

1. Comparing the Efficiency of Sequential Search on Ordered and Unordered Tables

1(a). No Record with the Key Target is Present

- **Unordered Table:**
 - **Worst-case Time Complexity:** $O(n)$
 - You have to search through all n elements to determine that the key is not present.
- **Ordered Table:**
 - **Worst-case Time Complexity:** $O(n)$
 - Even though the table is ordered, a sequential search will still require scanning all elements to determine the key is not present.
- **Conclusion:** Both ordered and unordered tables have the same worst-case time complexity of $O(n)$ when the target key is not present.

1(b). One Record with the Key Target is Present and Only One is Sought

- **Unordered Table:**
 - **Average-case Time Complexity:** $O(n/2)=O(n)$
 - On average, you will find the key after searching through half of the table.
- **Ordered Table:**
 - **Average-case Time Complexity:** $O(n/2)=O(n)$
 - Even though the table is ordered, sequential search does not benefit from this ordering, so it also takes on average $n/2$ comparisons.
- **Conclusion:** Both ordered and unordered tables have the same average-case time complexity of $O(n)$ when searching for a single key.

2. Sequential Search with Multiple Records with the Same Key

2(a). Finding Only the First Record with the Key Target

- **Unordered Table:**
 - **Average-case Time Complexity:** $O(n/2)=O(n)$
 - You search through the table until you find the first occurrence of the key.
- **Ordered Table:**
 - **Average-case Time Complexity:** $O(n/2)=O(n)$

- Even though the table is ordered, finding the first occurrence of the key still requires scanning sequentially through the elements.
- **Conclusion:** Both ordered and unordered tables have the same average-case time complexity of $O(n)$ for finding the first occurrence of the key.

2(b). Finding All Records with the Key Target

- **Unordered Table:**
 - **Worst-case Time Complexity:** $O(n)$
 - You need to search through all elements to find all occurrences of the key.
- **Ordered Table:**
 - **Worst-case Time Complexity:** $O(n)$
 - Even though the table is ordered, sequential search will still require checking all elements to find all occurrences of the key.
- **Conclusion:** Both ordered and unordered tables have the same worst-case time complexity of $O(n)O(n)O(n)$ for finding all occurrences of the key.

3. Delete Method for a Binary Search Tree (BST)

Pseudo-code for `delete(key1, key2):`

```
function delete(key1, key2)
    function deleteNode(root, key)
        if root is null
            return null
        if key < root.key
            root.left = deleteNode(root.left, key)
        else if key > root.key
            root.right = deleteNode(root.right, key)
        else
            if root.left is null
                return root.right
            else if root.right is null
                return root.left
            minLargerNode = findMin(root.right)
            root.key = minLargerNode.key
            root.right = deleteNode(root.right, minLargerNode.key)
        return root

    function findMin(node)
        while node.left is not null
            node = node.left
        return node
```

```

function rangeDelete(root, key1, key2)
if root is null
    return null
if root.key > key2
    root.left = rangeDelete(root.left, key1, key2)
else if root.key < key1
    root.right = rangeDelete(root.right, key1, key2)
else
    root.left = rangeDelete(root.left, key1, key2)
    root.right = rangeDelete(root.right, key1, key2)
    root = deleteNode(root, root.key)
return root

root = rangeDelete(root, key1, key2)
return root

```

This method recursively traverses the tree, deletes nodes whose keys fall within the range `[key1, key2]`, and restructures the tree accordingly.

4. Delete a Record from a B-Tree of Order n

Pseudo-code for `delete(key)` in a B-Tree:

```

function delete(key)
    node = findNode(key)
    if node is a leaf
        delete key from node
    if node underflows
        fixUnderflow(node)
    else
        predecessor = findPredecessor(key)
        swap key with predecessor
        delete(predecessor)

function fixUnderflow(node)
    if node has a sibling with more than the minimum number of keys
        borrow a key from sibling
    else
        merge node with a sibling
        if parent underflows

```

```
fixUnderflow(parent)

function findNode(key)
    // Traverse the B-Tree to find the node containing the key

function findPredecessor(key)
    // Find the predecessor key in the subtree
```

This method first locates the node containing the key, then handles the deletion depending on whether the node is a leaf or an internal node. It also ensures that the B-Tree properties are maintained after deletion, by fixing underflows through borrowing keys or merging nodes as necessary.