## **Entropy and KL Divergence**

From https://www.youtube.com/watch?v=KHVR587oW8I

## **Entropy**

- Entropy can be thought of as average surprise
- Before you toss a coin, suppose someone predicts it lands on tails
  - You would be surprised, but not that surprised
- Before you roll a dice, suppose someone predicts it lands on 1
  - You would be a lot more surprised
- To formalize this, we have an idea of a "surprise" function that indicates how surprised you are to see a certain state *s*:
  - $\circ \ \ h(s)$  should be a function of  $p_s$
  - $\circ$  Should be high for small values of  $p_s$  and low for large values
  - o If we see three events we are surprised at, the surprise should be 3x as much
    - However, the probabilities were multiplied instead of added together
    - Therefore, when probabilities multiply, surprise should add
- ullet This leads to  $h(s) = -\log p_s$  for a single state s
- The expected surprise for a whole distribution would be:

$$H = \sum_s -p_s \log(p_s) = \mathbb{E}\left[-\log p_s
ight]$$

## **Cross-Entropy**

- When we see real world events, we don't have the exact probability model that we can use to compute entropy
- Instead, we have an internal model, and we compute surprise based on that
- Cross-entropy is H(P,Q), which is the average surprise you will get by observing a random variable governed by P, but you believe in Q

$$H(P,Q) = \sum_s -p_s \log q_s$$

- If P and Q are the same, this just becomes normal entropy
  - $\circ H(P,Q) \geq H(P)$ , so you can never be less surprised than if you had just known the true model directly
- This is **not** symmetric

## **KL Divergence**

- How can we quantify the difference between two distributions P and Q?
  - We have cross entropy, but this is already shifted up by a baseline for how surprised we are from just viewing the model P directly
- We can get a more general difference by taking:

$$D_{KL}(P||Q) = H(P,Q) - H(P) = \sum_s p_s \log\left(rac{p_s}{q_s}
ight)$$