfies the **weak energy condition**) with the following behavior:

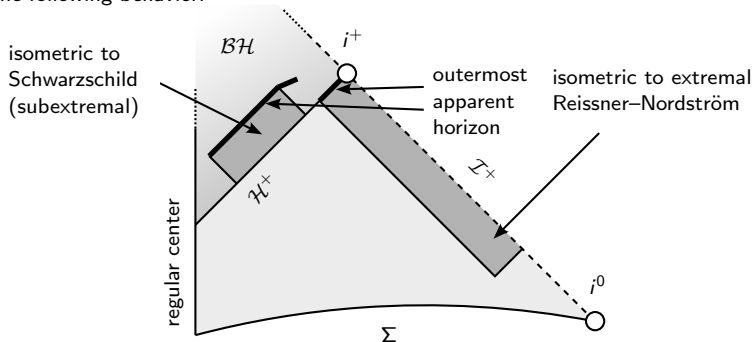
Counterexample to the third law: detailed statement of our theorem

There exist **regular** solutions of the Einstein–Maxwell–charged scalar field system with the following behavior:



Counterexample to the third law: detailed statement of our theorem

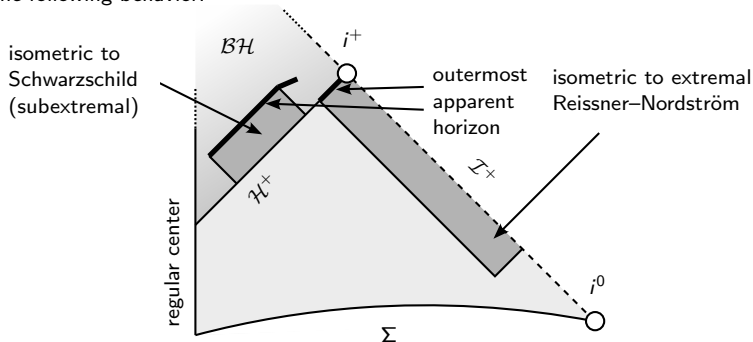
There exist **regular** solutions of the Einstein–Maxwell–charged scalar field system with the following behavior:



- Spherically symmetric Cauchy data for the Einstein–Maxwell–charged scalar field system which undergo gravitational collapse.

Counterexample to the third law: detailed statement of our theorem

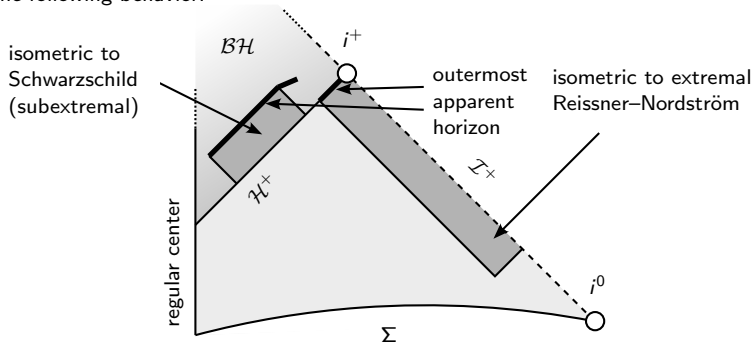
There exist **regular** solutions of the Einstein–Maxwell–charged scalar field system with the following behavior:



- Spherically symmetric Cauchy data for the Einstein–Maxwell–charged scalar field system which undergo gravitational collapse.
- Forms an exactly Schwarzschild “apparent horizon.”

Counterexample to the third law: detailed statement of our theorem

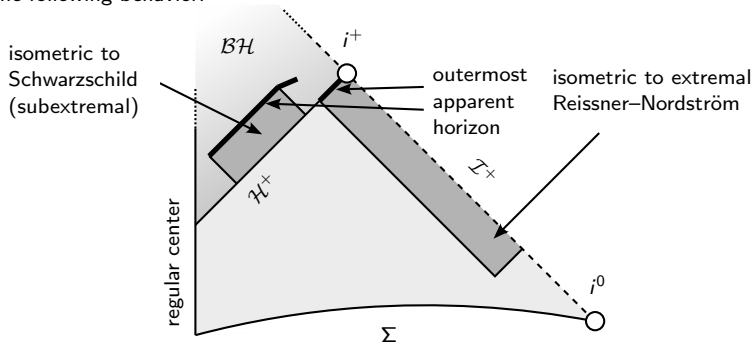
There exist **regular** solutions of the Einstein–Maxwell–charged scalar field system with the following behavior:



- ▶ Spherically symmetric Cauchy data for the Einstein–Maxwell–charged scalar field system which undergo gravitational collapse.
- ▶ Forms an exactly Schwarzschild “apparent horizon.”
- ▶ Forms an exactly extremal Reissner–Nordström event horizon at a later advanced time.

Counterexample to the third law: detailed statement of our theorem

There exist **regular** solutions of the Einstein–Maxwell–charged scalar field system with the following behavior:



- ▶ Spherically symmetric Cauchy data for the Einstein–Maxwell–charged scalar field system which undergo gravitational collapse.
- ▶ Forms an exactly Schwarzschild “apparent horizon.”
- ▶ Forms an exactly extremal Reissner–Nordström event horizon at a later advanced time.
- ▶ These solutions are arbitrarily **regular**: for any $k \in \mathbb{N}$, there exists a C^k example.

Einstein–Maxwell-charged scalar field system

- ▶ Lorentzian manifold (\mathcal{M}^{3+1}, g)
- ▶ 2-form $F = dA$ (electromagnetism)
- ▶ Charged (complex) scalar field ϕ

Einstein–Maxwell-charged scalar field system

- Lorentzian manifold (\mathcal{M}^{3+1}, g)
- 2-form $F = dA$ (electromagnetism)
- Charged (complex) scalar field ϕ
- Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2 \left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}} \right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\epsilon \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

Einstein–Maxwell-charged scalar field system

- Lorentzian manifold (\mathcal{M}^{3+1}, g)
- 2-form $F = dA$ (electromagnetism)
- Charged (complex) scalar field ϕ
- Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2 \left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}} \right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\mathfrak{e} \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

- In an appropriate gauge, this is a nonlinear hyperbolic system for (g, F, ϕ) .

Einstein–Maxwell-charged scalar field system

- ▶ Lorentzian manifold (\mathcal{M}^{3+1}, g)
- ▶ 2-form $F = dA$ (electromagnetism)
- ▶ Charged (complex) scalar field ϕ
- ▶ Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2 \left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}} \right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\mathfrak{e} \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

- ▶ In an appropriate gauge, this is a nonlinear hyperbolic system for (g, F, ϕ) .
- ▶ Can be thought of as an **initial value problem**.

Einstein–Maxwell-charged scalar field system

- ▶ Lorentzian manifold (\mathcal{M}^{3+1}, g)
- ▶ 2-form $F = dA$ (electromagnetism)
- ▶ Charged (complex) scalar field ϕ
- ▶ Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2 \left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}} \right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\epsilon \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

- ▶ In an appropriate gauge, this is a nonlinear hyperbolic system for (g, F, ϕ) .
- ▶ Can be thought of as an **initial value problem**.
- ▶ Spherical symmetry!

Einstein–Maxwell-charged scalar field system

- ▶ Lorentzian manifold (\mathcal{M}^{3+1}, g)
- ▶ 2-form $F = dA$ (electromagnetism)
- ▶ Charged (complex) scalar field ϕ
- ▶ Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2 \left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}} \right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\epsilon \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

- ▶ In an appropriate gauge, this is a nonlinear hyperbolic system for (g, F, ϕ) .
- ▶ Can be thought of as an **initial value problem**.
- ▶ Spherical symmetry! Scalar field ϕ degree of freedom required to break the rigidity of pure Einstein–Maxwell in spherical symmetry.

Einstein–Maxwell-charged scalar field system

- ▶ Lorentzian manifold (\mathcal{M}^{3+1}, g)
- ▶ 2-form $F = dA$ (electromagnetism)
- ▶ Charged (complex) scalar field ϕ
- ▶ Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2 \left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}} \right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\epsilon \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

- ▶ In an appropriate gauge, this is a nonlinear hyperbolic system for (g, F, ϕ) .
- ▶ Can be thought of as an **initial value problem**.
- ▶ Spherical symmetry! Scalar field ϕ degree of freedom required to break the rigidity of pure Einstein–Maxwell in spherical symmetry.
- ▶ Scalar field carries charge in order to charge up the black hole to extremality.

Einstein–Maxwell-charged scalar field system

- ▶ Lorentzian manifold (\mathcal{M}^{3+1}, g)
- ▶ 2-form $F = dA$ (electromagnetism)
- ▶ Charged (complex) scalar field ϕ
- ▶ Equations:

$$R_{\mu\nu}(g) - \frac{1}{2}R(g)g_{\mu\nu} = 2\left(T_{\mu\nu}^{\text{EM}} + T_{\mu\nu}^{\text{CSF}}\right) \quad (1)$$

$$\nabla^\mu F_{\mu\nu} = 2\mathfrak{e} \operatorname{Im}(\phi \overline{D_\nu \phi}) \quad (2)$$

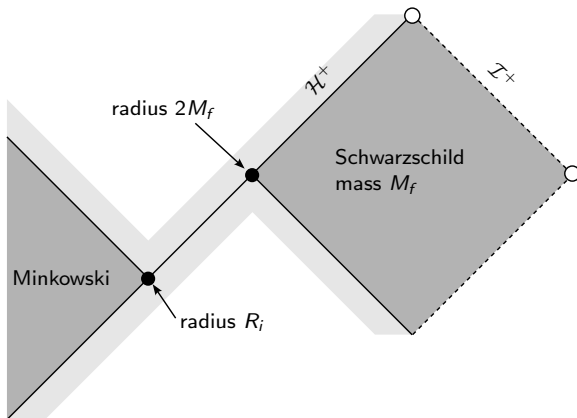
$$g^{\mu\nu} D_\mu D_\nu \phi = 0 \quad (3)$$

$$T_{\mu\nu}^{\text{EM}} = g^{\alpha\beta} F_{\alpha\nu} F_{\beta\mu} - \frac{1}{4} F^{\alpha\beta} F_{\alpha\beta} g_{\mu\nu} \quad (4)$$

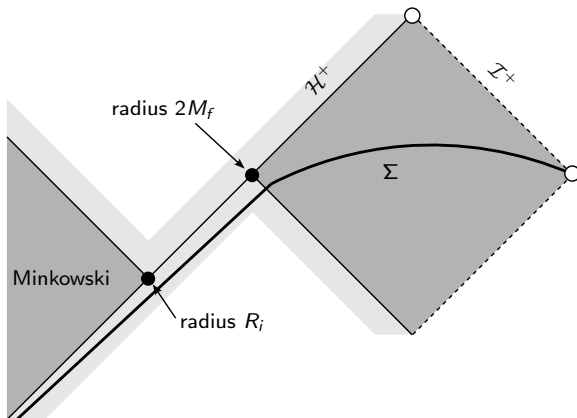
$$T_{\mu\nu}^{\text{CSF}} = \operatorname{Re}(D_\mu \phi \overline{D_\nu \phi}) - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} D_\alpha \phi \overline{D_\beta \phi} \quad (5)$$

- ▶ In an appropriate gauge, this is a nonlinear hyperbolic system for (g, F, ϕ) .
- ▶ Can be thought of as an **initial value problem**.
- ▶ Spherical symmetry! Scalar field ϕ degree of freedom required to break the rigidity of pure Einstein–Maxwell in spherical symmetry.
- ▶ Scalar field carries charge in order to charge up the black hole to extremality.
- ▶ Model satisfies the **dominant energy condition** (\implies **weak energy condition**).

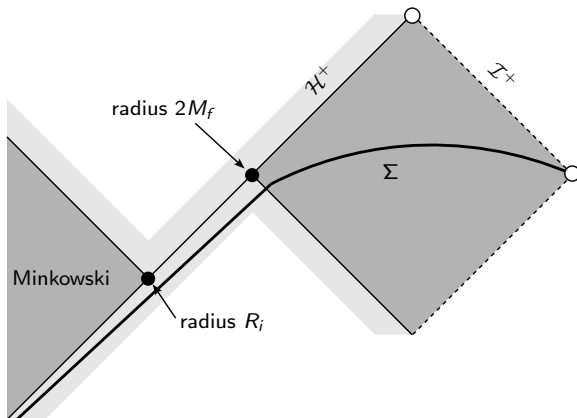
Prototype: Minkowski to Schwarzschild gluing



Prototype: Minkowski to Schwarzschild gluing

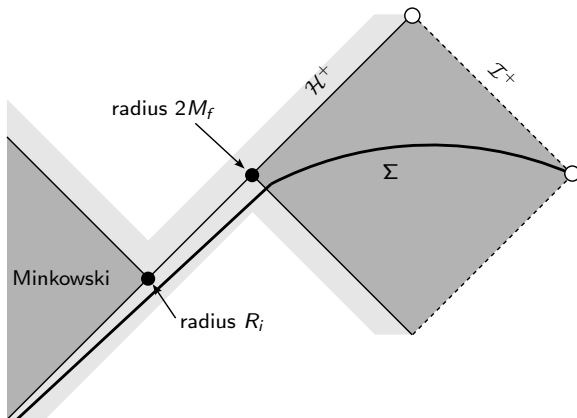


Prototype: Minkowski to Schwarzschild gluing



Characteristic gluing for the vacuum Einstein equations recently initiated in fundamental works of Aretakis–Czimek–Rodnianski and refined by Czimek–Rodnianski, but in a **perturbative** regime around Minkowski space which is inapplicable here.

Prototype: Minkowski to Schwarzschild gluing



Characteristic gluing for the vacuum Einstein equations recently initiated in fundamental works of Aretakis–Czimek–Rodnianski and refined by Czimek–Rodnianski, but in a **perturbative** regime around Minkowski space which is inapplicable here.

The present problem is fundamentally **nonlinear** and **nonperturbative**, but is tractable because of the symmetry assumption.

Toy model: gluing for the linear wave equation

We now fix a spacetime (\mathcal{M}^{3+1}, g) and consider the **linear wave equation**

$$\square_g \phi = 0 \tag{*}$$

Toy model: gluing for the linear wave equation

We now fix a spacetime (\mathcal{M}^{3+1}, g) and consider the **linear wave equation**

$$\square_g \phi = 0 \tag{*}$$

Question.

Given two domains $\mathfrak{R}_1, \mathfrak{R}_2 \subset \mathcal{M}$ and functions

$$\phi_1 : \mathfrak{R}_1 \rightarrow \mathbb{R}$$

$$\phi_2 : \mathfrak{R}_2 \rightarrow \mathbb{R}$$

solving (*)

Toy model: gluing for the linear wave equation

We now fix a spacetime (\mathcal{M}^{3+1}, g) and consider the **linear wave equation**

$$\square_g \phi = 0 \tag{*}$$

Question.

Given two domains $\mathfrak{R}_1, \mathfrak{R}_2 \subset \mathcal{M}$ and functions

$$\phi_1 : \mathfrak{R}_1 \rightarrow \mathbb{R}$$

$$\phi_2 : \mathfrak{R}_2 \rightarrow \mathbb{R}$$

solving (*), when does there exist a function

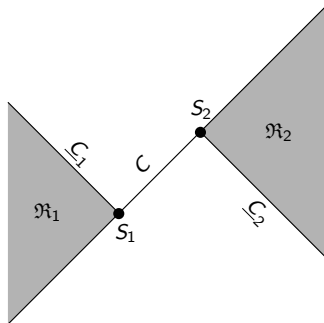
$$\phi : \mathcal{M} \rightarrow \mathbb{R}$$

solving (*), such that

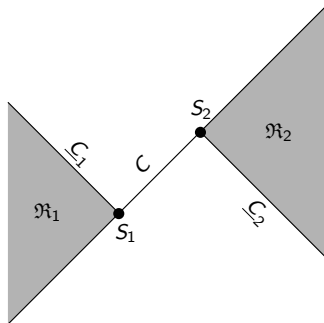
$$\phi|_{\mathfrak{R}_1} = \phi_1$$

$$\phi|_{\mathfrak{R}_2} = \phi_2 ?$$

Characteristic/null gluing for the linear wave equation



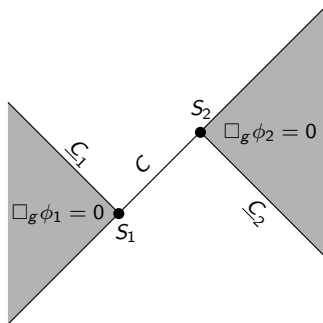
Characteristic/null gluing for the linear wave equation



Analogy:

- ▶ \mathfrak{R}_1 is Minkowski
- ▶ \mathfrak{R}_2 is Schwarzschild
- ▶ C will be the event horizon \mathcal{H}^+

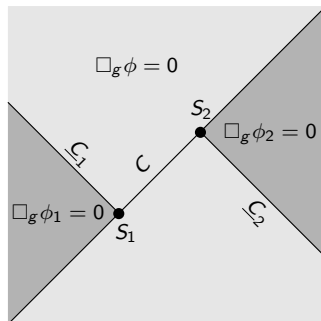
Characteristic/null gluing for the linear wave equation



Analogy:

- ▶ \mathfrak{R}_1 is Minkowski
- ▶ \mathfrak{R}_2 is Schwarzschild
- ▶ C will be the event horizon \mathcal{H}^+

Characteristic/null gluing for the linear wave equation



Analogy:

- ▶ \mathfrak{R}_1 is Minkowski
- ▶ \mathfrak{R}_2 is Schwarzschild
- ▶ C will be the event horizon \mathcal{H}^+

The characteristic initial value problem

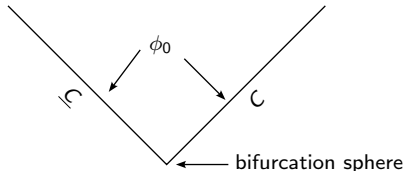
Bifurcate null hypersurface: $C \cup \underline{C}$ where C and \underline{C} meet transversally, $C \cap \underline{C} \approx S^2$

Proposition (Characteristic IVP for the wave equation).

Given a bifurcate null hypersurface $C \cup \underline{C}$ and $\phi_0 : C \cup \underline{C} \rightarrow \mathbb{R}$, there exists a unique function ϕ defined to the future of $C \cup \underline{C}$ such that

$$\square_g \phi = 0 \quad (*)$$

and $\phi|_{C \cup \underline{C}} = \phi_0$.



The characteristic initial value problem

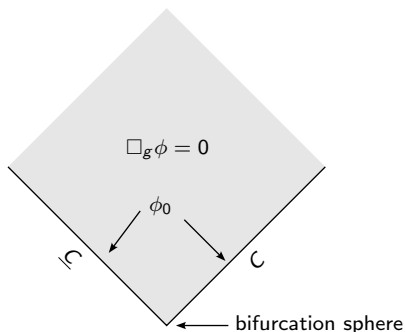
Bifurcate null hypersurface: $C \cup \underline{C}$ where C and \underline{C} meet transversally, $C \cap \underline{C} \approx S^2$

Proposition (Characteristic IVP for the wave equation).

Given a bifurcate null hypersurface $C \cup \underline{C}$ and $\phi_0 : C \cup \underline{C} \rightarrow \mathbb{R}$, there exists a unique function ϕ defined to the future of $C \cup \underline{C}$ such that

$$\square_g \phi = 0 \quad (*)$$

and $\phi|_{C \cup \underline{C}} = \phi_0$.



The characteristic initial value problem

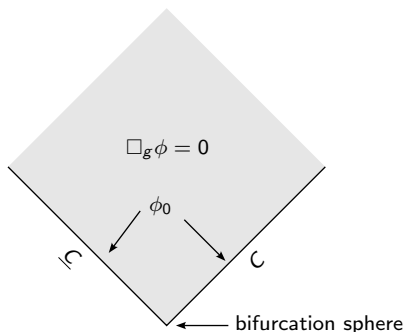
Bifurcate null hypersurface: $C \cup \underline{C}$ where C and \underline{C} meet transversally, $C \cap \underline{C} \approx S^2$

Proposition (Characteristic IVP for the wave equation).

Given a bifurcate null hypersurface $C \cup \underline{C}$ and $\phi_0 : C \cup \underline{C} \rightarrow \mathbb{R}$, there exists a unique function ϕ defined to the future of $C \cup \underline{C}$ such that

$$\square_g \phi = 0 \quad (*)$$

and $\phi|_{C \cup \underline{C}} = \phi_0$.



Characteristic data for the wave equation does not involve derivatives.

The null “constraints”

In any well posed initial value problem, there needs to be a mechanism to compute the full solution on the initial data hypersurface.

The null “constraints”

In any well posed initial value problem, there needs to be a mechanism to compute the full solution on the initial data hypersurface. Toy problem for the toy problem:

- ▶ Wave equation on Minkowski \mathbb{R}^{3+1}
- ▶ $u = t - r, v = t + r$ double null coordinates

The null “constraints”

In any well posed initial value problem, there needs to be a mechanism to compute the full solution on the initial data hypersurface. Toy problem for the toy problem:

- ▶ Wave equation on Minkowski \mathbb{R}^{3+1}
- ▶ $u = t - r$, $v = t + r$ double null coordinates
- ▶ $\phi = \phi(t, r, \vartheta, \varphi) = \phi(u, v, \vartheta, \varphi)$ satisfies

$$\square\phi = -\partial_t^2\phi + r^{-2}\partial_r(r^2\partial_r\phi) + \Delta\phi = 0$$

$$\partial_u\partial_v(r\phi) = \Delta(r\phi) \tag{*}$$

The null “constraints”

In any well posed initial value problem, there needs to be a mechanism to compute the full solution on the initial data hypersurface. Toy problem for the toy problem:

- ▶ Wave equation on Minkowski \mathbb{R}^{3+1}
- ▶ $u = t - r$, $v = t + r$ double null coordinates
- ▶ $\phi = \phi(t, r, \vartheta, \varphi) = \phi(u, v, \vartheta, \varphi)$ satisfies

$$\square\phi = -\partial_t^2\phi + r^{-2}\partial_r(r^2\partial_r\phi) + \Delta\phi = 0$$

$$\partial_u\partial_v(r\phi) = \Delta(r\phi) \quad (*)$$

- ▶ Integrate $(*)$ on C :

$$\partial_u(r\phi)|_{v_2} - \partial_u(r\phi)|_{v_1} = \int_{v_1}^{v_2} \Delta(r\phi) dv'$$

The null “constraints”

In any well posed initial value problem, there needs to be a mechanism to compute the full solution on the initial data hypersurface. Toy problem for the toy problem:

- ▶ Wave equation on Minkowski \mathbb{R}^{3+1}
- ▶ $u = t - r$, $v = t + r$ double null coordinates
- ▶ $\phi = \phi(t, r, \vartheta, \varphi) = \phi(u, v, \vartheta, \varphi)$ satisfies

$$\square\phi = -\partial_t^2\phi + r^{-2}\partial_r(r^2\partial_r\phi) + \Delta\phi = 0$$

$$\partial_u\partial_v(r\phi) = \Delta(r\phi) \quad (*)$$

- ▶ Integrate $(*)$ on C :

$$\partial_u(r\phi)|_{v_2} - \partial_u(r\phi)|_{v_1} = \int_{v_1}^{v_2} \Delta(r\phi) dv'$$

- ▶ $\implies \partial_u\phi|_C$ can be calculated from (1) $\partial_u\phi$ at the bifurcation sphere and (2) $\phi|_C$

The null “constraints”

In any well posed initial value problem, there needs to be a mechanism to compute the full solution on the initial data hypersurface. Toy problem for the toy problem:

- ▶ Wave equation on Minkowski \mathbb{R}^{3+1}
- ▶ $u = t - r$, $v = t + r$ double null coordinates
- ▶ $\phi = \phi(t, r, \vartheta, \varphi) = \phi(u, v, \vartheta, \varphi)$ satisfies

$$\square\phi = -\partial_t^2\phi + r^{-2}\partial_r(r^2\partial_r\phi) + \Delta\phi = 0$$

$$\partial_u\partial_v(r\phi) = \Delta(r\phi) \quad (*)$$

- ▶ Integrate $(*)$ on C :

$$\partial_u(r\phi)|_{v_2} - \partial_u(r\phi)|_{v_1} = \int_{v_1}^{v_2} \Delta(r\phi) dv'$$

- ▶ $\implies \partial_u\phi|_C$ can be calculated from (1) $\partial_u\phi$ at the bifurcation sphere and (2) $\phi|_C$
- ▶ $(*)$ lets us compute $\partial_u^i\phi$ on C to all orders

The null “constraints”

In general, the wave equation can be interpreted as a transport equation for the transverse derivative of ϕ , sourced by ϕ and tangential derivatives (which are a part of the characteristic data)

The null “constraints”

In general, the wave equation can be interpreted as a transport equation for the transverse derivative of ϕ , sourced by ϕ and tangential derivatives (which are a part of the characteristic data)

On C , the wave equation is equivalent to

$$(\partial_v + \text{known function})\partial_u\phi = \text{known function},$$

where “known function” depends on underlying geometry and data.

The null “constraints”

In general, the wave equation can be interpreted as a transport equation for the transverse derivative of ϕ , sourced by ϕ and tangential derivatives (which are a part of the characteristic data)

On C , the wave equation is equivalent to

$$(\partial_v + \text{known function})\partial_u\phi = \text{known function},$$

where “known function” depends on underlying geometry and data.

Commuting the wave equation with transverse derivatives gives an inductive system of transport equations for all orders!

The null “constraints”

In general, the wave equation can be interpreted as a transport equation for the transverse derivative of ϕ , sourced by ϕ and tangential derivatives (which are a part of the characteristic data)

On C , the wave equation is equivalent to

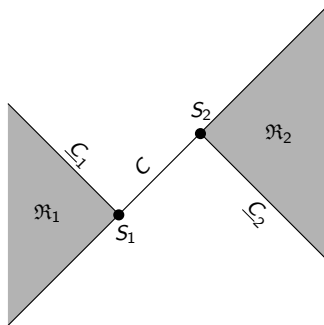
$$(\partial_v + \text{known function})\partial_u\phi = \text{known function},$$

where “known function” depends on underlying geometry and data.

Commuting the wave equation with transverse derivatives gives an inductive system of transport equations for all orders!

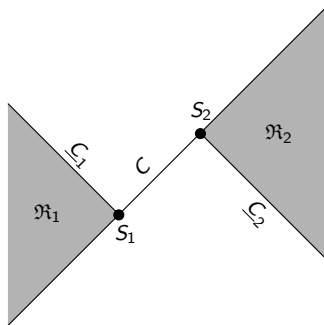
These equations have become known as the *null “constraints”*.

Back to characteristic gluing



The C^k characteristic gluing problem reduces to:

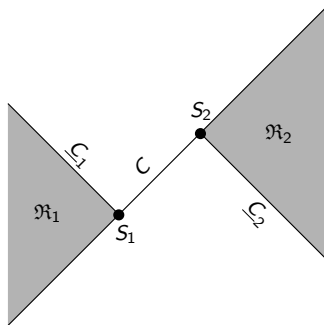
Back to characteristic gluing



The C^k characteristic gluing problem reduces to:

- ▶ Given two spheres S_1 and S_2 along an outgoing null cone C
- ▶ Given k ingoing and outgoing derivatives of ϕ at S_1 and S_2

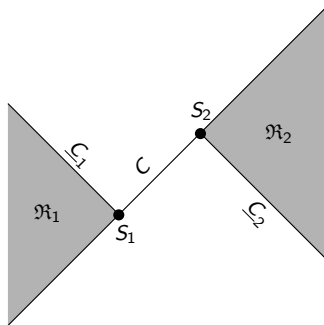
Back to characteristic gluing



The C^k characteristic gluing problem reduces to:

- ▶ Given two spheres S_1 and S_2 along an outgoing null cone C
- ▶ Given k ingoing and outgoing derivatives of ϕ at S_1 and S_2
- ▶ Prescribe ϕ along the part of C between S_1 and S_2 so that the outgoing derivatives agree with the given ones and the solutions of the transport equations for the ingoing derivatives have the specified initial and final values.

Back to characteristic gluing



The C^k characteristic gluing problem reduces to:

- ▶ Given two spheres S_1 and S_2 along an outgoing null cone C
- ▶ Given k ingoing and outgoing derivatives of ϕ at S_1 and S_2
- ▶ Prescribe ϕ along the part of C between S_1 and S_2 so that the outgoing derivatives agree with the given ones and the solutions of the transport equations for the ingoing derivatives have the specified initial and final values.
- ▶ Initial/boundary value problem for a system of coupled ODEs where you are allowed to (almost) freely prescribe the potential

Obstructions to characteristic gluing

- For the linear wave equation, not all solutions can be characteristically glued.

Obstructions to characteristic gluing

- ▶ For the linear wave equation, not all solutions can be characteristically glued.
- ▶ Example: Minkowski space

$$\partial_v \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

Obstructions to characteristic gluing

- For the linear wave equation, not all solutions can be characteristically glued.
- Example: Minkowski space

$$\partial_v \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

$\int_{S^2} \partial_u(r\phi) d\vartheta$ is conserved for any solution of the wave equation

Obstructions to characteristic gluing

- For the linear wave equation, not all solutions can be characteristically glued.
- Example: Minkowski space

$$\partial_v \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

$\int_{S^2} \partial_u(r\phi) d\vartheta$ is conserved for any solution of the wave equation

- Therefore, in general S_1 and S_2 have to satisfy compatibility conditions.

Obstructions to characteristic gluing

- For the linear wave equation, not all solutions can be characteristically glued.
- Example: Minkowski space

$$\partial_v \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

$\int_{S^2} \partial_u(r\phi) d\vartheta$ is conserved for any solution of the wave equation

- Therefore, in general S_1 and S_2 have to satisfy compatibility conditions.
- A complete geometric characterization of first order conservation laws for $\square_g \phi = 0$ was given by Aretakis '17.

Obstructions to characteristic gluing

- ▶ For the linear wave equation, not all solutions can be characteristically glued.
- ▶ Example: Minkowski space

$$\partial_v \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

$\int_{S^2} \partial_u(r\phi) d\vartheta$ is conserved for any solution of the wave equation

- ▶ Therefore, in general S_1 and S_2 have to satisfy compatibility conditions.
- ▶ A complete geometric characterization of first order conservation laws for $\square_g \phi = 0$ was given by Aretakis '17.
- ▶ These linear obstructions are a fundamental difficulty if one wishes to approach the nonlinear problem via linearization (as in Aretakis–Czimek–Rodnianski '21)

Obstructions to characteristic gluing

- ▶ For the linear wave equation, not all solutions can be characteristically glued.
- ▶ Example: Minkowski space

$$\partial_v \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

$\int_{S^2} \partial_u(r\phi) d\vartheta$ is conserved for any solution of the wave equation

- ▶ Therefore, in general S_1 and S_2 have to satisfy compatibility conditions.
- ▶ A complete geometric characterization of first order conservation laws for $\square_g \phi = 0$ was given by Aretakis '17.
- ▶ These linear obstructions are a fundamental difficulty if one wishes to approach the nonlinear problem via linearization (as in Aretakis–Czimek–Rodnianski '21)
- ▶ The linearized Einstein equations around Minkowski space and extremal Reissner–Nordström have conservation laws of the above type.

Obstructions to characteristic gluing

- ▶ For the linear wave equation, not all solutions can be characteristically glued.
- ▶ Example: Minkowski space

$$\partial_\nu \int_{S^2} \partial_u(r\phi) d\vartheta = \int_{S^2} \Delta(r\phi) d\vartheta = 0$$

$\int_{S^2} \partial_u(r\phi) d\vartheta$ is conserved for any solution of the wave equation

- ▶ Therefore, in general S_1 and S_2 have to satisfy compatibility conditions.
- ▶ A complete geometric characterization of first order conservation laws for $\square_g \phi = 0$ was given by Aretakis '17.
- ▶ These linear obstructions are a fundamental difficulty if one wishes to approach the nonlinear problem via linearization (as in Aretakis–Czimek–Rodnianski '21)
- ▶ The linearized Einstein equations around Minkowski space and extremal Reissner–Nordström have conservation laws of the above type.
- ▶ By exploiting “high frequency” perturbations, Czimek–Rodnianski '22 have shown how to avoid some of the conservation laws in the perturbative regime around Minkowski space.
- ▶ We completely avoid these conservation laws by having a fully nonperturbative mechanism.

Einstein-scalar field in spherical symmetry

► $\mathcal{M}^{3+1} = \mathcal{Q}^{1+1} \times S^2$

$$g = -\Omega^2 du dv + r^2 g_{S^2}$$

► $\Omega(u, v) > 0$ lapse, $r(u, v) > 0$ area-radius

Einstein-scalar field in spherical symmetry

► $\mathcal{M}^{3+1} = \mathcal{Q}^{1+1} \times S^2$

$$g = -\Omega^2 du dv + r^2 g_{S^2}$$

► $\Omega(u, v) > 0$ lapse, $r(u, v) > 0$ area-radius

► Wave equations

$$\partial_u \partial_v \phi = -\frac{\partial_u \phi \partial_v r}{r} - \frac{\partial_u r \partial_v \phi}{r} \quad (6)$$

$$\partial_u \partial_v r = -\frac{\Omega^2}{4r} - \frac{\partial_u r \partial_v r}{r} \quad (7)$$

$$\partial_u \partial_v \log(\Omega^2) = \frac{\Omega^2}{2r^2} + 2 \frac{\partial_u r \partial_v r}{r^2} \quad (8)$$

Einstein-scalar field in spherical symmetry

► $\mathcal{M}^{3+1} = \mathcal{Q}^{1+1} \times S^2$

$$g = -\Omega^2 du dv + r^2 g_{S^2}$$

► $\Omega(u, v) > 0$ lapse, $r(u, v) > 0$ area-radius

► Wave equations

$$\partial_u \partial_v \phi = -\frac{\partial_u \phi \partial_v r}{r} - \frac{\partial_u r \partial_v \phi}{r} \quad (6)$$

$$\partial_u \partial_v r = -\frac{\Omega^2}{4r} - \frac{\partial_u r \partial_v r}{r} \quad (7)$$

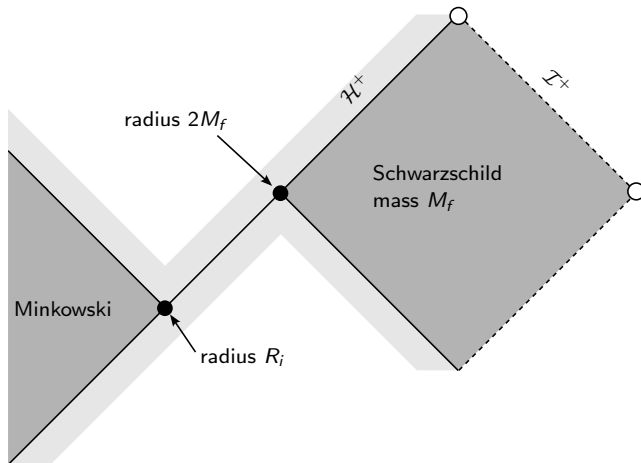
$$\partial_u \partial_v \log(\Omega^2) = \frac{\Omega^2}{2r^2} + 2 \frac{\partial_u r \partial_v r}{r^2} \quad (8)$$

► Raychaudhuri's equations (constraints)

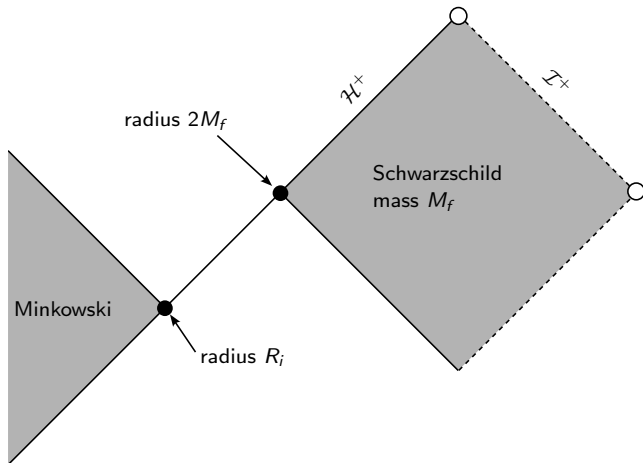
$$\partial_u \left(\frac{\partial_u r}{\Omega^2} \right) = -\frac{r}{\Omega^2} (\partial_u \phi)^2 \quad (9)$$

$$\partial_v \left(\frac{\partial_v r}{\Omega^2} \right) = -\frac{r}{\Omega^2} (\partial_v \phi)^2 \quad (10)$$

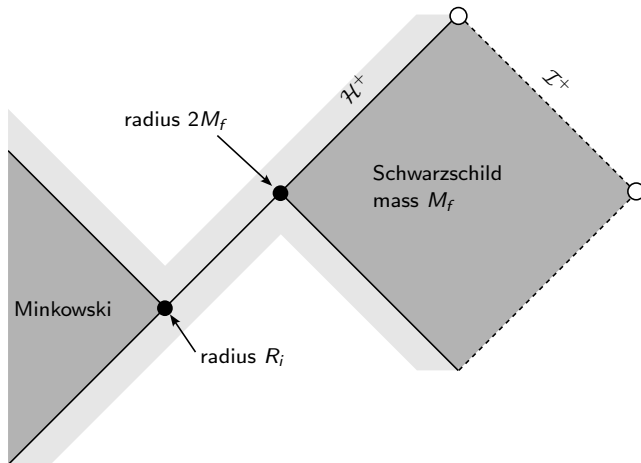
Minkowski to Schwarzschild gluing



Minkowski to Schwarzschild gluing



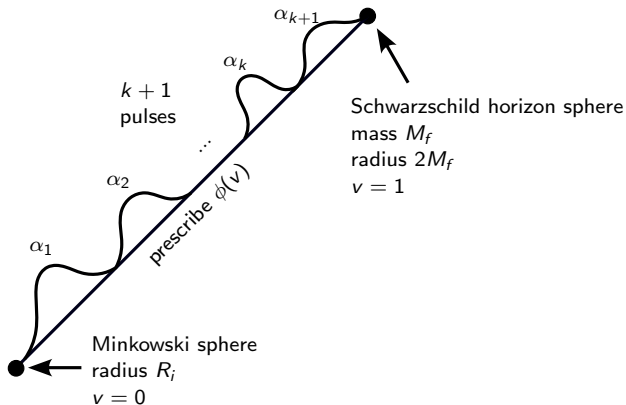
Minkowski to Schwarzschild gluing



Minkowski to Schwarzschild gluing

Theorem (Kehle–U. '22).

For any $k \in \mathbb{N}$ and $0 < R_i < 2M_f$, the Minkowski sphere of radius R_i can be characteristically glued to the Schwarzschild event horizon sphere with mass M_f to order C^k within the Einstein-scalar field model in spherical symmetry.



Idea of the proof

- Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$
- ▶ Initialize $r(v)$ teleologically at $v = 1$ ($\partial_v r(0)$ is a gauge choice, but $\partial_v r(1) = 0!$)

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$
- ▶ Initialize $r(v)$ teleologically at $v = 1$ ($\partial_v r(0)$ is a gauge choice, but $\partial_v r(1) = 0!$)
- ▶ For each α , generate $r(v)$, $\partial_u r(v)$, $\partial_u \phi_\alpha(v)$, etc.

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$
- ▶ Initialize $r(v)$ teleologically at $v = 1$ ($\partial_v r(0)$ is a gauge choice, but $\partial_v r(1) = 0!$)
- ▶ For each α , generate $r(v)$, $\partial_u r(v)$, $\partial_u \phi_\alpha(v)$, etc.
- ▶ The antipodal map $\alpha \mapsto -\alpha$ leaves geometric quantities fixed (r , Ω^2 , and derivatives)

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$
- ▶ Initialize $r(v)$ teleologically at $v = 1$ ($\partial_v r(0)$ is a gauge choice, but $\partial_v r(1) = 0!$)
- ▶ For each α , generate $r(v)$, $\partial_u r(v)$, $\partial_u \phi_\alpha(v)$, etc.
- ▶ The antipodal map $\alpha \mapsto -\alpha$ leaves geometric quantities fixed (r , Ω^2 , and derivatives)
- ▶ The antipodal map $\alpha \mapsto -\alpha$ changes the sign of the scalar field and its derivatives

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$
- ▶ Initialize $r(v)$ teleologically at $v = 1$ ($\partial_v r(0)$ is a gauge choice, but $\partial_v r(1) = 0!$)
- ▶ For each α , generate $r(v)$, $\partial_u r(v)$, $\partial_u \phi_\alpha(v)$, etc.
- ▶ The antipodal map $\alpha \mapsto -\alpha$ leaves geometric quantities fixed (r , Ω^2 , and derivatives)
- ▶ The antipodal map $\alpha \mapsto -\alpha$ changes the sign of the scalar field and its derivatives
- ▶ In particular, the map

$$\alpha \mapsto \left(\partial_u \phi_\alpha(1), \dots, \partial_u^k \phi_\alpha(1) \right)$$

Idea of the proof

- ▶ Null constraint system becomes a coupled nonlinear system of ODEs sourced by $\phi(v)$
- ▶ Scalar field ansatz

$$\phi_\alpha(v) = \sum_{1 \leq j \leq k+1} \alpha_j \chi_j(v), \quad \alpha \in \mathbb{R}^{k+1}$$

- ▶ Initialize $\partial_u \phi_\alpha(0) = \dots = \partial_u^k \phi_\alpha(0) = 0$
- ▶ Initialize $r(v)$ teleologically at $v = 1$ ($\partial_v r(0)$ is a gauge choice, but $\partial_v r(1) = 0!$)
- ▶ For each α , generate $r(v)$, $\partial_u r(v)$, $\partial_u \phi_\alpha(v)$, etc.
- ▶ The antipodal map $\alpha \mapsto -\alpha$ leaves geometric quantities fixed (r , Ω^2 , and derivatives)
- ▶ The antipodal map $\alpha \mapsto -\alpha$ changes the sign of the scalar field and its derivatives
- ▶ In particular, the map

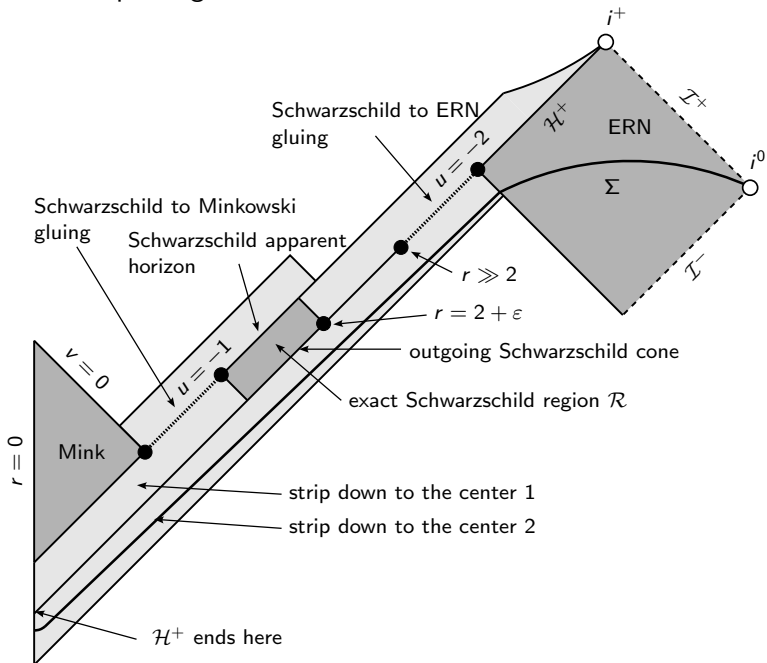
$$\alpha \mapsto \left(\partial_u \phi_\alpha(1), \dots, \partial_u^k \phi_\alpha(1) \right)$$

is odd

- ▶ **Borsuk–Ulam theorem:** there exists α_* such that

$$\left(\partial_u \phi_{\alpha_*}(1), \dots, \partial_u^k \phi_{\alpha_*}(1) \right) = 0.$$

Blueprint to disproving the third law



Future work: the vacuum case

We believe that matter is not necessary to provide a counterexample to the third law:

Future work: the vacuum case

We believe that matter is not necessary to provide a counterexample to the third law:

Conjecture.

There exist Cauchy data for the Einstein vacuum equations

$$R_{\mu\nu} = 0$$

which undergo gravitational collapse and form an exactly Schwarzschild apparent horizon, only for the spacetime to form an exactly extremal Kerr event horizon at a later advanced time. In particular, already in vacuum, the “third law of black hole thermodynamics” is false.

Future work: the vacuum case

We believe that matter is not necessary to provide a counterexample to the third law:

Conjecture.

There exist Cauchy data for the Einstein vacuum equations

$$R_{\mu\nu} = 0$$

which undergo gravitational collapse and form an exactly Schwarzschild apparent horizon, only for the spacetime to form an exactly extremal Kerr event horizon at a later advanced time. In particular, already in vacuum, the “third law of black hole thermodynamics” is false.

This would follow from characteristic gluing, in vacuum, of a Minkowski sphere to a Kerr horizon sphere.

Future work: the vacuum case

We believe that matter is not necessary to provide a counterexample to the third law:

Conjecture.

There exist Cauchy data for the Einstein vacuum equations

$$R_{\mu\nu} = 0$$

which undergo gravitational collapse and form an exactly Schwarzschild apparent horizon, only for the spacetime to form an exactly extremal Kerr event horizon at a later advanced time. In particular, already in vacuum, the “third law of black hole thermodynamics” is false.

This would follow from characteristic gluing, in vacuum, of a Minkowski sphere to a Kerr horizon sphere. No symmetry reductions are possible.

Future work: the vacuum case

We believe that matter is not necessary to provide a counterexample to the third law:

Conjecture.

There exist Cauchy data for the Einstein vacuum equations

$$R_{\mu\nu} = 0$$

which undergo gravitational collapse and form an exactly Schwarzschild apparent horizon, only for the spacetime to form an exactly extremal Kerr event horizon at a later advanced time. In particular, already in vacuum, the “third law of black hole thermodynamics” is false.

This would follow from characteristic gluing, in vacuum, of a Minkowski sphere to a Kerr horizon sphere. No symmetry reductions are possible.

Theorem (Kehle–U. forthcoming).

For any $a/M \ll 1$, Minkowski space can be characteristically glued to the event horizon of a Kerr black hole with parameters M and a .

Future work: critical behavior near extremality

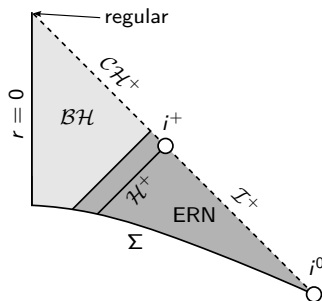
Theorem (Kehle–U.).

There exists a solution of the EMCSF system with the following Penrose diagram and containing no trapped surfaces.

Future work: critical behavior near extremality

Theorem (Kehle–U.).

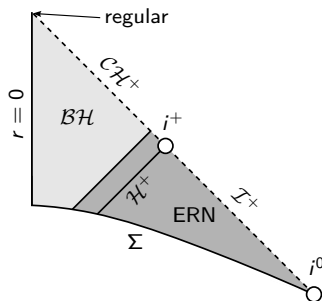
There exists a solution of the EMCSF system with the following Penrose diagram and containing no trapped surfaces.



Future work: critical behavior near extremality

Theorem (Kehle–U.).

There exists a solution of the EMCSF system with the following Penrose diagram and containing no trapped surfaces.

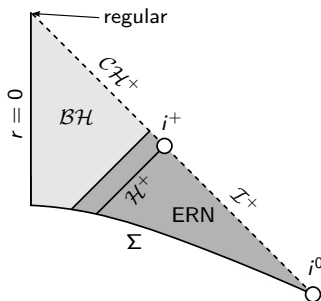


Spacetimes with this diagram are expected to be nongeneric (Van de Moortel '19).

Future work: critical behavior near extremality

Theorem (Kehle–U.).

There exists a solution of the EMCSF system with the following Penrose diagram and containing no trapped surfaces.



Spacetimes with this diagram are expected to be nongeneric (Van de Moortel '19).

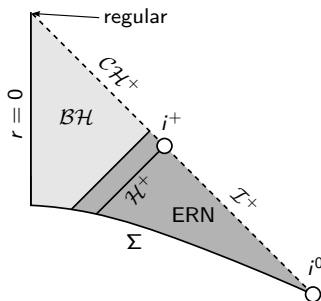
Conjecture.

There exist regular Cauchy data for the Einstein–Maxwell–charged scalar field system, leading to the formation of an extremal Reissner–Nordström black hole, that can be perturbed to disperse, i.e. no black hole forms.

Future work: critical behavior near extremality

Theorem (Kehle–U.).

There exists a solution of the EMCSF system with the following Penrose diagram and containing no trapped surfaces.



Spacetimes with this diagram are expected to be nongeneric (Van de Moortel '19).

Conjecture.

There exist regular Cauchy data for the Einstein–Maxwell–charged scalar field system, leading to the formation of an extremal Reissner–Nordström black hole, that can be perturbed to disperse, i.e. no black hole forms.

Critical behavior: the very black-holeness of certain spacetimes is unstable.

Questions related to characteristic gluing

Questions related to characteristic gluing

- Are there actually any obstructions to nonlinear gluing?

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved. The third law cannot be violated in axisymmetry.

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved.
The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved.
The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved.
The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.
 - ▶ Conjecture: a generic spacetime has no conservation laws at the linear level.

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved.
The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.
 - ▶ Conjecture: a generic spacetime has no conservation laws at the linear level.
- ▶ The current approach to characteristic gluing operates at finite regularity in u -derivatives. Is there a better way of doing the problem?

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved. The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.
 - ▶ Conjecture: a generic spacetime has no conservation laws at the linear level.
- ▶ The current approach to characteristic gluing operates at finite regularity in u -derivatives. Is there a better way of doing the problem?
 - ▶ Computations become extremely cumbersome when trying to glue to high order in u -derivatives. Is there a systematic way of approaching this for nonlinear problems?

Questions related to characteristic gluing

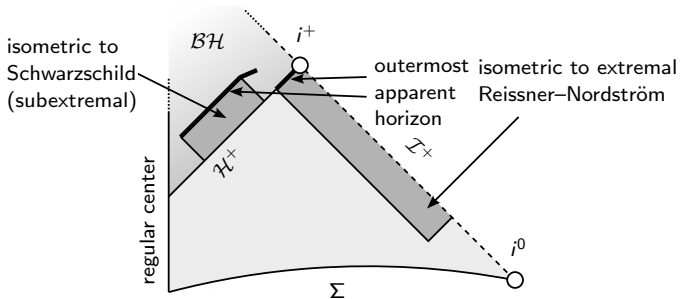
- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved. The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.
 - ▶ Conjecture: a generic spacetime has no conservation laws at the linear level.
- ▶ The current approach to characteristic gluing operates at finite regularity in u -derivatives. Is there a better way of doing the problem?
 - ▶ Computations become extremely cumbersome when trying to glue to high order in u -derivatives. Is there a systematic way of approaching this for nonlinear problems?
 - ▶ The number of conservation laws might be dependent on the number of u -derivatives one wishes to glue.

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved. The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.
 - ▶ Conjecture: a generic spacetime has no conservation laws at the linear level.
- ▶ The current approach to characteristic gluing operates at finite regularity in u -derivatives. Is there a better way of doing the problem?
 - ▶ Computations become extremely cumbersome when trying to glue to high order in u -derivatives. Is there a systematic way of approaching this for nonlinear problems?
 - ▶ The number of conservation laws might be dependent on the number of u -derivatives one wishes to glue.
 - ▶ Is C^∞ characteristic gluing even possible?

Questions related to characteristic gluing

- ▶ Are there actually any obstructions to nonlinear gluing?
 - ▶ Obstruction 1: Monotonicity from Raychaudhuri's equation—if S_1 is trapped then S_2 has to be trapped as well.
 - ▶ Obstruction 2: If no charged matter is present, then charge is conserved, even nonlinearly. Angular momentum is required to violate the third law in (electro-)vacuum.
 - ▶ Obstruction 3: In axisymmetry, angular momentum is conserved. The third law cannot be violated in axisymmetry.
- ▶ Is there a general geometric characterization of conservation laws associated to the linearized Einstein equations?
 - ▶ Want some relatively gauge-invariant answer.
 - ▶ Conjecture: a generic spacetime has no conservation laws at the linear level.
- ▶ The current approach to characteristic gluing operates at finite regularity in u -derivatives. Is there a better way of doing the problem?
 - ▶ Computations become extremely cumbersome when trying to glue to high order in u -derivatives. Is there a systematic way of approaching this for nonlinear problems?
 - ▶ The number of conservation laws might be dependent on the number of u -derivatives one wishes to glue.
 - ▶ Is C^∞ characteristic gluing even possible?



Thank you!