Daniele Reda

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Education

University of British Columbia

PhD in Computer Science

September 2019 – ongoing

Vancouver, BC, Canada

o Advisor: Michiel Van de Panne

o Topic: Reinforcement Learning, Representation Learning, Control

Telecom ParisTech - Eurecom Research Center

September 2016 - April 2018 Sophia Antipolis, France

Master of Science in Computer Science Polytechnic University of Turin

September 2015 - April 2018

Master of Science in Computer Engineering, full honours

Turin, Italy

• Thesis: Non-invasive markers for the detection of truth telling in surveys through statistical modelling

Polytechnic University of Turin

September 2012 - July 2015

Bachelor of Science in Computer Engineering

Turin, Italy

Experience

Inverted AI

May 2020 - May 2021

Vancouver, BC, Canada

o MITACS scolarship between UBC and Inverted AI with Frank Wood

Conditional Variational Methods for Stochastic Belief Modeling of Realistic Human Behaviors in Autonomous Driving

University of British Columbia

September 2019 - ongoing

Graduate Student

Vancouver, BC, Canada

• Graduate Student Researcher

o Teaching Assistant for different courses, see Teaching section below

Wayve Technologies

PhD Student Researcher

May 2018 - June 2019

Reinforcement learning Research Engineer

Cambridge, UK

• Reinforcement learning on autonomous vehicles

University of California, Berkeley

August 2017 – February 2018

Visiting Research Scholar at Berkeley AI Research Lab

Berkeley, CA

• Research scholar with professor Ruzena Bajcsy working on statistical models for truth telling recognition

Polytechnic University of Turin

September 2015 – June 2016

Teaching Assistant

Turin, Italy

• Teaching Assistant for Object Oriented Programming course

Publications

- [1] Adam Scibior, Vasileios Lioutas, Reda, Daniele, Peyman Bateni, and Frank Wood. Imagining the road ahead: Multi-agent trajectory prediction via differentiable simulation. 24th International Conference on Intelligent Transportation (ITSC), 2021. Also BEST PAPER AWARD at CVPR Workshop on Autonomous Driving: Perception, Prediction and Planning, ADP3, 2021.
- [2] Daniele Reda, Tianxin Tao, and Michiel van de Panne. Learning to locomote: Understanding how environment design matters for deep reinforcement learning. In Proc. ACM SIGGRAPH Conference on Motion, Interaction and Games, 2020. Webpage at https://www.cs.ubc.ca/~van/papers/2020-MIG-envdesign.

- [3] Jeffrey Hawke*, Richard Shen*, Corina Gurau*, Siddharth Sharma*, **Daniele Reda***, Nikolay Nikolov*, Przemyslaw Mazur*, Sean Micklethwaite*, Nicolas Griffiths*, Amar Shah*, and Alex Kendall*. Urban driving with conditional imitation learning. *International Conference on Robotics and Automation (ICRA)*, 2020. Blog post at https://wayve.ai/blog/learned-urban-driving.
- [4] Alex Kendall, Jeffrey Hawke, David Janz, Przemyslaw Mazur, **Daniele Reda**, John-Mark Allen, Vinh-Dieu Lam, Alex Bewley, and Amar Shah. Learning to drive in a day. *International Conference on Robotics and Automation (ICRA)*, 2019. Blog post at https://wayve.ai/blog/l2diad.

OTHER PROJECTS

Learning to Drive in Imagination

2018

- We demonstrate a model-based algorithm trained solely in imagination drive and generalize to multiple weathers in the real-world.
- $\circ~$ Blog post: https://wayve.ai/blog/dreaming-about-driving-imagination-rl

TEACHING

Object-Oriented Programming: Spring Term, 2016 CPSC 422 Intelligent Systems: Winter Term 1, 2019

IVADO/MILA/DSI Deep Learning Winter School 5th Edition: December 2019

DSCI 572 Supervised Learning II: Winter Term 2, 2020 DSCI 563 Unsupervised Learning: Winter Term 2, 2020 DSCI 575 Advanced Machine Learning: Winter Term 2, 2020

WON THE MDS TA AWARD: Winter Term 2, 2020

CPSC 340 Machine Learning and Data Mining: Winter Term 2, 2021

6th IVADO/MILA Deep Learning School: April 2021

SKILLS

Computer Languages: Python, Java, C

Human Languages: English, Italian, French, Spanish Technologies: PyTorch, GitHub, LATEX, ROS and others

Soft skills: communication and leadership skills, organizational and team working skills, 7+ years of volunteering