

ROBERT DYRO

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I am interested in cutting-edge computational engineering research, like distributed computing for LLMs. My current focus is on high-level computational frameworks that accelerate research iteration and model development. I am passionate about exploring new, high-impact technologies. I thrive in environments that prioritize effective teamwork and a results-oriented approach.

EDUCATION

Stanford University	Stanford, CA
PhD, Robotics, GPA 3.93	2020 - 2024
MS, Aeronautics & Astronautics Engineering, GPA 3.89	2018 - 2020
University of California, Los Angeles	Los Angeles, CA
BS, Aerospace Engineering, Minor in Philosophy, GPA 3.94, Summa Cum Laude	2014 - 2018

RELEVANT COURSEWORK

Convex Optimization ■ Reinforcement Learning ■ Meta-Learning ■ Robot Autonomy ■ Large-scale Matrix Computations
Computer Architecture ■ Optimal and Learning-based Control ■ Decision-Making under Uncertainty ■ Game Theory
Model Reduction ■ ML with Graphs ■ ML Theory ■ Trustworthy & Explainable ML ■ ML under Distribution Shift

EXPERIENCE

Software Engineer, JAX External at Google	Mountain View, CA
- JAX framework development for external researchers and industry partners	2024 - present
- Cutting-edge experience in multi-host multi-chip distributed computing with TPUs for LLMs	
- Experience with state-of-the-art distributed computation and communication optimization	
- Open-source outreach and education in newest research engineering technology for LLMs	
- Open-source custom kernel development for TPUs and GPUs for maximal accelerated hardware utilization	
Graduate Student, Autonomous Systems Laboratory (ASL) at Stanford University	Stanford, CA
Stress Testing Autonomous Vehicles via Counterfactual Editing of Trained Behavior Models	2023
- Extracting learned behavior distribution for realistic counterfactual generation via efficient and scalable Hessian sketching	
Optimization-based Online Intent Inference in Autonomous Driving	2022
- Developed a real-time, structured behavior inference method for online behavior identification in autonomous driving	
Second-Order Sensitivity Analysis for Bilevel Optimization	2021
- 2nd order sensitivity analysis of optimization, enabling much faster optimization of bilevel/inverse/sensitivity problems	
Control under Arbitrary Uncertainty using Particle Model Predictive Control	2020
- Implemented and experimentally evaluated consensus control particle MPC for control under arbitrary uncertainty	
Convex Last-layer Meta-learning for Behavior & Physics-based Modeling	2019
- Incorporated constraints into the meta-learning model for structured learning to allow adding a priori modeling knowledge	
PhD Intern, Cruise	San Francisco, CA
Machine Learning Acceleration - Architecture Optimization - Zero-Shot Neural Architecture Search	June - December 2022
Research Intern, Toyota Research Institute	Los Altos, CA
Intelligent Driver Behavior Modeling using Human Interpretable Rules	June - September 2020
- Embedded human logic within path planning via Signal Temporal Logic (STL) to capture human-interpretable specifications	
Student Researcher, TANMS at UCLA	Los Angeles, CA
Multi-Physics Dynamics Simulation in Computational Multiferroic Systems	2017

TECHNICAL EXPERIENCE

Projects:

- *torch2jax* - zero-overhead PyTorch computation wrapping for JAX computation graph under JIT and autodifferentiation
- Automatic short answer grading (NLP) via meta-learning – BERT and T5 NLP models
- Custom quadratic program (QP) solver in CUDA
- Fair and robust machine learning via local explainability enforcement exploiting the LIME technique
- Experimental dynamic graph autodifferentiation library for full sparse 1st & 2nd order matrix algebra differentiation
- Optimal driving and intersection collision avoidance via Monte Carlo Tree Search for partially observable planning

Software Skills:

Python, C++, C, Julia, Matlab ■ JAX, PyTorch, TF, ROS ■ embedded systems, Linux, HPC, Slurm, CUDA, Google Cloud

MISC

Philosophy Minor, UCLA ■ LA Marathon ■ Amateur Radio License ■ PADI Assistant Instructor