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function [xopt, fopt, exitflag, output] = optimize_spring()

% -----Starting point and bounds-----
%var= d D n hf    %design variables
x0 = [0.01, 0.01, 1, 1]; %starting point
ub = [0.2, 1, 50, 10]; %upper bound
lb = [0.01,0.01,1,1.0]; %lower bound

% -----Linear constraints-----
A = [];
b = [];
Aeq = [];
beq = [];

% -----Objective and Non-linear Constraints-----
function [f, c, ceq] = objcon(x)

    %design variables
    d = x(1); % height (in)
    D = x(2); % diameter (in)
    n = x(3); % number of coils (treating as continuous for this example)
    hf = x(4); % free height (in)

    % Constants
    G = 12e6; % psi
    Se = 45000; % psi
    w = 0.18;
    Sf = 1.5;
    Q= 150000; % psi

    % Analysis variables
    h0 = 1.0; % preload height
    delta0 = 0.4;

    % Output variables
    hdef = h0-delta0;
    k = (G*d^4)/(8*D^3*n);
    K = (4*D-d)/(4*(D-d))+0.62*d/D;
    F_h0 = k*(hf-h0); %Fmin
    F_hdef = k*(hf-hdef); %Fmax
    tauh0 = (8*F_h0*D)/(pi*d^3)*K; %taumin
    tauhdef = (8*F_hdef*D)/(pi*d^3)*K; %taumax

    taumean = (tauhdef+tauh0)/2;
    tauavg = (tauhdef-tauh0)/2;

    hs = n*d;
    Fhs = k*(hf-hs);
    tauhs = (8*Fhs*D)/(pi*d^3)*K;

    Sy = 0.44*Q/(d^w);

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%objective function
f = -F_h0; %maximize F_h0

%inequality constraints (c<=0)
c = zeros(7,1); % create column vector
c(1) = (tauhs - Sy)/1e4; %scaled
c(2) = (tauavg - (Se/Sf))/1e4; %scaled
c(3) = (tauavg+taumean)-(Sy/Sf);
c(4) = (D/d)-16;
c(5) = 4-(D/d);
c(6) = (D+d) - 0.75;
c(7) = hs - (hdef-0.05);
%equality constraints (ceq=0)
ceq = [];

end

% -----Call fmincon-----
options = optimoptions(@fmincon,'display','iter-detailed','Diagnostics','on');
[xopt, fopt, exitflag, output] = fmincon(@obj, x0, A, b, Aeq, beq, lb, ub, @co
xopt %design variables at the minimum
fopt %objective function value at the minumum fopt = f(xopt)
[f,c,ceq] = objcon(xopt);
c
%contour_plot(xopt(3),xopt(4));

% -----Separate obj/con (do not change)-----
function [f] = obj(x)
    [f, ~, ~] = objcon(x);
end
function [c, ceq] = con(x)
    [~, c, ceq] = objcon(x);
end
end
end

```

Your initial point x_0 is not between bounds lb and ub ; FMINCON shifted x_0 to strictly satisfy the bounds.

Diagnostic Information

Number of variables: 4

Functions

Objective:

Gradient:

Hessian:

Nonlinear constraints:

optimize_spring/obj

finite-differencing

finite-differencing (or Quasi-Newton

optimize_spring/con

Nonlinear constraints gradient: *finite-differencing*

Constraints

Number of nonlinear inequality constraints: 7

Number of nonlinear equality constraints: 0

Number of linear inequality constraints: 0

Number of linear equality constraints: 0

Number of lower bound constraints: 4

Number of upper bound constraints: 4

Algorithm selected

interior-point

End diagnostic information

Iter	F-count	$f(x)$	Feasibility	First-order optimality	Norm of step
0	5	-6.567827e+02	1.565e+06	1.137e+05	
1	10	-6.867149e+02	1.092e+06	5.648e+04	3.049e-01
2	15	-6.540337e+02	8.646e+05	4.126e+04	6.016e-01
3	20	-6.320025e+02	8.486e+05	4.112e+04	9.827e-03
4	25	-2.251413e+02	5.436e+05	4.034e+04	7.968e-02
5	30	-2.230312e+02	5.420e+05	4.038e+04	1.070e-03
6	35	-2.230193e+02	5.420e+05	4.038e+04	4.212e-06
7	40	-3.623346e+00	1.304e+05	5.711e+04	1.756e+00
8	45	-1.438662e-01	5.094e+00	6.205e+04	3.743e-01
9	50	-1.426911e-01	5.100e+00	6.604e+02	1.643e-03
10	55	-9.617007e-02	4.607e+00	1.132e+03	9.210e-02
11	60	-9.595835e-02	4.580e+00	1.139e+03	7.258e-03
12	65	-9.856008e-04	2.522e+00	1.122e+03	3.697e-01
13	70	-4.961714e-06	2.498e+00	1.127e+03	9.421e-04
14	75	-2.483553e-08	2.492e+00	1.128e+03	1.008e-03
15	80	-4.194285e-06	4.402e-01	1.150e+03	4.307e-01
16	85	-9.380372e-06	1.427e-02	1.266e+03	8.500e-02
17	90	-2.052171e-04	0.000e+00	3.108e+02	3.189e-03
18	95	-3.953216e-02	0.000e+00	1.706e+02	3.686e-02
19	100	-3.265267e-02	0.000e+00	1.689e+02	9.883e-03
20	106	-5.194312e-02	0.000e+00	1.588e+02	7.885e-02
21	112	-9.213069e-02	0.000e+00	1.499e+02	1.040e-01
22	118	-3.540567e-01	0.000e+00	1.101e+02	4.663e-01
23	134	-4.882138e-01	0.000e+00	1.092e+01	1.365e-01
24	139	-1.866662e+00	0.000e+00	7.207e+01	9.719e-01
25	144	-2.483754e+00	0.000e+00	5.984e+01	3.296e-01
26	149	-2.645003e+00	0.000e+00	7.161e+01	9.487e-02
27	154	-3.450745e+00	0.000e+00	1.256e+02	4.791e-01
28	159	-5.797646e+00	0.000e+00	2.481e+02	1.100e+00
29	168	-5.626449e+00	0.000e+00	6.095e+00	8.902e-02
30	173	-5.682070e+00	0.000e+00	8.647e+00	2.334e-02

Iter	F-count	$f(x)$	Feasibility	First-order optimality	Norm of step
31	178	-6.082542e+00	0.000e+00	2.616e+01	1.651e-01

32	183	-6.238794e+00	0.000e+00	3.281e+01	7.749e-02
33	188	-6.296937e+00	1.395e-04	3.525e+01	2.907e-02
34	193	-6.286596e+00	0.000e+00	3.207e+01	3.230e-03
35	198	-6.285148e+00	0.000e+00	3.199e+01	5.182e-04
36	203	-6.285085e+00	0.000e+00	3.198e+01	5.185e-05
37	208	-6.285205e+00	0.000e+00	3.199e+01	2.188e-04
38	213	-6.285815e+00	0.000e+00	3.202e+01	1.093e-03
39	218	-6.288832e+00	0.000e+00	3.218e+01	5.454e-03
40	223	-6.303067e+00	0.000e+00	3.294e+01	2.701e-02
41	228	-6.353881e+00	0.000e+00	2.971e+01	1.290e-01
42	234	-6.390078e+00	0.000e+00	2.715e+01	2.158e-01
43	239	-6.431686e+00	0.000e+00	2.531e+01	1.168e-01
44	244	-6.442943e+00	0.000e+00	3.170e+00	2.135e-03
45	249	-6.442101e+00	0.000e+00	1.102e-01	1.071e-03
46	254	-6.454019e+00	0.000e+00	3.061e-01	4.145e-03
47	259	-6.454101e+00	0.000e+00	7.386e-02	7.731e-05
48	264	-6.454101e+00	0.000e+00	9.172e-03	3.033e-04
49	269	-6.454101e+00	0.000e+00	8.009e-06	1.134e-04

Optimization completed: The relative first-order optimality measure, 2.247e-08, is less than options.TolFun = 1.000000e-06, and the relative maximum constraint violation, 0.000000e+00, is less than options.TolCon = 1.000000e-06.

Optimization Metric	Options
relative first-order optimality = 2.25e-08	TolFun = 1e-06 (default)
relative max(constraint violation) = 0.00e+00	TolCon = 1e-06 (default)

xopt =

0.0724	0.6776	7.5928	1.3691
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fopt =

-6.4541

c =

-3.0700
-1.1647
-0.0420
-6.6461
-5.3539
-0.0000
-0.0000

ans =

0.0724	0.6776	7.5928	1.3691
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