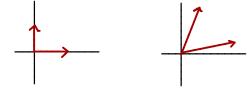
Lecture # 11: Dimension & Rank

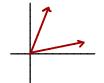
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Dimension

Objective: IF V has a finite basis, all bases For I have the same number of elements. This number is the dimension of V, dim (V).

Ex. 1 dim(\mathbb{R}^2) = 2. The following are bases:







Thm. If V has a basis $\{\vec{v}_1, \vec{v}_2...\vec{v}_n\}$ then any set ₹ w,,..., wm3 in V having >n elements is linearly dependent.

PF. Want to Find Ci,..., cm not all O, s.L. $C_1 \vec{\omega}_1 + \dots + C_m \vec{\omega}_m = \vec{D}$

Since & U,,..., vm3 is a basis,

$$\vec{\omega}_1 = \alpha_{11} \vec{v}_1 + \dots + \alpha_{n_1} \vec{v}_n$$

 $\vec{w}_m = a_{im} \vec{v}_i + ... + a_{nm} \vec{v}_n$

50 (1) requires $C_1(\alpha_{11} \vee_1 + ... + \alpha_{n_1} \vee_{n_1}) + ... + C_m(\alpha_{1m} \vee_1 + ... + \alpha_{n_m} \vee_m) = \vec{O}$

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PF. (Contid)

Rearranging

 $[a_{i1}C_{i} + ... + a_{im}C_{m}]\vec{v}_{i} + ... [a_{n_{i}}C_{i} + ... + a_{nm}C_{m}]\vec{v}_{n} = \vec{o}$

Since $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis, it is lin. indep. so each expression in [] must be []. i.e.

 $\begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & \vdots & \vdots \\ a_{n1} & \dots & a_{nm} \end{bmatrix} \begin{bmatrix} c_{1} \\ \vdots \\ c_{m} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \qquad \begin{array}{c} n & eqns \\ m & unknowns \end{array}$

Since m>n, this system has free variables Hence, a nontrivial soln i.e.

$$\begin{bmatrix} c_1 \\ \vdots \\ c_m \end{bmatrix} \neq \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

so a set w/ >n elements must be lin. dep.

Thm. If V has a basis of n vectors, every basis of V has exactly n vectors.

Pf. Let B, be a basis with n vectors & let B₂
be another basis. B₂ is lin. indep., 50 it
has ≤ n elements by prev. thm.
Since B₂ is a basis & B, is lin.indep., B₂
has ≥ n elements. i.e. B₂ must have exactly
n elements.

Def. The number of elements in any basis for V is the dimension of V, dim(V).

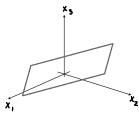
Ex.3 dim $(R^n) = n$

$$E_{\underline{X},\underline{Y}}$$
 $V = \begin{cases} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} \in \mathbb{R}^3 : X_1 + X_2 = X_3 \end{cases}$ (a plane in \mathbb{R}^3)

Typical Vector in V:

$$\begin{bmatrix}
A \\ t \\
4+t
\end{bmatrix} = A \begin{bmatrix} 1 \\ 0 \\
1
\end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\
1
\end{bmatrix}$$

Basis:
$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \Rightarrow dim(v) = a$$



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Ex.5) IF AER MXN $dim(Null(A)) = number of free variables in <math>A\vec{x} = \vec{0}$

dim(Col(A)) = number of pivot col.s in A

$$\begin{array}{c}
E \times .6 \\
A = \begin{bmatrix} 2 & 1 & 0 \\ 4 & 0 & 1 \\ 6 & 1 & 1 \end{bmatrix}
\end{array}$$
Find Free variables in $A\vec{x} = \vec{o}$:

$$\begin{bmatrix}
2 & 1 & 0 & | & 0 \\
4 & 0 & 1 & | & 0
\end{bmatrix}$$

$$\begin{bmatrix}
2 & 1 & 0 & | & 0 \\
4 & 0 & 1 & | & 0
\end{bmatrix}$$

$$\begin{bmatrix}
2 & 1 & 0 & | & 0 \\
4 & 0 & 1 & | & 0
\end{bmatrix}$$
Free variable $X_3 = E$

$$\Rightarrow \begin{bmatrix}
X_1 \\
X_2
\end{bmatrix} = \begin{bmatrix} -\frac{t}{4} \\ \frac{t}{2} \end{bmatrix} = E \begin{bmatrix} -\frac{1}{4} \\ \frac{t}{2} \end{bmatrix}$$

$$\begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} = \begin{bmatrix} -\frac{t}{4} \\ \frac{t}{2} \\ t \end{bmatrix} = -t \begin{bmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

$$\begin{cases}
\begin{bmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}
\end{cases}$$
is a basis; dim (Null(A)) = 1

dim ((OI(A)) = # pivot Cold = # nonzero rows in REF = a

Row space

Given
$$A \in \mathbb{R}^{m \times n}$$
, write it as $A = \begin{bmatrix} \vec{a}_1 \\ \vdots \\ \vec{a}_m \end{bmatrix}$ [a₁₁...a_{1n}]

Def the row space of
$$A = \begin{bmatrix} \vec{a}_i \\ \vdots \\ \vec{a}_m \end{bmatrix}$$
 is

Row(A) = 5pan { à,,..., àn}

Facts about Row(A):

1. If $A \rightarrow U$ (REF), then Row(A) = Row(U)Example:

$$A = \begin{bmatrix} 2 & 1 & 0 \\ 4 & 0 & 1 \\ 6 & 1 & 1 \end{bmatrix} \qquad \overrightarrow{REF} \qquad \begin{bmatrix} 1 & 1/2 & 0 \\ 0 & 1 & 1/2 \\ 0 & 0 & 0 \end{bmatrix} = 0$$

$$RD\omega(A) = Ro\omega(U) = Span \{(1, 1/2, 0), (0, 1, -1/2)\}$$

 $\Rightarrow dim(Row(A)) = 2$
on REF

Note: if U is in REF, its nonzero rows from a basis for row(U).

2. If U is in REF then

dim(Row(U)) = # of nonzero = # of basic variables
rows

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$$A = \begin{bmatrix} 2 & 1 & 0 \\ 4 & 0 & 1 \\ 6 & 1 & 1 \end{bmatrix} \xrightarrow{REF} \begin{bmatrix} 1 & 1/2 & 0 \\ 0 & 1 & 1/2 \\ 0 & 0 & 0 \end{bmatrix} = 0$$
 a nonzero rows $\Rightarrow \dim(Row(v)) = 2$

$$\Rightarrow$$
 Row(A) = Row(U) = Span $\{(1, \frac{1}{2}, 0), (0, 1, -\frac{1}{2})\}$

Kank

The <u>nullity</u> of A is dim(Null(A))

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$$\begin{array}{c|c}
E \times . & 8 \\
\hline
A = \begin{bmatrix} 1 & 3 & -1 & 2 \\ 2 & 10 & 2 & 6 \\ 0 & 2 & 2 & 1 \end{bmatrix}$$

$$\begin{array}{c}
RREF \\
\hline
0 & 0 & 1 & \frac{1}{2} \\
0 & 0 & 0 & 0
\end{array}$$

50 $\{(1, 3, -1, 2), (0, 1, 1, \frac{1}{2})\}\$ is a basis For Row(u) = Fow(A)

$$\Rightarrow$$
 rank(A) = dim(Row(A)) = 2.

Remark:

to find a basis for col(A) we use the cols of A in which U has leading 1's $Col(A) = Span \begin{cases} 1 \\ 2 \\ 1 \end{cases}, \begin{bmatrix} 3 \\ 10 \\ 2 \end{bmatrix}$

To find a basis for Null(A) use REF: Since $A\vec{x}=\vec{o}$ iff $U\vec{x}=\vec{o}$, Null(A) = Null(U)

General Soln:

$$\begin{bmatrix} X_1 \\ X_2 \\ X_3 \\ X_4 \end{bmatrix} = \begin{bmatrix} 4t - \frac{1}{2} & A \\ -t - \frac{1}{2} & A \end{bmatrix} = t \begin{bmatrix} 4 \\ -1 \\ 1 \\ 0 \end{bmatrix} + A \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 0 \\ 1 \end{bmatrix}$$

50, $\begin{cases} \begin{bmatrix} 4 \\ -1 \\ 0 \end{bmatrix} \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 0 \end{bmatrix} & \text{is a basis for Null(1)} = \text{Null(1+y(A))} \\ = \# \text{ or free variables} \end{cases}$

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Observation: for this matrix $A \in \mathbb{R}^{3\times 4}$,

Rank(A) + dim(Null(A)) = 4

Rank(A) + nullity(A) = 4

Thm. For any AERMAN

runk(A) + dim (Num (A)) = n (# oz cols)

PF. Reduce A to REF. Then

of basic + # of free = nVariables

Variables

Variables

Variables

Variables

= dim(Row(A))

Rank and dimension allow us to say even more regarding invertible matrices:

Thm. IC AER^{nxn} (Square!), TFAE:

- (1) A is invertible
- (a) Cols of A form a basis for R^
- (3) COI(A) = R^
- (4) rank(A) =n
- (5) Num (A) = { 6}
- (b) dim (NULL (A)) = 0

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In Summary:

For AERMXN:		
Mull (A)	(a) (A)	Pow (A)
{xern Ax = 0}	span { columns of A}	span { rows of A }
< R"	c Rm	c Rn
dim(Null (A)) = number of free variables in REF	dim (Gl(A)) = rank(A) = number of basic variables in REF = number of pivot columns	dim (Row (A)) = dim (Col (A))
basis: write general solution to $Ax = Q$ Separate the parameters	basis: columns of A corresp to pivot columns in REF	hasis: Monzero rows of the REF.