

GVN-Hoist: Hoisting Computations from Branches

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ABSTRACT

Code-hoisting identifies identical computations across the program with the help of a Global Value Numbering (GVN) analysis, identifies a hoisting position that dominates all the identical computations and in which all operands are available, duplicates one of the expressions in the hoisting position, and removes all the computations now redundant in their original position.

Code-hoisting is often confused with CSE (Common Subexpression Elimination) although code-hoisting is not bound to find redundancies within a single basic block. Code-hoisting could also be confused with Partial Redundancy Elimination (PRE) or with Global Common Subexpression Elimination (GCSE) although the main goal of code-hoisting is not to remove redundancies: code-hoisting effectively exposes redundancies and enables other passes like LICM to remove more redundancies. The main goal of code-hoisting is to reduce code size with the added benefit of exposing more instruction level parallelism and reduced register pressure.

1. INTRODUCTION

Compiler techniques to remove redundant computations are composed of an analysis phase that detects identical computations in the program and a transformation phase that reduces the number of run-time computations. Classical scalar optimizations like CSE [3] work very well on single basic blocks. When it comes to detect redundancies across basic blocks these techniques fall short: more complex passes like GCSE and PRE have been designed to handle these cases based on dataflow analysis [14]. At first these techniques were described in the classical data-flow analysis framework, and later the use of the SSA representation lowered the cost in terms of compilation time [4, 5, 13] and brought these techniques in the main stream: nowadays SSA based PRE is available in every industrial compiler.

This paper describes code-hoisting, a technique that uses the information computed for PRE to detect identical computations and has a transformation phase whose goal differs

from PRE: it removes identical computations from different branches of execution. These identical computations in different branches of execution are not redundant computations at run-time and the number of run-time computations is not reduced. Code-hoisting is not a redundancy elimination pass, and thus it has different cost function and heuristics than PRE or CSE. Code-hoisting is also different from global code scheduling [3, 6] in the sense that code-hoisting will only hoist computations when there are identical computations sharing a common dominator. The goals of code hoisting are:

- to reduce the code size of the program;
- to improve function inlining heuristics: functions become cheaper to inline by reducing their code size;
- to expose more instruction level parallelism: by hoisting identical computations to be executed earlier, instruction schedulers can move heavy computations earlier in order to avoid pipeline bubbles;
- to help out-of-order processors with speculative execution of branches: by hoisting expressions out of branches, code hoisting can effectively reduce the amount of code to be speculatively executed and can reduce the critical path;
- to reduce register pressure: by moving computations closer to the definitions of their operands;
- to improve passes that do not work well with branches:
 - to improve loop vectorization by reducing a loop with control flow to a loop with a single BB, should all the instructions in a conditional get hoisted and sunk;
 - to enable more loop invariant code motion (LICM): as LICM does not reason about instructions in the context of loops with conditional branches, code-hoisting is needed to move instructions out of conditional expressions and expose them to LICM.

The main contributions of this paper are:

- a new algorithm to hoist computations from branches,
- cost models to reduce live-range and reduce spills,
- performance evaluation of the implementation in LLVM,
- comparison against other algorithms for code hoisting.

2. RELATED WORK

Rosen et al. explain moving computations successors to remove redundancies [17]. Their algorithm iterates on computations of same rank and move the code with identical computations from the sibling branch. This is a pessimistic approach (TODO: is it?). Also there is no notion of partially hoisting the computations so their approach may result in missing many hoisting opportunities.

A lot of bug reports in GCC and LLVM bugzillas [1, 2], no papers on this topic yet.

Dhamdhere [10], Muchnick [15] mention code hoisting in a data flow framework.

3. CODE HOISTING

The algorithm for code hoisting uses several common representations of the program that we shortly describe below:

- Control Flow Graph (CFG) and the Dominance (DOM) and Post-Dominance (PDOM) relations [3];
- Single Entry Single Exit (SESE) [12] and Single Entry Multiple Exit (SEME) regions;
- Static Single Assignment (SSA) [9];
- Global Value Numbering (GVN) [17, 6]: to identify similar computations compilers use GVN. Each expression is given a unique number and the expressions that the compiler can prove identical are given the same number;
- Memory SSA [16]: memory operations that the compiler is able to prove in dependence are linked through use-def chains.

The code-hoisting pass can be divided into the following steps that we will describe in the rest of this section:

- find candidates: instructions computing same values,
- compute a point in the program where it is both legal and profitable to move the code,
- transform the code.

3.1 Finding candidates to hoist

The first step is to find a set of instructions that perform identical computations: this is performed by a linear scan of all instructions of the program and classifying all instructions by their value given by GVN.

The current implementation of GVN in LLVM has some limitations when it comes to loads and stores so we compute the GVN of loads and stores separately. Our short-time solution to value number loads is to hash the address from where the value is to be loaded. For stores, we value number the address as well as the value to be stored at that address.

Another limitation of the current GVN implementation in LLVM is that the instructions dependent on the loads will not get numbered correctly, and so after hoisting all candidates we need to rerun the GVN analysis in order to discover new candidates now available after having hoisted load instructions. This limitation should be addressed in a new implementation of the GVN based on MemorySSA, that would better account for equivalent loads and their dependent instructions.

The process of computing GVN can be on-demand (as we come across an instruction) or, precomputed (computing GVN of all the instructions beforehand). Which process to choose is determined by the scope of code-hoisting we want to perform. In a pessimistic approach, as described in Section 4.2, we want to hoist a limited set of instructions from the sibling branches as we iterate the DFS tree bottom-up, it is sufficient to compute GVN values on-demand. Whereas, in the optimistic approach, as described in Section 4.1, we want to hoist as many instructions as possible, and it would require GVN values to be precomputed.

Once the instructions have been classified in equivalence classes, we compute for each group of equivalent instructions a point in the program that is both legal and profitable for the instructions to be moved to.

3.2 Legality check

Since the equality of candidates is purely based on the value they compute, we need to establish if hoisting them to a common dominator would be feasible. Once a common dominator is found, we check whether all the use-operands of the set of instructions are available at that position. In some cases when the operands are not available, it is possible to re-instantiate (re-materialize) the use-operands, thus passing the legality check.

Subsequently, it is checked that the side-effects of the computations does not intersect with any side-effects between the instructions to be hoisted and their hoisting point. For memory operations like loads, stores, calls etc., it is also required to check that all the paths from the hoisting point to the end of the function should execute the exact instruction, in order to guarantee correctness.

Moreover, hoisting of memory operations is tricky on paths which have indirect branch targets e.g., landing pad, case statements, goto labels etc., because it becomes difficult to prove that all the paths from hoisting point to the end of the function would execute the instruction. In our current implementation we discard hoisting through such paths.

In the optimistic approach, described in Section 4.1, it is possible that a common hoisting point of all the instructions is either too far away, or not legally possible. In these cases, it is still possible to ‘partially’ hoist a subset of instructions by splitting the set of candidates and finding a closer hoisting point for each subset. For more details see Section 4.1.1.

3.2.1 Legality of hoisting scalars

Scalars are the easiest to hoist because we do not have to analyze them for aliasing memory references. As long as all the operands are available (or can be made available by re-materialization), the scalar computation can be hoisted.

3.2.2 Legality of hoisting loads

The availability of operand to the load (an address) is checked at the hoisting point. If that is not available we try to re-materialize the address if possible. Along the path, from current position of the load instruction backwards on the control flow to the hoisting point, we check whether there are writes to memory that may alias with the load, in which case we discard the candidate.

3.2.3 Legality of hoisting stores

For stores, we check the dependency requirements similar to the hoisting of loads. We check that the operands of the store instruction are available at the hoisting point, that there are no aliasing loads or store along the path from the current position to the hoisting point.

3.2.4 Legality of hoisting calls

Call instructions can be divided into three categories: those calls equivalent to purely scalar computations, calls reading from memory, and most of the time, without further information, calls have to be classified as writing to memory, that is the most restrictive form. Each category of call instructions will be handled as described for scalar, load, and store instructions.

3.3 Profitability check

After the legality checks have passed, we check for profitability of hoisting. That takes into account the impact

code-hoisting would have on various parameters that affect runtime performance e.g., impact on live-range, gain in the code size. We have established a set of cost models described in Section 5 for each parameter and tuned them for performance against representative benchmarks.

3.3.1 Profitability of hoisting scalars

Since scalars are the majority of instructions which are hoisted, we pay special attention in case of hoisting scalars too far, as that may increase register pressure and result in spills. For example hoisting a scalar past a call, as described in Section 5.2. In our current implementation we hoist scalars past a call only when optimizing for code-size (-Os). Ideally, a later stage of live-range splitting pass should split the live-ranges for optimal performance, however, that is not the case with llvm as we have found regressions when scalars are hoisted too far, as in Section 5. Another way to mitigate this problem is to re-instantiate (re-materialize) the computation after a call (may be as a different optimization pass).

3.3.2 Profitability of hoisting loads

A load instruction introduces a register where the value loaded will be kept, the register pressure increases by one (unless the operand to load becomes dead at the load). On the other hand, loading a value early will reduce the stall during execution should the value is not in the cache. We generally prefer to hoist load except the hoisting point is too far (this distance is computed by looking at the experimental results of representative benchmarks, see Section 6).

3.3.3 Profitability of hoisting stores

Since stores do not increase the live-range of any registers, and in some cases it ends the liveness of registers, we hoist all the stores.

3.3.4 Profitability of hoisting calls

Currently we hoist all the calls that are suitable candidates for hoisting.

3.4 Code generation

Once all the legality and profitability checks are satisfied for a set of identical instructions, they are suitable candidates for hoisting. A copy of the computation is inserted at the hoisting point along with any instructions which needed to be re-materialized. Thereafter, all the computations made redundant by the new copy are removed, and the SSA form is restored by updating the intermediate representation (IR) to reflect the changes.

After one iteration of algorithm runs through the entire function, it creates more opportunities for *higher ranked* computations [17]. Currently, this is a limitation of the GVN analysis pass, and so we rerun the code-hoisting algorithm until there are no more instructions left to be hoisted. Obviously, this is not the most optimal approach and can be improved by ranking the computations [17], or by improving the GVN analysis to correctly number loads and dependent instructions.

Finally after the transform is done, we verify a set of post-conditions to establish that program invariants are maintained: e.g., consistency of use-defs, and SSA semantics.

3.5 Illustrative Example

Code hoisting can also reduce the critical path length of execution in out of order machines. As more instructions are available at the hoisting point, the hardware has more instructions to reorder. Following example illustrates how hoisting can improve performance by exposing more ILP.

```
float foo(float d, float min, float max, float a)
{
    float tmin, tmax, inv;

    inv = 1.0f / d;
    if (inv >= 0) {
        tmin = (min - a) * inv;
        tmax = (max - a) * inv;
    } else {
        tmin = (max - a) * inv;
        tmax = (min - a) * inv;
    }
    return tmax + tmin;
}
```

In this program the computations of tmax and tmin are identical to the computations of tmin and tmax of sibling branch respectively. Both tmax and tmin depends on inv which depends on a division operation which is generally more expensive than the addition, subtraction and multiplication operations. The total latency of computation across each branch is: $O(div) + 2(O(sub) + O(mul))$ Or, for out of order processors with two add units and two multiply units: $O(div) + O(sub) + O(mul)$

Now if the computation of tmax and tmin are hoisted outside the conditionals, the C code version would look like this:

```
float foo(float d, float min, float max, float a)
{
    float tmin, tmax, tmin1, tmax1, inv;

    tmin1 = (min - a);
    tmax1 = (max - a);

    inv = 1.0f / d;
    tmin1 = tmin1 * inv;
    tmax1 = tmax1 * inv;

    if (inv >= 0) {
        tmin = tmin1;
        tmax = tmax1;
    } else {
        tmin = tmax1;
        tmax = tmin1;
    }

    return tmax + tmin;
}
```

In this code the two subtractions and the division operations can be executed in parallel because there are no dependencies among them. So the total number of cycles will be $max(O(div), O(sub)) + O(mul) = O(div) + O(mul)$; since $O(div)$ is usually much greater than $O(sub)$ [?, ?]

Of course, a partial redundancy elimination pass could just remove the entire if-block because final operation is an addition (asociative under fast math).

```
float foo(float d, float min, float max, float a)
{
    float tmin1, tmax1, inv;

    tmin1 = (min - a);
    tmax1 = (max - a);

    inv = 1.0f / d;
    tmin1 = tmin1 * inv;
    tmax1 = tmax1 * inv;

    return tmax1 + tmin1;
}
```

GCC: 23286 has interesting test cases.

4. CODE HOISTING POLICIES

The amount of hoisting depends on whether we collect GVN of instructions before finding candidates (optimistic) or, on-demand (pessimistic). It also depends on the generality of the GVN algorithm, however, that analysis is beyond the scope of this paper.

4.1 Hoisting bottom up with optimistic approach

In this approach, the goal is to maximise the total number of hoistings in the entire function. This algorithm is very useful when optimizing for code-size. We collect the GVN of all the instructions in the function and iterate on the list of instructions having identical GVNs. After that we find the common dominator dominating all such identical computations and perform legality checks, as described in Section 3.2. Often times it is not possible to hoist all the instructions to one common dominator, due to legality constraints e.g., intersecting side-effects or, profitability constraints e.g., hoisting point too far. In those cases, this algorithm would partition the list of identical instructions into subsets which can be partially hoisted to their respective common dominators. The partition algorithm is described as follows:

4.1.1 Partition the list of hoisting candidates to maximize hoisting

In order to hoist a subset of identical instructions, we partition the list of all candidates in a way to maximise the total number of hoistings. By sorting the list of all the candidates in the increasing order of their depth first search discovery time stamp [8] (DFSIn numbers), we make sure that candidates closer in the list have their common dominator nearby in cases when there are no fully redundant instructions. Essentially if,

```
// B1 != B2 != B3
BasicBlock B1, B2, B3
DFSIn(B1) = depth first discovery time stamp
DFSIn(B1,B2) = |DFSIn(B1) - DFSIn(B2)|
DFSIn(B1,B3) = |DFSIn(B1) - DFSIn(B3)|
```

```
Depth(B1) = depth of tree from the root node.
// When B1 dominates B2
BBDist(B1, B2) = |Depth(B1) - Depth(B2)|
```

```
NCD(B1, B2) = nearest common dominator of B1 and B2
BBDist(B1,B2) = BBDist(B1, NCD(B1, B2))
BBDist(B1,B3) = BBDist(B1, NCD(B1, B3))
```

Then,

```
DFSIn(B1,B2) < DFSIn(B1,B3) implies
BBDist(B1,B2) <= BBDist(B1,B3)
```

Same property would hold for instructions I1, I2, I3 provided they are not fully redundant i.e., none of the basic blocks containing I1, I2 and I3 respectively dominate the other:

```
Instruction I1, I2, I3
// I1, I2, I3 are not fully redundant
// B1, B2, B3 contains I1, I2, I3 respectively
DFSIn(I1) = DFSIn(B1)
BBDist(I1, I2) = BBDist(B1, B2)
DFSIn(I1) = DFSIn(B1)
DFSIn(I1,I3) = DFSIn(B1, B3)
NCD(I1, I2) = NCD(B1, B2)
```

Then,

```
DFSIn(I1,I2) < DFSIn(I1,I3) implies
BBDist(I1,I2) <= BBDist(I1,I3)
```

It says that if I1 is closer to I2 than I3 in the list of candidates sorted by DFSIn numbers, then the nearest common dominator of I1 and I2 will be closer (in terms of basic block distance) to I1, than nearest common dominator of I1 and I3.

In the presence of fully redundant computations in the list of hoistable candidates this equation may not hold. For example, if there is another instruction I4 which is dominated by I1, but I4 is present in a basic block which is farther than DFSIn(I1, I2) i.e., $DFSIn(I1, I2) < DFSIn(I1, I4)$; however, $BBDist(I1, I4) = 0 < BBDist(I1, I2) \geq 1$.

So by sorting candidates w.r.t. their DFSIn numbers:

1. would make fewer checks for legality and profitability.
2. hoisting point will be closer, so the intersection of live-range of the instruction with other instructions will be minimal.

In our current implementation we keep as many candidates in one set as possible (greedy approach). We split the list at a point where the legality checks fail to hoist subset of candidates which are legal to hoist and then start finding new hoisting point for the remaining ones. So there are two limitations of the current implementation of the partition algorithm: First, sorting by DFSIn numbers does not give the desired order when there are fully redundant instructions; Second, it lacks cost model for partitioning in order to preserve/improve performance, see Section 7.

4.2 Hoisting bottom up with pessimistic approach

In the pessimistic approach, the basic blocks are traversed in the inverse depth-first order, computing the GVN of instructions as they come by. The GVN of sibling branches are compared for equality. Once such a candidate is found, it is hoisted in the common dominator. All the leaf nodes are visited before the non-leaf nodes (bottom-up) because instructions are hoisted upwards.

The pessimistic algorithm is fast, results in fewer spills but hoists very less instructions. We have implemented optimistic approach because it is more general and can be tuned down to closely mimic pessimistic approach by changing a flag.

4.3 Time complexity of algorithm

The complexity of code hoisting is linear in number of instructions that could be hoisted in the program, matching the complexity of PRE on SSA form. The analysis phase is based on the Global Value Numbering (GVN), the same analysis used for PRE, followed by the computation of a partition of identical expressions to be hoisted in a same location to guarantee safety properties and program performance, and followed by a simple code generation that adds the identified instruction in the hoisting point and removes all the now redundant expressions.

5. COST MODELS

Similar to any compiler optimization pass, there are several cost functions that are deployed to tune for optimal combination of performance and code-size. Since this is mostly a code-size optimization pass, the goal is to not regress in performance across popular benchmarks at the same time reduce code size as much as possible. Following are the cost models which are implemented:

5.1 Reduce register pressure

Following example explains how code hoisting can actually reduce the register pressure. Consider the following example where the labels prefixed with 'P' represent the position of instruction in a basic block (names prefixed with 'B').

```
B0: P0: b = 1
    goto B1

B1: P1: c = 2
    goto B2

B2: P2: if c is true then goto B3 else goto B4

B3: P3: a0 = b + c
    goto B5

B4: P4: a1 = b + c
    goto B5

B5: P5: d = phi {a0(B3), a1(B4)}
```

If we measure $D(P_x, P_y)$ as total instruction count in the path from the position of P_x to P_y

```
live-range(a0) = D(P0,P3) + D(P1,P3) + D(P3,P5)
                = 6 + 4 + 2 = 12
live-range(a1) = D(P0,P4) + D(P1,P4) + D(P4,P5)
                = 6 + 4 + 2 = 12
```

```
old-live-range = max(live-range(a0), live-range(a1))
                = 12
```

After hoisting a0 and a1 are removed and a copy of a0 as a01 is placed in B2 just before P2.

```
live-range(a01) = D(P0,P2-1) + D(P1,P2-1) + D(P2-1,P5)
                = 4 + 3 + 3 = 10
new-live-range = live-range(a01)
```

If the new live-range is less than the old one it will be a good candidate for hoisting. The live ranges can remain same as well if there is only one operand on the right hand

side e.g., an assignment operation or, one of the operands is not a register. That means hoisting upwards will decrease the live-range of its use but increase the live-range of its definition.

In a special case where the instruction to be hoisted has the last use of its operands then the code hoisting will always reduce the register pressure if it has two register operands because the gain in live-range will be in the ratio of 2:1. Based on the above formulae we can also deduce that, as long as there is one register operand in the right hand side with its last use, code hoisting will either decrease or preserve the register pressure.

5.2 In the presence of calls

Hoisting scalars across calls is tricky because it can increase the number of spills. During the frame lowering of calls, the argument registers, in general, the caller saved registers are saved because they might be modified by the callee and after the call they are restored [?]. So before the call, the register pressure is high because the number of available registers are reduced by the number of caller saved registers. In that situation if a computation is hoisted across the call, that would increase the total number of registers required by one, thus contributing to the register pressure. However, in the special case discussed in Section 5.1, it will be okay to hoist because the register pressure would not decrease.

Hoisting loads/stores across calls also require precise analysis of all the memory addresses accessed by the call. Our implementation being an intraprocedural pass, the analysis is very conservative. In the presence of pure calls, loads can be hoisted but stores can't. Also, if the call throws exceptions, or it it may not return, memory references cannot be hoisted.

5.3 Hoisting too far away

If there are several instructions in between the hoisting point and the instruction to be hoisted, the instruction to be hoisted crosses several instructions while hoisting, that means we are adding one register to all the live-ranges spanning the instructions. That could result in spills. In the current implementation we choose to hoist if the number of instructions crossed is below a threshold. Ideally, it should be okay to hoist all the instructions and a later a live-range-splitting [7] pass should make the right decision of rematerializing the instruction should it be beneficial to do so. But the current live-range splitting pass of llvm is not making the optimal decision and we have found spills if the threshold is exceeded. The threshold was computed as a result of tuning the llvm testsuite [?] and spec benchmark [11].

Also, hoisting a load increases the register pressure by one across all the instructions which the load would cross. That could result in spills later in the register allocation.

However, in the special case discussed in Section 5.1, it will be okay to hoist because the register pressure would not decrease.

6. EXPERIMENTAL EVALUATION

We ran llvm-testsuite (trunk:d87471f8) with the patch (trunk:86940146) and the results are listed in Table 1. The table lists the number of scalars, loads, stores and calls hoisted as well as removed. For each category, the number of instructions removed is greater or equal to the number of instructions hoisted because each hoisting is performed only

when at least one identical computation is found.

Loads are hoisted the most followed by scalars, stores and calls in decreasing order. This was the common trend in all our experiments. One reason why loads are hoisted the most is the early execution of this pass (before mem2reg) in the llvm pass pipeline. Passes like mem2reg, instcombine might actually remove those loads so this order may change should this pass be scheduled later.

Metric	Number
Scalars hoisted	6791
Scalars removed	9696
Loads hoisted	14802
Loads removed	20719
Stores hoisted	15
Stores removed	15
Calls hoisted	8
Calls removed	8
Total Instructions hoisted	21616
Total Instructions removed	30438

Table 1: Code hoisting metrics on llvm-testsuite

Metric	Before	After
Call sites deleted, not inlined	1988	1988
Functions deleted (all callers found)	38250	38255
Functions inlined	154986	154985
Allocas merged together	212	212
Caller-callers analyzed	193042	193092
Call sites analyzed	414336	414381
Rematerialized defs for spilling	18321	18326
Rematerialized defs for splitting	5719	5842
Spill slots allocated	42912	42970
Spilled live ranges	61330	61362
Spills inserted	50724	50784

Table 2: Static metrics before and after code-hoisting on llvm-testsuite

Other static metrics are listed in Table 2. Here we can see that except for rematerializing defs for splitting, which has an overhead of 2%, all other parameters have less than 1% overhead. This is to explain why the performance does not go down with our implementation (and cost-model) of code hoisting pass.

Code-size metric (.text)	Number
Total benchmarks	497
Total gained in size	39
Total decrease in size	58
Median decrease in size	2.9%
Median increase in size	2.4%

Table 3: Code size metrics on llvm-testsuite

While benchmarking llvm-testsuite we see both increase as well as decrease in the codesizes of the final binaries. Since the pass runs early, it has affect on many optimizations which rely on number of instructions, length of the use-

def chain etc metrics which are affected by code-hoisting. Specially the inliner where the total inline cost (in llvm) is heavily dependent on the total count of instructions in the caller and callee. Various code-size metrics are shown in Table 3. All but one benchmark varied between -5.32% and 5.43%. In one benchmark FreeBench/distray/distray.test, the codesize increased by 35.38%. In this benchmark 3 more (15 as compared to 12) functions got inlined and because of that 10 more (81 vs. 71) vector instructions got generated, 3 calls got hoisted/sunk as (compared to 0), one loop got unswitched (compared to 0), 6 high latency machine instructions got hoisted out of loop, 59 (compared to 30) machine instructions got hoisted out of loop, 70 (compared to 39) machine instructions were sunk.

7. CONCLUSION AND FUTURE WORK

We have presented the GVN based code hoisting algorithm. The primary goal is to reduce the code size but it benefits performance in some cases as well. To preserve performance and not hoist too much we have implemented several cost models described in Section 5. Since those cost models depend on a set of thresholds, it requires tuning, as such, we used representative benchmarks to tune them.

Currently, we rerun the algorithm until there are no more instructions left to be hoisted. This is not the most optimal approach and results in expensive analyses to be recomputed. This can be improved by ranking the computations [17].

With the implementation of code-hoisting in llvm, the passes which rely on the code-size/instruction-count to make optimization decisions needs to be revisited. The first candidate would be the inliner. We have seen different inlining decisions in Table 3, before and after code-hoisting was enabled. Since inliner has several magic numbers tuned for the previous pass layout, it would need some improvement.

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