

**Doc Version**

**2.0**



# **ET-332**

## **GPS RECEIVER ENGINE BOARD**

GLOBALSAT TECHNOLOGY CORPORATION

# GPS Engine Board Specifications

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## ET-332 GPS BOARD OVERVIEW

The ET-332 GPS engine board is low cost but maintains high reliability and accuracy making it an ideal choice for integration with OEM/ODM systems.

### **FEATURES:**

1. SiRF III high performance, low power consumption chipset
2. Very high sensitivity (Tracking Sensitivity: -159dBm)
3. Extremely fast TTFF (Time To First Fix) at low signal levels
4. Compact PCB allows for easier integration into space limited environments.
5. Supports the NMEA 0183 data protocol
6. Foliage Lock for weak signal tracking
7. All-in-view 20-channel parallel processing
8. Snap Lock 100mc re-acquisition time
9. Enhanced algorithm for navigation stability
10. Superior urban canyon performance
11. WAAS / EGNOS support

# SPECIFICATIONS

## General - Receiver

Chipset: SiRF Star III  
Frequency: L1, 1575.42 MHz  
C/A Code: 1.023 MHz chip rate  
Channels: 12 channel all-in-view tracking  
Sensitivity: -159dBm

## Accuracy

Position: 10 meters, 2D RMS  
5 meters, 2D RMS, WAAS enabled  
Velocity: 0.1 ms  
Time: 1 $\mu$ s synchronized to GPS time

## Datum

Default: WGS-84

## Acquisition Time

Reacquisition: 0.1 sec., average  
Hot Start: 1 sec., average  
Warm Start: 38 sec., average  
Cold Start: 42 sec., average

## Dynamic Conditions

Altitude: 18,000 meters (60,000 feet) max  
Velocity: 515 meters/second (1000 knots) max  
Acceleration: Less than 4g  
Jerk: 20m/sec \*\*3

## Power

Main Power Input: 3.8V~6.5V DC Input  
Power Consumption: 75mA (continuous)  
30mA (trickle mode)  
Backup voltage: +2.5V to +3.6V  
Backup current: 10uA typical

## Protocol

Electrical Level: TTL level,  
Output Voltage Level: 0V~2.85V  
Baud Rate: 4800 bps  
Output Message: NMEA 0183 GGA, GSA, GSV,  
RMC (VTG, GLL optional)

## Physical Characteristics

Dimensions: 1.1594" x 1.377" x 0.393"  
(40.5mm \* 35 mm \* 10mm)  
Operating Temperature: -40F to +176F  
(-40C to +85C)  
Humidity: Up to 95% non-condensing

## PIN ASSIGNMENT

Pin	Name	Description	Type
1	GND	Ground	
2	VBAT	Backup Battery	Input
3	VDC	3.8V~6.5V DC Power Input	Input
4	PBRES	Push Button Reset Input (Active Low)	Input
5	GPIO1	(Reserved)	
6	TXA	Serial Data Output A (GPS Data)	Output
7	RXA	Serial Data Input A (Command)	Input
8	GND	Ground	
9	GND	Ground	
10	SELECT	(Reserved)	
11	TIMEMARK	1PPS Time Mark Output	Output
12	GND	Ground	

## PIN DESCRIPTIONS

**VCC: (DC power input):** This is the main DC supply for a 3.8V ~ 6.5V power module board.

**VBAT:** This is the battery backup input that powers the SRAM and RTC when main power is removed. Typical current draw is 10uA. Without an external backup battery, the module/engine board will execute a cold start after every turn on. To achieve the faster start-up offered by a hot or warm start, a battery backup must be connected. To maximize battery lifetime, the battery voltage should be between 2.5v and 3.6v.

**PBRES:** (Push Button Reset): This pin provides an active-low reset input to the engine board. It causes the engine board to reset and start searching for satellites.

**SELECT:** Do not connect (do not use)

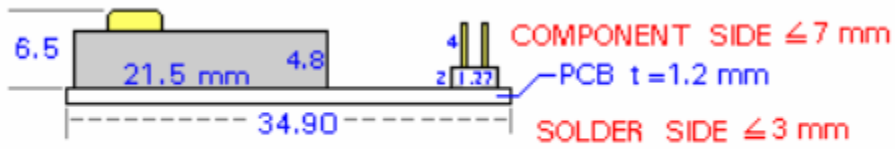
**TX:** This is the main transmit channel for outputting navigation and measurement data to user's navigation software or user-written software. Output TTL level , 0V ~ 2.85V

**RX:** This is the main receive channel for receiving software commands to the engine board from SiRfdemo software or from user-written software. Normally this pin must be kept High and if you don't use this pin please connect a resistor to 3.5V to pull it high.

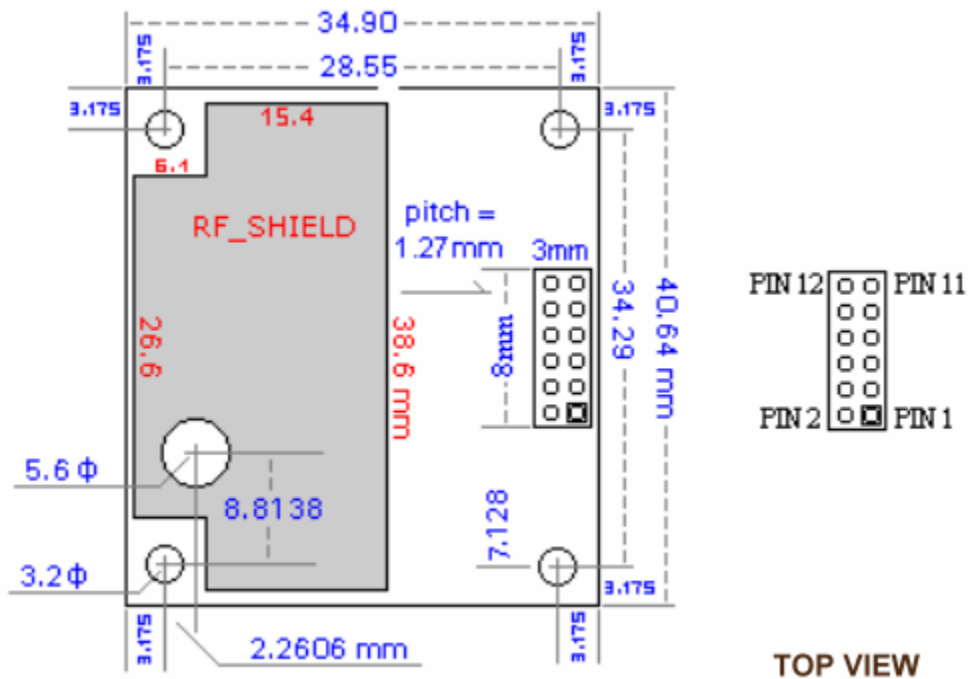
**TIME MARK (1PPS):** This pin provides one pulse-per-second output from the engine board that is synchronized to GPS time

**GND:** GND provides the ground for the engine boards. Be sure to connect all grounds

## DIMENSIONS



**PCB SIDE VIEW**



## MOUNTING

Recommended mounting methods:

- a. Use industrial grade double-sided foam tape. Place it on the bottom side of the engine board.
- b. A recessed cavity in your housing design with a foam pad to eliminate shifting or movement.
- c. Use provided mounting holes on the GPS engine board PCB.

## NMEA & SiRF COMMAND LINKS

Please download the latest output and control commands from our web-site:

**[NMEA Command Reference Manual](http://www.usglobalsat.com/downloads/NMEA_commands.pdf)**

([http://www.usglobalsat.com/downloads/NMEA\\_commands.pdf](http://www.usglobalsat.com/downloads/NMEA_commands.pdf))

**[SiRF Binary Protocol Reference Manual](http://www.usglobalsat.com/downloads/SiRF_Binary_Protocol.pdf)**

([http://www.usglobalsat.com/downloads/SiRF\\_Binary\\_Protocol.pdf](http://www.usglobalsat.com/downloads/SiRF_Binary_Protocol.pdf))

*All product specifications contained in this document are subject to change without notice.*



NOTES: