

# Non Bayesian Parameter Estimation

In many problems, it is unnatural to assign a prior distribution to the latent variable of interest

- We instead treat it as deterministic, but unknown
- Instead of having observation models conditioned on some variable  $x$ , we instead have it be parameterized by  $x$ 
  - This is the notation  $p(y|x)$  versus  $p(y; x)$

The first thing to note is that if we look at our previous formulation of BLS:

$$\hat{x} = \arg \min_f \mathbb{E} [(x - f(y))^2]$$

- However since  $x$  is now fixed, we have this is minimized when we just choose  $f(y) = x$
- We can't do this!
- We need to restrict our search to valid estimators that are just statistics of the data

Estimators themselves are functions  $\hat{x}(y)$ :

- Their bias and variance are functions of  $x$  because we take the expectation over all possible  $y$

For the beginning, we will focus on just scalar values of  $x$  (but  $y$  can be vector valued)

## Minimum Variance Unbiased (MVU) Estimators

### ■ MVU

A MVU estimator  $\hat{x}_*$  is an estimator such that it has 0 bias and of all estimators that have 0 bias, it has the minimum variance  $\lambda_{\hat{x}}(x)$  for every possible  $x$

This could potentially not exist if:

- There are no unbiased estimators
- There are no estimators that uniformly have lower variance for all  $x$

In general, there is no systematic procedure to find these or determine if they exist

## Cramer-Rao Bound

### ■ Cramer-Rao Bound (Scalar Version)

Suppose  $p_y(y; \cdot)$  for every  $y$  is positive and differentiable on  $\mathcal{X} \in \mathbb{R}$  and satisfies the regularity condition for all  $x$ :

$$\mathbb{E} \left[ \frac{\partial}{\partial x} \ln p_y(y; x) \right]$$

Then for any unbiased  $\hat{x}(\cdot)$ :

$$\lambda_{\hat{x}}(x) \geq \frac{1}{J_y(x)}$$

where  $J_y(X)$  is the Fisher information in  $y$  about  $x$ :

$$J_y(x) = \mathbb{E} [S(y; x)^2]$$

where  $S(y; x)$  is the score function for  $x$  based on  $y$ :

$$S(y; x) = \frac{\partial}{\partial x} \ln p_y(y; x)$$

With an extra regularity condition, we can express the Fisher information as:

### Corollary

If  $p_y(y; \cdot)$  also satisfies the regularity condition:

$$\mathbb{E} \left[ \left( \frac{\partial}{\partial x} \ln p_y(y; x) \right)^2 + \frac{\partial^2}{\partial x^2} \ln p_y(y; x) \right] = 0$$

then the Fisher information can also be expressed as:

$$J_y(x) = -\mathbb{E} \left[ \frac{\partial^2}{\partial x^2} \ln p_y(y; x) \right]$$