

Estimation and Inference in Boundary Discontinuity Designs: Distance-Based Methods Supplemental Appendix

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Abstract

This supplemental appendix presents more general theoretical results encompassing those reported in the paper, their theoretical proofs, and other technical results. In particular, it presents a new strong approximation result for multiplicative-separable empirical processes leveraging and extending ideas from [Cattaneo and Yu \[2025\]](#).

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SA-1 Setup

This supplemental appendix considers a generalized version of the problems studied in the main paper. Specifically, the underlying bivariate location variable \mathbf{X}_i is d -dimensional ($d \geq 1$) with support $\mathcal{X} \subseteq \mathbb{R}^d$, and the boundary region \mathcal{B} is a low dimensional manifold with “effective dimension” $d - 1$. The results in the paper correspond to $d = 2$, that is, \mathbf{X}_i is bivariate and \mathcal{B} is a one-dimensional (boundary assignment) curve.

Assumption 1 in the paper generalizes as follows.

Assumption SA-1 (Data Generating Process). *Let $t \in \{0, 1\}$.*

- (i) $(Y_1(t), \mathbf{X}_1^\top)^\top, \dots, (Y_n(t), \mathbf{X}_n^\top)^\top$ are independent and identically distributed random vectors with $\mathcal{X} = \prod_{l=1}^d [a_l, b_l]$ for $-\infty < a_l < b_l < \infty$ for $l = 1, \dots, d$.
- (ii) The distribution of \mathbf{X}_i has a Lebesgue density $f_X(\mathbf{x})$ that is continuous and bounded away from zero on \mathcal{X} .
- (iii) $\mu_t(\mathbf{x}) = \mathbb{E}[Y_i(t)|\mathbf{X}_i = \mathbf{x}]$ is $(p + 1)$ -times continuously differentiable on \mathcal{X} .
- (iv) $\sigma_t^2(\mathbf{x}) = \mathbb{V}[Y_i(t)|\mathbf{X}_i = \mathbf{x}]$ is bounded away from zero and continuous on \mathcal{X} .
- (v) $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[|Y_i(t)|^{2+v}|\mathbf{X}_i = \mathbf{x}] < \infty$ for some $v \geq 2$.

The support \mathcal{X} is partitioned into two (assignment) areas, $\mathcal{A}_0 \subset \mathbb{R}^d$ and $\mathcal{A}_1 \subset \mathbb{R}^d$, representing the control and treatment regions, respectively. Thus, $\mathcal{X} = \mathcal{A}_0 \cup \mathcal{A}_1$ with \mathcal{A}_0 and \mathcal{A}_1 disjoint regions in \mathbb{R}^d . The observed outcome is $Y_i = \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_0)Y_i(0) + \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1)Y_i(1)$, and $\mathcal{B} = \text{bd}(\mathcal{A}_0) \cap \text{bd}(\mathcal{A}_1)$ is the boundary determined by the assignment regions, where $\text{bd}(\mathcal{A}_t)$ denotes the topological boundary of \mathcal{A}_t .

The conditional treatment effect curve at the boundary is

$$\tau(\mathbf{x}) = \mathbb{E}[Y_i(1) - Y_i(0)|\mathbf{X}_i = \mathbf{x}], \quad \mathbf{x} \in \mathcal{B}.$$

The univariate distance score induced by the bivariate location variable is

$$D_i(\mathbf{x}) = [\mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) - \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_0)]\mathcal{d}(\mathbf{X}_i, \mathbf{x}), \quad \mathbf{x} \in \mathcal{B},$$

where $\mathcal{d}(\cdot, \cdot)$ denotes a distance function. The distance-based treatment effect estimator process along the boundary based is $(\tau(\mathbf{x}) : \mathbf{x} \in \mathcal{B})$ is

$$\left(\hat{\vartheta}(\mathbf{x}) = \hat{\theta}_{1,\mathbf{x}}(0) - \hat{\theta}_{0,\mathbf{x}}(0) : \mathbf{x} \in \mathcal{B} \right),$$

where, for $t \in \{0, 1\}$,

$$\hat{\theta}_{t,\mathbf{x}}(0) = \mathbf{e}_1^\top \hat{\gamma}_t(\mathbf{x}), \quad \hat{\gamma}_t(\mathbf{x}) = \arg \min_{\gamma \in \mathbb{R}^{p+1}} \mathbb{E}_n \left[(Y_i - \mathbf{r}_p(D_i(\mathbf{x}))^\top \gamma)^2 K_h(D_i(\mathbf{x})) \mathbf{1}_{\mathcal{J}_t}(D_i(\mathbf{x})) \right],$$

$\mathbf{r}_p(u) = (1, u, \dots, u^p)^\top$ and $K_h(u) = K(u/h)/h^2$ with $K(\cdot)$ a univariate kernel and h a bandwidth parameter, and $\mathcal{J}_0 = (-\infty, 0)$ and $\mathcal{J}_1 = [0, \infty)$. More generally, the least squares projection is

$$\hat{\theta}_{t,\mathbf{x}}(D_i(\mathbf{x})) = \mathbf{r}_p(D_i(\mathbf{x}))^\top \hat{\gamma}_t(\mathbf{x}), \quad t \in \{0, 1\}, \quad \mathbf{x} \in \mathcal{B}.$$

We impose the following assumptions on the kernel function, distance function, and assignment boundary

manifold. Let

$$\Psi_{t,\mathbf{x}} = \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right)^\top K_h(D_i(\mathbf{x})) \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right],$$

for $t \in \{0, 1\}$.

Assumption SA-2 (Kernel, Distance, and Boundary). *Let $t \in \{0, 1\}$.*

- (i) \mathcal{B} is compact $(d-1)$ -rectifiable, with $\mathfrak{H}^{d-1}(\mathcal{B})$ positive and finite.
- (ii) $\mathcal{d} : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}_+$ is a metric on \mathbb{R}^d equivalent to the Euclidean distance, that is, there exists positive constants C_u and C_l such that $C_l \|\mathbf{x} - \mathbf{x}'\| \leq \mathcal{d}(\mathbf{x}, \mathbf{x}') \leq C_u \|\mathbf{x} - \mathbf{x}'\|$ for all $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$.
- (iii) $K : \mathbb{R} \rightarrow [0, \infty)$ is compact supported and Lipschitz continuous, or $K(u) = \mathbf{1}(u \in [-1, 1])$.
- (iv) $\liminf_{h \downarrow 0} \inf_{\mathbf{x} \in \mathcal{B}} \lambda_{\min}(\Psi_{t,\mathbf{x}}) \gtrsim 1$.

For each $t \in \{0, 1\}$, the induced conditional expectation based on univariate distance is

$$\theta_{t,\mathbf{x}}(r) = \mathbb{E}[Y_i | D_i(\mathbf{x}) = r] = \mathbb{E}[Y_i | \mathcal{d}(\mathbf{X}_i, \mathbf{x}) = |r|, \mathbf{X}_i \in \mathcal{A}_t], \quad r \in \mathcal{J}_t, \quad \mathbf{x} \in \mathcal{B}.$$

More rigorously, for each $t \in \{0, 1\}$, and letting $S_{t,\mathbf{x}}(r) = \{\mathbf{v} \in \mathcal{X} : \mathcal{d}(\mathbf{v}, \mathbf{x}) = r, \mathbf{v} \in \mathcal{A}_t\}$ for $r \geq 0$ and $\mathbf{x} \in \mathcal{B}$,

$$\theta_{t,\mathbf{x}}(r) = \frac{\int_{S_{t,\mathbf{x}}(|r|)} \mu_t(\mathbf{v}) f_X(\mathbf{v}) \mathfrak{H}^{d-1}(d\mathbf{v})}{\int_{S_{t,\mathbf{x}}(|r|)} f_X(\mathbf{v}) \mathfrak{H}^{d-1}(d\mathbf{v})},$$

for $|r| > 0, \mathbf{x} \in \mathcal{B}, t \in \{0, 1\}$, and therefore (under our assumptions)

$$\theta_{t,\mathbf{x}}(0) = \lim_{r \rightarrow 0} \mathbb{E}[Y_i | \mathcal{d}(\mathbf{X}_i, \mathbf{x}) = |r|, \mathbf{X}_i \in \mathcal{A}_t] = \lim_{r \rightarrow 0} \frac{\int_{S_{t,\mathbf{x}}(|r|)} \mu_t(\mathbf{v}) f_X(\mathbf{v}) \mathfrak{H}^{d-1}(d\mathbf{v})}{\int_{S_{t,\mathbf{x}}(|r|)} f_X(\mathbf{v}) \mathfrak{H}^{d-1}(d\mathbf{v})}.$$

Thus, the population limit based on the induced conditional expectations is $\theta_{\mathbf{x}}(0) = \theta_{1,\mathbf{x}}(0) - \theta_{0,\mathbf{x}}(0)$.

Theorem SA-1 shows that $\theta_{\mathbf{x}}(0) = \tau(\mathbf{x})$ under Assumptions SA-1 and SA-2.

The best mean square approximation is

$$\theta_{t,\mathbf{x}}^*(D_i(\mathbf{x})) = \mathbf{r}_p(D_i(\mathbf{x}))^\top \gamma_t^*(\mathbf{x}),$$

where

$$\gamma_t^*(\mathbf{x}) = \arg \min_{\gamma \in \mathbb{R}^{p+1}} \mathbb{E} \left[(Y_i - \mathbf{r}_p(D_i(\mathbf{x}))^\top \gamma)^2 K_h(D_i(\mathbf{x})) \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right],$$

and uniqueness will follow from the results below. The estimation error decomposes into *linear error*, *approximation error*, and *non-linear error*: for all $t \in \{0, 1\}$ and $\mathbf{x} \in \mathcal{B}$,

$$\begin{aligned} \hat{\theta}_{t,\mathbf{x}}(0) - \theta_{t,\mathbf{x}}(0) &= \mathbf{e}_1^\top \hat{\Psi}_{t,\mathbf{x}}^{-1} \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) Y_i \right] - \theta_{t,\mathbf{x}}(0) \\ &= \mathbf{e}_1^\top \hat{\Psi}_{t,\mathbf{x}}^{-1} \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) (Y_i - \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))) \right] + \theta_{t,\mathbf{x}}^*(0) - \theta_{t,\mathbf{x}}(0) \\ &= \underbrace{\theta_{t,\mathbf{x}}^*(0) - \theta_{t,\mathbf{x}}(0)}_{\text{approximation error}} + \underbrace{\mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}}}_{\text{linear error}} + \underbrace{\mathbf{e}_1^\top (\hat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}) \mathbf{O}_{t,\mathbf{x}}}_{\text{non-linear error}}, \end{aligned} \tag{SA-1}$$

where

$$\mathbf{O}_{t,\mathbf{x}} = \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) (Y_i - \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))) \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right],$$

$$\widehat{\Psi}_{t,\mathbf{x}} = \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right)^\top K_h(D_i(\mathbf{x})) \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right],$$

and the misspecification bias is

$$\mathfrak{B}_t(\mathbf{x}) = \theta_{t,\mathbf{x}}^*(0) - \theta_{t,\mathbf{x}}(0).$$

Finally, we define the following for quantities for future analysis: for $t \in \{0, 1\}$, $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}$,

$$\begin{aligned} \widehat{\Upsilon}_{t,\mathbf{x}_1,\mathbf{x}_2} &= h^d \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x}_1)}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{x}_2)}{h} \right)^\top K_h(D_i(\mathbf{x}_1)) K_h(D_i(\mathbf{x}_2)) \right. \\ &\quad \left. (Y_i - \widehat{\theta}_{t,\mathbf{x}_1}(D_i(\mathbf{x}_1))) (Y_i - \widehat{\theta}_{t,\mathbf{x}_2}(D_i(\mathbf{x}_2))) \mathbf{1}_{\mathcal{J}_t}(D_i(\mathbf{x}_1)) \right], \\ \Upsilon_{t,\mathbf{x}_1,\mathbf{x}_2} &= h^d \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x}_1)}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{x}_2)}{h} \right)^\top K_h(D_i(\mathbf{x}_1)) K_h(D_i(\mathbf{x}_2)) \right. \\ &\quad \left. (Y_i - \theta_{t,\mathbf{x}_1}^*(D_i(\mathbf{x}_1))) (Y_i - \theta_{t,\mathbf{x}_2}^*(D_i(\mathbf{x}_2))) \right], \end{aligned}$$

$$\widehat{\Xi}_{\mathbf{x}_1,\mathbf{x}_2} = \widehat{\Xi}_{0,\mathbf{x}_1,\mathbf{x}_2} + \widehat{\Xi}_{1,\mathbf{x}_1,\mathbf{x}_2}, \quad \widehat{\Xi}_{t,\mathbf{x}_1,\mathbf{x}_2} = \frac{1}{nh^d} \mathbf{e}_1^\top \widehat{\Psi}_{t,\mathbf{x}_1}^{-1} \widehat{\Upsilon}_{t,\mathbf{x}_1,\mathbf{x}_2} \widehat{\Psi}_{t,\mathbf{x}_2}^{-1} \mathbf{e}_1$$

and

$$\Xi_{\mathbf{x}_1,\mathbf{x}_2} = \Xi_{0,\mathbf{x}_1,\mathbf{x}_2} + \Xi_{1,\mathbf{x}_1,\mathbf{x}_2}, \quad \Xi_{t,\mathbf{x}_1,\mathbf{x}_2} = \frac{1}{nh^d} \mathbf{e}_1^\top \Psi_{t,\mathbf{x}_1}^{-1} \Upsilon_{t,\mathbf{x}_1,\mathbf{x}_2} \Psi_{t,\mathbf{x}_2}^{-1} \mathbf{e}_1.$$

In particular, $\widehat{\Xi}_{\mathbf{x}} = \widehat{\Xi}_{\mathbf{x},\mathbf{x}}$, $\Xi_{\mathbf{x}} = \Xi_{\mathbf{x},\mathbf{x}}$, $\mathfrak{B}(\mathbf{x}) = \mathfrak{B}_1(\mathbf{x}) - \mathfrak{B}_0(\mathbf{x})$, etc.

SA-1.1 Notation and Definitions

For textbook references on empirical process, see [van der Vaart and Wellner \[1996\]](#), [Dudley \[2014\]](#), and [Giné and Nickl \[2016\]](#). For textbook reference on geometric measure theory, see [Simon et al. \[1984\]](#), [Federer \[2014\]](#), and [Folland \[2002\]](#).

- (i) *Multi-index Notations.* For a multi-index $\mathbf{u} = (u_1, \dots, u_d) \in \mathbb{N}^d$, denote $|\mathbf{u}| = \sum_{i=1}^d u_i$, $\mathbf{u}! = \prod_{i=1}^d u_i!$. Denote $\mathbf{r}_p(\mathbf{u}) = (1, u_1, \dots, u_d, u_1^2, \dots, u_d^2, \dots, u_1^p, \dots, u_d^p)$, that is, all monomials $u_1^{\alpha_1} \dots u_d^{\alpha_d}$ such that $\alpha_i \in \mathbb{N}$ and $\sum_{i=1}^d \alpha_i \leq p$. Define $\mathbf{e}_{1+\nu}$ to be the $p_d = \frac{(d+p)!}{d!p!}$ -dimensional vector such that $\mathbf{e}_{1+\nu}^\top \mathbf{r}_p(\mathbf{u}) = \mathbf{u}^\nu$ for all $\mathbf{u} \in \mathbb{R}^d$.
- (ii) *Norms.* For a vector $\mathbf{v} \in \mathbb{R}^k$, $\|\mathbf{v}\| = (\sum_{i=1}^k \mathbf{v}_i^2)^{1/2}$, $\|\mathbf{v}\|_\infty = \max_{1 \leq i \leq k} |\mathbf{v}_i|$. For a matrix $A \in \mathbb{R}^{m \times n}$, $\|A\|_p = \sup_{\|\mathbf{x}\|_p=1} \|A\mathbf{x}\|_p$, $p \in \mathbb{N} \cup \{\infty\}$, and $\lambda_{\min}(A)$ denotes its minimum eigenvalue. For a function f on a metric space (S, d) , $\|f\|_\infty = \sup_{\mathbf{x} \in \mathcal{X}} |f(\mathbf{x})|$. For a probability measure Q on $(\mathcal{S}, \mathcal{S})$ and $p \geq 1$, define $\|f\|_{Q,p} = (\int_{\mathcal{S}} |f|^p dQ)^{1/p}$. For a set $E \subseteq \mathbb{R}^d$, denote by $\mathfrak{m}(E)$ the Lebesgue measure of E .
- (iii) *Empirical Process.* We use standard empirical process notations: $\mathbb{E}_n[g(\mathbf{v}_i)] = \frac{1}{n} \sum_{i=1}^n g(\mathbf{v}_i)$ and

$\mathbb{G}_n[g(\mathbf{v}_i)] = \frac{1}{\sqrt{n}} \sum_{i=1}^n (g(\mathbf{v}_i) - \mathbb{E}[g(\mathbf{v}_i)])$. Let (\mathcal{S}, d) be a semi-metric space. The covering number $N(\mathcal{S}, d, \varepsilon)$ is the minimal number of balls $B_s(\varepsilon) = \{t : d(t, s) < \varepsilon\}$ needed to cover \mathcal{S} . A \mathbb{P} -Brownian bridge is a mean-zero Gaussian random function $W_n(f), f \in L_2(\mathcal{X}, \mathbb{P})$ with the covariance $\mathbb{E}[W_{\mathbb{P}}(f)W_{\mathbb{P}}(g)] = \mathbb{P}(fg) - \mathbb{P}(f)\mathbb{P}(g)$, for $f, g \in L_2(\mathcal{X}, \mathbb{P})$. A class $\mathcal{F} \subseteq L_2(\mathcal{X}, \mathbb{P})$ is \mathbb{P} -pregaussian if there is a version of \mathbb{P} -Brownian bridge $W_{\mathbb{P}}$ such that $W_{\mathbb{P}} \in C(\mathcal{F}; \rho_{\mathbb{P}})$ almost surely, where $\rho_{\mathbb{P}}$ is the semi-metric on $L_2(\mathcal{X}, \mathbb{P})$ is defined by $\rho_{\mathbb{P}}(f, g) = (\|f - g\|_{\mathbb{P}, 2}^2 - (\int f d\mathbb{P} - \int g d\mathbb{P})^2)^{1/2}$, for $f, g \in L_2(\mathcal{X}, \mathbb{P})$.

- (iv) *Geometric Measure Theory.* For a set $E \subseteq \mathcal{X}$, the *De Giorgi perimeter of E related to \mathcal{X}* is $\mathcal{L}(E) = \text{TV}_{\{\mathbf{1}_E\}, \mathcal{X}}$. For $d \in \mathbb{N}$ and $0 \leq m \leq d$, the m -dimensional Hausdorff (outer) measure is given by $\mathfrak{H}^m(A) = \lim_{\delta \downarrow 0} \mathfrak{H}_{\delta}^m(A)$, $A \subseteq \mathbb{R}^d$, where for each $\delta > 0$, $\mathfrak{H}_{\delta}^m(A)$ is defined by taking $\mathfrak{H}_{\delta}^m(\emptyset) = 0$, and for any non-empty $A \subseteq \mathbb{R}^d$, $\mathfrak{H}_{\delta}^m(A) = \frac{\pi^{m/2}}{\Gamma(m/2+1)} \inf \sum_{j=1}^{\infty} (\text{diam}(C_j)/2)^m$, and the infimum is taken over all countable collections C_1, C_2, \dots of subsets of \mathbb{R}^d such that $\text{diam}(C_j) < \delta$ and $A \subseteq \cup_{j=1}^{\infty} C_j$. Integration against \mathfrak{H}^m is defined via Carathéodory's Theorem following the classical measure-theoretic literature. The Hausdorff dimension $\dim_{\mathfrak{H}}(A)$ of A is defined by $\dim_{\mathfrak{H}}(A) = \inf\{t \geq 0 : \mathfrak{H}^t(A) = 0\}$. A set $A \subseteq \mathbb{R}^d$ is said to be k -rectifiable if A is of Hausdorff dimension k , and there exist a countable collection $\{f_i\}$ of continuously differentiable maps $f_i : \mathbb{R}^k \rightarrow \mathbb{R}^d$ such that $\mathfrak{H}^k(E \setminus \cup_{i=0}^{\infty} f_i(\mathbb{R}^k)) = 0$. B is a *rectifiable curve* if there exists a Lipschitz continuous function $\gamma : [0, 1] \rightarrow \mathbb{R}^d$ such that $B = \gamma([0, 1])$. We define the curve length function of B to be $\mathfrak{L}(B) = \sup_{\pi \in \Pi} s(\pi, \gamma)$, where $\Pi = \{(t_0, t_1, \dots, t_N) : N \in \mathbb{N}, 0 \leq t_0 < t_1 < \dots \leq t_N \leq 1\}$ and $s(\pi, \gamma) = \sum_{i=0}^N \|\gamma(t_i) - \gamma(t_{i+1})\|_2$ for $\pi = (t_0, t_1, \dots, t_N)$.
- (v) *Bounds and Asymptotics.* For reals sequences $|a_n| = o(|b_n|)$ if $\limsup \frac{a_n}{b_n} = 0$, $|a_n| \lesssim |b_n|$ if there exists some constant C and $N > 0$ such that $n > N$ implies $|a_n| \leq C|b_n|$. For sequences of random variables $a_n = o_{\mathbf{bP}}(b_n)$ if $\text{plim}_{n \rightarrow \infty} \frac{a_n}{b_n} = 0$, $|a_n| \lesssim_{\mathbb{P}} |b_n|$ if $\limsup_{M \rightarrow \infty} \limsup_{n \rightarrow \infty} \mathbb{P}[\frac{a_n}{b_n} \geq M] = 0$.
- (vi) *Distributions and Statistical Distances.* For $\boldsymbol{\mu} \in \mathbb{R}^k$ and $\boldsymbol{\Sigma}$ a $k \times k$ positive definite matrix, $\text{Normal}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ denotes the Gaussian distribution with mean $\boldsymbol{\mu}$ and covariance $\boldsymbol{\Sigma}$. For $-\infty < a < b < \infty$, $\text{Uniform}([a, b])$ denotes the uniform distribution on $[a, b]$. $\text{Bernoulli}(p)$ denotes the Bernoulli distribution with success probability p . $\Phi(\cdot)$ denotes the standard Gaussian cumulative distribution function. For two distributions P and Q , $d_{\text{KL}}(P, Q)$ denotes the KL-distance between P and Q , and $d_{\chi^2}(P, Q)$ denotes the χ^2 distance between P and Q .

SA-1.2 Mapping between Main Paper and Supplement

The results in the main paper are special cases of the results in this supplemental appendix as follows.

- Theorem 1 in the paper corresponds to Theorem SA-1 with $d = 2$.
- Theorem 2 in the paper is proven in Section SA-6.14.
- Theorem 3 in the paper is proven in Section SA-6.15.
- Theorem 4(i) in the paper corresponds in Theorem SA-2 with $d = 2$.
- Theorem 4(ii) in the paper corresponds in Theorem SA-3 with $d = 2$.
- Theorem 5(i) in the paper corresponds in Theorem SA-4 with $d = 2$.
- Theorem 5(ii) in the paper corresponds in Theorem SA-7 with $d = 2$.

- Theorem 6 in the paper is proven in Section SA-6.16.

SA-2 Preliminary Lemmas

Recall that $t \in \{0, 1\}$.

The following lemma gives a sufficient condition for Assumption SA-2.

Lemma SA-1 (Gram Invertibility). *Suppose the following conditions hold:*

1. Assumptions SA-1(i)(ii) and Assumption SA-2 (iii) hold.
2. $\mathcal{d}(\cdot, \cdot)$ is the Euclidean distance.
3. There exists a set $U \subseteq \mathbb{R}^d$, such that $K(\|\mathbf{u}\|) \geq \kappa > 0$ for all $\mathbf{u} \in U$, $\lambda_{\min}(\int_U \mathbf{r}_p(\|\mathbf{z}\|) \mathbf{r}_p(\|\mathbf{z}\|)^\top d\mathbf{z}) > 0$, and $\liminf_{h \downarrow 0} \inf_{\mathbf{x} \in \mathcal{B}} \int_U K(\|\mathbf{u}\|) \mathbf{1}(\mathbf{x} + h\mathbf{u} \in \mathcal{A}_t) d\mathbf{u} \gtrsim 1$.

Then Assumption SA-2 (iv) holds.

Lemma SA-2 (Gram). *Suppose Assumptions SA-1(i)(ii) and SA-2 hold. If $\frac{nh^d}{\log(1/h)} \rightarrow \infty$, then*

$$\begin{aligned} \sup_{\mathbf{x} \in \mathcal{B}} \|\widehat{\Psi}_{t,\mathbf{x}} - \Psi_{t,\mathbf{x}}\| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}}, & 1 &\lesssim_{\mathbb{P}} \inf_{\mathbf{x} \in \mathcal{B}} \|\widehat{\Psi}_{t,\mathbf{x}}\| \leq \sup_{\mathbf{x} \in \mathcal{B}} \|\widehat{\Psi}_{t,\mathbf{x}}\| \lesssim_{\mathbb{P}} 1, \\ \sup_{\mathbf{x} \in \mathcal{B}} \|\widehat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}\| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}}. \end{aligned}$$

Lemma SA-3 (Stochastic Linear Approximation). *Suppose Assumptions SA-1(i)(ii)(iii)(v) and SA-2 hold.*

If $\frac{nh^d}{\log(1/h)} \rightarrow \infty$, then

$$\begin{aligned} \sup_{\mathbf{x} \in \mathcal{B}} \|\mathbf{O}_{t,\mathbf{x}}\| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d}, \\ \sup_{\mathbf{x} \in \mathcal{B}} |\mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}}| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d}, \\ \sup_{\mathbf{x} \in \mathcal{B}} |\mathbf{e}_1^\top (\widehat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}) \mathbf{O}_{t,\mathbf{x}}| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d} \right). \end{aligned}$$

Lemma SA-4 (Covariance). *Suppose Assumptions SA-1 and SA-2 hold. If $\frac{nh^d}{\log(1/h)} \rightarrow \infty$, then*

$$\begin{aligned} \sup_{\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}} \|\widehat{\Upsilon}_{t,\mathbf{x}_1, \mathbf{x}_2} - \Upsilon_{t,\mathbf{x}_1, \mathbf{x}_2}\| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d}, \\ \sup_{\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}} nh^d |\widehat{\Xi}_{t,\mathbf{x}_1, \mathbf{x}_2} - \Xi_{t,\mathbf{x}_1, \mathbf{x}_2}| &\lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d}. \end{aligned}$$

If, in addition, $\frac{n^{\frac{v}{2+v}} h^d}{\log(1/h)} \rightarrow \infty$, then

$$\inf_{\mathbf{x} \in \mathcal{B}} \lambda_{\min}(\widehat{\Upsilon}_{t,\mathbf{x}, \mathbf{x}}) \gtrsim_{\mathbb{P}} 1, \quad \inf_{\mathbf{x} \in \mathcal{B}} \widehat{\Xi}_{t,\mathbf{x}, \mathbf{x}} \gtrsim_{\mathbb{P}} (nh^d)^{-1},$$

and

$$\sup_{\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}} \left| \frac{\widehat{\Xi}_{t, \mathbf{x}_1, \mathbf{x}_2}}{\sqrt{\widehat{\Xi}_{t, \mathbf{x}_1, \mathbf{x}_2} \widehat{\Xi}_{t, \mathbf{x}_2, \mathbf{x}_2}}} - \frac{\Xi_{t, \mathbf{x}_1, \mathbf{x}_2}}{\sqrt{\Xi_{t, \mathbf{x}_2, \mathbf{x}_2} \Xi_{t, \mathbf{x}_2, \mathbf{x}_2}}} \right| \lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d}.$$

Lemma SA-5 (Uniform Bias: Minimal Guarantee). *Suppose Assumptions SA-1 (i)(ii)(iii) and SA-2 hold. If $h \rightarrow 0$, then*

$$\sup_{\mathbf{x} \in \mathcal{B}} |\mathfrak{B}(\mathbf{x})| \lesssim h.$$

SA-3 Identification and Point Estimation

Theorem SA-1 (Distance-Based Identification). *Suppose Assumptions SA-1(i)-(iii) and SA-2 hold. Then, $\tau(\mathbf{x}) = \lim_{r \downarrow 0} \theta_{1, \mathbf{x}}(r) - \lim_{r \uparrow 0} \theta_{0, \mathbf{x}}(r)$ for all $\mathbf{x} \in \mathcal{B}$.*

Theorem SA-2 (Pointwise Convergence Rate). *Suppose Assumptions SA-1 and SA-2 hold. If $nh^d \rightarrow \infty$, then*

$$|\widehat{\vartheta}(\mathbf{x}) - \tau(\mathbf{x})| \lesssim_{\mathbb{P}} \frac{1}{\sqrt{nh^d}} + \frac{1}{n^{\frac{1+v}{2+v}} h^d} + |\mathfrak{B}(\mathbf{x})|.$$

Theorem SA-3 (Uniform Convergence Rate). *Suppose Assumptions SA-1 and SA-2 hold. If $\frac{nh^d}{\log(1/h)} \rightarrow \infty$, then*

$$\sup_{\mathbf{x} \in \mathcal{B}} |\widehat{\vartheta}(\mathbf{x}) - \tau(\mathbf{x})| \lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d} + \sup_{\mathbf{x} \in \mathcal{B}} |\mathfrak{B}(\mathbf{x})|.$$

SA-4 Distributional Approximation and Inference

Let $\mathbf{W} = ((\mathbf{X}_1^\top, Y_1), \dots, (\mathbf{X}_n^\top, Y_n))$, and recall that $t \in \{0, 1\}$. The feasible t-statistics is

$$\widehat{\mathbf{T}}(\mathbf{x}) = \frac{\widehat{\vartheta}(\mathbf{x}) - \tau(\mathbf{x})}{\sqrt{\widehat{\Xi}_{\mathbf{x}, \mathbf{x}}}}, \quad \mathbf{x} \in \mathcal{B}.$$

The associated $100(1 - \alpha)\%$ confidence interval estimator is

$$\widehat{\mathbf{I}}_\alpha(\mathbf{x}) = \left[\widehat{\vartheta}(\mathbf{x}) - \mathbf{q}_\alpha \sqrt{\widehat{\Xi}_{\mathbf{x}, \mathbf{x}}}, \widehat{\vartheta}(\mathbf{x}) + \mathbf{q}_\alpha \sqrt{\widehat{\Xi}_{\mathbf{x}, \mathbf{x}}} \right],$$

where \mathbf{q}_α denotes an appropriate quantile depending on the desired confidence level $\alpha \in (0, 1)$, and coverage objective (pointwise vs. uniform over \mathcal{B}). The following theorem establishes pointwise asymptotic normality and validity of confidence intervals. Let $\Phi(\cdot)$ be the cumulative distribution function of a standard univariate Gaussian random variable.

Theorem SA-4 (Confidence Intervals). *Suppose Assumptions SA-1 and SA-2 hold. If $n^{\frac{v}{2+v}} h^d \rightarrow \infty$ and*

$\sqrt{nh^d}|\mathfrak{B}(\mathbf{x})| \rightarrow 0$, then

$$\sup_{u \in \mathbb{R}} \left| \mathbb{P}(\widehat{\mathbf{T}}(\mathbf{x}) \leq u) - \Phi(u) \right| = o(1), \quad \mathbf{x} \in \mathcal{B},$$

and

$$\mathbb{P}(\tau(\mathbf{x}) \in \widehat{\mathbf{I}}_\alpha(\mathbf{x})) = 1 - \alpha + o(1), \quad \mathbf{x} \in \mathcal{B},$$

provided that $\mathbf{q}_\alpha = \inf\{c > 0 : \mathbb{P}(|\widehat{Z}| \geq c|\mathbf{W}) \leq \alpha\}$ with $\widehat{Z}|\mathbf{W} \sim \text{Normal}(0, \widehat{\Xi}_{\mathbf{x}, \mathbf{x}})$.

To conduct uniform inference, and in particular construct confidence bands, we rely on a new strong approximation result established in Section SA-5. First, we approximate (uniformly over $\mathbf{x} \in \mathcal{B}$) the feasible statistic $\widehat{\mathbf{T}}^{(\nu)}$ by the following linear statistic (which is a sum of independent random variables):

$$\overline{\mathbf{T}}_{\text{dis}}(\mathbf{x}) = \Xi_{\mathbf{x}, \mathbf{x}}^{-1/2} \left(\mathbf{e}_1^\top \Psi_{1, \mathbf{x}}^{-1} \mathbf{O}_{1, \mathbf{x}} - \mathbf{e}_1^\top \Psi_{0, \mathbf{x}}^{-1} \mathbf{O}_{0, \mathbf{x}} \right), \quad \mathbf{x} \in \mathcal{B}.$$

Theorem SA-5 (Stochastic Linearization). *Suppose Assumptions SA-1 and SA-2 hold. If $\frac{nh^d}{\log(1/h)} \rightarrow \infty$, then*

$$\sup_{\mathbf{x} \in \mathcal{B}} |\widehat{\mathbf{T}}(\mathbf{x}) - \overline{\mathbf{T}}(\mathbf{x})| \lesssim_{\mathbb{P}} \sqrt{\log(1/h)} \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d} \right) + \sqrt{nh^d} \sup_{\mathbf{x} \in \mathcal{B}} |\mathfrak{B}(\mathbf{x})|.$$

The pointwise (in \mathcal{B}) analogue of this result removes the $\log(1/h)$ penalty. See the proof of Theorem SA-4 for more details. To establish a Gaussian strong approximation for $\overline{\mathbf{T}}(\mathbf{x})$, define the class of functions $\mathcal{G} = \{g_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}$ and $\mathcal{M} = \{m_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}$, where

$$\begin{aligned} g_{\mathbf{x}}(\mathbf{u}) &= \mathbf{1}(\mathbf{u} \in \mathcal{A}_1) \mathfrak{K}_1(\mathbf{u}; \mathbf{x}) - \mathbf{1}(\mathbf{u} \in \mathcal{A}_0) \mathfrak{K}_0(\mathbf{u}; \mathbf{x}), \\ m_{\mathbf{x}}(\mathbf{u}) &= -\mathbf{1}(\mathbf{u} \in \mathcal{A}_1) \mathfrak{K}_1(\mathbf{u}; \mathbf{x}) \theta_{1, \mathbf{x}}^*(\mathcal{d}(\mathbf{u}, \mathbf{x})) + \mathbf{1}(\mathbf{u} \in \mathcal{A}_0) \mathfrak{K}_0(\mathbf{u}; \mathbf{x}) \theta_{0, \mathbf{x}}^*(\mathcal{d}(\mathbf{u}, \mathbf{x})), \end{aligned} \quad (\text{SA-2})$$

with

$$\mathfrak{K}_t(\mathbf{u}; \mathbf{x}) = \frac{1}{\sqrt{n\Xi_{\mathbf{x}, \mathbf{x}}}} \mathbf{e}_1^\top \Psi_{t, \mathbf{x}}^{-1} \mathbf{r}_p \left(\frac{\mathcal{d}(\mathbf{u}, \mathbf{x})}{h} \right) K_h(\mathcal{d}(\mathbf{u}, \mathbf{x})),$$

for all $\mathbf{u} \in \mathcal{X}$, $\mathbf{x} \in \mathcal{B}$, and $t \in \{0, 1\}$. In addition, let \mathcal{R} be the class of functions containing the singleton identity function $\text{Id} : \mathbb{R} \mapsto \mathbb{R}$, $\text{Id}(x) = x$. Then, $\overline{\mathbf{T}}(\mathbf{x})$ can be represented as

$$\overline{\mathbf{T}}(\mathbf{x}) = \frac{1}{\sqrt{n}} \sum_{i=1}^n \left[g_{\mathbf{x}}(\mathbf{X}_i) \text{Id}(y_i) + m_{\mathbf{x}}(\mathbf{X}_i) - \mathbb{E}[g_{\mathbf{x}}(\mathbf{X}_i) \text{Id}(y_i) + m_{\mathbf{x}}(\mathbf{X}_i)] \right].$$

Following Cattaneo and Yu [2025], we define the multiplicative separable empirical processes by

$$M_n(g, r) = \frac{1}{\sqrt{n}} \sum_{i=1}^n [g(\mathbf{x}_i) r(y_i) - \mathbb{E}[g(\mathbf{x}_i) r(y_i)]], \quad g \in \mathcal{G}, r \in \mathcal{R},$$

which implies that

$$\overline{\mathbf{T}}(\mathbf{x}) = M_n(g_{\mathbf{x}}, \text{Id}) + M_n(m_{\mathbf{x}}, 1), \quad \mathbf{x} \in \mathcal{B}.$$

Leveraging ideas in Cattaneo and Yu [2025], Theorem SA-8 gives a new Gaussian strong approximation that can be applied to $\bar{T}(\mathbf{x})$. This new theorem allows for polynomial moment bound on the conditional distribution of $Y_i|\mathbf{X}_i$.

Theorem SA-6 (Gaussian Strong Approximation: \bar{T}). *Suppose Assumptions SA-1 and SA-2 hold, and that there exists a constant $C > 0$ such that for $t \in \{0, 1\}$ and for any $\mathbf{x} \in \mathcal{B}$, the De Giorgi perimeter of the set $E_{t,\mathbf{x}} = \{\mathbf{y} \in \mathcal{A}_t : (\mathbf{y} - \mathbf{x})/h \in \text{Supp}(K)\}$ satisfies $\mathcal{L}(E_{t,\mathbf{x}}) \leq Ch^{d-1}$. If $\liminf_{n \rightarrow \infty} \frac{\log h}{\log n} > -\infty$ and $nh^d \rightarrow \infty$ as $n \rightarrow \infty$, then (on a possibly enlarged probability space) there exists a mean-zero Gaussian process Z indexed by \mathcal{B} with almost surely continuous sample path such that*

$$\mathbb{E} \left[\sup_{\mathbf{x} \in \mathcal{B}} |\bar{T}(\mathbf{x}) - z(\mathbf{x})| \right] \lesssim (\log(n))^{\frac{3}{2}} \left(\frac{1}{nh^d} \right)^{\frac{1}{2d+2} \frac{v}{v+2}} + \log(n) \left(\frac{1}{n^{\frac{v}{2+v}} h^d} \right)^{\frac{1}{2}},$$

where \lesssim is up to a universal constant, and $Z^{(\nu)}$ has the same covariance structure as \bar{T} ; i.e., $\text{Cov}[\bar{T}(\mathbf{x}_1), \bar{T}(\mathbf{x}_2)] = \text{Cov}[Z(\mathbf{x}_1), Z(\mathbf{x}_2)]$ for all $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}$.

Theorem SA-6 can be used to construct confidence bands for $(\tau(\mathbf{x}) : \mathbf{x} \in \mathcal{B})$. Let $(\hat{Z}(\mathbf{x}) : \mathbf{x} \in \mathcal{B})$ be a (conditionally on \mathbf{W}) mean-zero Gaussian process with feasible (conditional) covariance function

$$\text{Cov} \left[\hat{Z}(\mathbf{x}_1), \hat{Z}(\mathbf{x}_2) \middle| \mathbf{W} \right] = \frac{\sqrt{\hat{\Xi}_{\mathbf{x}_1, \mathbf{x}_2}}}{\sqrt{\hat{\Xi}_{\mathbf{x}_1, \mathbf{x}_1}} \sqrt{\hat{\Xi}_{\mathbf{x}_2, \mathbf{x}_2}}}, \quad \mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}.$$

Theorem SA-7 (Confidence Bands). *Suppose the assumptions and conditions in Theorem SA-6 hold. If $\liminf_{n \rightarrow \infty} \frac{\log h}{\log n} > -\infty$, $\frac{n^{\frac{v}{2+v}} h^d}{(\log n)^3} \rightarrow \infty$ and $\sqrt{nh^d} \sup_{\mathbf{x} \in \mathcal{B}} |\mathfrak{B}(\mathbf{x})| \rightarrow 0$, then*

$$\sup_{u \in \mathbb{R}} \left| \mathbb{P} \left(\sup_{\mathbf{x} \in \mathcal{B}} |\hat{T}(\mathbf{x})| \leq u \right) - \mathbb{P} \left(\sup_{\mathbf{x} \in \mathcal{B}} |\hat{Z}(\mathbf{x})| \leq u \middle| \mathbf{W} \right) \right| = o_{\mathbb{P}}(1)$$

and

$$\mathbb{P} \left[\tau^{(\nu)}(\mathbf{x}) \in \hat{\Gamma}_{\alpha}^{(\nu)}(\mathbf{x}), \text{ for all } \mathbf{x} \in \mathcal{B} \right] = 1 - \alpha + o(1),$$

provided that $\mathbf{q}_{\alpha} = \inf \{c > 0 : \mathbb{P}(\sup_{\mathbf{x} \in \mathcal{B}} |\hat{Z}^{(\nu)}(\mathbf{x})| \geq c | \mathbf{W}) \leq \alpha\}$.

SA-5 Gaussian Strong Approximation

We present a Gaussian strong approximation theorem, which is the key technical tool behind Theorem SA-6. The theorem builds on and generalizes the results in Cattaneo and Yu [2025]. Consider the *residual-based empirical process* given by

$$M_n[g, r] = \frac{1}{\sqrt{n}} \sum_{i=1}^n \left[g(\mathbf{x}_i) r(y_i) - \mathbb{E}[g(\mathbf{x}_i) r(y_i)] \right], \quad g \in \mathcal{G}, r \in \mathcal{R}.$$

where \mathcal{G} and \mathcal{R} are classes of functions satisfying certain regularity conditions.

SA-5.1 Definitions for Function Spaces

Let \mathcal{F} be a class of measurable functions from a probability space $(\mathbb{R}^q, \mathcal{B}(\mathbb{R}^q), \mathbb{P})$ to \mathbb{R} . We introduce several definitions that capture properties of \mathcal{F} .

- (i) \mathcal{F} is pointwise measurable if it contains a countable subset \mathcal{G} such that for any $f \in \mathcal{F}$, there exists a sequence $(g_m : m \geq 1) \subseteq \mathcal{G}$ such that $\lim_{m \rightarrow \infty} g_m(\mathbf{u}) = f(\mathbf{u})$ for all $\mathbf{u} \in \mathbb{R}^q$.
- (ii) Let $\text{Supp}(\mathcal{F}) = \cup_{f \in \mathcal{F}} \text{Supp}(f)$. A probability measure $\mathbb{Q}_{\mathcal{F}}$ on $(\mathbb{R}^q, \mathcal{B}(\mathbb{R}^q))$ is a surrogate measure for \mathbb{P} with respect to \mathcal{F} if

- (i) $\mathbb{Q}_{\mathcal{F}}$ agrees with \mathbb{P} on $\text{Supp}(\mathbb{P}) \cap \text{Supp}(\mathcal{F})$.
- (ii) $\mathbb{Q}_{\mathcal{F}}(\text{Supp}(\mathcal{F}) \setminus \text{Supp}(\mathbb{P})) = 0$.

Let $\mathcal{Q}_{\mathcal{F}} = \text{Supp}(\mathbb{Q}_{\mathcal{F}})$.

- (iii) For $q = 1$ and an interval $\mathcal{J} \subseteq \mathbb{R}$, the pointwise total variation of \mathcal{F} over \mathcal{J} is

$$\text{pTV}_{\mathcal{F}, \mathcal{J}} = \sup_{f \in \mathcal{F}} \sup_{P \geq 1} \sup_{\mathcal{P}_P \in \mathcal{J}} \sum_{i=1}^{P-1} |f(a_{i+1}) - f(a_i)|,$$

where $\mathcal{P}_P = \{(a_1, \dots, a_P) : a_1 \leq \dots \leq a_P\}$ denotes the collection of all partitions of \mathcal{J} .

- (iv) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the total variation of \mathcal{F} over \mathcal{C} is

$$\text{TV}_{\mathcal{F}, \mathcal{C}} = \inf_{\mathcal{U} \in \mathcal{O}(\mathcal{C})} \sup_{f \in \mathcal{F}} \sup_{\phi \in \mathcal{D}_q(\mathcal{U})} \int_{\mathbb{R}^q} f(\mathbf{u}) \text{div}(\phi)(\mathbf{u}) d\mathbf{u} / \|\phi\|_2 \|\phi\|_{\infty},$$

where $\mathcal{O}(\mathcal{C})$ denotes the collection of all open sets that contains \mathcal{C} , and $\mathcal{D}_q(\mathcal{U})$ denotes the space of infinitely differentiable functions from \mathbb{R}^q to \mathbb{R}^q with compact support contained in \mathcal{U} .

- (v) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the local total variation constant of \mathcal{F} over \mathcal{C} , is a positive number $K_{\mathcal{F}, \mathcal{C}}$ such that for any cube $\mathcal{D} \subseteq \mathbb{R}^q$ with edges of length ℓ parallel to the coordinate axes,

$$\text{TV}_{\mathcal{F}, \mathcal{D} \cap \mathcal{C}} \leq K_{\mathcal{F}, \mathcal{C}} \ell^{d-1}.$$

- (vi) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the envelopes of \mathcal{F} over \mathcal{C} are

$$\mathbf{M}_{\mathcal{F}, \mathcal{C}} = \sup_{\mathbf{u} \in \mathcal{C}} M_{\mathcal{F}, \mathcal{C}}(\mathbf{u}), \quad M_{\mathcal{F}, \mathcal{C}}(\mathbf{u}) = \sup_{f \in \mathcal{F}} |f(\mathbf{u})|, \quad \mathbf{u} \in \mathcal{C}.$$

- (vii) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the Lipschitz constant of \mathcal{F} over \mathcal{C} is

$$\mathbf{L}_{\mathcal{F}, \mathcal{C}} = \sup_{f \in \mathcal{F}} \sup_{\mathbf{u}_1, \mathbf{u}_2 \in \mathcal{C}} \frac{|f(\mathbf{u}_1) - f(\mathbf{u}_2)|}{\|\mathbf{u}_1 - \mathbf{u}_2\|_{\infty}}.$$

- (viii) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the L_1 bound of \mathcal{F} over \mathcal{C} is

$$\mathbf{E}_{\mathcal{F}, \mathcal{C}} = \sup_{f \in \mathcal{F}} \int_{\mathcal{C}} |f| d\mathbb{P}.$$

(ix) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the uniform covering number of \mathcal{F} with envelope $M_{\mathcal{F},\mathcal{C}}$ over \mathcal{C} is

$$\mathbf{N}_{\mathcal{F},\mathcal{C}}(\delta, M_{\mathcal{F},\mathcal{C}}) = \sup_{\mu} N(\mathcal{F}, \|\cdot\|_{\mu,2}, \delta \|M_{\mathcal{F},\mathcal{C}}\|_{\mu,2}), \quad \delta \in (0, \infty),$$

where the supremum is taken over all finite discrete measures on $(\mathcal{C}, \mathcal{B}(\mathcal{C}))$. We assume that $M_{\mathcal{F},\mathcal{C}}(\mathbf{u})$ is finite for every $\mathbf{u} \in \mathcal{C}$.

(x) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, the uniform entropy integral of \mathcal{F} with envelope $M_{\mathcal{F},\mathcal{C}}$ over \mathcal{C} is

$$J_{\mathcal{C}}(\delta, \mathcal{F}, M_{\mathcal{F},\mathcal{C}}) = \int_0^\delta \sqrt{1 + \log \mathbf{N}_{\mathcal{F},\mathcal{C}}(\varepsilon, M_{\mathcal{F},\mathcal{C}})} d\varepsilon,$$

where it is assumed that $M_{\mathcal{F},\mathcal{C}}(\mathbf{u})$ is finite for every $\mathbf{u} \in \mathcal{C}$.

(xi) For a non-empty $\mathcal{C} \subseteq \mathbb{R}^q$, \mathcal{F} is a VC-type class with envelope $M_{\mathcal{F},\mathcal{C}}$ over \mathcal{C} if (i) $M_{\mathcal{F},\mathcal{C}}$ is measurable and $M_{\mathcal{F},\mathcal{C}}(\mathbf{u})$ is finite for every $\mathbf{u} \in \mathcal{C}$, and (ii) there exist $\mathbf{c}_{\mathcal{F},\mathcal{C}} > 0$ and $\mathbf{d}_{\mathcal{F},\mathcal{C}} > 0$ such that

$$\mathbf{N}_{\mathcal{F},\mathcal{C}}(\varepsilon, M_{\mathcal{F},\mathcal{C}}) \leq \mathbf{c}_{\mathcal{F},\mathcal{C}} \varepsilon^{-\mathbf{d}_{\mathcal{F},\mathcal{C}}}, \quad \varepsilon \in (0, 1).$$

If a surrogate measure $\mathbb{Q}_{\mathcal{F}}$ for \mathbb{P} with respect to \mathcal{F} has been assumed, and it is clear from the context, we drop the dependence on $\mathcal{C} = \mathcal{Q}_{\mathcal{F}}$ for all quantities in the previous definitions. That is, to save notation, we set $\text{TV}_{\mathcal{F}} = \text{TV}_{\mathcal{F},\mathcal{Q}_{\mathcal{F}}}$, $\mathbf{K}_{\mathcal{F}} = \mathbf{K}_{\mathcal{F},\mathcal{Q}_{\mathcal{F}}}$, $\mathbf{M}_{\mathcal{F}} = \mathbf{M}_{\mathcal{F},\mathcal{Q}_{\mathcal{F}}}$, $M_{\mathcal{F}}(\mathbf{u}) = M_{\mathcal{F},\mathcal{Q}_{\mathcal{F}}}(\mathbf{u})$, $\mathbf{L}_{\mathcal{F}} = \mathbf{L}_{\mathcal{F},\mathcal{Q}_{\mathcal{F}}}$, and so on, whenever there is no confusion.

SA-5.2 Multiplicative-Separable Empirical Process

The following theorem generalizes Cattaneo and Yu [2025, Theorem SA.1] by requiring only bounded polynomial moments for y_i conditional on \mathbf{x}_i .

Theorem SA-8 (Strong Approximation for $(M_n(g, r) + M_n(h, s) : g \in \mathcal{G}, r \in \mathcal{R}, h \in \mathcal{H}, s \in \mathcal{S})$). *Suppose $(\mathbf{z}_i = (\mathbf{x}_i, y_i) : 1 \leq i \leq n)$ are i.i.d. random vectors taking values in $(\mathbb{R}^{d+1}, \mathcal{B}(\mathbb{R}^{d+1}))$ with common law \mathbb{P}_Z , where \mathbf{x}_i has distribution \mathbb{P}_X supported on $\mathcal{X} \subseteq \mathbb{R}^d$, y_i has distribution \mathbb{P}_Y supported on $\mathcal{Y} \subseteq \mathbb{R}$, $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[|y_i|^{2+v} | \mathbf{x}_i = \mathbf{x}] \leq 2$ for some $v > 0$, and the following conditions hold.*

- (i) \mathcal{G} and \mathcal{H} are real-valued pointwise measurable classes of functions on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d), \mathbb{P}_X)$.
- (ii) There exists a surrogate measure $\mathbb{Q}_{\mathcal{G} \cup \mathcal{H}}$ for \mathbb{P}_X with respect to $\mathcal{G} \cup \mathcal{H}$ such that $\mathbb{Q}_{\mathcal{G} \cup \mathcal{H}} = \mathbf{m} \circ \phi_{\mathcal{G} \cup \mathcal{H}}$, where the normalizing transformation $\phi_{\mathcal{G} \cup \mathcal{H}} : \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}} \mapsto [0, 1]^d$ is a diffeomorphism.
- (iii) \mathcal{G} is a VC-type class with envelope $\mathbf{M}_{\mathcal{G},\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}$ over $\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}$ with $\mathbf{c}_{\mathcal{G},\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \geq e$ and $\mathbf{d}_{\mathcal{G},\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \geq 1$. \mathcal{H} is a VC-type class with envelope $\mathbf{M}_{\mathcal{H},\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}$ over $\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}$ with $\mathbf{c}_{\mathcal{H},\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \geq e$ and $\mathbf{d}_{\mathcal{H},\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \geq 1$.
- (iv) \mathcal{R} and \mathcal{S} are real-valued pointwise measurable classes of functions on $(\mathbb{R}, \mathcal{B}(\mathbb{R}), \mathbb{P}_Y)$.
- (v) \mathcal{R} is a VC-type class with envelope $M_{\mathcal{R},\mathcal{Y}}$ over \mathcal{Y} with $\mathbf{c}_{\mathcal{R},\mathcal{Y}} \geq e$ and $\mathbf{d}_{\mathcal{R},\mathcal{Y}} \geq 1$, where $M_{\mathcal{R},\mathcal{Y}}(y) + \text{pTV}_{\mathcal{R},(-|y|,|y|)} \leq \mathbf{v}(1 + |y|)$ for all $y \in \mathcal{Y}$, for some $\mathbf{v} > 0$. \mathcal{S} is a VC-type class with envelope $M_{\mathcal{S},\mathcal{Y}}$ over \mathcal{Y} with $\mathbf{c}_{\mathcal{S},\mathcal{Y}} \geq e$ and $\mathbf{d}_{\mathcal{S},\mathcal{Y}} \geq 1$, where $M_{\mathcal{S},\mathcal{Y}}(y) + \text{pTV}_{\mathcal{S},(-|y|,|y|)} \leq \mathbf{v}(1 + |y|)$ for all $y \in \mathcal{Y}$, for some $\mathbf{v} > 0$.

- (vi) There exists a constant \mathbf{k} such that $|\log_2 \mathbf{E}| + |\log_2 \mathbf{TV}| + |\log_2 \mathbf{M}| \leq \mathbf{k} \log_2(n)$, where $\mathbf{E} = \max\{\mathbf{E}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}, \mathbf{E}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}\}$, $\mathbf{TV} = \max\{\mathbf{TV}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}, \mathbf{TV}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}\}$ and $\mathbf{M} = \max\{\mathbf{M}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}, \mathbf{M}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}\}$.

Consider the empirical process

$$A_n(g, h, r, s) = M_n(g, r) + M_n(h, s), \quad g \in \mathcal{G}, r \in \mathcal{R}, h \in \mathcal{H}, s \in \mathcal{S}.$$

Then, on a possibly enlarged probability space, there exists a sequence of mean-zero Gaussian processes $(Z_n^A(g, h, r, s) : g \in \mathcal{G}, h \in \mathcal{H}, r \in \mathcal{R}, s \in \mathcal{S})$ with almost sure continuous trajectories such that:

- $\mathbb{E}[A_n(g_1, h_1, r_1, s_1)A_n(g_2, h_2, r_2, s_2)] = \mathbb{E}[Z_n^A(g_1, h_1, r_1, s_1)Z_n^A(g_2, h_2, r_2, s_2)]$ holds for all $(g_1, h_1, r_1, s_1), (g_2, h_2, r_2, s_2) \in \mathcal{G} \times \mathcal{H} \times \mathcal{R} \times \mathcal{S}$, and
- $\mathbb{E}[\|A_n - Z_n^A\|_{\mathcal{G} \times \mathcal{H} \times \mathcal{R} \times \mathcal{S}}] \leq C\mathbf{v}((\mathbf{d} \log(\mathbf{c}n))^{\frac{3}{2}} \mathbf{r}_n^{\frac{\mathbf{v}}{\mathbf{v}+2}} (\sqrt{\mathbf{ME}})^{\frac{2}{\mathbf{v}+2}} + \mathbf{d} \log(\mathbf{c}n) \mathbf{M} n^{-\frac{\mathbf{v}/2}{2+\mathbf{v}}} + \mathbf{d} \log(\mathbf{c}n) \mathbf{M} n^{-\frac{1}{2}} \left(\frac{\sqrt{\mathbf{ME}}}{\mathbf{r}_n}\right)^{\frac{2}{\mathbf{v}+2}}),$

where C is a universal constant, $\mathbf{c} = \mathbf{c}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} + \mathbf{c}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} + \mathbf{c}_{\mathcal{R}, \mathcal{Y}} + \mathbf{c}_{\mathcal{S}, \mathcal{Y}} + \mathbf{k}$, $\mathbf{d} = \mathbf{d}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \mathbf{d}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \mathbf{d}_{\mathcal{R}, \mathcal{Y}} \mathbf{d}_{\mathcal{S}, \mathcal{Y}} \mathbf{k}$,

$$\mathbf{r}_n = \min \left\{ \frac{(\mathbf{c}_1^d \mathbf{M}^{d+1} \mathbf{TV}^d \mathbf{E})^{1/(2d+2)}}{n^{1/(2d+2)}}, \frac{(\mathbf{c}_1^{\frac{d}{2}} \mathbf{c}_2^{\frac{d}{2}} \mathbf{MTV}^{\frac{d}{2}} \mathbf{EL}^{\frac{d}{2}})^{1/(d+2)}}{n^{1/(d+2)}} \right\},$$

$$\mathbf{c}_1 = d \sup_{\mathbf{x} \in \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \prod_{j=1}^{d-1} \sigma_j(\nabla \phi_{\mathcal{G} \cup \mathcal{H}}(\mathbf{x})), \quad \mathbf{c}_2 = \sup_{\mathbf{x} \in \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \frac{1}{\sigma_d(\nabla \phi_{\mathcal{G} \cup \mathcal{H}}(\mathbf{x}))}.$$

SA-6 Proofs

SA-6.1 Proof of Lemma SA-1

Assumption SA-1 (ii) implies

$$\begin{aligned} \Psi_{t, \mathbf{x}} &= \mathbb{E} \left[\mathbf{r}_p \left(\frac{\|\mathbf{X}_i - \mathbf{x}\|}{h} \right) \mathbf{r}_p \left(\frac{\|\mathbf{X}_i - \mathbf{x}\|}{h} \right)^\top K_h(\|\mathbf{X}_i - \mathbf{x}\|) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t) \right] \\ &= \int_{\mathcal{A}_t} \mathbf{r}_p \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h} \right) \mathbf{r}_p \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h} \right)^\top K_h(\|\mathbf{u} - \mathbf{x}\|) f(\mathbf{u}) d\mathbf{u} \\ &= f(\mathbf{x}) \int_{\mathcal{A}_t} \mathbf{r}_p \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h} \right) \mathbf{r}_p \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h} \right)^\top K_h(\|\mathbf{u} - \mathbf{x}\|) d\mathbf{u} + o(1), \end{aligned}$$

where in the last line we have used $\int_{\mathcal{A}_t} \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h}\right)^{\mathbf{v}} K_h(\|\mathbf{u} - \mathbf{x}\|) d\mathbf{u} = O(1)$ for any multi-index \mathbf{v} from standard change of variable argument.

I. Polynomial Representation of Minimum Eigenvalue

For simplicity, call

$$\mathbf{S}_{t, \mathbf{x}} = \lim_{h \rightarrow 0} \mathbf{S}_{t, \mathbf{x}}(h), \quad \mathbf{S}_{t, \mathbf{x}}(h) = \int_{\mathcal{A}_t} \mathbf{r}_p \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h} \right) \mathbf{r}_p \left(\frac{\|\mathbf{u} - \mathbf{x}\|}{h} \right)^\top K_h(\|\mathbf{u} - \mathbf{x}\|) d\mathbf{u}.$$

A change of variable gives

$$\mathbf{S}_{t, \mathbf{x}}(h) = \int \mathbf{r}_p(\|\mathbf{z}\|) \mathbf{r}_p(\|\mathbf{z}\|)^\top K(\|\mathbf{z}\|) \mathbf{1}(\mathbf{x} + h\mathbf{z} \in \mathcal{A}_t) d\mathbf{z}.$$

Let $\mathbf{a} \in \mathbb{R}^{\mathfrak{p}_p}$, where $\mathfrak{p}_p = \frac{(d+p)!}{d!p!}$. Then the equivalent representation of minimum eigenvalue gives

$$\begin{aligned}\lambda_{\min}(\mathbf{S}_{t,\mathbf{x}}(h)) &= \min_{\|\mathbf{a}\|=1} \int (\mathbf{a}^\top \mathbf{r}_p(\|\mathbf{z}\|))^2 K(\|\mathbf{z}\|) \mathbf{1}(\mathbf{x} + h\mathbf{z} \in \mathcal{A}_t) d\mathbf{z} \\ &\geq \kappa \min_{\|\mathbf{a}\|=1} \int_U (\mathbf{a}^\top \mathbf{r}_p(\|\mathbf{z}\|))^2 \mathbf{1}(\mathbf{x} + h\mathbf{z} \in \mathcal{A}_t) d\mathbf{z},\end{aligned}\tag{SA-3}$$

where in the last line we have used $K(\mathbf{u}) \geq \kappa$ for all $\mathbf{u} \in U$.

II. Mass Retaining Ratio in Treatment/Control Region

Denote $E_h(\mathbf{x}, t) = \{\mathbf{z} \in U : \mathbf{x} + h\mathbf{z} \in \mathcal{A}_t\}$. Assumption SA-2 (iii) implies there is some upper bound $\Lambda > 0$ of $K(\cdot)$. Hence for $c_0 = 1/2 \liminf_{h \downarrow 0} \inf_{\mathbf{x} \in \mathcal{B}} \int_U K(\|\mathbf{u}\|) \mathbf{1}(\mathbf{x} + h\mathbf{u} \in \mathcal{A}_t) d\mathbf{u}$, we have

$$\Lambda \mathfrak{m}(E_h(\mathbf{x}, t)) \geq \int_U K(\|\mathbf{u}\|) \mathbf{1}(\mathbf{x} + h\mathbf{u} \in \mathcal{A}_t) d\mathbf{u} \geq c_0$$

for small enough h , which implies

$$\mathfrak{m}(E_h(\mathbf{x}, t)) \geq \alpha \mathfrak{m}(U), \quad \alpha = \frac{c_0}{\Lambda \mathfrak{m}(U)}.\tag{SA-4}$$

III. L_2 Integral of Polynomials in Full v.s. Treatment/Control Regions

Consider $S = \{f \in \mathcal{P}_{p+1} : \int_U f(\|\mathbf{u}\|)^2 d\mathbf{u} = 1\}$, where \mathcal{P}_{p+1} is the collection of all $(p+1)$ -order polynomials. Let $(\phi_j, 1 \leq j \leq p+1)$ be a set of orthonormal basis of $(\mathcal{P}_{p+1}, \|\cdot\|_{L_2})$. Then $T(\mathbf{a}) = \sum_{j=1}^{p+1} a_j \phi_j$ is an isometry. Since $T(S) = \{\mathbf{a} \in \mathbb{R}^{p+1} : \|\mathbf{a}\| = 1\}$ is compact, S is also compact in $(\mathcal{P}_{p+1}, \|\cdot\|_{L_2})$. Since \mathcal{P}_{p+1} is $(p+1)$ -dimensional, equivalent of norms implies that S is also compact in $(\mathcal{P}_{p+1}, \|\cdot\|_{L_\infty})$. Now consider

$$\Phi_q(\varepsilon) = \mathfrak{m}(\{\mathbf{u} \in U : |q(\mathbf{u})| < \varepsilon\}), \quad q \in S, \varepsilon > 0,$$

and

$$\psi(q) = \sup \left\{ \varepsilon > 0 : \Phi_q(\varepsilon) \leq \frac{\alpha}{2} \mathfrak{m}(U) \right\}.$$

Since $\int_U q^2 = 1$ and q is polynomial on norm, $\lim_{\varepsilon \downarrow 0} \Phi_q(\varepsilon) = 0$ and $\Phi_q(\|q\|_\infty) = \mathfrak{m}(U)$. Continuity and Lipchitzness of $q \in S$ imply $\psi(q) > 0$ for all $q \in S$.

Next, we want to show ψ is lower-semicontinuous function on $(\mathcal{P}_{p+1}, \|\cdot\|_{L_\infty})$. Suppose $q_n \rightarrow q$ uniformly on U . For every $\varepsilon_0 \in (0, \psi(q))$, there exists $\eta > 0$ such that $\Phi_q(\varepsilon_0) \leq \frac{\alpha}{2} \mathfrak{m}(U) - \eta$. Continuity of polynomials and the fact that level sets of polynomials have zero Lebesgue measure imply $\mathbf{1}_{\{|q_n| < \varepsilon_0\}}(\cdot) \rightarrow \mathbf{1}_{\{|q| < \varepsilon_0\}}(\cdot)$ almost surely. By Dominated Convergence Theorem, $\Phi_{q_n}(\varepsilon_0) \rightarrow \Phi_q(\varepsilon_0)$. Hence for large enough n , $\Phi_{q_n}(\varepsilon_0) \leq \frac{\alpha}{2} \mathfrak{m}(U)$, which implies $\varepsilon_0 \leq \psi(q_n)$. This implies $\liminf_{n \rightarrow \infty} \psi(q_n) \geq \varepsilon_0$. Since ε_0 is arbitrary in $(0, \psi(q))$, we have $\liminf_{n \rightarrow \infty} \psi(q_n) \geq \psi(q)$.

Compactness of S and lower-semicontinuity of ψ implies ψ attains its minimum on S . Since $\psi(q) > 0$ for

all $q \in S$, we know $\varepsilon_* = \inf_{q \in S} \psi(q) > 0$. Then for every $q \in S$,

$$\begin{aligned} \int_{E_h(\mathbf{x}, t)} q^2 &\geq \varepsilon_*^2 \mathbf{m}\left(E_h(\mathbf{x}, t) \setminus \{|q| \leq \varepsilon_*\}\right) \\ &\geq \varepsilon_*^2 \left(\mathbf{m}(E_h(\mathbf{x}, t)) - \mathbf{m}(\{|q| \leq \varepsilon_*\})\right) \\ &\geq \varepsilon_*^2 \frac{\alpha}{2} \mathbf{m}(U). \end{aligned}$$

Scaling q from S gives

$$\int_{E_h(\mathbf{x}, t)} q^2 \geq \varepsilon_*^2 \frac{\alpha}{2} \int_U q^2, \quad q \in \mathcal{P}_{p+1}. \quad (\text{SA-5})$$

IV. Lower Bound of Minimum Eigenvalue

Equations (SA-3), (SA-4) and (SA-5) together give for small enough h ,

$$\begin{aligned} \inf_{\mathbf{x} \in \mathcal{B}} \lambda_{\min}(\mathbf{S}_{t, \mathbf{x}}(h)) &\geq \kappa \inf_{\mathbf{x} \in \mathcal{B}} \min_{\|\mathbf{a}\|=1} \int_{E_h(\mathbf{x}, t)} (\mathbf{a}^\top \mathbf{r}_p(\|\mathbf{z}\|))^2 d\mathbf{z}, \\ &\geq \kappa \varepsilon_*^2 \frac{\alpha}{2} \min_{\|\mathbf{a}\|=1} \int_U (\mathbf{a}^\top \mathbf{r}_p(\|\mathbf{z}\|))^2 d\mathbf{z} \\ &\geq \kappa \varepsilon_*^2 \frac{\alpha}{2} \lambda_{\min} \left(\int_U \mathbf{r}_p(\|\mathbf{z}\|) \mathbf{r}_p(\|\mathbf{z}\|)^\top d\mathbf{z} \right), \end{aligned}$$

which implies $\liminf_{h \rightarrow 0} \inf_{\mathbf{x} \in \mathcal{B}} \lambda_{\min}(\mathbf{S}_{t, \mathbf{x}}(h)) > 0$.

SA-6.2 Proof of Lemma SA-2

Since $\widehat{\Psi}_{t, \mathbf{x}}$ is a finite dimensional matrix, it suffices to show the stated rate of convergence for each entry. For $0 \leq v \leq p$, define $\mathcal{G} = \{g_n(\cdot, \mathbf{x}) \mathbf{1}(\cdot \in \mathcal{A}_t) : \mathbf{x} \in \mathcal{X}\}$ with

$$g_n(\xi, \mathbf{x}) = \left(\frac{\mathcal{d}(\xi, \mathbf{x})}{h} \right)^v \frac{1}{h^d} K\left(\frac{\mathcal{d}(\xi, \mathbf{x})}{h} \right), \quad \xi, \mathbf{x} \in \mathcal{X}.$$

We will show \mathcal{G} is a VC-type of class.

Constant Envelope Function. We assume K is continuous and has compact support, and hence there exists a constant C_1 such that $\sup_{\mathbf{x} \in \mathcal{X}} \|g_n(\cdot, \mathbf{x})\|_\infty \leq C_1 h^{-d} = G$.

Diameter of \mathcal{G} in L_2 . For each $\mathbf{x} \in \mathcal{X}$, $g_n(\cdot, \mathbf{x})$ is supported on $\{\xi : \mathcal{d}(\xi, \mathbf{x}) \leq h\}$. By Assumption SA-1(ii) and Assumption SA-2(i), $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{P}(\mathcal{d}(\mathbf{X}_i, \mathbf{x}) \leq h) \lesssim h^d$. It follows that $\sup_{\mathbf{x} \in \mathcal{X}} \|g_n(\cdot, \mathbf{x})\|_{\mathbb{P}, 2} \leq C_2 h^{-d/2}$ for some constant C_2 . We can take C_1 large enough so that $\sigma = C_2 h^{-d/2} \leq G = C_1 h^{-d}$.

Ratio. For some constant C_3 , $\delta = \frac{\sigma}{F} = C_3 \sqrt{h^d}$.

Covering Numbers. Case 1: K is Lipschitz. Let $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$. By Assumption SA-2,

$$\begin{aligned} &\sup_{\xi \in \mathcal{X}} |g_n(\xi, \mathbf{x}) - g_n(\xi, \mathbf{x}')| \\ &\leq \sup_{\xi \in \mathcal{X}} \left[\left(\frac{\mathcal{d}(\xi, \mathbf{x})}{h} \right)^v - \left(\frac{\mathcal{d}(\xi, \mathbf{x}')}{h} \right)^v \right] K_h(\mathcal{d}(\xi, \mathbf{x})) + \left(\frac{\mathcal{d}(\xi, \mathbf{x}')}{h} \right)^v \left[K_h(\mathcal{d}(\xi, \mathbf{x})) - K_h(\mathcal{d}(\xi, \mathbf{x}')) \right] \\ &\lesssim h^{-d-1} \|\mathbf{x} - \mathbf{x}'\|_\infty. \end{aligned}$$

By Lipschitz continuity property of \mathcal{G} , for any $\varepsilon \in (0, 1]$ and for any finitely supported measure Q and metric $\|\cdot\|_{Q,2}$ based on $L_2(Q)$,

$$N(\{g_n(\cdot, \mathbf{x}) : \mathbf{x} \in \mathcal{X}\}, \|\cdot\|_{Q,2}, \varepsilon \|G\|_{Q,2}) \leq N(\mathcal{X}, \|\cdot\|_\infty, \varepsilon \|G\|_{Q,2} h^{d+1}) \stackrel{(i)}{\lesssim} \left(\frac{\text{diam}(\mathcal{X})}{\varepsilon \|G\|_{Q,2} h^{d+1}} \right)^d \lesssim \left(\frac{\text{diam}(\mathcal{X})}{\varepsilon h} \right)^d,$$

where inequality (i) uses the fact that $\varepsilon \|G\|_{Q,2} h^{d+1} \lesssim \varepsilon h \lesssim 1$. Thus, \mathcal{G} forms a VC-type class in that $\sup_Q N(\mathcal{G}, \|\cdot\|_{Q,2}, \varepsilon \|G\|_{Q,2}) \lesssim (C_1/\varepsilon)^{C_2}$ for all $\varepsilon \in (0, 1]$ with $C_1 = \frac{\text{diam}(\mathcal{X})}{h}$ and $C_2 = d$. Moreover, for any discrete measure Q , and for any $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$, $\|g_n(\cdot, \mathbf{x})\mathbf{1}(\cdot \in \mathcal{A}_t) - g_n(\cdot, \mathbf{x}')\mathbf{1}(\cdot \in \mathcal{A}_t)\|_{Q,2} \leq \|g_n(\cdot, \mathbf{x}) - g_n(\cdot, \mathbf{x}')\|_{Q,2}$. Therefore,

$$\sup_Q N(\mathcal{G}, \|\cdot\|_{Q,2}, \varepsilon \|G\|_{Q,2}) \leq N(\mathcal{G}, \|\cdot\|_{Q,2}, \varepsilon \|G\|_{Q,2}) \leq (C_1/\varepsilon)^{C_2}, \quad \varepsilon \in (0, 1],$$

where the supremum is taken over all finite discrete measures on \mathcal{X} .

Case 2: $k = \mathbf{1}(\cdot \in [-1, 1])$. Consider

$$m_n(\xi, \mathbf{x}) = \left(\frac{\mathcal{d}(\xi, \mathbf{x})}{h} \right)^v \frac{1}{h} \mathbf{1}(\xi \in \mathcal{A}_t), \quad \xi, \mathbf{x} \in \mathcal{X},$$

$\mathcal{M} = \{m_n(\mathcal{d}(\cdot, \mathbf{x}) : \mathbf{x} \in \mathcal{B})\}$ and the constant envelope function $M = C_4 h^{-v-1}$, for some constant C_4 only depending on diameter of \mathcal{X} . The same argument as before shows that for any discrete measure Q , we have

$$N(\mathcal{M}, \|\cdot\|_{Q,2}, \varepsilon \|M\|_{Q,2}) \leq N(\mathcal{X}, \|\cdot\|_\infty, \varepsilon \|M\|_{Q,2} h^{1+v+1}) \lesssim \left(\frac{\text{diam}(\mathcal{X})}{\varepsilon \|M\|_{Q,2} h^{1+v+1}} \right)^d \lesssim \left(\frac{\text{diam}(\mathcal{X})}{\varepsilon h} \right)^d.$$

The class $\mathcal{L} = \{\mathbf{1}((\cdot - \mathbf{x})/h \in [-1, 1]^d) : \mathbf{x} \in \mathcal{B}\}$ has VC dimension no greater than $2d$ [van der Vaart and Wellner, 1996, Example 2.6.1], and by van der Vaart and Wellner [1996, Theorem 2.6.4],

$$\sup_Q N(\mathcal{G}, \|\cdot\|_{Q,2}, \varepsilon \|G\|_{Q,2}) \leq N(\mathcal{G}, \|\cdot\|_{Q,2}, \varepsilon \|G\|_{Q,2}) \leq (C_1/\varepsilon)^{C_2}, \quad \varepsilon \in (0, 1],$$

where the supremum is taken over all finite discrete measures on \mathcal{X} .

Maximal Inequality. By Chernozhukov et al. [2014b, Corollary 5.1] for the empirical process on class \mathcal{G} ,

$$\begin{aligned} \mathbb{E} \left[\sup_{l \in \mathcal{G}} |\mathbb{E}_n[l(\mathbf{X}_i)] - \mathbb{E}[l(\mathbf{X}_i)]| \right] &\lesssim \frac{\sigma}{\sqrt{n}} \sqrt{C_2 \log(C_1/\delta)} + \frac{\|G\|_{\mathbb{P},2} C_2 \log(C_1/\delta)}{n} \\ &\lesssim \frac{1}{\sqrt{nh^d}} \sqrt{d \log \left(\frac{\text{diam}(\mathcal{X})}{h^{1+d/2}} \right)} + \frac{1}{nh^d} d \log \left(\frac{\text{diam}(\mathcal{X})}{h^{1+d/2}} \right) \\ &\lesssim \sqrt{\frac{\log n}{nh^d}}. \end{aligned}$$

Thus, $\sup_{\mathbf{x} \in \mathcal{X}} \|\hat{\Psi}_{t,\mathbf{x}} - \Psi_{t,\mathbf{x}}\| \lesssim \sqrt{\frac{\log n}{nh^d}}$.

By Weyl's Theorem, $\sup_{\mathbf{x} \in \mathcal{X}} |\lambda_{\min}(\hat{\Psi}_{t,\mathbf{x}}) - \lambda_{\min}(\Psi_{t,\mathbf{x}})| \leq \sup_{\mathbf{x} \in \mathcal{X}} \|\hat{\Psi}_{t,\mathbf{x}} - \Psi_{t,\mathbf{x}}\| \lesssim \sqrt{\frac{\log n}{nh^d}}$. Therefore, we can lower bound the minimum eigenvalue by $\inf_{\mathbf{x} \in \mathcal{X}} \lambda_{\min}(\hat{\Psi}_{t,\mathbf{x}}) \geq \inf_{\mathbf{x} \in \mathcal{X}} \lambda_{\min}(\Psi_{t,\mathbf{x}}) - \sup_{\mathbf{x} \in \mathcal{X}} |\lambda_{\min}(\hat{\Psi}_{t,\mathbf{x}}) - \lambda_{\min}(\Psi_{t,\mathbf{x}})| \gtrsim_{\mathbb{P}} 1$.

Finally, it follows that $\sup_{\mathbf{x} \in \mathcal{X}} \|\hat{\Psi}_{t,\mathbf{x}}^{-1}\| \lesssim_{\mathbb{P}} 1$ and hence

$$\sup_{\mathbf{x} \in \mathcal{X}} \|\hat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}\| \leq \sup_{\mathbf{x} \in \mathcal{X}} \|\Psi_{t,\mathbf{x}}^{-1}\| \|\Psi_{t,\mathbf{x}} - \hat{\Psi}_{t,\mathbf{x}}\| \|\hat{\Psi}_{t,\mathbf{x}}^{-1}\| \lesssim_{\mathbb{P}} \sqrt{\frac{\log n}{nh^d}},$$

which completes the proof. \square

SA-6.3 Proof of Lemma SA-3

Consider the class $\mathcal{F} = \{(\mathbf{z}, u) \mapsto \mathbf{e}_\nu^\top g_\mathbf{x}(\mathbf{z})(u - h_\mathbf{x}(\mathbf{z})) : \mathbf{x} \in \mathcal{B}\}$, $0 \leq \nu \leq p$, where for $\mathbf{z} \in \mathcal{X}$,

$$g_\mathbf{x}(\mathbf{z}) = \mathbf{r}_p\left(\frac{\mathcal{d}(\mathbf{z}, \mathbf{x})}{h}\right) K_h(\mathcal{d}(\mathbf{z}, \mathbf{x})), \quad h_\mathbf{x}(\mathbf{z}) = \gamma_t^*(\mathbf{x})^\top \mathbf{r}_p(\mathcal{d}(\mathbf{z}, \mathbf{x})).$$

By definition of $\gamma_t^*(\mathbf{x})$,

$$\gamma_t^*(\mathbf{x}) = \mathbf{H}^{-1} \Psi_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}}, \quad \mathbf{S}_{t,\mathbf{x}} = \mathbb{E}\left[\mathbf{r}_p\left(\frac{D_i(\mathbf{x})}{h}\right) K_h(D_i(\mathbf{x})) Y_i \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t)\right]. \quad (\text{SA-6})$$

Assumption SA-1 implies $\mathbf{S}_{t,\mathbf{x}}$ is continuous in \mathbf{x} , hence $\sup_{\mathbf{x} \in \mathcal{X}} \|\mathbf{S}_{t,\mathbf{x}}\| \lesssim 1$. And by Assumption SA-2(ii), $\inf_{\mathbf{x} \in \mathcal{X}} \lambda_{\min}(\Psi_{t,\mathbf{x}}) \gtrsim 1$. Hence

$$\sup_{\mathbf{x} \in \mathcal{B}} \|\Psi_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}}\| \lesssim 1. \quad (\text{SA-7})$$

Now, consider properties of \mathcal{F} . Definition of $\gamma_t^*(\mathbf{x})$ implies $\mathbb{E}[f(\mathbf{X}_i, Y_i)] = 0$ for all $f \in \mathcal{F}$. Since K is compactly supported, there exists $C_1, C_2 > 0$ such that $F(\mathbf{z}, u) = C_1 h^{-d}(|u| + C_2)$ is an envelope function for \mathcal{F} . Denote $M = \max_{1 \leq i \leq n} F(\mathbf{X}_i, Y_i)$, then

$$\begin{aligned} \mathbb{E}[M^2]^{1/2} &\lesssim h^{-d} \mathbb{E}\left[\max_{1 \leq i \leq n} |Y_i|^2 + 1\right]^{1/2} \lesssim h^{-d} \mathbb{E}\left[\max_{1 \leq i \leq n} |Y_i|^{2+v}\right]^{1/(2+v)} \\ &\lesssim h^{-d} \left[\sum_{i=1}^n \mathbb{E}[|\varepsilon_i| + \sum_{t \in \{0,1\}} \mathbf{1}(\mathbf{x} \in \mathcal{A}_t) \mu_t(\mathbf{x})|^{2+v}]\right]^{1/(2+v)} \lesssim h^{-d} n^{1/(2+v)}, \end{aligned}$$

where we have used \mathbf{X} is compact and μ_t is continuous, hence $\sup_{\mathbf{x} \in \mathcal{X}} |\sum_{t \in \{0,1\}} \mathbf{1}(\mathbf{x} \in \mathcal{A}_t) \mu_t(\mathbf{x})| \lesssim 1$. Denote $\sigma = \sup_{f \in \mathcal{F}} \mathbb{E}[f(\mathbf{X}_i, Y_i)^2]^{1/2}$. Then,

$$\sigma^2 \lesssim \sup_{\mathbf{x} \in \mathcal{B}} \mathbb{E}[\|\mathbf{e}_\nu^\top g_\mathbf{x}\|_\infty^2 (|Y_i| + \|\mathbf{e}_\nu^\top h_\mathbf{x}\|_\infty)^2 \mathbf{1}(K_h(D_i(\mathbf{x})) \neq 0)] \lesssim h^{-d}.$$

To check for the covering number of \mathcal{F} , notice that compare to the proof of Lemma SA-2, we have one more term $\mathbf{e}_\nu^\top g_\mathbf{x} h_\mathbf{x} = \mathbf{r}_p\left(\frac{\mathcal{d}(\mathbf{z}, \mathbf{x})}{h}\right) K_h(\mathcal{d}(\mathbf{z}, \mathbf{x})) \gamma_t^*(\mathbf{x})^\top \mathbf{r}_p(\mathcal{d}(\mathbf{z}, \mathbf{x}))$. All terms except for $\gamma_t^*(\mathbf{x})$ can be handled as in the proof of Lemma SA-2. Recall Equation (SA-6), and consider $l_{t,\mathbf{x}} = \mathbf{e}_\mathbf{v}^\top [\mathbf{R}(\mathcal{d}(\cdot, \mathbf{x})/h) K_h(\mathcal{d}(\cdot, \mathbf{x})) \mu_t] \mathbf{1}(\cdot \in \mathcal{A}_t)$ and $\mathcal{L}_t = \{l_{t,\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}$, \mathbf{v} is a any multi-index. Then, for any $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{B}$,

$$|\mathbf{S}_{t,\mathbf{x}_1} - \mathbf{S}_{t,\mathbf{x}_2}| \leq \|l_{t,\mathbf{x}_1} - l_{t,\mathbf{x}_2}\|_{\mathbb{P}_{\mathcal{X},2}},$$

and hence

$$N(\{\mathbf{e}_\nu^\top \mathbf{S}_{t,\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}, \|\cdot\|, \varepsilon h^{-d}) \leq N(\mathcal{L}_t, \|\cdot\|_{\mathbb{P}_{\mathbf{x},2}}, \varepsilon h^{-d}) \leq \sup_Q N(\mathcal{L}_t, \|\cdot\|_{Q,2}, \varepsilon h^{-d}),$$

Same argument as paragraph **Covering Numbers** in the proof of Lemma SA-2 then shows

$$\begin{aligned} \sup_Q N(\{g_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}, \|\cdot\|_{Q,2}, \varepsilon C_1 h^{-d}) &\leq \left(\frac{\text{diam}(\mathcal{X})}{h\varepsilon} \right)^d, \quad 0 < \varepsilon \leq 1, \\ \sup_Q N(\{g_{\mathbf{x}} h_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}, \|\cdot\|_{Q,2}, \varepsilon C_1 h^{-d}) &\leq \left(\frac{\text{diam}(\mathcal{X})}{h\varepsilon} \right)^d, \quad 0 < \varepsilon \leq 1, \end{aligned}$$

where sup is taken over all discrete measures on \mathcal{X} . Product $\{g_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}$ with the singleton of identity function $\{u \mapsto u, u \in \mathbb{R}\}$, and adding $\{g_{\mathbf{x}} h_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}$,

$$\sup_Q N(\mathcal{F}, \|\cdot\|_{Q,2}, \varepsilon \|F\|_{Q,2}) \leq 2 \left(\frac{2 \text{diam}(\mathcal{X})}{h\varepsilon} \right)^d, \quad 0 < \varepsilon \leq 1,$$

where sup is taken over all discrete measures on $\mathcal{X} \times \mathbb{R}$. Denote $\mathbf{C}_1 = d$, $\mathbf{C}_2 = \frac{2(2 \text{diam}(\mathcal{X}))^d}{h^d}$. Hence, by Chernozhukov et al. [2014b, Corollary 5.1]

$$\begin{aligned} \mathbb{E} \left[\sup_{\mathbf{x} \in \mathcal{B}} |\mathbf{e}_\nu^\top \mathbf{O}_{t,\mathbf{x}}| \right] &= \mathbb{E} \left[\sup_{f \in \mathcal{F}} |\mathbb{E}_n[f(\mathbf{X}_i, Y_i)] - \mathbb{E}[f(\mathbf{X}_i, Y_i)]| \right] \\ &\lesssim \frac{\sigma}{\sqrt{n}} \sqrt{\mathbf{C}_2 \log(\mathbf{C}_1 \|M\|_{\mathbb{P},2} / \sigma)} + \frac{\|M\|_{\mathbb{P},2} \mathbf{C}_2 \log(\mathbf{C}_1 \|M\|_{\mathbb{P},2} / \sigma)}{n} \\ &\lesssim \frac{1}{\sqrt{nh^d}} \sqrt{d \log \left(\frac{\text{diam}(\mathcal{X})}{h^{1+d/2}} \right)} + \frac{1}{n^{\frac{1+v}{2+v}} h^d} d \log \left(\frac{\text{diam}(\mathcal{X})}{h^{1+d/2}} \right) \\ &\lesssim \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d}. \end{aligned}$$

The rest follows from finite dimensionality of $\mathbf{O}_{t,\mathbf{x}}$, and Lemma SA-2. \square

SA-6.4 Proof of Lemma SA-4

Denote $\eta_{i,t,\mathbf{x}} = Y_i - \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))$ and $\xi_{i,t,\mathbf{x}} = \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x})) - \hat{\theta}_{t,\mathbf{x}}(D_i(\mathbf{x}))$. Then

$$\hat{\Upsilon}_{t,\mathbf{x},\mathbf{y}} = \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{y})}{h} \right)^\top h^d K_h(D_i(\mathbf{x})) K_h(D_i(\mathbf{y})) (\eta_{i,t,\mathbf{x}} + \xi_{i,t,\mathbf{x}})^2 \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right],$$

and we decompose the error into

$$\begin{aligned} \hat{\Upsilon}_{t,\mathbf{x},\mathbf{y}} - \Upsilon_{t,\mathbf{x},\mathbf{y}} &= \Delta_{1,t,\mathbf{x},\mathbf{y}} + \Delta_{2,t,\mathbf{x},\mathbf{y}} + \Delta_{3,t,\mathbf{x},\mathbf{y}}, \\ \Delta_{1,t,\mathbf{x},\mathbf{y}} &= \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{y})}{h} \right)^\top h^d K_h(D_i(\mathbf{x})) K_h(D_i(\mathbf{y})) \xi_{i,t,\mathbf{x}}^2 \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right], \\ \Delta_{2,t,\mathbf{x},\mathbf{y}} &= 2\mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{y})}{h} \right)^\top h^d K_h(D_i(\mathbf{x})) K_h(D_i(\mathbf{y})) \eta_{i,t,\mathbf{x}} \xi_{i,t,\mathbf{x}} \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right], \end{aligned}$$

$$\begin{aligned}\Delta_{3,t,\mathbf{x},\mathbf{y}} &= \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{y})}{h} \right)^\top h^d K_h(D_i(\mathbf{x})) K_h(D_i(\mathbf{y})) \eta_{i,t,\mathbf{x}}^2 \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right] \\ &\quad - \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{y})}{h} \right)^\top h^d K_h(D_i(\mathbf{x})) K_h(D_i(\mathbf{y})) \eta_{i,t,\mathbf{x}}^2 \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right].\end{aligned}$$

By Assumption SA-2, $K_h(D_i(\mathbf{x})) \neq 0$ implies $\|\mathbf{r}_p(D_i(\mathbf{x})/h)\|_2 \lesssim 1$. Hence by Lemma SA-2 and SA-3,

$$\begin{aligned}& \max_{t \in \{0,1\}} \max_{1 \leq i \leq n} \sup_{\mathbf{x} \in \mathcal{B}} |\xi_{i,t,\mathbf{x}}| \\ &= \max_{t \in \{0,1\}} \max_{1 \leq i \leq n} \sup_{\mathbf{x} \in \mathcal{B}} |\mathbf{r}_p(D_i(\mathbf{x}))^\top (\hat{\gamma}_{t,\mathbf{x}} - \gamma_{t,\mathbf{x}}^*)| \mathbf{1}(K_h(D_i(\mathbf{x})) \geq 0) \\ &= \max_{t \in \{0,1\}} \max_{1 \leq i \leq n} \sup_{\mathbf{x} \in \mathcal{B}} |\mathbf{r}_p(D_i(\mathbf{x}))^\top \mathbf{H}^{-1}(\hat{\Psi}_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} + (\hat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}) \mathbf{U}_{t,\mathbf{x}})| \mathbf{1}(K_h(D_i(\mathbf{x})) \geq 0) \\ &\leq \max_{t \in \{0,1\}} \sup_{\mathbf{x} \in \mathcal{B}} \left\| \hat{\Psi}_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \right\|_2 + \max_{t \in \{0,1\}} \sup_{\mathbf{x} \in \mathcal{B}} \left\| (\hat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}) \mathbf{U}_{t,\mathbf{x}} \right\|_2 \\ &\lesssim \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d},\end{aligned}$$

where

$$\mathbf{U}_{t,\mathbf{x}} = \mathbb{E}_n \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) \theta_{t,\mathbf{x}}^*(\mathbf{X}_i) \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right].$$

Assuming $\frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d} \rightarrow \infty$, similar maximal inequality as in the proof of Lemma SA-2 shows

$$\begin{aligned}\sup_{\mathbf{x}, \mathbf{y} \in \mathcal{X}} \|\Delta_{1,t,\mathbf{x},\mathbf{y}}\| &\lesssim \mathbb{P} \max_{t \in \{0,1\}} \max_{1 \leq i \leq n} \sup_{\mathbf{x} \in \mathcal{B}} |\xi_{i,t,\mathbf{x}}|^2 \lesssim \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d} \right)^2, \\ \sup_{\mathbf{x}, \mathbf{y} \in \mathcal{X}} \|\Delta_{2,t,\mathbf{x},\mathbf{y}}\| &\lesssim \mathbb{P} \max_{t \in \{0,1\}} \max_{1 \leq i \leq n} \sup_{\mathbf{x} \in \mathcal{B}} |\xi_{i,t,\mathbf{x}}| \lesssim \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d}.\end{aligned}\tag{SA-8}$$

Consider the (μ, ν) entry of $\Delta_{3,t,\mathbf{x},\mathbf{y}}$. Consider the class

$$\mathcal{F} = \left\{ (\mathbf{z}, u) \mapsto \left(\frac{\mathcal{d}(\mathbf{z}, \mathbf{x})}{h} \right)^{\mu+\nu} h^d K_h(\mathcal{d}(\mathbf{z}, \mathbf{x})) K_h(\mathcal{d}(\mathbf{z}, \mathbf{y})) (u - \mathbf{r}_p(\mathcal{d}(\mathbf{z}, \mathbf{x}))^\top \gamma_{t,\mathbf{x}}^*)^2 : \mathbf{x}, \mathbf{y} \in \mathcal{X} \right\}.$$

By Assumption SA-2 and SA-1(v), we have $\sup_{f \in \mathcal{F}} \mathbb{E}[f(\mathbf{X}_i, Y_i)^2]^{1/2} \lesssim h^{-d/2}$. Moreover, Assumption SA-2 and Equation (SA-7) imply there exists $C_1, C_2 > 0$ such that $F(\mathbf{z}, u) = C_1 h^{-d}(u^2 + C_2)$ is an envelope function for \mathcal{F} , with

$$\mathbb{E} \left[\max_{1 \leq i \leq n} F(\mathbf{X}_i, Y_i)^2 \right]^{\frac{1}{2}} \lesssim C_1 h^{-d} (\mathbb{E} \left[\max_{1 \leq i \leq n} Y_i^4 \right]^{\frac{1}{2}} + C_2) \lesssim C_1 h^{-d} (\mathbb{E} \left[\max_{1 \leq i \leq n} Y_i^{2+v} \right]^{\frac{2}{2+v}} + C_2) \lesssim h^{-d} n^{\frac{2}{2+v}}.$$

Apply Chernozhukov et al. [2014b, Corollary 5.1] similarly as in Lemma SA-3 gives

$$\mathbb{E} \left[\sup_{f \in \mathcal{F}} |\mathbb{E}_n[f(\mathbf{X}_i, Y_i)] - \mathbb{E}[f(\mathbf{X}_i, Y_i)]| \right] \lesssim \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d}.$$

Finite dimensionality of $\Delta_{3,t,\mathbf{x},\mathbf{y}}$ then implies

$$\mathbb{E} \left[\sup_{\mathbf{x}, \mathbf{y} \in \mathcal{X}} \|\Delta_{3,t,\mathbf{x},\mathbf{y}}\| \right] \lesssim \sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d}. \quad (\text{SA-9})$$

Putting together Equations (SA-8), (SA-9) and Lemma SA-2 gives the result. \square

SA-6.5 Proof of Lemma SA-5

By Theorem SA-1 and Equation (SA-6), we have

$$\begin{aligned} \sup_{\mathbf{x} \in \mathcal{B}} |\mathfrak{B}_{n,t}(\mathbf{x})| &= \sup_{\mathbf{x} \in \mathcal{B}} \left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}} - \mu_t(\mathbf{x}) \right| \\ &= \sup_{\mathbf{x} \in \mathcal{B}} \left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) \mathbf{R}_p(D_i(\mathbf{x}))^\top (\mu_t(\mathbf{X}_i) - \mu_t(\mathbf{x}), 0, \dots, 0) \right) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t) \right] \right| \\ &\lesssim \sup_{\mathbf{x} \in \mathcal{B}} \sup_{\mathbf{z} \in \mathcal{X}} |\mu_t(\mathbf{x}) - \mu_t(\mathbf{z})| \mathbf{1}(K_h(\mathcal{A}(\mathbf{z}, \mathbf{x})) > 0) \\ &\lesssim h. \end{aligned}$$

\square

SA-6.6 Proof of Theorem SA-1

Since $\theta_{\mathbf{x}}(0) = \theta_{1,\mathbf{x}}(0) - \theta_{0,\mathbf{x}}(0)$ and $\tau(\mathbf{x}) = \mu_1(\mathbf{x}) - \mu_0(\mathbf{x})$, it is enough to prove the result for one treatment assignment group $t \in \{0, 1\}$. By Assumption SA-1(iii) and Assumption SA-2(ii), for any $r \neq 0$, for any $\mathbf{x} \in \mathcal{B}$ and $\mathbf{y} \in S_{t,\mathbf{x}}(r)$, $|\mu_t(\mathbf{y}) - \mu_t(\mathbf{x})| \lesssim |r|$. Hence, for any $r \neq 0$, for any $\mathbf{x} \in \mathcal{B}$, $t \in \{0, 1\}$,

$$|\theta_{t,\mathbf{x}}(r) - \mu_t(\mathbf{x})| \leq \frac{\int_{S_{t,\mathbf{x}}(|r|)} |\mu_t(\mathbf{y}) - \mu_t(\mathbf{x})| f_X(\mathbf{y}) \mathfrak{H}^{d-1}(d\mathbf{y})}{\int_{S_{t,\mathbf{x}}(|r|)} f_X(\mathbf{y}) \mathfrak{H}^{d-1}(d\mathbf{y})} \lesssim r.$$

implying

$$|\theta_{t,\mathbf{x}}(0) - \mu_t(\mathbf{x})| \leq \lim_{r \rightarrow 0} |\theta_{t,\mathbf{x}}(r) - \mu_t(\mathbf{x})| = 0,$$

which establishes the result. \square

SA-6.7 Proof of Theorem SA-2

The proofs of Lemma SA-2 and Lemma SA-3 can be done when the index set is the singleton $\{\mathbf{x}\}$ instead of \mathcal{B} , replacing Chernozhukov et al. [2014b, Corollary 5.1] by Bernstein inequality, and thus obtaining

$$\begin{aligned} \left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \right| &\lesssim_{\mathbb{P}} \sqrt{\frac{1}{nh^d}} + \frac{1}{n^{\frac{1+v}{2+v}} h^d}, \\ \left| \mathbf{e}_1^\top (\hat{\Psi}_{t,\mathbf{x}}^{-1} - \Psi_{t,\mathbf{x}}^{-1}) \mathbf{O}_{t,\mathbf{x}} \right| &\lesssim_{\mathbb{P}} \sqrt{\frac{1}{nh^d}} \left(\sqrt{\frac{1}{nh^d}} + \frac{1}{n^{\frac{1+v}{2+v}} h^d} \right). \end{aligned}$$

for all $\mathbf{x} \in \mathcal{B}$. In words, uniformity only adds a $\log(1/h)$ penalty. Therefore, using decomposition (SA-1), the pointwise convergence rate follows. \square

SA-6.8 Proof of Theorem SA-3

Follows from Lemma SA-2, Lemma SA-3 and decomposition (SA-1). \square

SA-6.9 Proof of Theorem SA-4

Define $\bar{T}(\mathbf{x}) = \sum_{i=1}^n Z_i$, with $Z_i = Z_{1,i} - Z_{0,i}$ independent random variables ($i = 1, 2, \dots, n$),

$$Z_{t,i} = \frac{1}{n} \Xi_{\mathbf{x},\mathbf{x}}^{-1/2} \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) (Y_i - \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t),$$

$\mathbb{E}[Z_i] = 0$ and $\mathbb{V}[Z_i] = n^{-1}$. By the Berry-Essen Theorem,

$$\sup_{u \in \mathbb{R}} \left| \mathbb{P}(\bar{T}(\mathbf{x}) \leq u) - \Phi(u) \right| \lesssim \sum_{i=1}^n \mathbb{E}[|Z_i|^3] \lesssim \sum_{i=1}^n \mathbb{E}[|Z_{1,i}|^3] + \sum_{i=1}^n \mathbb{E}[|Z_{0,i}|^3]$$

where

$$\begin{aligned} \mathbb{E}[|Z_{t,i}|^3] &= \sum_{i=1}^n n^{-3} \Xi_{\mathbf{x},\mathbf{x}}^{-3/2} \mathbb{E} \left[\left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t) (Y_i - \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))) \right|^3 \right] \\ &\lesssim n^{-2} \Xi_{\mathbf{x},\mathbf{x}}^{-3/2} \mathbb{E}[|K_h(D_i(\mathbf{x}))(Y_i - \theta_{t,\mathbf{x}}^*(D_i(\mathbf{x})))|^3] \\ &\lesssim n^{-2} \Xi_{\mathbf{x},\mathbf{x}}^{-3/2} \mathbb{E}[|K_h(D_i(\mathbf{x}))(\mathbb{E}[|Y_i|^3 | \mathbf{X}_i] + |\theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))|^3)|] \\ &\lesssim (nh^d)^{-1/2}, \end{aligned}$$

noting that $\sup_{\mathbf{x} \in \mathcal{B}} \left\| \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) \right\| \lesssim 1$ holds almost surely in \mathbf{X}_i , $\Xi_{\mathbf{x},\mathbf{x}} \gtrsim (nh^d)^{-1/2}$ by Lemma SA-4, $\mathbb{E}[|Y_i|^3 | \mathbf{X}_i] \lesssim 1$ by Assumption SA-1(v), and $\max_{1 \leq i \leq n} \sup_{\mathbf{x} \in \mathcal{B}} |\theta_{t,\mathbf{x}}^*(D_i(\mathbf{x}))| \lesssim 1$ because

$$\theta_{t,\mathbf{x}}^*(D_i(\mathbf{x})) = \gamma_t^*(\mathbf{x})^\top \mathbf{r}_p(D_i(\mathbf{x})) = (\Psi_{t,\mathbf{x}} \mathbf{S}_{t,\mathbf{x}})^{-1} \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right).$$

Since

$$|\hat{T}(\mathbf{x}) - \bar{T}(\mathbf{x})| \lesssim \mathbb{P} \frac{1}{\sqrt{nh^d}} + \frac{1}{n^{\frac{v}{2+v}} h^d} + \sqrt{nh^d} |\mathfrak{B}(\mathbf{x})|,$$

the pointwise asymptotic normality follows, under the conditions imposed. Finally, validity of the confidence interval estimator is immediate. \square

SA-6.10 Proof of Theorem SA-5

We make the decomposition based on Equation (SA-1) and convergence of $\hat{\Xi}_{\mathbf{x},\mathbf{x}}$,

$$\begin{aligned} \hat{T}_{\text{dis}}(\mathbf{x}) - \bar{T}_{\text{dis}}(\mathbf{x}) &= \hat{\Xi}_{\mathbf{x},\mathbf{x}}^{-1/2} \left(\sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} (\hat{\theta}_{t,\mathbf{x}}(0) - \theta_{t,\mathbf{x}}(0)) \right) - \Xi_{\mathbf{x},\mathbf{x}}^{-1/2} \left(\sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \right) \\ &= \hat{\Xi}_{\mathbf{x},\mathbf{x}}^{-1/2} \left(\sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} (\hat{\theta}_{t,\mathbf{x}}(0) - \theta_{t,\mathbf{x}}(0)) - \sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \right) \quad (= \Delta_{1,\mathbf{x}}) \\ &\quad + (\hat{\Xi}_{\mathbf{x},\mathbf{x}}^{-1/2} - \Xi_{\mathbf{x},\mathbf{x}}^{-1/2}) \sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \quad (= \Delta_{2,\mathbf{x}}) \end{aligned}$$

By Lemma SA-2 and SA-3, and the decomposition Equation (SA-1),

$$\begin{aligned} & \sup_{\mathbf{x} \in \mathcal{X}} \left| \sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} (\hat{\theta}_{t,\mathbf{x}}(0) - \theta_{t,\mathbf{x}}(0)) - \sum_{t \in \{0,1\}} (-1)^{\frac{t+1}{2}} \mathbf{e}_1^\top \boldsymbol{\Psi}_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \right| \\ & \lesssim_{\mathbb{P}} \sqrt{\frac{\log(1/h)}{nh^d}} \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d} \right) + \sup_{\mathbf{x} \in \mathcal{B}} \sum_{t \in \{0,1\}} |\theta_{t,\mathbf{x}}^*(0) - \theta_{t,\mathbf{x}}(0)|. \end{aligned}$$

Together with Lemma SA-4,

$$\sup_{\mathbf{x} \in \mathcal{B}} |\Delta_{1,\mathbf{x}}| \lesssim_{\mathbb{P}} \frac{\log(1/h)}{\sqrt{nh^d}} + \frac{(\log(1/h))^{\frac{3}{2}}}{n^{\frac{1+v}{2+v}} h^d} + \sqrt{nh^d} \sup_{\mathbf{x} \in \mathcal{B}} \sum_{t \in \{0,1\}} |\theta_{t,\mathbf{x}}^*(0) - \theta_{t,\mathbf{x}}(0)|. \quad (\text{SA-10})$$

By Lemma SA-2, Lemma SA-3 and Lemma SA-4, and assume $\frac{n^{\frac{v}{2+v}} h^d}{\log(1/h)} \rightarrow \infty$, then

$$\begin{aligned} \sup_{\mathbf{x} \in \mathcal{X}} \left| \mathbf{e}_1^\top \boldsymbol{\Psi}_{t,\mathbf{x}}^{-1} \mathbf{O}_{t,\mathbf{x}} \left(\Xi_{\mathbf{x},\mathbf{x}}^{-1/2} - \hat{\Xi}_{\mathbf{x},\mathbf{x}}^{-1/2} \right) \right| & \lesssim_{\mathbb{P}} \sqrt{nh^d} \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{1+v}{2+v}} h^d} \right) \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d} \right) \\ & = \sqrt{\log(1/h)} \left(1 + \sqrt{\frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d}} \right) \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d} \right) \\ & \lesssim \sqrt{\log(1/h)} \left(\sqrt{\frac{\log(1/h)}{nh^d}} + \frac{\log(1/h)}{n^{\frac{v}{2+v}} h^d} \right). \end{aligned}$$

Hence

$$\sup_{\mathbf{x} \in \mathcal{B}} |\Delta_{2,\mathbf{x}}| \lesssim_{\mathbb{P}} \frac{\log(1/h)}{\sqrt{nh^d}} + \frac{(\log(1/h))^{\frac{3}{2}}}{n^{\frac{1+v}{2+v}} h^d}. \quad (\text{SA-11})$$

Putting together Equations (SA-10), (SA-11) give the result. \square

SA-6.11 Proof of Theorem SA-6

We will verify the high level conditions stated in Theorem SA-8.

Without loss of generality, we can assume $\mathcal{X} = [0, 1]^d$, and $\mathcal{Q}_{\mathcal{T}_t} = \mathbb{P}_X$ is a valid surrogate measure for \mathbb{P}_X with respect to \mathcal{G} , and $\phi_{\mathcal{G}} = \text{Id}$ is a valid normalizing transformation (as in Theorem SA-8). This implies the constants \mathbf{c}_1 and \mathbf{c}_2 from Theorem SA-8 are all 1.

Recall $\mathcal{G} = \{g_{\mathbf{x}} : \mathbf{x} \in \mathcal{B}\}$ where

$$g_{\mathbf{x}}(\mathbf{u}) = \mathbf{1}(\mathbf{u} \in \mathcal{A}_1) \mathfrak{K}_1(\mathbf{u}; \mathbf{x}) - \mathbf{1}(\mathbf{u} \in \mathcal{A}_0) \mathfrak{K}_0(\mathbf{u}; \mathbf{x}).$$

By standard arguments and [Cattaneo et al., 2024, Lemma 7], we get properties of \mathcal{G} as follows:

$$\mathbf{M}_{\mathcal{G}} \lesssim h^{-d/2}, \quad \mathbf{E}_{\mathcal{G}} \lesssim h^{d/2}, \quad \text{TV}_{\mathcal{G}} \lesssim h^{d/2-1}, \quad \sup_{\mathcal{Q}} N(\mathcal{G}, \|\cdot\|_{Q,2}, \varepsilon(2c+1)^{d+1} \mathbf{M}_{\mathcal{G}}) \leq 2\mathbf{c}' \varepsilon^{-d-1} + 2.$$

By definition of $\theta_{t,\mathbf{x}}^*(\cdot)$, for each $\mathbf{x} \in \mathcal{B}$, $t \in \{0, 1\}$,

$$\theta_{t,\mathbf{x}}^*(\mathcal{d}(\mathbf{u}, \mathbf{x})) = \gamma_t^*(\mathbf{x})^\top \mathbf{r}_p(\mathcal{d}(\mathbf{u}, \mathbf{x})) = (\mathbf{H}^{-1} \boldsymbol{\Psi}_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}})^\top \mathbf{r}_p(\mathcal{d}(\mathbf{u}, \mathbf{x})) = (\boldsymbol{\Psi}_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}})^\top \mathbf{r}_p\left(\frac{\mathcal{d}(\mathbf{u}, \mathbf{x})}{h}\right),$$

recalling

$$\Psi_{t,\mathbf{x}} = \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right)^\top K_h(D_i(\mathbf{x})) \mathbf{1}(D_i(\mathbf{x}) \in \mathcal{J}_t) \right], \quad \mathbf{S}_{t,\mathbf{x}} = \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) Y_i \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t) \right].$$

We can check that $\|\Psi_{t,\mathbf{x}}^{-1}\| \lesssim 1$, $\|\mathbf{S}_{t,\mathbf{x}}\| \lesssim 1$ and

$$\mathbf{M}_{\mathcal{M}_t} \lesssim h^{-d/2}, \quad \mathbf{E}_{\mathcal{M}_t} \lesssim h^{-d/2}, \quad t \in \{0, 1\}.$$

In what follows, we verify the entropy and total variation properties of \mathcal{M} . Using product rule we can verify

$$\sup_{\mathbf{u} \in \mathcal{X}} \sup_{\mathbf{x}, \mathbf{x}' \in \mathcal{B}} \frac{|\theta_{t,\mathbf{x}}^*(\mathcal{d}(\mathbf{u}, \mathbf{x})) - \theta_{t,\mathbf{x}}^*(\mathcal{d}(\mathbf{u}, \mathbf{x}'))|}{\|\mathbf{x} - \mathbf{x}'\|} \lesssim h^{-1}.$$

Define $f_{t,\mathbf{x}}(\cdot) = \frac{h^{-d/2}}{\sqrt{n\Xi_{\mathbf{x},\mathbf{x}}}} \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{r}_p(\cdot) K(\cdot) (\Psi_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}})^\top \mathbf{r}_p(\cdot)$. Then,

$$\mathfrak{R}_t(\mathbf{u}; \mathbf{x}) \theta_{t,\mathbf{x}}^*(\mathcal{d}(\mathbf{u}, \mathbf{x})) = h^{-d/2} f_{t,\mathbf{x}} \left(\frac{\mathcal{d}(\mathbf{u}, \mathbf{x})}{h} \right), \quad \mathbf{u} \in \mathcal{X}, \mathbf{x} \in \mathcal{B}, t \in \{0, 1\}.$$

Take $\mathcal{M}_t = \{\mathfrak{R}_t(\cdot; \mathbf{x}) \theta_{t,\mathbf{x}}^*(\mathcal{d}(\cdot, \mathbf{x})) : \mathbf{x} \in \mathcal{B}\}$, $t \in \{0, 1\}$. For $t \in \{0, 1\}$, $f_{t,\mathbf{x}}$ satisfies:

$$\begin{aligned} (i) \text{ boundedness} & \quad \sup_{\mathbf{x} \in \mathcal{B}} \sup_{\mathbf{u} \in \mathcal{X}} |f_{t,\mathbf{x}}(\mathbf{u})| \leq \mathbf{c}, \\ (ii) \text{ compact support} & \quad \text{supp}(f_{t,\mathbf{x}}(\cdot)) \subseteq [-\mathbf{c}, \mathbf{c}]^d, \forall \mathbf{x} \in \mathcal{B}, \\ (iii) \text{ Lipschitz continuity} & \quad \sup_{\mathbf{x} \in \mathcal{B}} \sup_{\mathbf{u}, \mathbf{u}' \in \mathcal{X}} \frac{|f_{t,\mathbf{x}}(\mathbf{u}) - f_{t,\mathbf{x}}(\mathbf{u}')|}{\|\mathbf{u} - \mathbf{u}'\|} \leq \mathbf{c} \\ & \quad \sup_{\mathbf{u} \in \mathcal{X}} \sup_{\mathbf{x}, \mathbf{x}' \in \mathcal{B}} \frac{|f_{t,\mathbf{x}}(\mathbf{u}) - f_{t,\mathbf{x}'}(\mathbf{u})|}{\|\mathbf{x} - \mathbf{x}'\|} \leq \mathbf{c} h^{-1}, \end{aligned}$$

for some constant \mathbf{c} not depending on n . Then, by an argument similar to Cattaneo et al. [2024, Lemma 7], there exists a constant \mathbf{c}' only depending on \mathbf{c} and d that for any $0 \leq \varepsilon \leq 1$,

$$\sup_Q N \left(h^{d/2} \mathcal{H}_t, \|\cdot\|_{Q,1}, (2c+1)^{d+1} \varepsilon \right) \leq \mathbf{c}' \varepsilon^{-d-1} + 1,$$

where supremum is taken over all finite discrete measures. Taking a constant envelope function $\mathbf{M}_{\mathcal{M}_t} = (2c+1)^{d+1} h^{-d/2}$, we have for any $0 < \varepsilon \leq 1$,

$$\sup_Q N \left(\mathcal{H}_t, \|\cdot\|_{Q,1}, \varepsilon \mathbf{M}_{\mathcal{H}_t} \right) \leq \mathbf{c}' \varepsilon^{-d-1} + 1.$$

By Lemma SA-6, above implies the uniform covering number for \mathcal{H}_t satisfies

$$\mathbf{N}_{\mathcal{M}_t}(\varepsilon) \leq 4\mathbf{c}'(\varepsilon/2)^{-d-1}, \quad 0 < \varepsilon \leq 1.$$

Since $\mathcal{M} \subseteq \mathcal{M}_0 + \mathcal{M}_1$, here $+$ denotes the Minkowski sum, with $\mathbf{M}_{\mathcal{M}}$ taken to be $\mathbf{M}_{\mathcal{M}_0} + \mathbf{M}_{\mathcal{M}_1}$, a bound on the uniform covering number of \mathcal{M} can be given by

$$\mathbf{N}_{\mathcal{M}}(\varepsilon) \leq 16(\mathbf{c}')^2(\varepsilon/2)^{-2d-2}, \quad 0 < \varepsilon \leq 1.$$

With the assumption that $\mathcal{L}(E_{t,\mathbf{x}}) \leq Ch^{d-1}$ for $E_{t,\mathbf{x}} = \{\mathbf{y} \in \mathcal{A}_t : (\mathbf{y} - \mathbf{x})/h \in \text{Supp}(K)\}$ for all $t \in \{0, 1\}$, $\mathbf{x} \in \mathcal{B}$, and the fact that $\text{TV}_{\mathcal{M}_t} \lesssim h^{d/2-1}$ for $t \in \{0, 1\}$, the same argument as in the paragraph **Total Variation** in the proof of Theorem SA-8 shows

$$\text{TV}_{\mathcal{M}} \lesssim h^{d/2-1}.$$

Now apply Theorem SA-8 with \mathcal{G}, \mathcal{M} defined in Equation (SA-2), $\mathcal{R} = \{\text{Id}\}$, $\mathcal{S} = \{1\}$, noticing that

$$(\bar{\text{T}}_{\text{dis}} : \mathbf{x} \in \mathcal{B}) = (A_n(g, m, r, s) : (g, m, r, s) \in \mathcal{F} \times \mathcal{R} \times \mathcal{S}), \quad \mathcal{F} = \{(g_{\mathbf{x}}, m_{\mathbf{x}}) : \mathbf{x} \in \mathcal{B}\} \subseteq \mathcal{G} \times \mathcal{M},$$

the result then follows. \square

Lemma SA-6 (VC Class to VC2 Class). *Assume \mathcal{F} is a VC class on a measure space $(\mathcal{X}, \mathcal{B})$: there exists an envelope function F and positive constants $c(\mathcal{F}), d(\mathcal{F})$ such that for all $\varepsilon \in (0, 1)$,*

$$\sup_Q N(\mathcal{F}, \|\cdot\|_{Q,1}, \varepsilon \|F\|_{Q,1}) \leq c(\mathcal{F}) \varepsilon^{-d(\mathcal{F})},$$

where the supremum is taken over all finite discrete measures. Then, \mathcal{F} is also VC2 class: for all $\varepsilon \in (0, 1)$,

$$\sup_Q N(\mathcal{F}, \|\cdot\|_{Q,2}, \varepsilon \|F\|_{Q,2}) \leq c(\mathcal{F}) (\varepsilon^2/2)^{-d(\mathcal{F})},$$

where the supremum is taken over all finite discrete measures.

Proof of Lemma SA-6. Let Q be a finite discrete probability measure. Let $f, g \in \mathcal{F}$. Then, $\int |f - g|^2 dQ \leq 2 \int |f - g| F dQ$. Define another probability measure $\tilde{Q}(c_k) = F(c_k)Q(c_k)/\|F\|_{Q,1}$ on the support of Q , denoted by $\{c_1, \dots, c_k, \dots\}$. Then,

$$\int |f - g|^2 dQ \leq 2 \|F\|_{Q,1} \int |f - g| d\tilde{Q} \leq 2 \|F\|_{Q,1} \|f - g\|_{\tilde{Q},1}.$$

Hence, if we take an $\varepsilon^2/2$ -net in $(\mathcal{F}, \|\cdot\|_{\tilde{Q},1})$ with cardinality no greater than $c(\mathcal{F}) \varepsilon^{-d(\mathcal{F})}$, then for any $f \in \mathcal{F}$, there exists a $g \in \mathcal{F}$ such that $\|f - g\|_{\tilde{Q},1} \leq \varepsilon^2/2 \|F\|_{\tilde{Q},1}$, and hence

$$\|f - g\|_{Q,2}^2 \leq 2\varepsilon^2/2 \|F\|_{Q,1} \|F\|_{\tilde{Q},1} \leq \varepsilon^2 \|F\|_{Q,2}^2,$$

which gives the result. \square

SA-6.12 Proof of Theorem SA-7

The result follows from Theorems SA-5 and SA-6, Chernozhukov et al. [2014a], and Chernozhukov et al. [2022]. \square

SA-6.13 Proof of Theorem SA-8

Since A_n is the addition of two M_n processes, indexed by $\mathcal{G} \times \mathcal{R}$ and $\mathcal{H} \times \mathcal{S}$ respectively, the Gaussian strong approximation error essentially depends on the *worst case scenario* between \mathcal{G} and \mathcal{H} , and between \mathcal{R} and \mathcal{S} . Hence (1) taking maximums $\mathbf{E} = \max\{\mathbf{E}_{\mathcal{G}}, \mathbf{E}_{\mathcal{H}}\}$, $\mathbf{M} = \max\{\mathbf{M}_{\mathcal{R}}, \mathbf{M}_{\mathcal{S}}\}$ and $\text{TV} = \max\{\text{TV}_{\mathcal{G}}, \text{TV}_{\mathcal{H}}\}$; (2) noticing that A_n is still indexed by a VC-type class of functions, we can get the claimed result.

For a more rigor proof, we can not apply [Cattaneo and Yu \[2025, Theorem SA.1\]](#) on $(M_n(g, r) : g \in \mathcal{G}, r \in \mathcal{R})$ and $(M_n(h, s) : h \in \mathcal{H}, s \in \mathcal{S})$ directly, since this ignores the dependence structure between the two empirical processes. However, we can still project the functions onto a Haar basis, and control the *strong approximation error for projected process* and the *projection error* as in the proof of [Cattaneo and Yu \[2025, Theorem SA.1\]](#) and show both errors can be controlled via *worst case scenario* between \mathcal{G} and \mathcal{H} , and between \mathcal{R} and \mathcal{S} .

Reductions: Here we present some reductions to our problem. By the same argument as in Section SA-II.3 (Proofs of Theorem 1) in the supplemental appendix of [Cattaneo and Yu \[2025\]](#), we can show there exists $\mathbf{u}_i, 1 \leq i \leq n$ i.i.d $\text{Uniform}([0, 1]^d)$ on a possibly enlarged probability space, such that

$$f(\mathbf{x}_i) = f(\phi_{\mathcal{G} \cup \mathcal{H}}^{-1}(\mathbf{u}_i)), \quad \forall f \in \mathcal{G} \cup \mathcal{H}, \forall 1 \leq i \leq n.$$

With the help of [Cattaneo and Yu \[2025, Lemma SA.10\]](#), we can assume w.l.o.g. that \mathbf{x}_i 's are i.i.d $\text{Uniform}(\mathcal{X})$ with $\mathcal{X} = [0, 1]^d$, and $\phi_{\mathcal{G} \cup \mathcal{H}} : [0, 1]^d \rightarrow [0, 1]^d$ is the identity function. Although we assume $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[|Y_i|^{2+v} | \mathbf{X}_i = \mathbf{x}] < \infty$, we first present the result under the assumption $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[\exp(|y_i|) | \mathbf{x}_i = \mathbf{x}] \leq 2$, which is the same as in [Cattaneo and Yu \[2025, Theorem 2\]](#). Also in correspondence to the notations in [Cattaneo and Yu \[2025, Theorem 2\]](#), we set $\alpha = 1$ throughout this proof.

Cell Constructions and Projections: The constructions here are the same as those in [Cattaneo and Yu \[2025\]](#), and we present them here for completeness. Let $\mathcal{A}_{M,N}(\mathbb{P}, 1) = \{\mathcal{C}_{j,k} : 0 \leq k < 2^{M+N-j}, 0 \leq j \leq M+N\}$ be an axis-aligned cylindered quasi-dyadic expansion of \mathbb{R}^{d+1} , with depth M for the main subspace \mathbb{R}^d and depth N for the multiplier subspace \mathbb{R} , with respect to \mathbb{P} , the joint distribution of (\mathbf{x}_i, y_i) taking values in $\mathbb{R}^d \times \mathbb{R}$, as in [Cattaneo and Yu \[2025, Definition SA.4\]](#). To see what $\mathcal{A}_{M,N}(\mathbb{P}, 1)$ is, it can be given by the following iterative partition procedure:

1. *Initialization* ($q = 0$): Take $\mathcal{C}_{M+N-q,0} = \mathcal{X} \times \mathbb{R}$ where $\mathcal{X} = [0, 1]^d$.
2. *Iteration* ($q = 1, \dots, M$): Given $\mathcal{C}_{K-l,k}$ for $0 \leq l \leq q-1, 0 \leq k < 2^l$, take $s = (q \bmod d) + 1$, and construct $\mathcal{C}_{K-q,2k} = \mathcal{C}_{K-q+1,k} \cap \{(\mathbf{x}, y) \in [0, 1]^d \times \mathbb{R} : \mathbf{e}_s^\top \mathbf{x} \leq c_{K-q+1,k}\}$ and $\mathcal{C}_{K-q,2k+1} = \mathcal{C}_{K-q+1,k} \cap \{(\mathbf{x}, y) \in [0, 1]^d \times \mathbb{R} : \mathbf{e}_s^\top \mathbf{x} > c_{K-q+1,k}\}$ such that $\mathbb{P}(\mathcal{C}_{K-q,2k})/\mathbb{P}(\mathcal{C}_{K-q+1,k}) \in [\frac{1}{1+\rho}, \frac{\rho}{1+\rho}]$ for all $0 \leq k < 2^{q-1}$. Continue until $(\mathcal{C}_{N,k} : 0 \leq k < 2^M)$ has been constructed. By construction, for each $0 \leq l < M$, $\mathcal{C}_{N,l} = \mathcal{X}_{0,l} \times \mathcal{Y}_{0,N,0}$, with $\mathcal{Y}_{0,N,0} = \mathbb{R}$.
3. *Iteration* ($q = M+1, \dots, M+N$): Given $\mathcal{C}_{K-l,k}$ for $0 \leq l \leq q-1, 0 \leq k < 2^l$, each $\mathcal{C}_{M+N-q,k}$ can be written as $\mathcal{X}_{0,l} \times \mathcal{Y}_{l,M+N-q,m}$ with $k = 2^{q-M}l + m$. Construct $\mathcal{C}_{M+N-q-1,2k} = \mathcal{X}_{0,l} \times \mathcal{Y}_{l,M+N-q-1,2m}$ and $\mathcal{C}_{M+N-q-1,2k+1} = \mathcal{X}_{0,l} \times \mathcal{Y}_{l,M+N-q-1,2m+1}$, such that there exists some $\mathbf{q}_{M+N-q,k} \in \mathbb{R}$ with $\mathcal{Y}_{l,M+N-q-1,2m} = \mathcal{Y}_{l,M+N-q,m} \cap (-\infty, \mathbf{q}_{M+N-q,k})$ and $\mathcal{Y}_{l,M+N-q-1,2m+1} = \mathcal{Y}_{l,M+N-q,m} \cap (\mathbf{q}_{M+N-q,k}, \infty)$, $\mathbb{P}(y_i \in \mathcal{Y}_{l,M+N-q-1,2m} | \mathbf{x}_i \in \mathcal{X}_{0,l}) = \mathbb{P}(y_i \in \mathcal{Y}_{l,M+N-q-1,2m+1} | \mathbf{x}_i \in \mathcal{X}_{0,l}) = \frac{1}{2} \mathbb{P}(y_i \in \mathcal{Y}_{l,M+N-q-1,m} | \mathbf{x}_i \in \mathcal{X}_{0,l})$.

Consider the projection $\Pi_1(\mathcal{A}_{M,N}(\mathbb{P}, 1))$ given in Equation (SA-7) in [Cattaneo and Yu \[2025\]](#), noticing that $\mathcal{A}_{M,N}(\mathbb{P}, 1)$ is one special instance of $\mathcal{C}_{M,N}(\mathbb{P}, \rho)$. That is, define $e_{j,k} = \mathbf{1}_{\mathcal{C}_{j,k}}$ and $\tilde{e}_{j,k} = e_{j-1,2k} - e_{j-1,2k+1}$,

$$\Pi_1(\mathcal{C}_{M,N}(\mathbb{P}, \rho))[g, r] = \gamma_{M+N,0}(g, r)e_{M+N,0} + \sum_{1 \leq j \leq M+N} \sum_{0 \leq k < 2^{M+N-j}} \tilde{\gamma}_{j,k}(g, r)\tilde{e}_{j,k}, \quad (\text{SA-12})$$

where $e_{j,k} = \mathbf{1}(\mathcal{E}_{j,k})$ and $\tilde{e}_{j,k} = \mathbf{1}(\mathcal{E}_{j-1,2k}) - \mathbf{1}(\mathcal{E}_{j-1,2k+1})$, and

$$\gamma_{j,k}(g, r) = \begin{cases} \mathbb{E}[g(X)r(Y)|X \in \mathcal{X}_{j-N,k}], & \text{if } N \leq j \leq M+N, \\ \mathbb{E}[g(X)|X \in \mathcal{X}_{0,l}] \cdot \mathbb{E}[r(Y)|X \in \mathcal{X}_{0,l}, Y \in \mathcal{Y}_{l,0,m}], & \text{if } j < N, k = 2^{N-j}l + m, \end{cases}$$

and $\tilde{\gamma}_{j,k}(g, r) = \gamma_{j-1,2k}(g, r) - \gamma_{j-1,2k+1}(g, r)$. We will use Π_1 as a shorthand for $\Pi_1(\mathcal{E}_{M,N}(\mathbb{P}, \rho))$.

For simplicity, we denote $\Pi_1(\mathcal{A}_{M,n}(\mathbb{P}, 1))$ by Π_1 instead. Now define the projected empirical process

$$\Pi_1 A_n(g, h, r, s) = \Pi_1 M_n(g, r) + \Pi_1 M_n(h, s), \quad g \in \mathcal{G}, h \in \mathcal{H}, r \in \mathcal{R}, s \in \mathcal{S},$$

where $\Pi_1 M_n(g, r)$ and $\Pi_1 M_n(h, s)$ are given in Equation (SA-10) in Cattaneo and Yu [2025], that is,

$$\begin{aligned} \Pi_1 M_n(g, r) &= \frac{1}{\sqrt{n}} \sum_{i=1}^n (\Pi_1[g, r](\mathbf{x}_i, y_i) - \mathbb{E}[\Pi_1[g, r](\mathbf{x}_i, y_i)]), \\ \Pi_1 M_n(h, s) &= \frac{1}{\sqrt{n}} \sum_{i=1}^n (\Pi_1[h, s](\mathbf{x}_i, y_i) - \mathbb{E}[\Pi_1[h, s](\mathbf{x}_i, y_i)]). \end{aligned}$$

Construction of Gaussian Process Suppose $(\tilde{\xi}_{j,k} : 0 \leq k < 2^{M+N-j}, 1 \leq j \leq M+N)$ are i.i.d. standard Gaussian random variables. Take $F_{(j,k),m}$ to be the cumulative distribution function of $(S_{j,k} - mp_{j,k})/\sqrt{mp_{j,k}(1-p_{j,k})}$, where $p_{j,k} = \mathbb{P}(\mathcal{E}_{j-1,2k})/\mathbb{P}(\mathcal{E}_{j,k})$ and $S_{j,k}$ is a $\text{Bin}(m, p_{j,k})$ random variable, and $G_{(j,k),m}(t) = \sup\{x : F_{(j,k),m}(x) \leq t\}$. We define $U_{j,k}, \tilde{U}_{j,k}$'s via the following iterative scheme:

1. *Initialization:* Take $U_{M+N,0} = n$.
2. *Iteration:* Suppose we've defined $U_{l,k}$ for $j < l \leq M+N, 0 \leq k < 2^{M+N-l}$, then solve for $U_{j,k}$'s s.t.

$$\begin{aligned} \tilde{U}_{j,k} &= \sqrt{U_{j,k}p_{j,k}(1-p_{j,k})}G_{(j,k),U_{j,k}} \circ \Phi(\tilde{\xi}_{j,k}), \\ \tilde{U}_{j,k} &= (1-p_{j,k})U_{j-1,2k} - p_{j,k}U_{j-1,2k+1} = U_{j-1,2k} - p_{j,k}U_{j,k}, \\ U_{j-1,2k} + U_{j-1,2k+1} &= U_{j,k}, \quad 0 \leq k < 2^{M+N-j}. \end{aligned}$$

Continue till we have defined $U_{0,k}$ for $0 \leq k < 2^{M+N}$.

Then, $\{U_{j,k} : 0 \leq j \leq K, 0 \leq k < 2^{M+N-j}\}$ have the same joint distribution as $\{\sum_{i=1}^n e_{j,k}(\mathbf{x}_i, y_i) : 0 \leq j \leq K, 0 \leq k < 2^{M+N-j}\}$. By Vorob'ev–Berkès–Philipp theorem [Dudley, 2014, Theorem 1.31], $\{\tilde{\xi}_{j,k} : 0 \leq k < 2^{M+N-j}, 1 \leq j \leq M+N\}$ can be constructed on a possibly enlarged probability space such that the previously constructed $U_{j,k}$ satisfies $U_{j,k} = \sum_{i=1}^n e_{j,k}(\mathbf{x}_i)$ almost surely for all $0 \leq j \leq M+N, 0 \leq k < 2^{M+N-j}$. We will show $\tilde{\xi}_{j,k}$'s can be given as a Brownian bridge indexed by $\tilde{e}_{j,k}$'s.

Since all of $\mathcal{G}, \mathcal{H}, \mathcal{R}$ and \mathcal{S} are VC-type, we can show $\mathcal{G} \times \mathcal{H} + \mathcal{R} \times \mathcal{S}$ is also VC-type, here $+$ is the Minkowski sum. Hence $\mathcal{F} = \mathcal{G} \times \mathcal{H} + \mathcal{R} \times \mathcal{S} \cup \Pi_1[\mathcal{G} \times \mathcal{H} + \mathcal{R} \times \mathcal{S}]$ is pre-Gaussian.

Then, by Skorohod Embedding lemma [Dudley, 2014, Lemma 3.35], on a possibly enlarged probability space, we can construct a Brownian bridge $(Z_n(f) : f \in \mathcal{F})$ that satisfies

$$\tilde{\xi}_{j,k} = \frac{\mathbb{P}(\mathcal{E}_{j,k})}{\sqrt{\mathbb{P}(\mathcal{E}_{j-1,2k})\mathbb{P}(\mathcal{E}_{j-1,2k+1})}} Z_n(\tilde{e}_{j,k}),$$

for $0 \leq k < 2^{M+N-j}, 1 \leq j \leq M+N$. Moreover, call

$$V_{j,k} = \sqrt{n}Z_n(e_{j,k}), \quad \tilde{V}_{j,k} = \sqrt{n}Z_n(\tilde{e}_{j,k}), \quad \tilde{\xi}_{j,k} = \frac{\mathbb{P}(\mathcal{E}_{j,k})}{\sqrt{n\mathbb{P}(\mathcal{E}_{j-1,2k})\mathbb{P}(\mathcal{E}_{j-1,2k+1})}}\tilde{V}_{j,k}.$$

for $0 \leq k < 2^{K-j}, 1 \leq j \leq K$. We have for $g \in \mathcal{G}, h \in \mathcal{H}, r \in \mathcal{R}, s \in \mathcal{S}$,

$$\begin{aligned} \sqrt{n}\Pi_1 A_n(g, h, r, s) &= \sum_{j=1}^{M+N} \sum_{0 \leq k < 2^{M+N-j}} (\tilde{\gamma}_{j,k}[g, r] + \tilde{\gamma}_{j,k}[h, s])\tilde{U}_{j,k}, \\ \sqrt{n}\Pi_1 Z_n(g, h, r, s) &= \sum_{j=1}^{M+N} \sum_{0 \leq k < 2^{M+N-j}} (\tilde{\gamma}_{j,k}[g, r] + \tilde{\gamma}_{j,k}[h, s])\tilde{V}_{j,k}. \end{aligned}$$

Decomposition Fix one $(g, h, r, s) \in \mathcal{G} \times \mathcal{H} \times \mathcal{R} \times \mathcal{S}$, we decompose by

$$\begin{aligned} &A_n(g, h, r, s) - Z_n(g, h, r, s) \\ &= \underbrace{\Pi_1 A_n(g, h, r, s) - \Pi_1 Z_n(g, h, r, s)}_{\text{strong approximation (SA) error for projected}} + \underbrace{A_n(g, h, r, s) - \Pi_1 A_n(g, h, r, s) + \Pi_1 Z_n(g, h, r, s) - Z_n(g, h, r, s)}_{\text{projection error}}. \end{aligned}$$

SA error for Projected Process The strong approximation error essentially depends on the Hilbertian pseudo norm

$$\sum_{j=1}^{M+N} \sum_{0 \leq k < 2^{M+N-j}} (\tilde{\gamma}_{j,k}[g, r] + \tilde{\gamma}_{j,k}[h, s])^2 \leq 2 \sum_{j=1}^{M+N} \sum_{0 \leq k < 2^{M+N-j}} (\tilde{\gamma}_{j,k}[g, r])^2 + 2 \sum_{j=1}^{M+N} \sum_{0 \leq k < 2^{M+N-j}} (\tilde{\gamma}_{j,k}[h, s])^2.$$

Hence, [Cattaneo and Yu \[2025, Lemma SA.19\]](#) gives with probability at least $1 - 2e^{-t}$,

$$|\Pi_1 A_n(g, h, r, s) - \Pi_1 Z_n(g, h, r, s)| \leq C_1 C_\alpha \sqrt{\frac{N^{2\alpha+1} 2^M \mathbf{EM}}{n}} t + C_1 C_\alpha \sqrt{\frac{(\|\Pi_1[g, r]\|_\infty + \|\Pi_1[h, s]\|_\infty)^2 (M+N)}{n}} t,$$

where $C_1 > 0$ is a universal constant and $C_\alpha = 1 + (2\alpha)^{\alpha/2}$.

Projection Error For the projection error, we use the simple observation that

$$|A_n(g, h, r, s) - \Pi_1 A_n(g, h, r, s)| \leq |M_n(g, r) - \Pi_1 M_n(g, r)| + |M_n(h, s) - \Pi_1 M_n(h, s)|,$$

and [Cattaneo and Yu \[2025, Lemma SA.23\]](#) to get for all $t > N$,

$$\begin{aligned} \mathbb{P}\left[|A_n(g, h, r, s) - \Pi_1 A_n(g, h, r, s)| > C_2 \sqrt{C_{2\alpha}} \sqrt{N^2 \mathbf{V} + 2^{-N} \mathbf{M}^2} t^{\alpha+\frac{1}{2}} + C_2 C_\alpha \frac{\mathbf{M}}{\sqrt{n}} t^{\alpha+1}\right] &\leq 4ne^{-t}, \\ \mathbb{P}\left[|Z_n(g, h, r, s) - \Pi_1 Z_n(g, h, r, s)| > C_2 \sqrt{C_{2\alpha}} \sqrt{N^2 \mathbf{V} + C_2 C_\alpha 2^{-N} \mathbf{M}^2} t^{\frac{1}{2}} + C_2 C_\alpha \frac{\mathbf{M}}{\sqrt{n}} t\right] &\leq 4ne^{-t}, \end{aligned}$$

where $C_\alpha = 1 + (2\alpha)^{\frac{\alpha}{2}}$ and $C_{2\alpha} = 1 + (4\alpha)^\alpha$ and C_2 is a constant that only depends on the distribution of (\mathbf{x}_1, y_1) , with

$$\mathbf{V} = \min\{2\mathbf{M}, \sqrt{d}\mathbf{L}2^{-M/d}\}2^{-M/d}\mathbf{TV}_{\mathcal{H}}.$$

Uniform SA Error: Since all of \mathcal{G} , \mathcal{H} , \mathcal{R} and \mathcal{S} are VC-type class, from a union bound argument and the same control over fluctuation error as in [Cattaneo and Yu \[2025, Lemma SA.18\]](#), denoting $\mathcal{F} = \mathcal{G} \times \mathcal{H} \times \mathcal{R} \times \mathcal{S}$, we get for all $t > 0$ and $0 < \delta < 1$,

$$\mathbb{P}[\|A_n - A_n \circ \pi_{\mathcal{F}_\delta}\|_{\mathcal{F}} + \|Z_n - Z_n \circ \pi_{\mathcal{F}_\delta}\|_{\mathcal{F}} > C_1 C_\alpha F_n(t, \delta)] \leq \exp(-t),$$

where $C_\alpha = 1 + (2\alpha)^{\frac{\alpha}{2}}$ and

$$F_n(t, \delta) = J(\delta)\mathbf{M} + \frac{(\log n)^{\alpha/2}\mathbf{M}J^2(\delta)}{\delta^2\sqrt{n}} + \frac{\mathbf{M}}{\sqrt{n}}t + (\log n)^\alpha \frac{\mathbf{M}}{\sqrt{n}}t^\alpha.$$

where

$$\begin{aligned} J(\delta) &= 3\delta \left(\sqrt{\mathbf{d}_{\mathcal{G}} \log\left(\frac{2\mathbf{c}_{\mathcal{G}}}{\delta}\right)} + \sqrt{\mathbf{d}_{\mathcal{H}} \log\left(\frac{2\mathbf{c}_{\mathcal{H}}}{\delta}\right)} + \sqrt{\mathbf{d}_{\mathcal{R}} \log\left(\frac{2\mathbf{c}_{\mathcal{R}}}{\delta}\right)} + \sqrt{\mathbf{d}_{\mathcal{S}} \log\left(\frac{2\mathbf{c}_{\mathcal{S}}}{\delta}\right)} \right) \\ &\lesssim \sqrt{\mathbf{d} \log(\mathbf{c}/\delta)}, \end{aligned}$$

recalling $\mathbf{c} = \mathbf{c}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} + \mathbf{c}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} + \mathbf{c}_{\mathcal{R}, \mathcal{Y}} + \mathbf{c}_{\mathcal{S}, \mathcal{Y}} + \mathbf{k}$, $\mathbf{d} = \mathbf{d}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \mathbf{d}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}} \mathbf{d}_{\mathcal{R}, \mathcal{Y}} \mathbf{d}_{\mathcal{S}, \mathcal{Y}} \mathbf{k}$. Choosing the optimal M^* , N^* gives $\mathbb{P}[\|A_n - Z_n^A\|_{\mathcal{F}} > C_1 \mathbf{v} \mathbf{T}_n(t)] \leq C_2 e^{-t}$ for all $t > 0$, where

$$\mathbf{T}_n(t) = \min_{\delta \in (0,1)} \{A_n(t, \delta) + F_n(t, \delta)\},$$

with

$$\begin{aligned} A_n(t, \delta) &= \sqrt{d} \min \left\{ \left(\frac{\mathbf{c}_1^d \mathbf{E} \mathbf{T} \mathbf{V}^d \mathbf{M}^{d+1}}{n} \right)^{\frac{1}{2(d+1)}}, \left(\frac{\mathbf{c}_1^d \mathbf{c}_2^d \mathbf{E}^2 \mathbf{M}^2 \mathbf{T} \mathbf{V}^d \mathbf{L}^d}{n^2} \right)^{\frac{1}{2(d+2)}} \right\} (t + \log(n\mathbf{N}(\delta)N^*))^{\alpha+1} \\ &\quad + \sqrt{\frac{\mathbf{M}^2(M^* + N^*)}{n}} (\log n)^\alpha (t + \log(n\mathbf{N}(\delta)N^*))^{\alpha+1}, \\ F_n(t, \delta) &= J(\delta)\mathbf{M} + \frac{(\log n)^{\alpha/2}\mathbf{M}J^2(\delta)}{\delta^2\sqrt{n}} + \frac{\mathbf{M}}{\sqrt{n}}\sqrt{t} + (\log n)^\alpha \frac{\mathbf{M}}{\sqrt{n}}t^\alpha, \end{aligned}$$

where

$$\begin{aligned} \mathcal{V}_{\mathcal{R}} &= \{\theta(\cdot, r) : r \in \mathcal{R}\}, \\ \mathbf{N}(\delta) &= \mathbf{N}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}(\delta/2, \mathbf{M}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}) \mathbf{N}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}(\delta/2, \mathbf{M}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}) \mathbf{N}_{\mathcal{R}, \mathcal{Y}}(\delta/2, M_{\mathcal{R}}) \mathbf{N}_{\mathcal{S}, \mathcal{Y}}(\delta/2, M_{\mathcal{S}, \mathcal{Y}}), \\ J(\delta) &= 2J_{\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}(\mathcal{G}, \mathbf{M}_{\mathcal{G}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}, \delta/2) + 2J_{\mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}(\mathcal{H}, \mathbf{M}_{\mathcal{H}, \mathcal{Q}_{\mathcal{G} \cup \mathcal{H}}}, \delta/2) + 2J_{\mathcal{Y}}(\mathcal{R}, M_{\mathcal{R}, \mathcal{Y}}, \delta/2) + 2J_{\mathcal{Y}}(\mathcal{S}, M_{\mathcal{S}, \mathcal{Y}}, \delta/2), \\ M^* &= \left\lceil \log_2 \min \left\{ \left(\frac{\mathbf{c}_1 n \mathbf{T} \mathbf{V}}{\mathbf{E}} \right)^{\frac{d}{d+1}}, \left(\frac{\mathbf{c}_1 \mathbf{c}_2 n \mathbf{L} \mathbf{T} \mathbf{V}}{\mathbf{E} \mathbf{M}} \right)^{\frac{d}{d+2}} \right\} \right\rceil, \\ N^* &= \left\lceil \log_2 \max \left\{ \left(\frac{n \mathbf{M}^{d+1}}{\mathbf{c}_1^d \mathbf{E} \mathbf{T} \mathbf{V}^d} \right)^{\frac{1}{d+1}}, \left(\frac{n^2 \mathbf{M}^{2d+2}}{\mathbf{c}_1^d \mathbf{c}_2^d \mathbf{T} \mathbf{V}^d \mathbf{L}^d \mathbf{E}^2} \right)^{\frac{1}{d+2}} \right\} \right\rceil. \end{aligned}$$

Truncation Argument for y_i 's with Finite Moments The above result is derived under the assumption that $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[\exp(|y_i|)|\mathbf{x}_i = \mathbf{x}] < \infty$. For the result under the condition $\sup_{\mathbf{x} \in \mathcal{X}} \mathbb{E}[|y_i|^{2+v}|\mathbf{x}_i = \mathbf{x}] < \infty$, we can use the same truncation argument as in [\[Cattaneo et al., 2025, Theorem SA-11 in the supplemental material\]](#) and the VC-type conditions for \mathcal{G} , \mathcal{H} , \mathcal{R} , \mathcal{S} to get the stated conclusions. \square

SA-6.14 Proof of Theorem 2

Part I: Upper Bound.

The proof is essentially the proof for Lemma SA-5 with the data generating process ranging over \mathcal{P} . By Theorem SA-1 and Equation (SA-6), we have

$$\begin{aligned}
& \sup_{\mathbb{P} \in \mathcal{P}} \sup_{\mathbf{x} \in \mathcal{B}} |\mathfrak{B}_{n,t}(\mathbf{x})| \\
&= \sup_{\mathbb{P} \in \mathcal{P}} \sup_{\mathbf{x} \in \mathcal{B}} \left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbf{S}_{t,\mathbf{x}} - \mu_t(\mathbf{x}) \right| \\
&= \sup_{\mathbb{P} \in \mathcal{P}} \sup_{\mathbf{x} \in \mathcal{B}} \left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) \mathbf{r}_p(D_i(\mathbf{x}))^\top (\mu_t(\mathbf{X}_i) - \mu_t(\mathbf{x}), 0, \dots, 0) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_t) \right] \right| \\
&\lesssim \sup_{\mathbb{P} \in \mathcal{P}} \sup_{\mathbf{x} \in \mathcal{B}} \sup_{\mathbf{z} \in \mathcal{X}} \left| \mathbf{e}_1^\top \Psi_{t,\mathbf{x}}^{-1} \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right) K_h(D_i(\mathbf{x})) \mathbf{r}_p \left(\frac{D_i(\mathbf{x})}{h} \right)^\top \right] \right. \\
&\quad \cdot \sup_{\mathbb{P} \in \mathcal{P}} \sup_{\mathbf{x} \in \mathcal{B}} \sup_{\mathbf{z} \in \mathcal{X}} |\mu_t(\mathbf{x}) - \mu_t(\mathbf{z})| \mathbf{1}(K_h(\mathcal{d}(\mathbf{z}, \mathbf{x})) > 0) \\
&\lesssim h.
\end{aligned}$$

Part II: Lower Bound.

The lower bound is proved by considering the following data generating process. Suppose $\mathbf{X}_i \sim \text{Uniform}([-2, 2]^2)$, and $\mu_0(x_1, x_2) = 0$ and $\mu_1(x_1, x_2) = x_2$ for all $(x_1, x_2) \in \mathcal{X} = [-2, 2]^2$. Suppose $Y_i(0) \sim \text{Normal}(\mu_0(\mathbf{X}_i), 1)$ and $Y_i(1) \sim \text{Normal}(\mu_1(\mathbf{X}_i), 1)$. Define the treatment and control region by $\mathcal{A}_1 = \{(x, y) \in \mathcal{X} : x \geq 0, y \geq 0\}$, $\mathcal{A}_0 = \mathcal{X} / \mathcal{A}_1$, $\mathcal{B} = \{(x, y) \in \mathbb{R} : 0 \leq x \leq 2, y = 0 \text{ or } x = 0, 0 \leq y \leq 2\}$. Suppose $Y_i = \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_0)Y_i(0) + \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1)Y_i(1)$. Suppose we choose \mathcal{d} to be the Euclidean distance and $D_i(\mathbf{x}) = \|\mathbf{X}_i - \mathbf{x}\|$. In this case, although the underlying conditional mean functions μ_t , $t \in \{0, 1\}$ are smooth, the conditional mean given distance $\theta_{t,\mathbf{x}}$ may not even be differentiable. In this example,

$$\theta_{1,(s,0)}(r) = \begin{cases} \frac{2}{\pi r}, & \text{if } 0 \leq r \leq s, \\ \frac{r+s}{\pi - \arccos(s/r)}, & \text{if } r > s. \end{cases}$$

Figure SA-1 plots $r \mapsto \theta_{1,(3/4,0)}(r)$ with the notation $\mathbf{x}_s = (s, 0)$.

Under this data generating process, we can show

$$\inf_{0 < h < 1} \sup_{\mathbf{x} \in \mathcal{B}} \frac{|\mathfrak{B}_{n,1}(\mathbf{x}) - \mathfrak{B}_{n,0}(\mathbf{x})|}{h} > 0.$$

The proof proceeds in two steps. First, we show a scaling property of the asymptotic bias under our example, which gives a reduction to fixed- h bias calculation. Second, we prove the lower bound via the reduction from previous step.

Step 1: A Scaling Property

Let $0 < h < 1, 0 < s < 1, 0 < C < 1$. Define $h' = Ch$ and $s' = Cs$. Here C is the scaling factor and denote $\mathbf{x}_s = (s, 0)$ and $\mathbf{x}_{s'} = (s', 0)$. Denote bias for $\mathbf{x}_{s'}$ under bandwidth h' to be

$$\text{bias}_{n,1}(h', s') = \mathbf{e}_1^\top \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i((s', 0))}{h'} \right) \mathbf{r}_p \left(\frac{D_i((s', 0))}{h'} \right)^\top K_{h'}(D_i((s', 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right]^{-1}$$

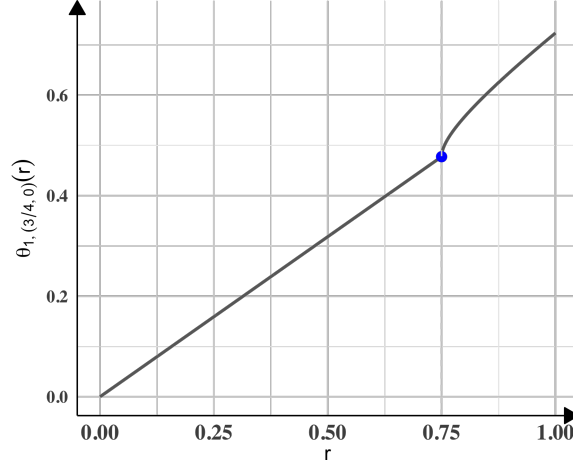


Figure SA-1: Conditional Mean Given Distance with One Kink

$$\mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i((s', 0))}{h'} \right) K_{h'}(D_i((s', 0))) (\mu_1(\mathbf{X}_i - (s', 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right], \quad (\text{SA-13})$$

where we have used the fact that μ_1 is linear in our example, hence $\mu_1(\mathbf{X}_i) - \mu_1((s', 0)) = \mu_1(\mathbf{X}_i - (s', 0))$. We reserve the notation $\mathfrak{B}_{n,t}$, $t = 0, 1$, to the bias when bandwidth is h , that is,

$$\mathfrak{B}_{n,t}(\mathbf{x}_s) \equiv \text{bias}_{n,t}(h, s), \quad h \in (0, 1), s \in (0, 1), t = 0, 1.$$

Inspecting each element of the last vector, for all $l \in \mathbb{N}$,

$$\begin{aligned} & \mathbb{E} \left[\left(\frac{\|\mathbf{X}_i - (s', 0)\|}{h'} \right)^l K_{h'}(\|\mathbf{X}_i - (s', 0)\|) (\mu_1(\mathbf{X}_i - (s', 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right] \\ &= \int_0^2 \int_0^2 \left(\frac{1}{h'} \right)^2 \left(\frac{\|(u' - s', v')\|}{h'} \right)^l k \left(\frac{\|(u' - s', v')\|}{h'} \right) \mu_1((u', v') - (s', 0)) \frac{1}{4} du' dv' \\ &\stackrel{(1)}{=} \int_0^{2/C} \int_0^{2/C} \left(\frac{1}{Ch} \right)^2 \left(\frac{\|(Cu - Cs, Cv)\|}{Ch} \right)^l k \left(\frac{\|(Cu - Cs, Cv)\|}{Ch} \right) \mu_1(C(u - s, v)) \frac{C^2}{4} dudv \\ &= \int_0^{2/C} \int_0^{2/C} \left(\frac{1}{h} \right)^2 \left(\frac{\|(u - s, v)\|}{h} \right)^l k \left(\frac{\|(u - s, v)\|}{h} \right) C \mu_1((u - s, v)) \frac{1}{4} dudv \\ &\stackrel{(2)}{=} \int_0^2 \int_0^2 \left(\frac{1}{h} \right)^2 \left(\frac{\|(u - s, v)\|}{h} \right)^l k \left(\frac{\|(u, v) - (s, 0)\|}{h} \right) C \mu_1((u, v) - (s, 0)) \frac{1}{4} dudv \\ &= C \mathbb{E} \left[\left(\frac{\|\mathbf{X}_i - (s, 0)\|}{h} \right)^l K_h(\|\mathbf{X}_i - (s, 0)\|) \mu_1(\mathbf{X}_i - (s, 0)) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right], \end{aligned}$$

where in (1) we have used a change of variable $(u, v) = \frac{1}{C}(u', v')$, and (2) holds since $k \left(\frac{\|\cdot - (s, 0)\|}{h} \right)$ is supported in $(s, 0) + hB(0, 1)$, which is contained in $[0, 2] \times [0, 2] \subseteq [0, 2/C] \times [0, 2/C]$ for all $0 < h < 1$, $0 < s < 1$, $0 < C < 1$. This means

$$\mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i((s', 0))}{h'} \right) K_{h'}(D_i((s', 0))) (\mu_1(\mathbf{X}_i - (s', 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right]$$

$$= C \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i((s, 0))}{h} \right) K_h(D_i((s, 0))) (\mu_1(\mathbf{X}_i - (s, 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right].$$

Similarly, for all $l \in \mathbb{N}$ and $0 < h < 1$, $0 < s < 1$, $0 < C < 1$,

$$\mathbb{E} \left[\left(\frac{D_i((s', 0))}{h'} \right)^l K_{h'}(D_i((s', 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right] = \mathbb{E} \left[\left(\frac{D_i((s, 0))}{h} \right)^l K_h(D_i((s, 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right],$$

implying

$$\begin{aligned} & \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i((s', 0))}{h'} \right) \mathbf{r}_p \left(\frac{D_i((s', 0))}{h'} \right)^\top K_{h'}(D_i((s', 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right] \\ &= \mathbb{E} \left[\mathbf{r}_p \left(\frac{D_i((s, 0))}{h} \right) \mathbf{r}_p \left(\frac{D_i((s, 0))}{h} \right)^\top K_h(D_i((s, 0))) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right]. \end{aligned}$$

It then follows that for all $0 < h < 1$, $0 < s < 1$, $0 < C < 1$,

$$\text{bias}_{n,1}(h', s') = C \text{bias}_{n,1}(h, s).$$

Moreover, for all $0 < h < 1$, $0 < s < h$,

$$\mathfrak{B}_{n,1}(\mathbf{x}_s) = \text{bias}_{n,1}(h, s) = h \text{bias}_{n,1} \left(1, \frac{s}{h} \right). \quad (\text{SA-14})$$

Since $\mu_0 \equiv 0$, it is easy to check that

$$\mathfrak{B}_{n,0}(\mathbf{x}_s) = \text{bias}_{n,0}(h, s) \equiv 0, \quad 0 < h < 1, 0 < s < h.$$

Step 2: Lower Bound on Bias

Now we want to show $\sup_{0 \leq s \leq 1} |\text{bias}_{n,1}(1, s) - \text{bias}_{n,0}(1, s)| > 0$. By Equation (SA-13),

$$\begin{aligned} \text{bias}_{n,1}(1, s) - \text{bias}_{n,0}(1, s) &= \mathbf{e}_1^\top \boldsymbol{\Psi}_s^{-1} \mathbf{S}_s - \mu_1(\mathbf{x}_s) - 0 = \mathbf{e}_1^\top \boldsymbol{\Psi}_s^{-1} \mathbf{S}_s, \\ \boldsymbol{\Psi}_s &= \mathbb{E} \left[\mathbf{r}_p(D_i(\mathbf{x}_s)) \mathbf{r}_p(D_i(\mathbf{x}_s))^\top K(D_i(\mathbf{x}_s)) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1) \right], \\ \mathbf{S}_s &= \mathbb{E} [\mathbf{r}_p(D_i(\mathbf{x}_s)) K(D_i(\mathbf{x}_s)) \mu_1(\mathbf{X}_i) \mathbf{1}(\mathbf{X}_i \in \mathcal{A}_1)]. \end{aligned}$$

Changing to polar coordinates, we have

$$\begin{aligned} \boldsymbol{\Psi}_s &= \int_0^\infty \int_{\Theta_s(r)}^\pi \mathbf{r}_p(r) \mathbf{r}_p(r)^\top K(r) r d\theta dr, \\ \mathbf{S}_s &= \int_0^\infty \int_{\Theta_s(r)}^\pi \mathbf{r}_p(r) K(r) r \sin(\theta) r d\theta dr, \end{aligned}$$

with

$$\Theta_s(r) = \begin{cases} 0, & \text{if } 0 \leq r \leq s, \\ \arccos(s/r), & \text{if } r > s. \end{cases}$$

For notation simplicity, denote

$$\begin{aligned}\mathbf{A}(s) &= \int_0^\infty \int_{\Theta_s(u)}^\pi \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) u d\theta du = \mathbf{A}_1(s) + \mathbf{A}_2(s), \\ \mathbf{B}(s) &= \int_0^\infty \int_{\Theta_s(u)}^\pi \mathbf{r}_p(u) K(u) u \sin(\theta) u d\theta du = \mathbf{B}_1(s) + \mathbf{B}_2(s),\end{aligned}$$

where

$$\begin{aligned}\mathbf{A}_1(s) &= \int_0^s \int_0^\pi \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) u d\theta du = \pi \int_0^s \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) u du, \\ \mathbf{A}_2(s) &= \int_s^\infty \int_{\arccos(s/u)}^\pi \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) u d\theta du = \int_s^\infty (\pi - \arccos(s/u)) \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) u du, \\ \mathbf{B}_1(s) &= \int_0^s \int_0^\pi \mathbf{r}_p(u) K(u) u \sin(\theta) u d\theta du = 2 \int_0^s \mathbf{r}_p(u) K(u) u^2 du, \\ \mathbf{B}_2(s) &= \int_s^\infty \int_{\arccos(s/u)}^\pi \mathbf{r}_p(u) K(u) u \sin(\theta) u d\theta du = \int_s^\infty (1 + \frac{s}{u}) \mathbf{r}_p(u) K(u) u^2 du.\end{aligned}$$

Evaluating the above at zero gives

$$\mathbf{A}(0) = \frac{\pi}{2} \int_0^\infty u \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) du, \quad \mathbf{B}(0) = \int_0^\infty u^2 \mathbf{r}_p(u) K(u) du.$$

Hence

$$\text{bias}_{n,1}(1, 0) - \text{bias}_{n,0}(1, 0) = \mathbf{e}_1^\top \mathbf{A}(0)^{-1} \mathbf{B}(0) = \mathbf{e}_1^\top \mathbf{A}(0)^{-1} \left[\frac{2}{\pi} \mathbf{A}(0) \mathbf{e}_2 \right] = 0. \quad (\text{SA-15})$$

Taking derivatives with respect to s , we have

$$\begin{aligned}\dot{\mathbf{A}}_1(s) &= \pi \mathbf{r}_p(s) \mathbf{r}_p(s)^\top K(s) s, \\ \dot{\mathbf{A}}_2(s) &= -\pi \mathbf{r}_p(s) \mathbf{r}_p(s)^\top K(s) s + \int_s^\infty \frac{1}{\sqrt{u^2 - s^2}} u \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) du, \\ \dot{\mathbf{B}}_1(s) &= 2 \mathbf{r}_p(s) K(s) s^2, \\ \dot{\mathbf{B}}_2(s) &= -2 \mathbf{r}_p(s) K(s) s^2 + \int_s^\infty u \mathbf{r}_p(u) K(u) du.\end{aligned}$$

Evaluating the above at zero gives

$$\dot{\mathbf{A}}(0) = \int_0^\infty \mathbf{r}_p(u) \mathbf{r}_p(u)^\top K(u) du, \quad \dot{\mathbf{B}}(0) = \int_0^\infty u \mathbf{r}_p(u) K(u) du.$$

Using matrix calculus, we know

$$\begin{aligned}& \left. \frac{d}{ds} \text{bias}_{n,1}(1, s) - \text{bias}_{n,0}(1, s) \right|_{s=0} \\ &= \left. \frac{d}{ds} \mathbf{e}_1^\top \mathbf{A}(s)^{-1} \mathbf{B}(s) \right|_{s=0} \quad (\text{SA-16}) \\ &= -\mathbf{e}_1^\top \mathbf{A}(0)^{-1} \dot{\mathbf{A}}(0) [\mathbf{A}(0)^{-1} \mathbf{B}(0)] + \mathbf{e}_1^\top \mathbf{A}(0)^{-1} \dot{\mathbf{B}}(0) \quad (\text{SA-17})\end{aligned}$$

$$\begin{aligned}
&= -\mathbf{e}_1^\top \mathbf{A}(0)^{-1} \dot{\mathbf{A}}(0) \left[\frac{2}{\pi} \mathbf{e}_2 \right] + \mathbf{e}_1^\top \left[\frac{2}{\pi} \mathbf{e}_1 \right] \\
&= -\frac{2}{\pi} \mathbf{e}_1^\top \mathbf{A}(0)^{-1} \int_0^\infty \begin{bmatrix} u \\ u^2 \\ \dots \\ u^{p+1} \end{bmatrix} K(u) du + \mathbf{e}_1^\top \left[\frac{2}{\pi} \mathbf{e}_1 \right] \\
&= -\frac{4}{\pi^2} + \frac{2}{\pi}.
\end{aligned} \tag{SA-18}$$

Combining Equations (SA-15) and (SA-16), and the fact that $\frac{d}{ds} \text{bias}_{n,1}(1, s) - \text{bias}_{n,0}(1, s)$ is continuous in s , we can show $\sup_{0 \leq s \leq 1} |\text{bias}_{n,1}(1, s) - \text{bias}_{n,0}(1, s)| > 0$. Combining with Equation (SA-14), we have

$$\begin{aligned}
\inf_{0 < h < 1} \sup_{\mathbf{x} \in \mathcal{B}} \frac{|\mathfrak{B}_{n,1}(\mathbf{x}) - \mathfrak{B}_{n,0}(\mathbf{x})|}{h} &\geq \inf_{0 < h < 1} \sup_{0 < s < h} \frac{|\text{bias}_{n,1}(s, h) - \text{bias}_{n,0}(s, h)|}{h} \\
&= \inf_{0 < h < 1} \sup_{0 < s < h} \left| \text{bias}_{n,1} \left(1, \frac{s}{h} \right) \right| \\
&> 0.
\end{aligned}$$

□

SA-6.15 Proof of Theorem 3

The proof of part (i) follows from part (ii) with $\mathcal{B} \cap B(\mathbf{x}, \varepsilon)$ as the boundary. To prove part (ii), without loss of generality, we assume that $\iota = p + 1$, and want to show $\sup_{\mathbf{x} \in \mathcal{B}^\circ} |\mathfrak{B}_{n,t}(\mathbf{x})| \lesssim h^{p+1}$. This means we have assumed that \mathcal{B} has a one-to-one curve length parametrization γ that is C^{p+3} with curve length L , there exists $\varepsilon, \delta > 0$ such that for all $\mathbf{x} \in \gamma([\delta, L - \delta])$ and $0 < r < \varepsilon$, $S(\mathbf{x}, r)$ intersects \mathcal{B} with two points, $s(\mathbf{x}, r)$ and $t(\mathbf{x}, r)$. Define $a(\mathbf{x}, r)$ and $b(\mathbf{x}, r)$ to be the number in $[0, 2\pi]$ such that

$$[a(\mathbf{x}, r), b(\mathbf{x}, r)] = \{\theta : \mathbf{x} + r(\cos \theta, \sin \theta) \in \mathcal{A}_1\}.$$

Then, for $\mathbf{x} \in \mathcal{B}$ and $0 < r < \varepsilon$, $\theta_{1,\mathbf{x}}(r)$ has the following explicit representation:

$$\theta_{1,\mathbf{x}}(r) = \frac{\int_{a(\mathbf{x},r)}^{b(\mathbf{x},r)} \mu_1(\mathbf{x} + r(\cos \theta, \sin \theta)) f_X(\mathbf{x} + r(\cos \theta, \sin \theta)) d\theta}{\int_{a(\mathbf{x},r)}^{b(\mathbf{x},r)} f_X(\mathbf{x} + r(\cos \theta, \sin \theta)) d\theta}.$$

Step 1: Curve length v.s. Distance to $\gamma(0)$

W.l.o.g., assume $\gamma(0) = \mathbf{x}$ and $\gamma'(0) = (1, 0)$. Let $T : [0, \infty) \rightarrow [0, \infty)$ to be a continuous increasing function that satisfies

$$\|\gamma \circ T(r)\|^2 = r^2, \quad \forall r \in [0, h].$$

Initial Case: $l = 1, 2, 3$.

We will show that T is C^l on $(0, h)$. For notational simplicity, define another function $\phi : [0, \infty) \rightarrow [0, \infty)$ by $\phi(t) = \|\gamma(t)\|^2$. Using implicit derivations iteratively,

$$\phi \circ T(r) = r^2,$$

$$\begin{aligned}
\phi'(T(r))T'(r) &= 2r, \\
\phi''(T(r))(T'(r))^2 + \phi'(T(r))T''(r) &= 2, \\
\phi'''(T(r))(T'(r))^3 + 3\phi''(T(r))T'(r)T''(r) + \phi'(T(r))T'''(r) &= 0.
\end{aligned} \tag{1}$$

From the above equalities, we get

$$\begin{aligned}
T'(r) &= \frac{2r}{\phi'(T(r))}, \\
T''(r) &= \frac{2 - \phi''(T(r))(T'(r))^2}{\phi'(T(r))}, \\
T'''(r) &= -\frac{\phi'''(T(r))(T'(r))^3 + 3\phi''(T(r))T'(r)T''(r)}{\phi'(T(r))}.
\end{aligned}$$

Since we have assumed γ is C^{p+3} on $(0, h)$, ϕ is also C^{p+1} on $(0, h)$. It follows from the above calculation that T is C^{p+3} on $(0, h)$. In order to find the limit of derivatives of T at 0, we need

$$\begin{aligned}
\phi(t) &= \gamma_1(t)^2 + \gamma_2(t)^2, & \phi(0) &= 0, \\
\phi'(t) &= 2\gamma_1(t)\gamma_1'(t) + 2\gamma_2(t)\gamma_2'(t), & \phi'(0) &= 0, \\
\phi''(t) &= 2\gamma_1'(t)\gamma_1'(t) + 2\gamma_1(t)\gamma_1''(t) + 2\gamma_2'(t)\gamma_2'(t) + 2\gamma_2(t)\gamma_2''(t), & \phi''(0) &= 2, \\
\phi'''(t) &= 6\gamma_1'(t)\gamma_1''(t) + 2\gamma_1(t)\gamma_1'''(t) + 6\gamma_2'(t)\gamma_2''(t) + 2\gamma_2(t)\gamma_2'''(t).
\end{aligned}$$

Using L'Hôpital's rule

$$\begin{aligned}
\lim_{r \downarrow 0} T'(r) &= \lim_{r \downarrow 0} \frac{2}{\phi''(T(r))T'(r)} = \frac{2}{2 \lim_{r \downarrow 0} T'(r)} \implies \lim_{r \downarrow 0} T'(r) = 1, \\
\lim_{r \downarrow 0} T''(r) &= \lim_{r \downarrow 0} \frac{-\phi'''(T(r))(T'(r))^3 - \phi''(T(r))2T'(r)T''(r)}{\phi''(T(r))T'(r)} \\
&= \frac{-\phi^{(3)}(0) - 4 \lim_{r \downarrow 0} T''(r)}{2} \\
&= \frac{-\phi^{(3)}(0)}{6} \\
\lim_{r \downarrow 0} T^{(3)}(r) &= -\lim_{r \downarrow 0} \frac{\phi^{(4)}(T(r))(T'(r))^4 + \phi^{(3)}(T(r))3(T'(r))^2T''(r) + 3\phi^{(3)}(T(r))(T'(r))^2T'''(r)}{\phi''(T(r))T'(r)} \\
&\quad + \lim_{r \downarrow 0} \frac{3\phi''(T(r))T'(r)T^{(3)}(r)}{\phi''(T(r))T'(r)} \\
&= -\frac{\phi^{(4)}(0) - (\phi^{(3)}(0))^2 + 6 \lim_{r \downarrow 0} T^{(3)}(r)}{2} \\
&= -\frac{\phi^{(4)}(0) - (\phi^{(3)}(0))^2}{8}.
\end{aligned}$$

Induction Step: $l \geq 4$.

Assume $\lim_{r \downarrow 0} T^{(i)}(r)$ exists and is finite for $0 \leq i \leq l-2$ and there exists a function $q(r)$ such that (i) $q(r)$ is a polynomial of $\phi^{(j)}(T(r))$, $1 \leq j \leq l-1$ and $T^{(k)}(r)$, $1 \leq k \leq l-2$, (ii) $\lim_{r \downarrow 0} q(r) = 0$ and (iii)

$$q(r) + \phi'(T(r))T^{(l-1)}(r) = 0. \quad (2)$$

For $l = 4$, this assumption can be verified from Equation (1). Using L'hospital's rule,

$$\begin{aligned} \lim_{r \downarrow 0} T^{(l-1)}(r) &= \lim_{r \downarrow 0} -\frac{q(r)}{\phi'(T(r))} \\ &\stackrel{L'h}{=} \lim_{r \downarrow 0} -\frac{q'(r)}{\phi''(T(r))T'(r)}. \end{aligned}$$

From the previous paragraph, $\lim_{r \downarrow 0} \phi''(T(r))T'(r)$ exists and is finite. And $q'(r)$ is a polynomial of $\phi^{(j)}(T(r))$, $1 \leq j \leq l$ and $T^{(k)}(r)$, $1 \leq k \leq l-1$. Hence $\lim_{r \downarrow 0} T^{(l-1)}(r)$ can be solved from the following equation and is finite:

$$\lim_{r \downarrow 0} q'(r) + \lim_{r \downarrow 0} \phi''(T(r))T'(r) \cdot \lim_{r \downarrow 0} T^{(l-1)}(r) = 0. \quad (3)$$

Taking derivatives on both sides of Equation (2),

$$q'(r) + \phi''(T(r))T'(r)T^{(l-1)}(r) + \phi'(T(r))T^{(l)}(r) = 0.$$

Take $q_2(r) = q'(r) + \phi''(T(r))T'(r)T^{(l-1)}(r)$. Then, (i) $q_2(r)$ is a polynomial of $\phi^{(j)}(T(r))$, $1 \leq j \leq l$ and $T^{(k)}(r)$, $1 \leq k \leq l-1$, (ii) $\lim_{r \downarrow 0} q_2(r) = 0$, and (iii)

$$q_2(r) + \phi'(T(r))T^{(l)}(r) = 0.$$

Continue this argument till $l = p+3$, $\lim_{r \downarrow 0} T^{(j)}(r)$ exists and is a polynomial of $\phi^{(0)}(0), \dots, \phi^{(j+1)}(0)$, which implies that it is bounded by a constant only depending on γ .

Step 2: $(p+1)$ -times continuously differentiable S_r

We use the notation $\gamma(t) = (\gamma_1(t), \gamma_2(t))$. Define

$$A(t) = \angle \gamma(t) - \gamma(0), \gamma'(0) = \arcsin \left(\frac{\gamma_2(t)}{\|\gamma(t)\|} \right).$$

Since γ is C^{p+3} , we can Taylor expand γ at 0 to get

$$\gamma(t) = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} t + \begin{pmatrix} u_2 \\ v_2 \end{pmatrix} t^2 + \dots + \begin{pmatrix} u_{p+2} \\ v_{p+2} \end{pmatrix} t^{p+2} + \begin{pmatrix} R_1(t) \\ R_2(t) \end{pmatrix},$$

where we have used the fact that $\gamma'_2(0) = 0$ and $\|\gamma'(0)\| = 1$ and

$$R_1(t) = \int_0^t \frac{\gamma_1^{(p+3)}(s)(t-s)^{p+2}}{(p+2)!} ds, \quad R_2(t) = \int_0^t \frac{\gamma_2^{(p+3)}(s)(t-s)^{p+2}}{(p+2)!} ds.$$

Since γ is C^{p+3} , $R_1(t)/t$ and $R_2(t)/t$ are C^{p+3} on $(0, \infty)$. We *claim* that $\lim_{t \downarrow 0} \frac{d^v}{dt^v}(R_1(t)/t)$ exists and is uniformly bounded for all $\mathbf{x} \in \mathcal{B}$, for all $0 \leq v \leq p+1$. Define $\varphi(t) = R_1(t)/t$. Then

$$\begin{aligned}\varphi'(t) &= -\frac{R_1(t)}{t^2} + \frac{R_1'(t)}{t}, \\ \varphi''(t) &= \frac{2R_1(t)}{t^3} - \frac{2R_1'(t)}{t^2} + \frac{R_1''(t)}{t}, \\ \varphi^{(3)}(t) &= -\frac{6R_1(t)}{t^4} + \frac{6R_1'(t)}{t^3} - \frac{3R_1^{(2)}(t)}{t^2} + \frac{R_1^{(3)}(t)}{t} \quad \dots\end{aligned}$$

where

$$R_1'(t) = \int_0^t \frac{\gamma_1^{(p+1)}(s)(t-s)^{p-1}}{(p-1)!} ds, \quad R_1''(t) = \int_0^t \frac{\gamma_1^{(p+1)}(s)(t-s)^{p-2}}{(p-2)!} ds, \quad \dots$$

Since γ_1 is C^{p+3} , there exists $C_1 > 0$ only depending on γ such that for all $0 \leq v \leq p+3$, $|\frac{d^v}{dt^v} R_1(t)| \leq C_1 t^{p+1-v}$. Hence

$$\lim_{r \downarrow 0} \varphi^{(j)}(r) = 0, \quad \forall 0 \leq j \leq p+1.$$

Similarly, $\lim_{r \downarrow 0} \frac{d^v}{dt^v}(R_2(t)/t)$ exists and is uniformly bounded for all $0 \leq v \leq p+1$. Then

$$\frac{\gamma_2(t)}{\|\gamma(t)\|} = \frac{v_2 t + \dots + v_{p+2} t^{p+2} + R_2(t)/t}{\sqrt{(1 + u_2 t + \dots + u_{p+2} t^{p+2} + R_1(t)/t)^2 + (v_2 t + \dots + v_{p+2} t^{p+2} + R_2(t)/t)^2}}, \quad t > 0.$$

Notice that $\gamma_2(t)/\|\gamma(t)\|$ is of the form

$$p(t)(1 + q(t))^\alpha,$$

where $\alpha < 0$ and $p(t), q(t)$ are C^{p+1} on $(0, \infty)$ with $\lim_{r \downarrow 0} d^v/dt^v p(t)$ and $\lim_{r \downarrow 0} d^v/dt^v q(t)$ finite. Since the derivative of $p(t)(1 + q(t))^\alpha$ is

$$p'(t)(1 + q(t))^\alpha + p(t)\alpha(1 + q(t))^{\alpha-1}q'(t),$$

which is the sum of two terms of the form $p_2(t)(1 + q_2(t))^\alpha$ with p_2 and q_2 functions that are C^p with finite limits at 0. Continue this argument, we see that $\frac{\gamma_2(\cdot)}{\|\gamma(\cdot)\|}$ is C^{p+1} on $(0, \infty)$ and $\lim_{r \downarrow 0} \frac{d^v}{dt^v}(\gamma_2(t)/\|\gamma(t)\|)$ exist and are uniformly bounded for all $\mathbf{x} \in \mathcal{B}$ and for all $0 \leq v \leq p+1$.

Since \arcsin is C^{p+1} with bounded (higher order derivatives) on $[-1/2, 1/2]$, A is C^{p+1} on $(0, \delta)$ and for all $0 \leq v \leq p+1$, $\lim_{r \downarrow 0} A^{(v)}(t)$ exist and are uniformly bounded for all $\mathbf{x} \in \mathcal{B}$.

Step 3: $(p+1)$ -times continuously differentiable conditional density

By the previous two steps, $a(\mathbf{x}, r) = A \circ T(r)$ is C^{p+1} on $(0, \infty)$ with $|\lim_{r \downarrow 0} \frac{d^v}{dr^v} a(\mathbf{x}, r)| < \infty$. Similarly, we can show that $b(\mathbf{x}, r)$ is C^{p+1} in r with finite limits at $r = 0$. By the assumption that f_X is C^{p+1} and bounded below by \underline{f} , $\theta_{1,\mathbf{x}}$ is C^{p+1} with $\lim_{r \downarrow 0} \frac{d^v}{dr^v} \theta_{1,\mathbf{x}}(r)$ uniformly bounded for all $\mathbf{x} \in \mathcal{B}$ and for all $0 \leq v \leq p+1$.

This completes the proof. □

SA-6.16 Proof of Theorem 6

Let $s > 0$ be a parameter that is chosen later. Consider the following two data generating processes.

Data Generating Process \mathbb{P}_0 .

Let $\mathcal{X} = \{r(\cos \theta, \sin \theta) : 0 \leq r \leq 1, 0 \leq \theta \leq \Theta(r)\}$, where

$$\Theta(r) = \begin{cases} \pi, & 0 \leq r < s, \\ \theta_k, & s + ks^2 \leq r < s + (k+1)s^2, 0 \leq k < K, \\ \theta_K, & s + Ks^2 \leq r < 1, \end{cases}$$

with $K = \lfloor \frac{1-s}{s^2} \rfloor$ and θ_k is the unique zero of

$$\frac{\sin(\theta)}{\theta} = \frac{(k + \frac{1}{2})s^2}{s + (k + \frac{1}{2})s^2}$$

over $\theta \in [0, \pi]$, and θ_K is the unique zero of

$$\frac{\sin(\theta)}{\theta} = \frac{Ks^2 + 1 - s}{s + Ks^2 + 1}$$

over $\theta \in [0, \pi]$. Suppose \mathbf{X}_i has density f_X given by

$$f_X(r(\cos \theta, \sin \theta)) = \frac{1}{2\Theta(r)}, \quad 0 \leq r \leq 1, 0 \leq \theta \leq \Theta(r).$$

Suppose

$$\mu_0(x_1, x_2) = \frac{1}{2} + \frac{1}{100}x_1, \quad (x_1, x_2) \in \mathbb{R}^2.$$

Suppose $Y_i = \mathbf{1}(\eta_i \leq \mu(\mathbf{X}_i))$ where $(\eta_i : i : 1, \dots, n)$ are i.i.d. random variables independent of $(\mathbf{X}_i : 1, \dots, n)$. Let $\eta_0(r) = \mathbb{E}_{\mathbb{P}_0}[Y_i | \|\mathbf{X}_i - (0, 0)\| = r]$, for $r \geq 0$. In particular, $\text{bd}(\mathcal{X})$ has length $\pi + 2$. Hence, $\text{bd}(\mathcal{X})$ is a rectifiable curve.

Data Generating Process \mathbb{P}_1 .

Let $\mathcal{X} = \{r(\cos \theta, \sin \theta) : 0 \leq r \leq 1, 0 \leq \theta \leq \pi/2\}$, \mathbf{X}_i is uniformly distributed on \mathcal{X} , and

$$\mu_1(x_1, x_2) = \frac{1}{2} + \frac{1}{100}(x_1 - s), \quad (x_1, x_2) \in \mathbb{R}^2.$$

Suppose $Y_i = \mathbf{1}(\eta_i \leq \mu(\mathbf{X}_i))$ where $(\eta_i : 1, \dots, n)$ are i.i.d random variables independent to $(\mathbf{X}_i : 1, \dots, n)$. Let $\eta_1(r) = \mathbb{E}_{\mathbb{P}_1}[Y_i | \|\mathbf{X}_i - (0, 0)\| = r]$, for $r \geq 0$. In particular, $\text{bd}(\mathcal{X})$ has length $\pi/2 + 2$. Hence, $\text{bd}(\mathcal{X})$ is a rectifiable curve.

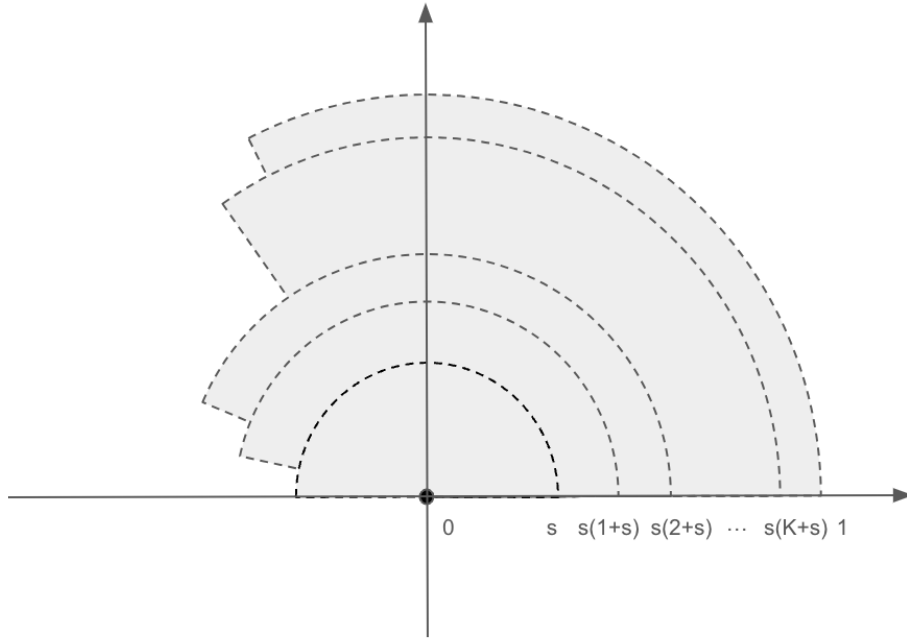


Figure SA-2: \mathcal{X} from DGP \mathbb{P}_0

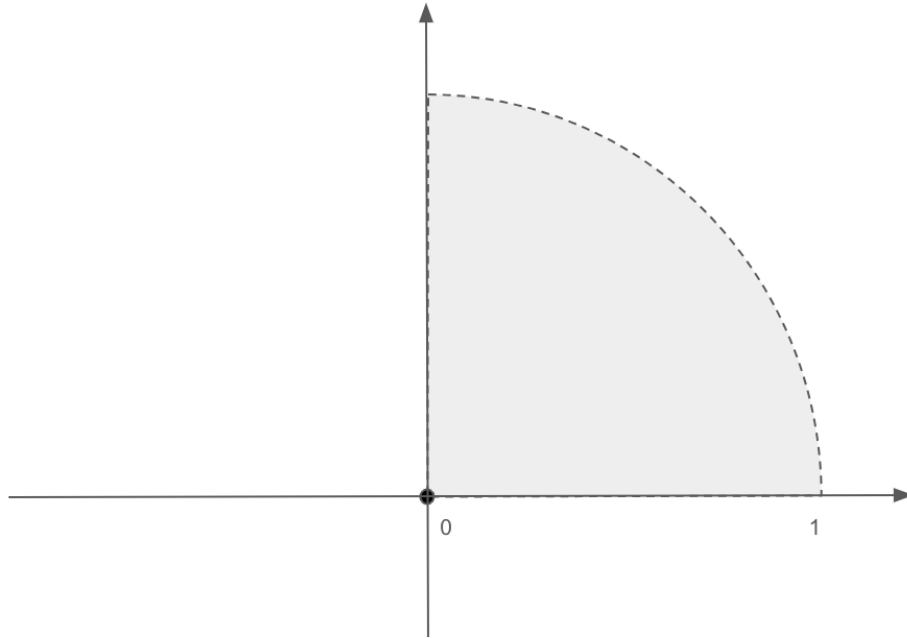


Figure SA-3: \mathcal{X} from DGP \mathbb{P}_1

Minimax Lower Bound.

First, we show under the previous two models, $\mathbb{P}_0(\|\mathbf{X}_i\| \leq r) = \mathbb{P}_1(\|\mathbf{X}_i\| \leq r)$ for all $r \geq 0$. Since in \mathbb{P}_1 , \mathbf{X}_i is uniform distributed on \mathbb{R} , we know $\mathbb{P}_1(\|\mathbf{X}_i\| \leq r) = r^2$, $0 \leq r \leq 1$.

$$\mathbb{P}_0(\|\mathbf{X}_i\| \leq r) = \int_0^r \int_0^{\Theta(s)} \frac{1}{2\Theta(s)} s d\theta ds = r^2, \quad 0 \leq r \leq 1.$$

Hence, choosing $(0, 0)$ as the point of evaluation in both \mathbb{P}_0 and \mathbb{P}_1 , we have

$$\begin{aligned} d_{\text{KL}}(\mathbb{P}_0(\|\mathbf{X}_i - (0, 0)\|, Y_i), \mathbb{P}_1(\|\mathbf{X}_i - (0, 0)\|, Y_i)) \\ &= \int_0^\infty \int_{-\infty}^\infty d\mathbb{P}_0(r, y) \log \frac{d\mathbb{P}_0(r, y)}{d\mathbb{P}_1(r, y)} \\ &= \int_0^\infty \int_{-\infty}^\infty d\mathbb{P}_0(r) d\mathbb{P}_0(y|r) \log \frac{d\mathbb{P}_0(r) d\mathbb{P}_0(y|r)}{d\mathbb{P}_1(r) d\mathbb{P}_1(y|r)} \\ &= \int_0^\infty d\mathbb{P}_0(r) \int_{-\infty}^\infty d\mathbb{P}_0(y|r) \log \frac{d\mathbb{P}_0(y|r)}{d\mathbb{P}_1(y|r)} \\ &= 2 \int_0^1 d_{\text{KL}}(\text{Bernoulli}(\eta_0(r)), \text{Bernoulli}(\eta_1(r))) r dr. \end{aligned}$$

Under \mathbb{P}_0 , \mathbf{X}_i is uniformly distributed on $\{r(\cos \theta, \sin \theta) : 0 \leq \theta \leq \Theta(r)\}$ for each $0 < r \leq 1$. Hence

$$\eta_0(r) = \frac{1}{2} + \frac{1}{100} \frac{1}{\Theta(r)} \int_0^{\Theta(r)} r \cos(u) du - \frac{s}{100} = \frac{1}{2} + \frac{1}{100} r \frac{\sin(\Theta(r))}{\Theta(r)}.$$

Thus, for $0 \leq k < K$,

$$\begin{aligned} \eta_0\left(s + \left(k + \frac{1}{2}\right)s^2\right) &= \frac{1}{2} + \frac{1}{100} \left(\left(s + \left(k + \frac{1}{2}\right)s^2\right) \frac{\sin(\Theta_k)}{\Theta_k} \right) \\ &= \frac{1}{2} + \frac{1}{100} \left(\left(s + \left(k + \frac{1}{2}\right)s^2\right) \frac{\left(k + \frac{1}{2}\right)s^2}{s + \left(k + \frac{1}{2}\right)s^2} \right) \\ &= \eta_1\left(s + \left(k + \frac{1}{2}\right)s^2\right). \end{aligned}$$

Since both η_0 and η_1 are 1-Lipschitz on all intervals $[s + ks^2, s + (k+1)s^2]$ for all $0 \leq k < K$, we know $|\eta_0(r) - \eta_1(r)| \leq 2s^2$ for all $r \in [s, 1]$. Moreover, $\eta_0(r) = \frac{1}{2}$ for all $0 \leq r \leq s$ and $\eta_1(r) = \frac{1}{2} + \frac{1}{100}(r\frac{2}{\pi} - s)$. Hence $|\eta_0(r) - \eta_1(r)| \leq s$ for all $0 \leq r \leq s$. Hence,

$$\begin{aligned} \int_0^1 d_{\text{KL}}(\text{Bernoulli}(\eta_0(r)), \text{Bernoulli}(\eta_1(r))) r dr &\leq \int_0^1 d_{\chi^2}(\text{Bernoulli}(\eta_0(r)), \text{Bernoulli}(\eta_1(r))) r dr \\ &= \int_0^1 \left(\eta_1(r) \left(\frac{\eta_0(r) - \eta_1(r)}{\eta_1(r)} \right)^2 + (1 - \eta_1(r)) \left(\frac{\eta_0(r) - \eta_1(r)}{1 - \eta_1(r)} \right)^2 \right) r dr \\ &\leq \frac{1}{\frac{1}{2} - \frac{3}{100}} \int_0^1 (\eta_0(r) - \eta_1(r))^2 r dr \\ &\leq \frac{1}{\frac{1}{2} - \frac{3}{100}} \int_0^s s^2 r dr + \frac{1}{\frac{1}{2} - \frac{3}{100}} \int_s^1 (2s^2)^2 r dr \\ &\leq \frac{5}{\frac{1}{2} - \frac{3}{100}} s^4. \end{aligned}$$

Moreover, $|\mu_0(0, 0) - \mu_1(0, 0)| = \frac{1}{100}s$. Hence, by Tsybakov [2008, Theorem 2.2 (iii)], take $\frac{5}{\frac{1}{2} - \frac{3}{100}}s_*^4 = \frac{\log 2}{n}$, and conclude that

$$\inf_{T_n \in \mathcal{T}} \sup_{\mathbb{P} \in \mathcal{P}} \sup_{\mathbf{x} \in \mathcal{B}(\mathbb{P})} \mathbb{E}_{\mathbb{P}}[|T_n(\mathbf{U}_n(\mathbf{x})) - \mu(\mathbf{x})|] \geq \frac{1}{1600}s_* \gtrsim n^{-\frac{1}{4}}.$$

This concludes the proof. \square

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