

Computational Photography

- * Study the basics of computation and its impact on the entire workflow of photography, from capturing, manipulating and collaborating on, and sharing photographs.



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Cameras, Optics, and Sensors

* Cameras: Pinhole Camera
and Optics



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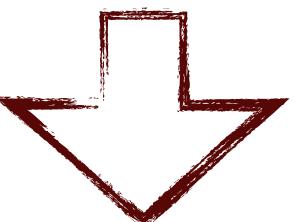


Lesson Objectives

1. Rays to pixels
2. A camera without optics
3. Lens in the camera system
4. The Lens Equation

Recall: Context of Computational Photography

Rays



3D Scene

Illumination

Optics

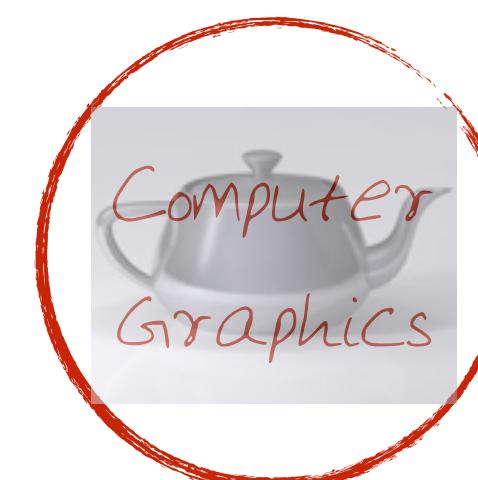
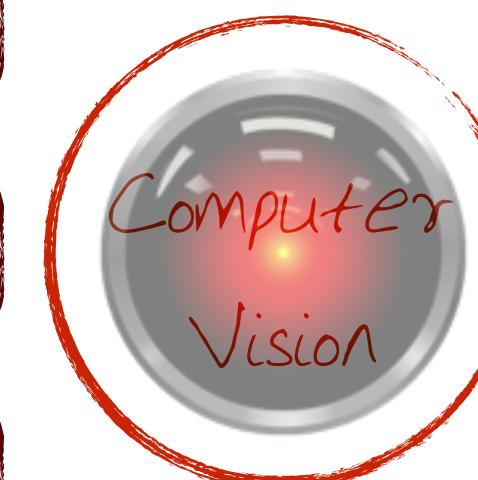
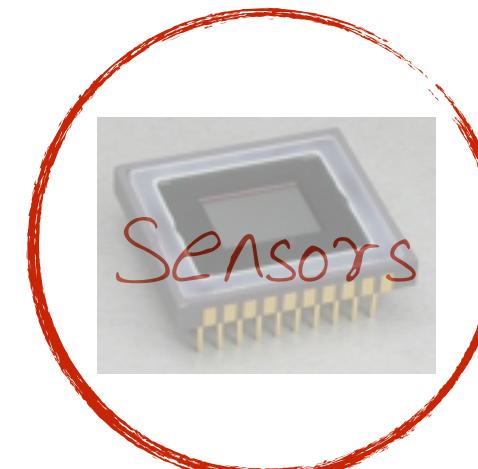
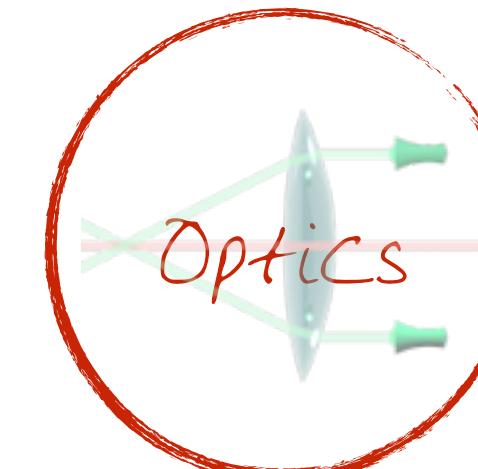
Sensor

Processing

Display

User

Pixels



Pixels vs. Rays



3D Scene

Illumination

Optics

Sensor

Processing

Display

User



- * Scene via a 2D array of pixels
- * Rays are fundamental primitives
- * Illumination (Light Rays) follows a path from the source to the SCENE
- * Computation can control the parameters of the optics, sensor and illumination

Evolution of the Camera



300 BC



1839



1907



1948



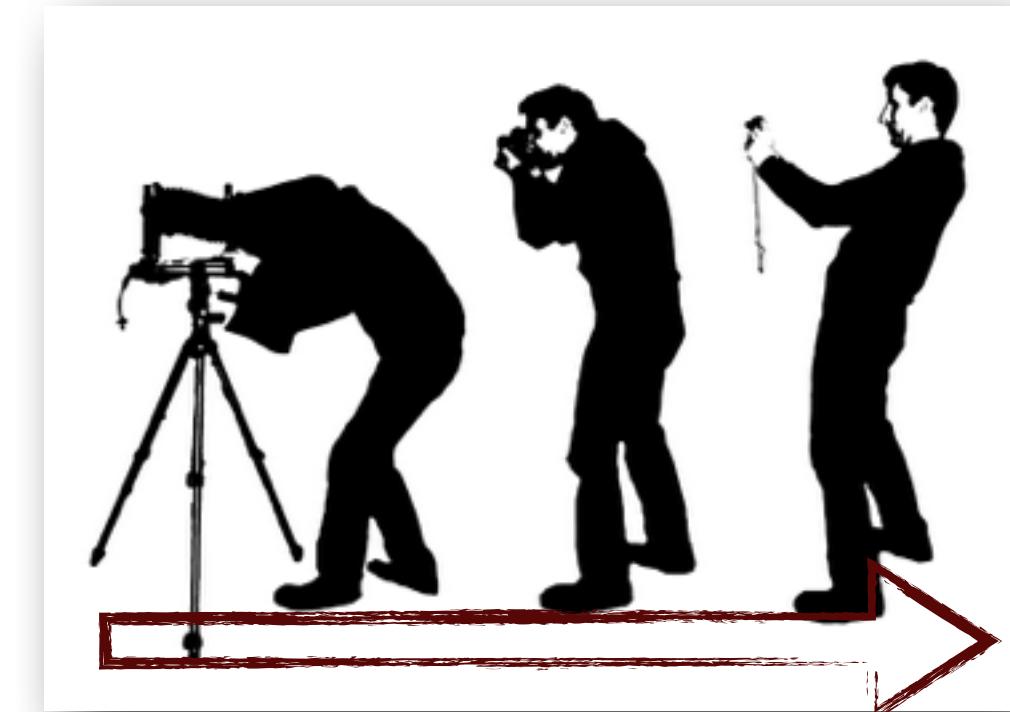
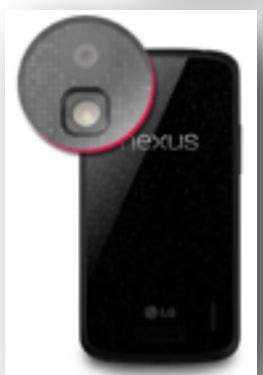
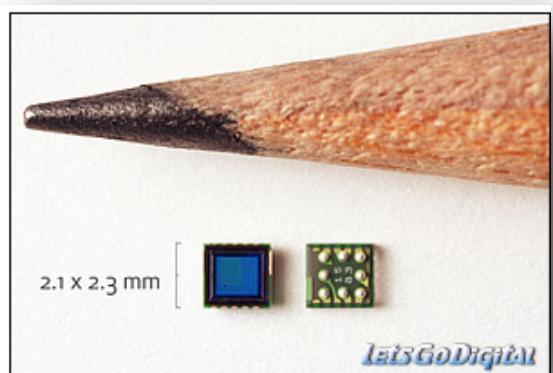
1986



1991

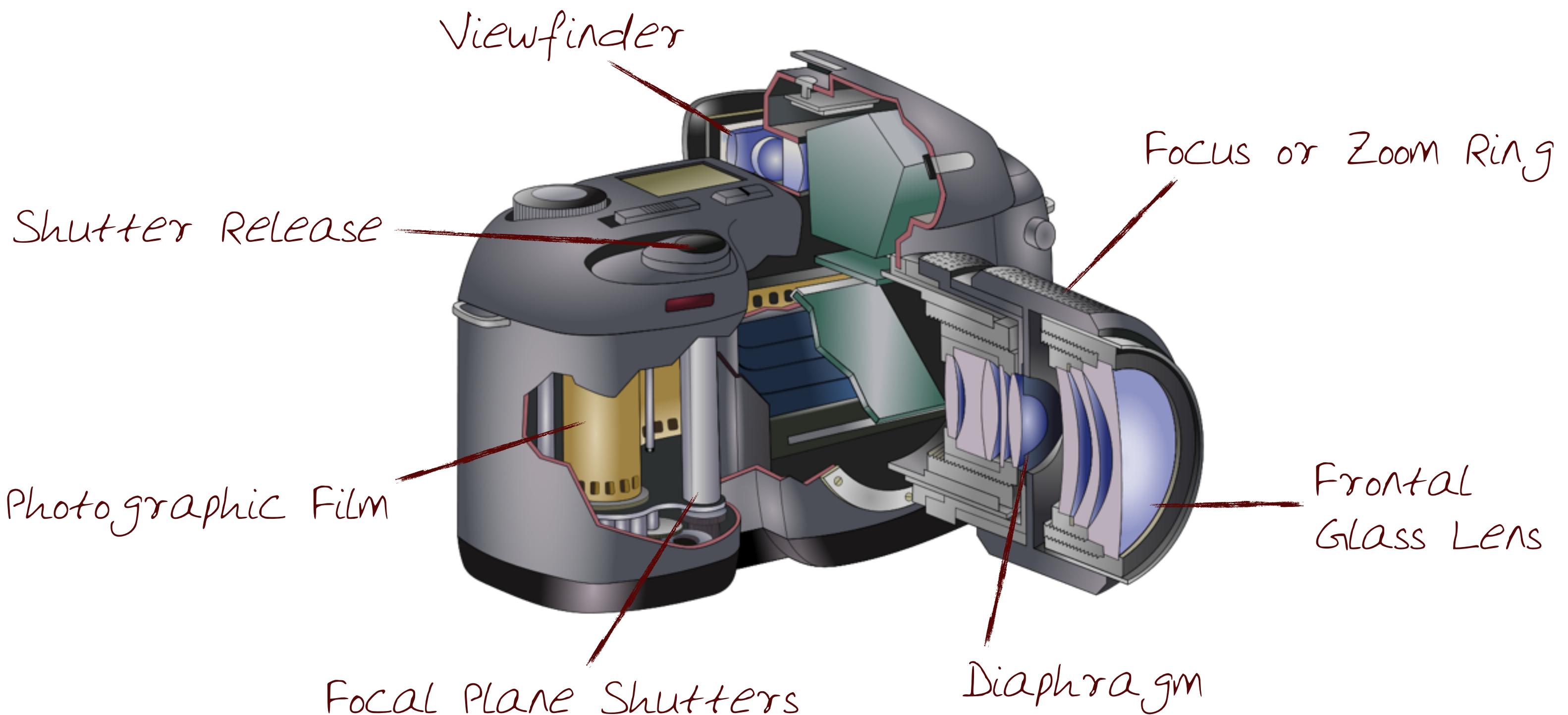


2000



Formal to Casual

Single-Lens Reflex Camera



When you take a picture

3D Scene

Illumination

Optics

Sensor

Processing

Display

User



Geometry
(Perspective)

Light
Scattering

When you take a picture using

3D SCENE

ILLUMINATION

OPTICS

SENSOR

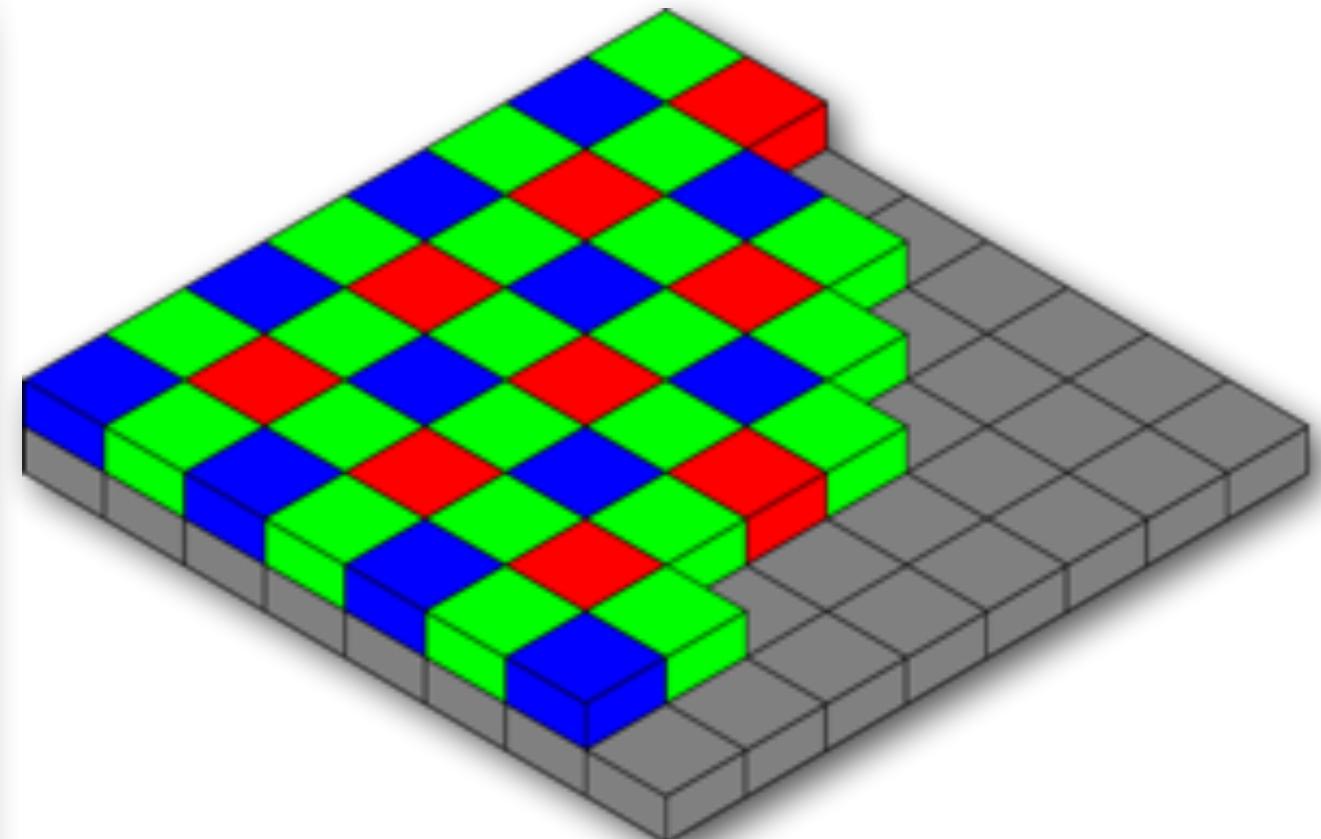
PROCESSING

DISPLAY

USER

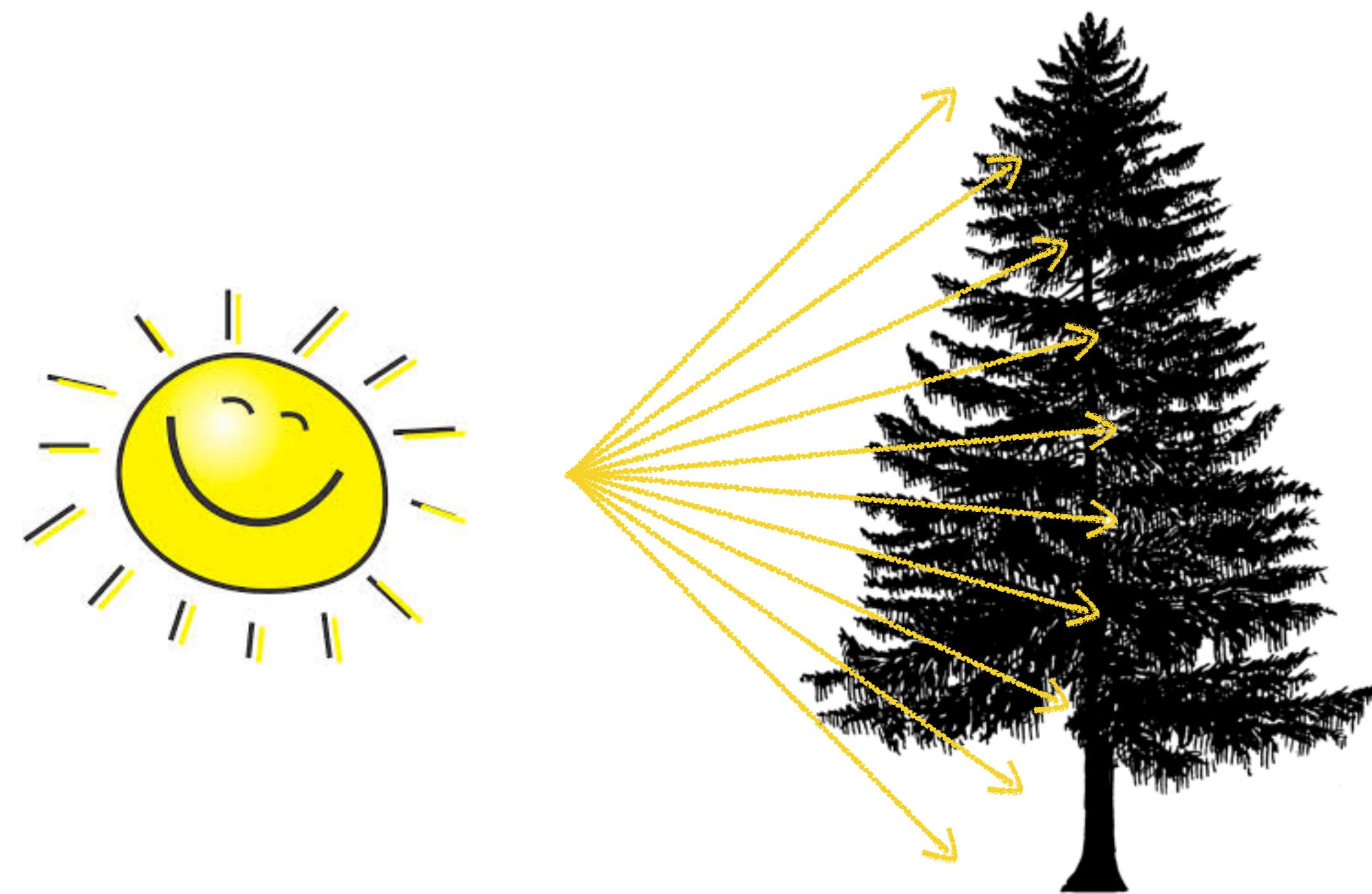


OPTICS / LENS

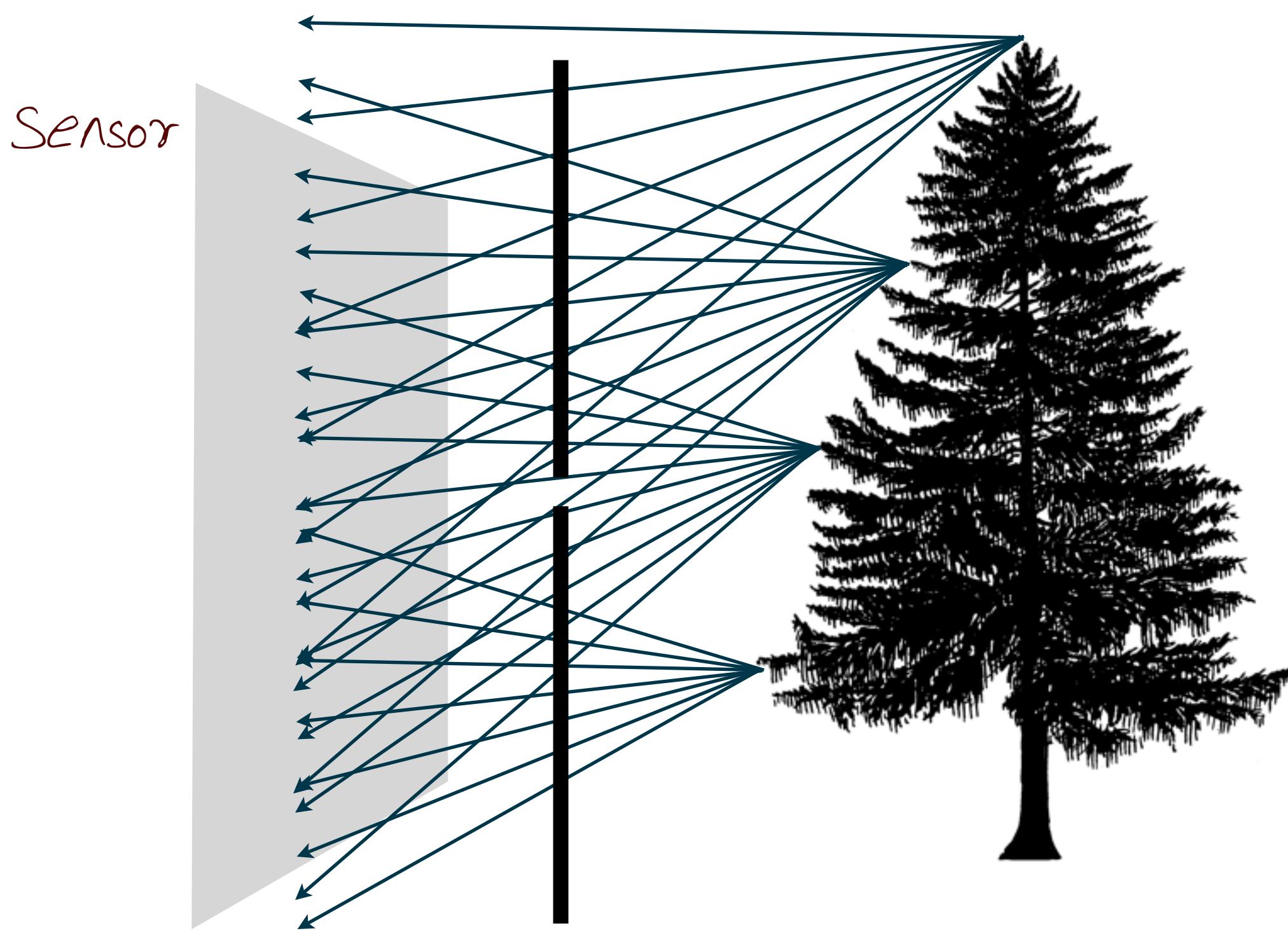


Sensor / Color
Filter

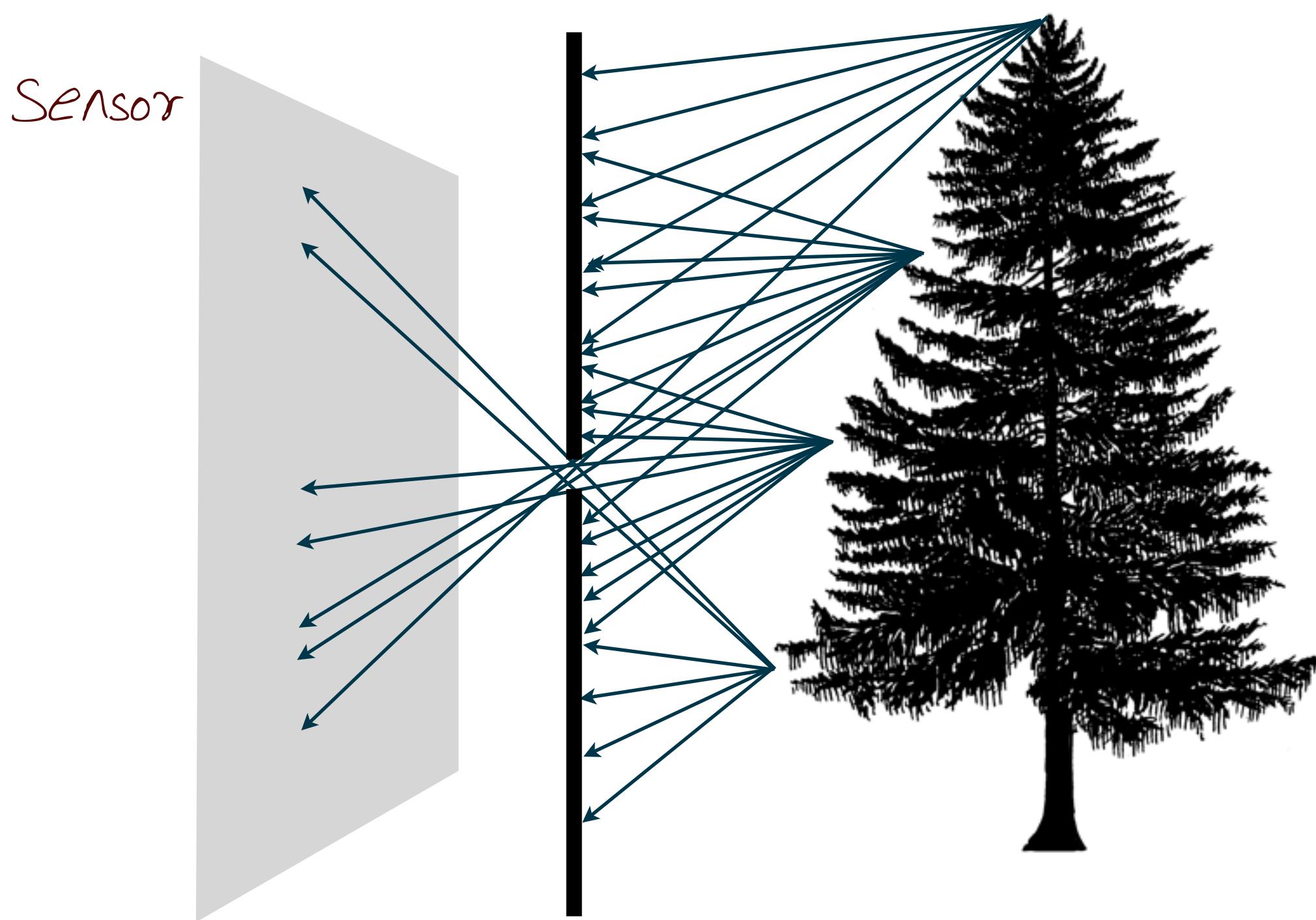
Cameras, without Optics



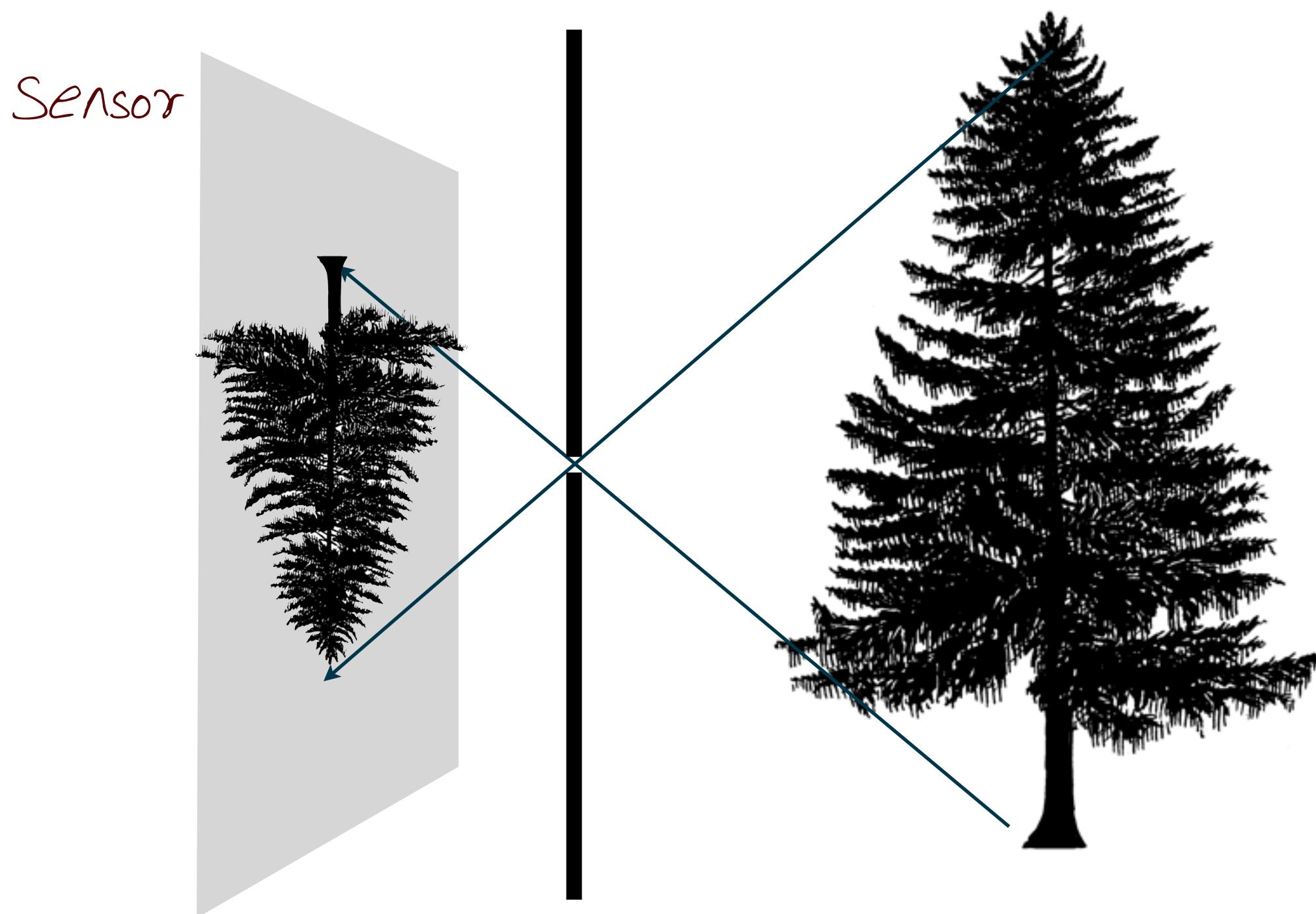
Cameras, without Optics



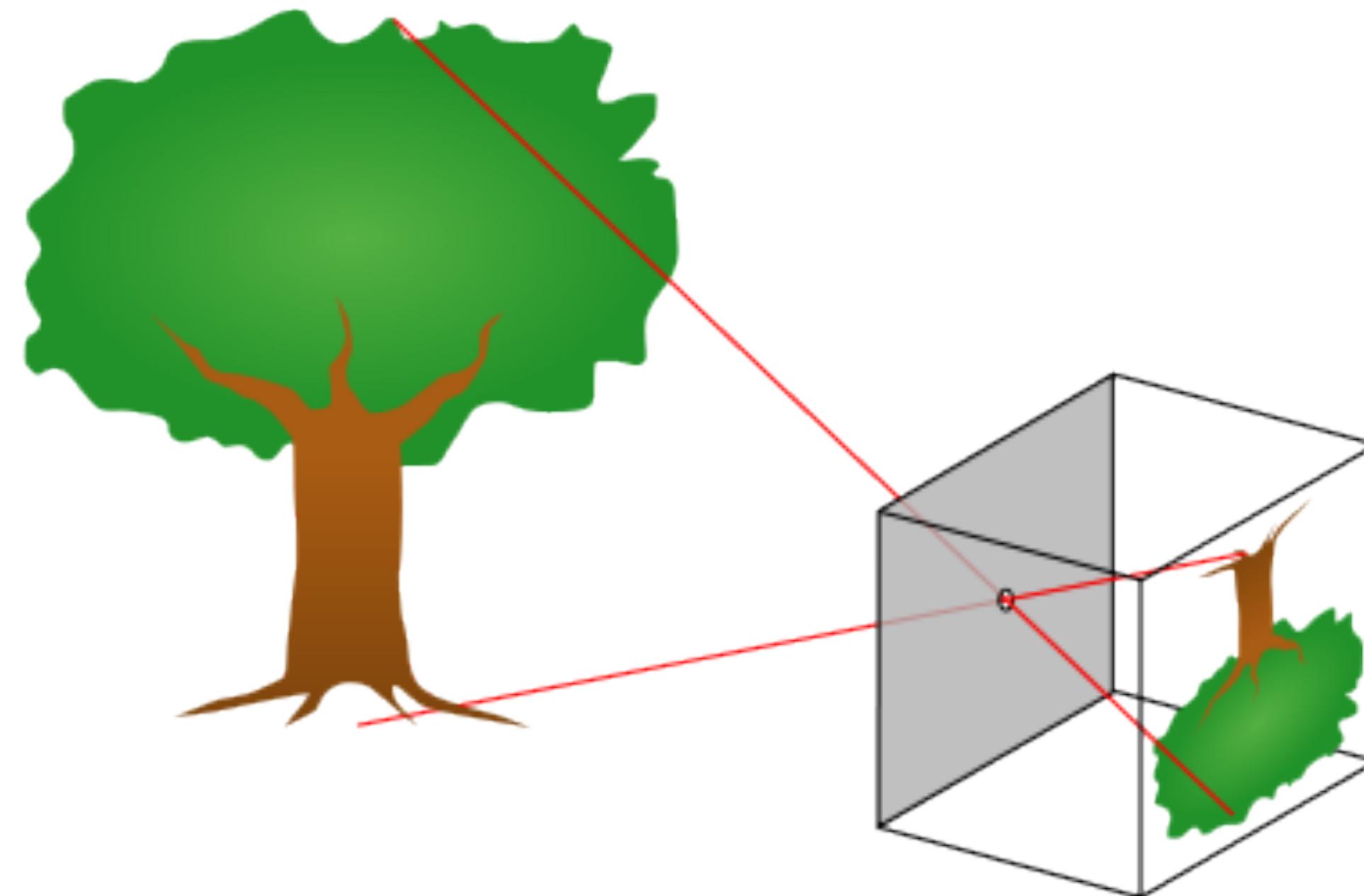
Cameras, without Optics



Cameras, without Optics



Camera Obscura (Pinhole Camera)



Camera Obscura (Pinhole Camera)

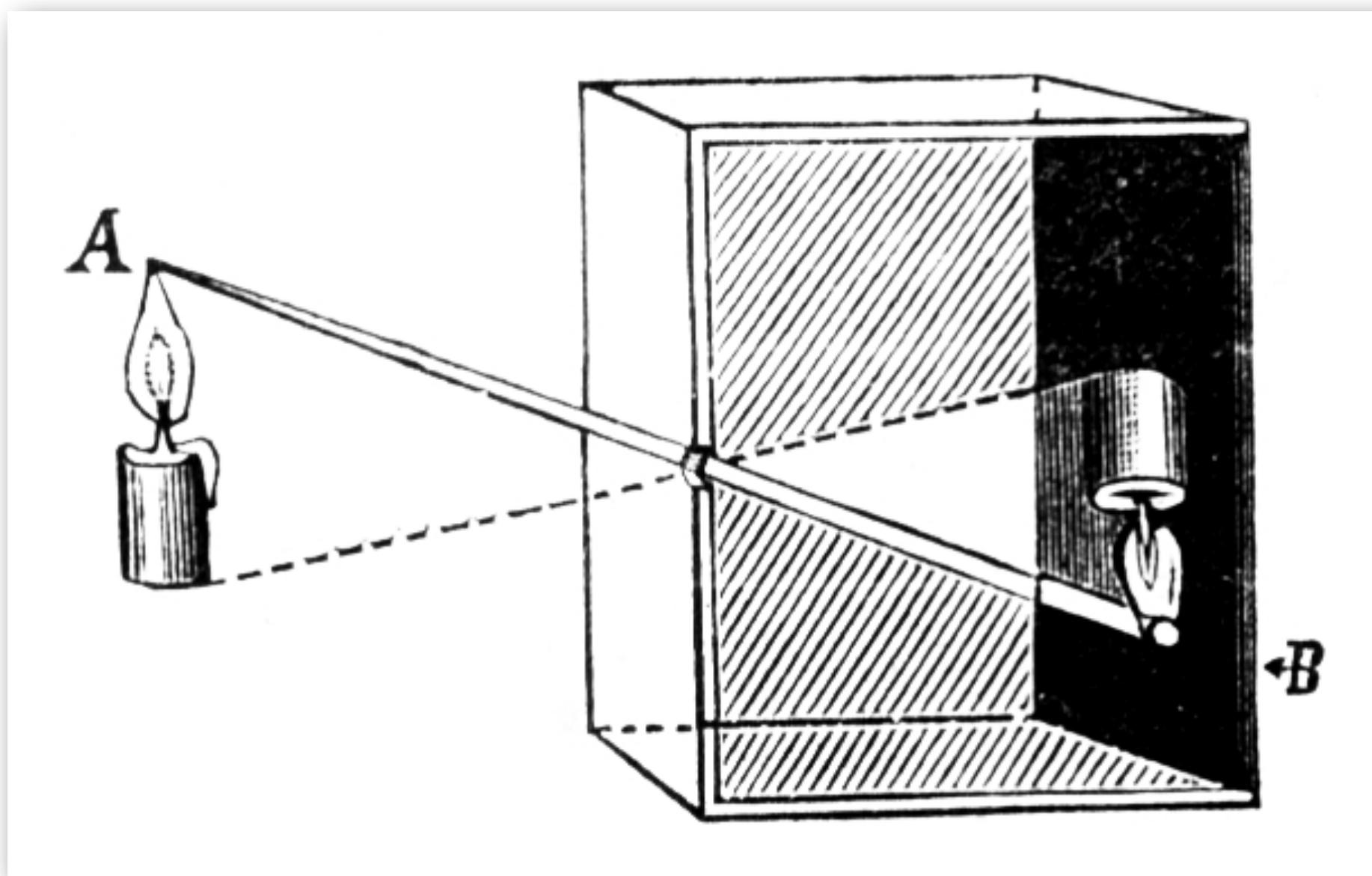




Illustration of camera obscura from "Sketchbook on military art, including geometry, fortifications, artillery, mechanics, and pyrotechnics"

Pinhole Photograph



Byelorussky Station: commons.wikimedia.org

- Theoretically,
- * No distortion:
Straight Lines remain straight
 - * Infinite depth of field:
Everything in focus (but there is optical blurring)

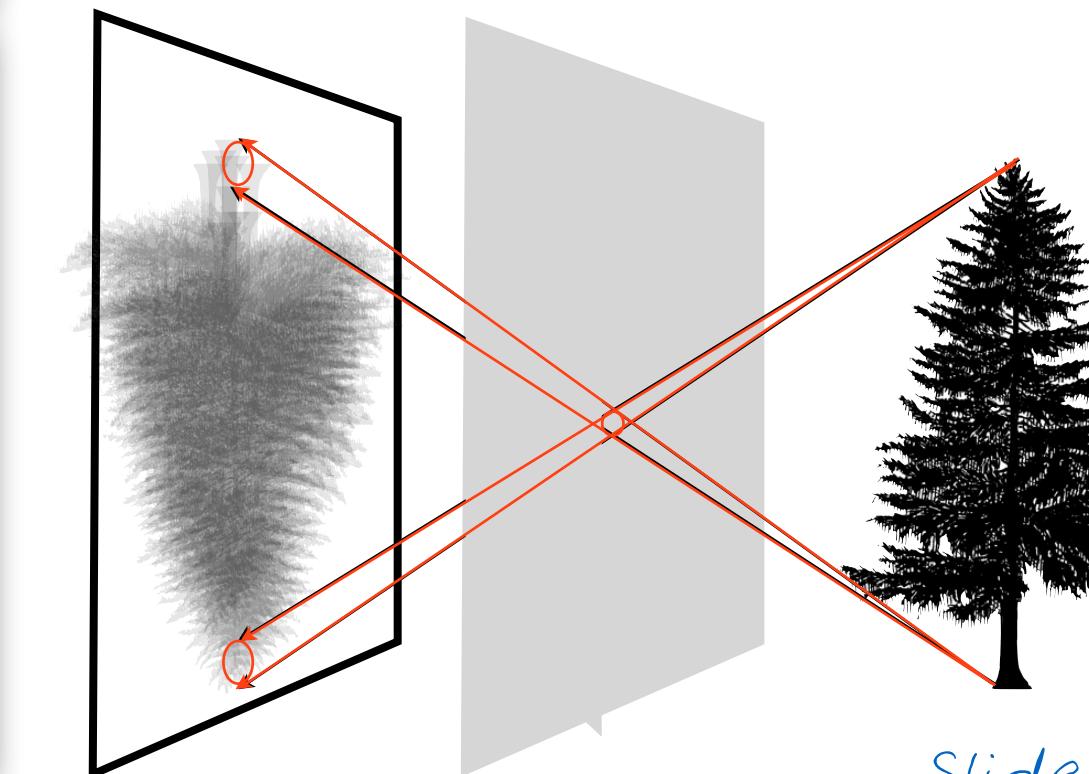
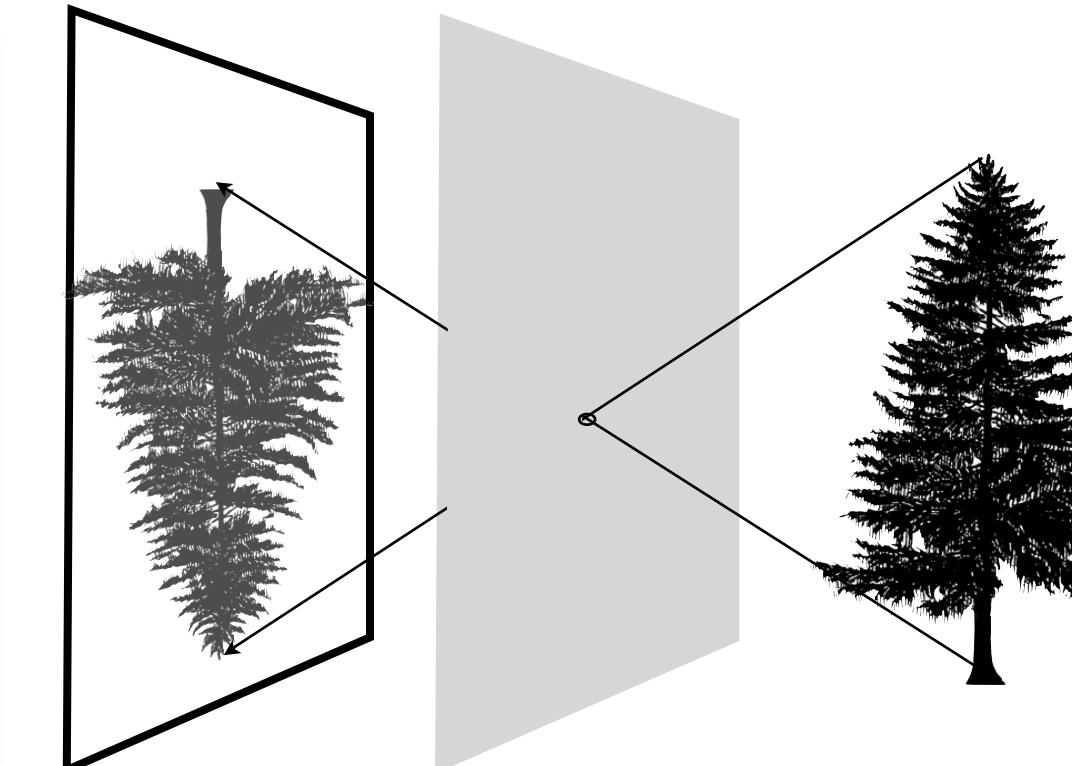
Slide adapted from Marc Levoy

This could be done as an explorational exercise.
“What would happen if we increased the pinhole size?”, followed by four images that simulate different changes (sharper, blurrier, double image, color change, etc.).

Pinhole Size and Image Quality



Pinhole
“blur”
simulated

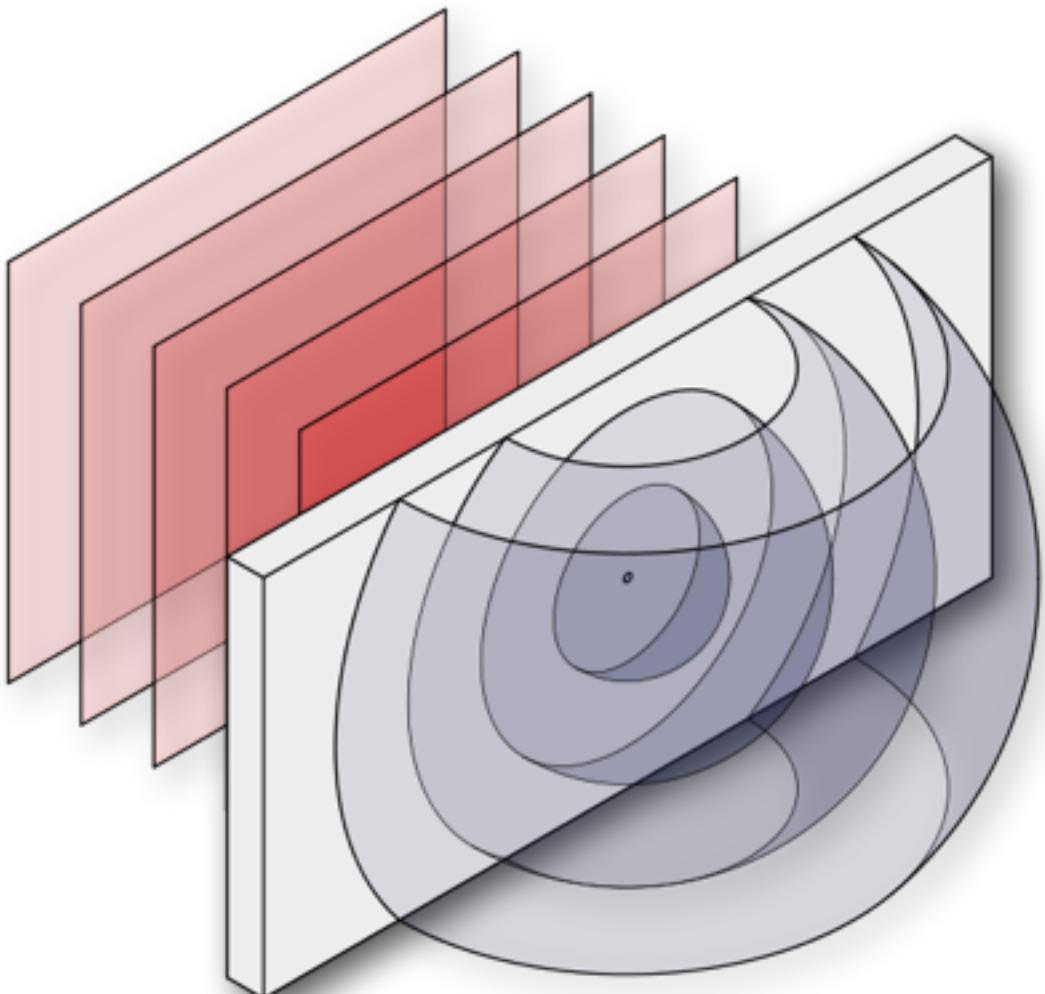


Pinhole Size
= Aperture!

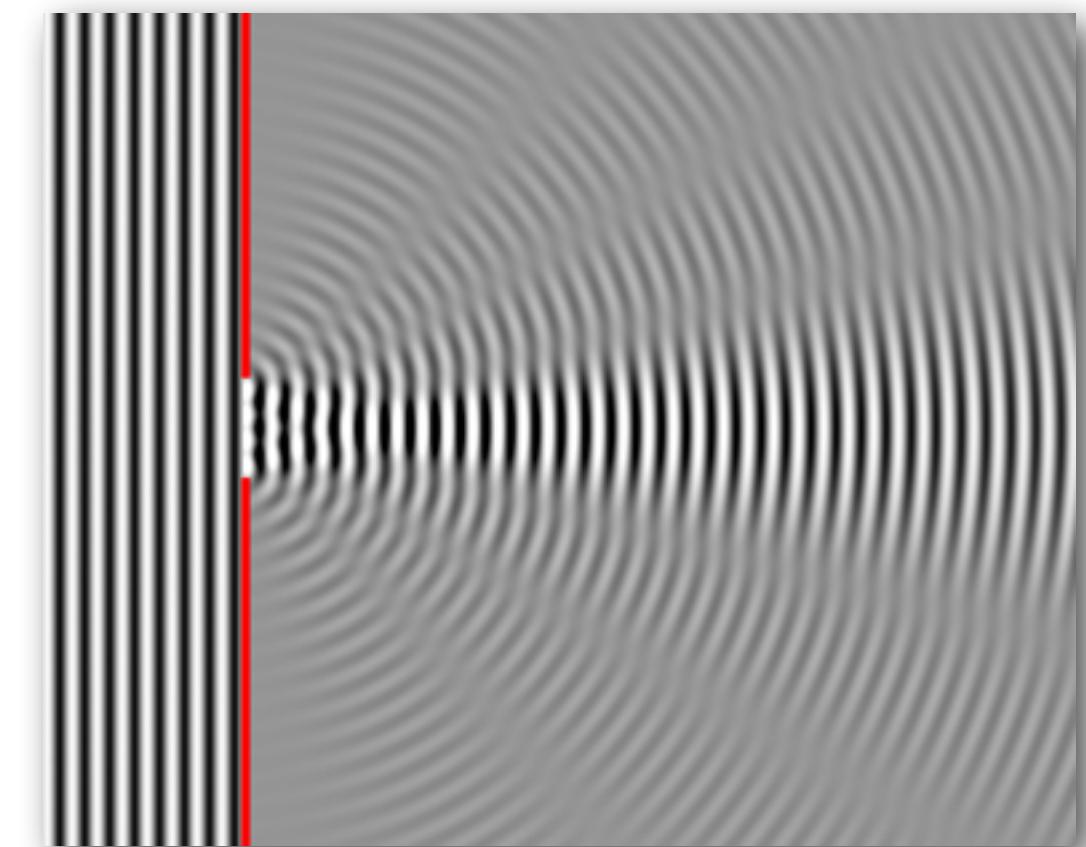
Slide adapted from Marc Levoy

Light Diffracts

- * Wave Nature of Light
- * Smaller Aperture means more Diffraction



3D Schematic



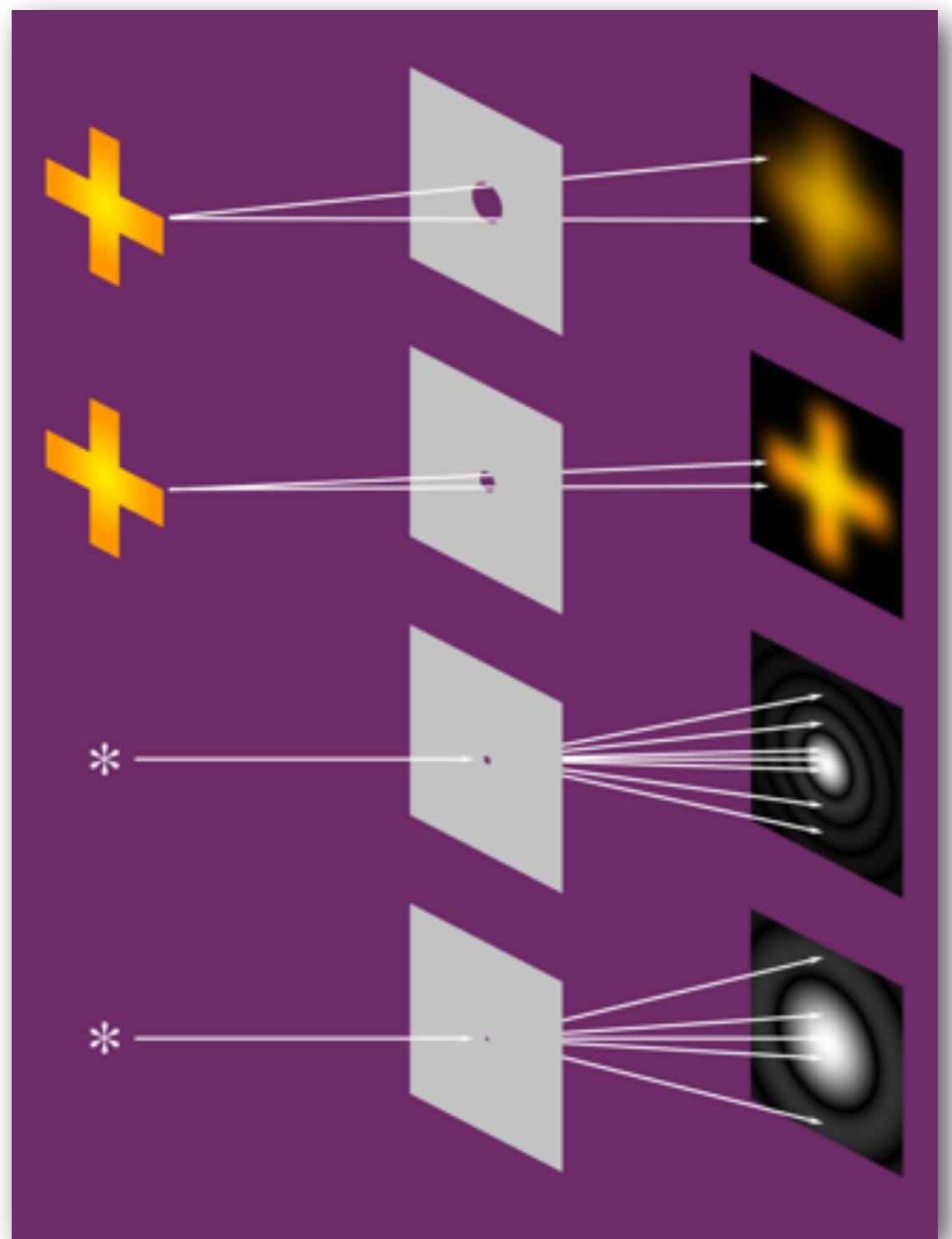
Actual Diffraction Pattern

Effect of Pinhole Size

Large Pinhole = Geometric Blur

Small Pinhole = Diffraction Blur

Best Pinhole = Very Little Light

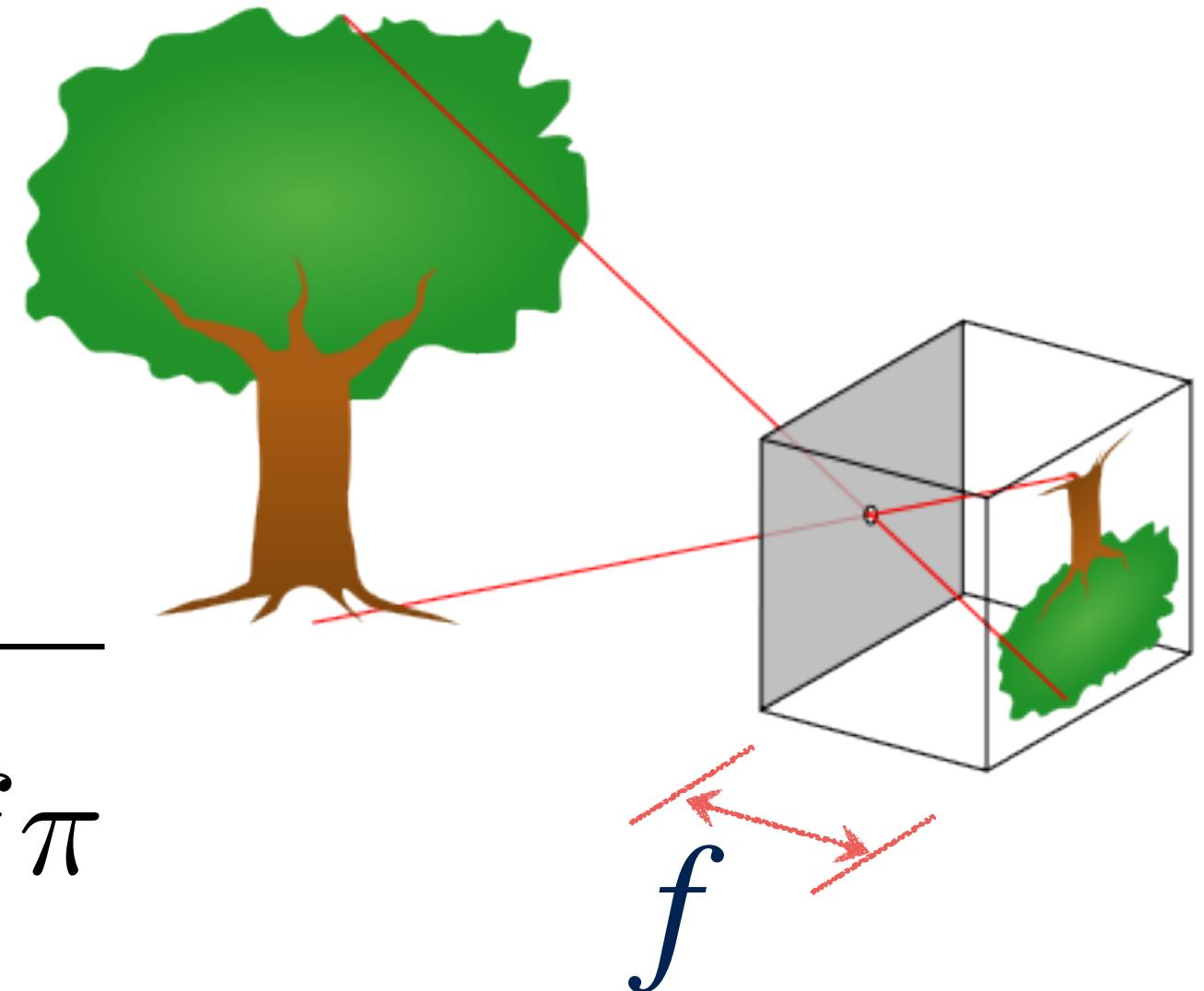


Slide adapted from Marc Levoy

Effect of Pinhole Size

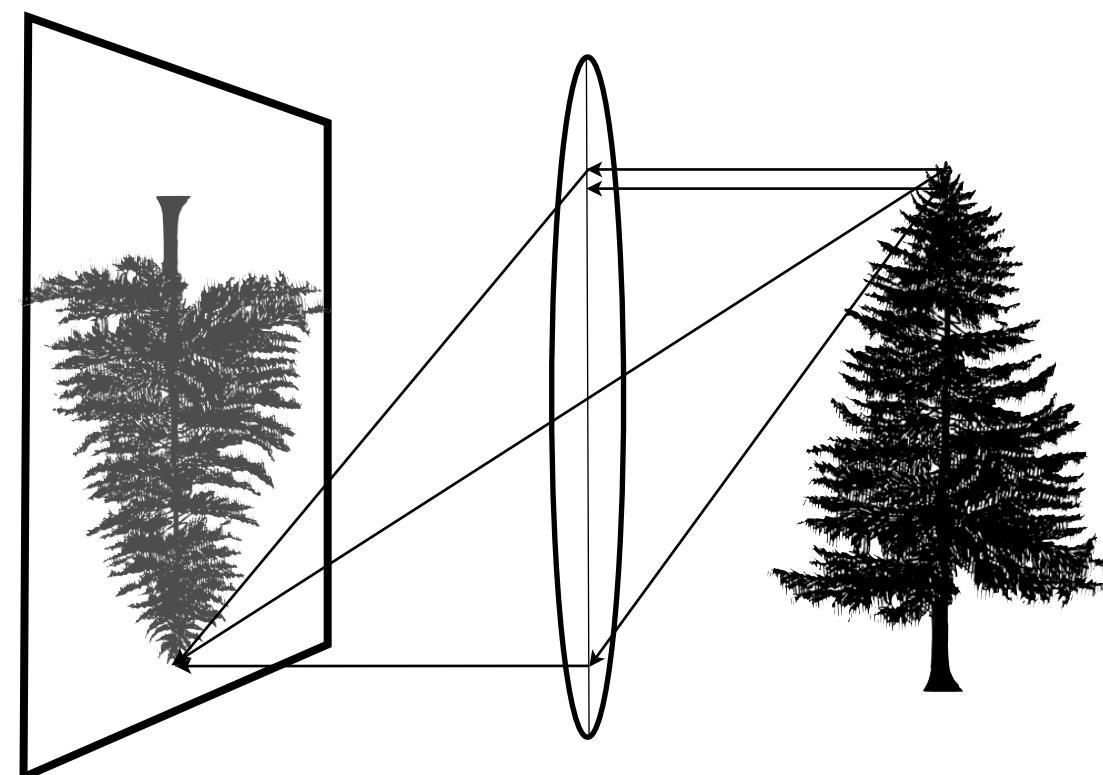
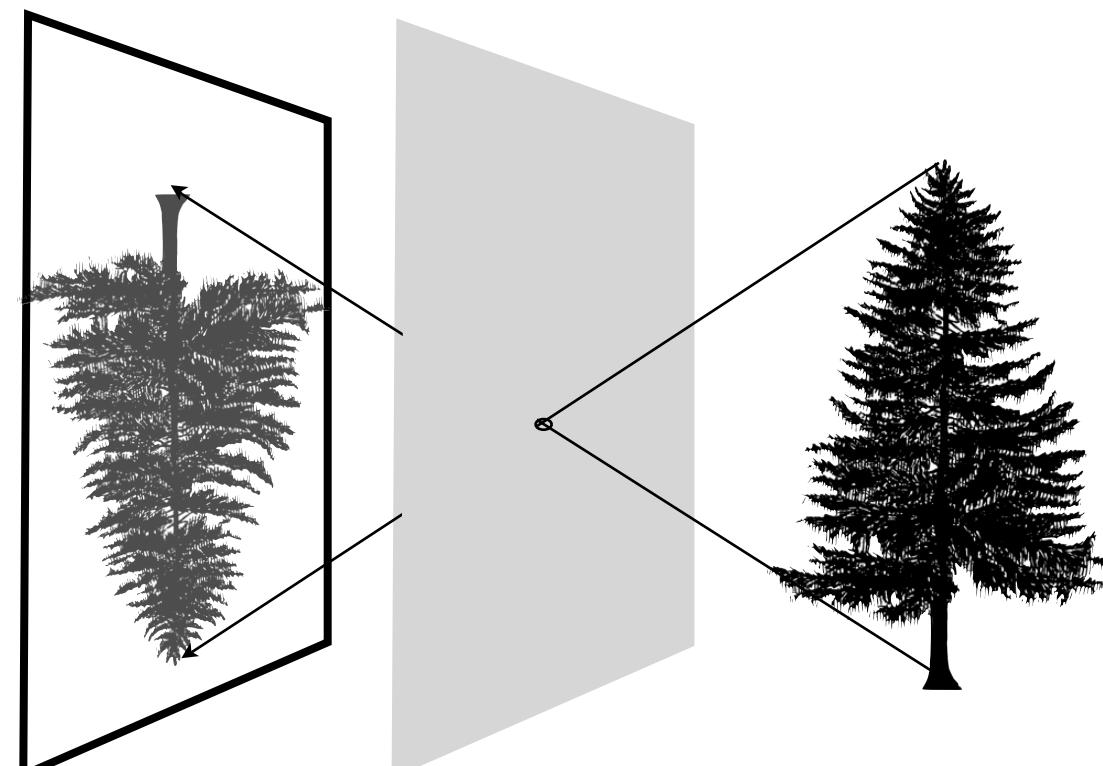
For d (pinhole diameter),
 f (distance from pinhole to sensor),
and π (wavelength of light):

$$d = 2\sqrt{\frac{1}{2}f\pi}$$

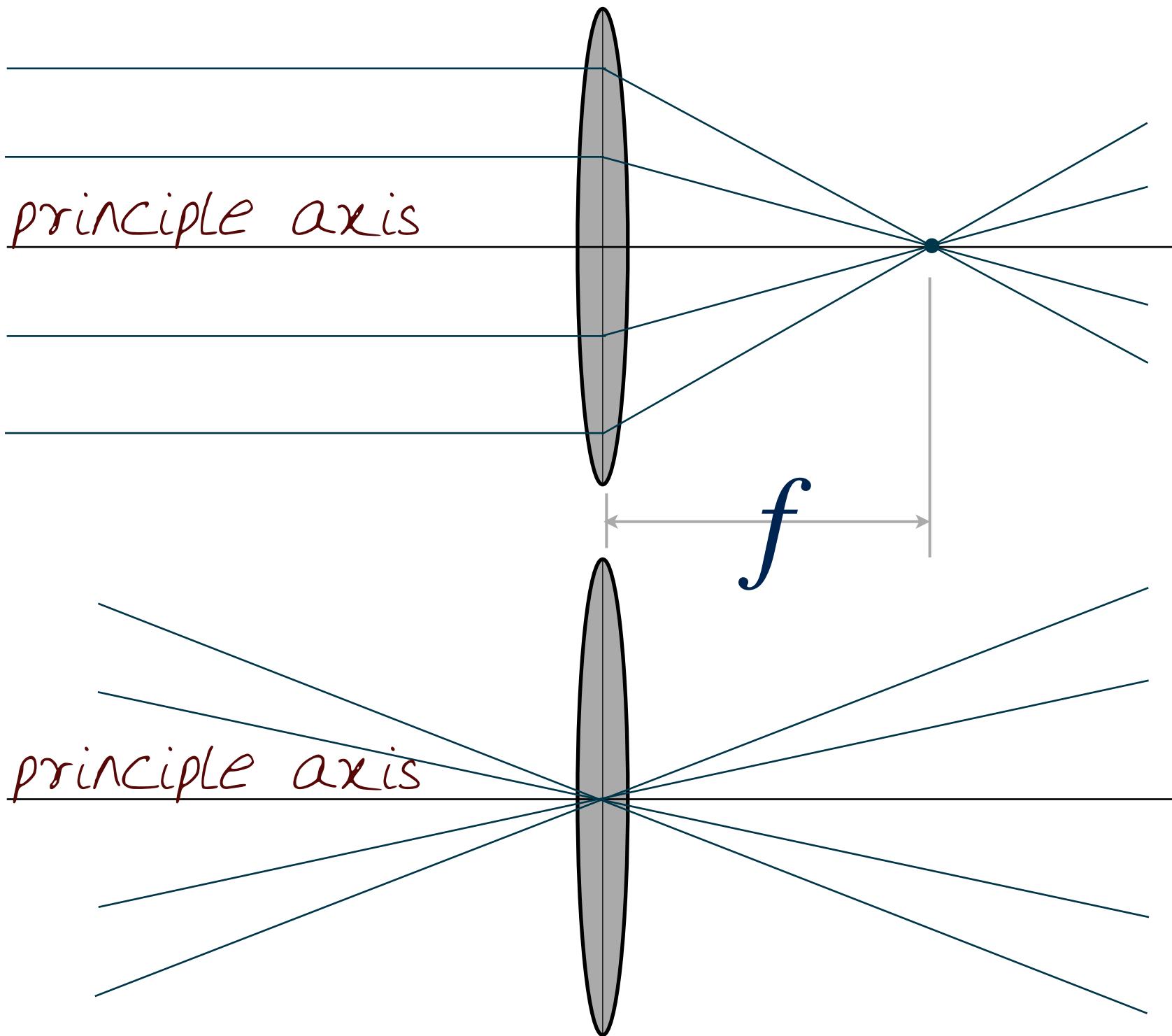


Slide adapted from Marc Levoy

Replacing the Pinhole with a Lens



Geometrical Optics



- * Parallel rays converge to a point located at focal length, f from lens
- * Rays going through center of lens do not deviate (functions like a pinhole)

Ray Tracing with Lenses

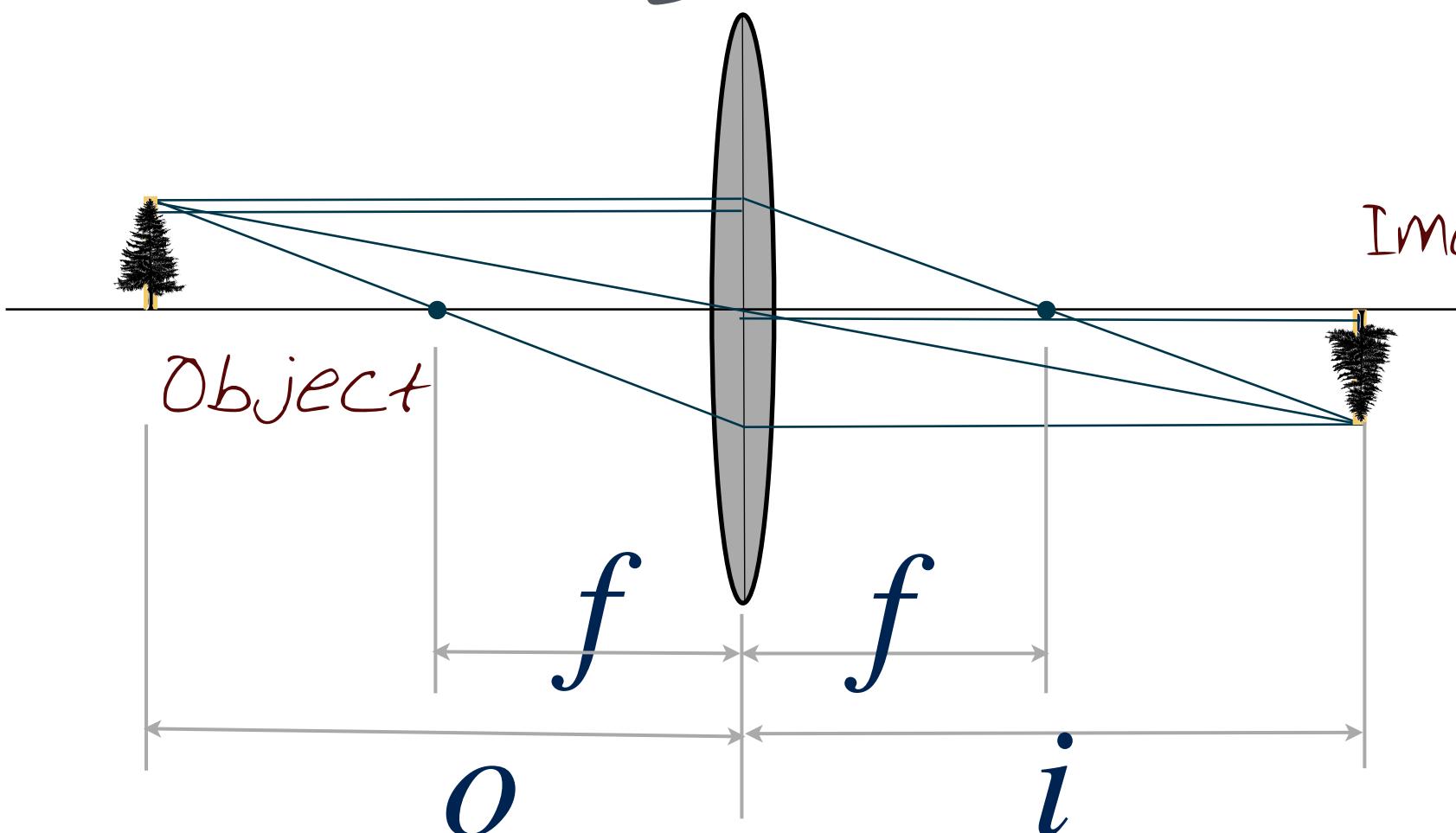


Image * Rays from points on a plane parallel to the lens, focus on a plane parallel to the lens on the other side

(and upside down).

* Lens Equation

$$\frac{1}{O} + \frac{1}{i} = \frac{1}{f}$$

Summary



- * Discussed the Foundations of How a Camera works
- * Presented the Concept of a Pinhole Camera
- * Introduced Optics and LENSES and the Role they play in a Camera

Neat Class

- * Cameras: Changes in
Focal Length,
Aperture, Shutter
and Sensor





Credits

- * For more information, see
 - * Hecht, E. Optics, 4th ed. Reading, MA: Addison-Wesley and
 - * London, B., Stone, J., & Upton, J., Photography, 10th ed. Upper Saddle River, NJ: Prentice Hall.
- * Images retrieved from
 - * <http://commons.wikimedia.org/>
 - * http://commons.wikimedia.org/wiki/File:Sun_Rays.jpg
- * List will be available on website
- * Some Slides adapted from Mark Levoy

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Cameras, Optics, and Sensors

* Cameras' Lenses and Impact
of Focal Length on Photography

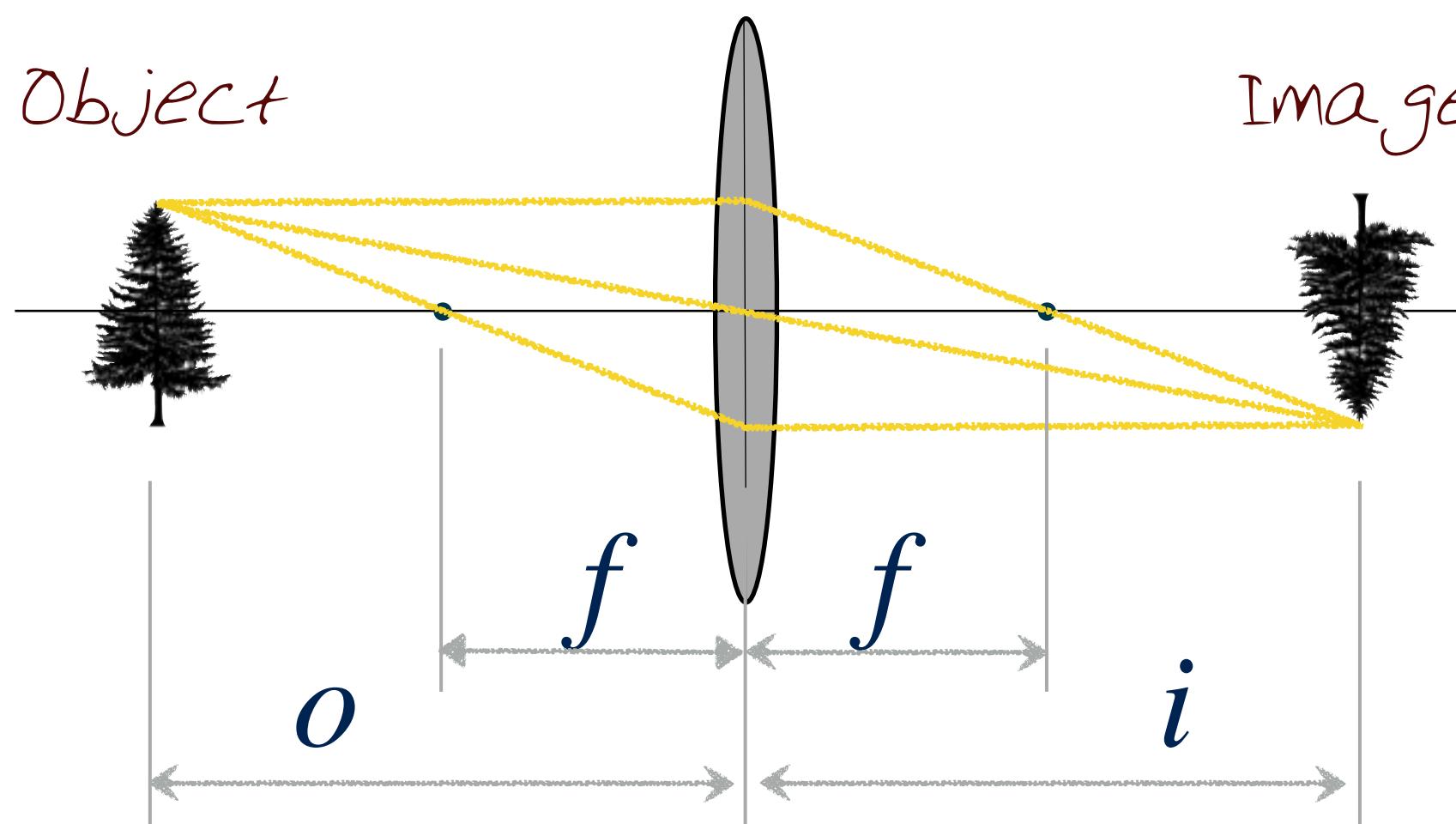


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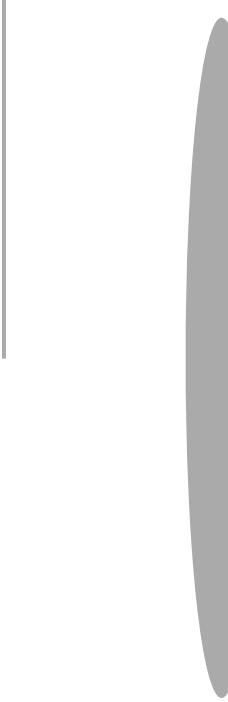
1. Focal Length
2. Field of View (FOV)
3. Sensor Size
4. Image Formation & Capture
5. Perspective Projection

Recall: Ray Tracing with Lenses

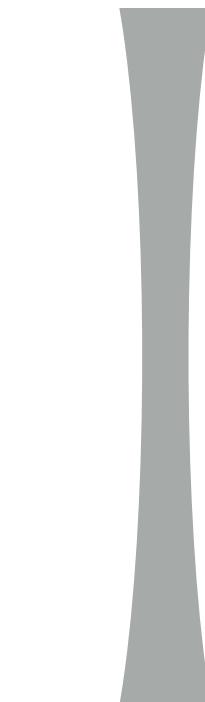


Thin lens equation

$$\frac{1}{O} + \frac{1}{i} = \frac{1}{f}$$

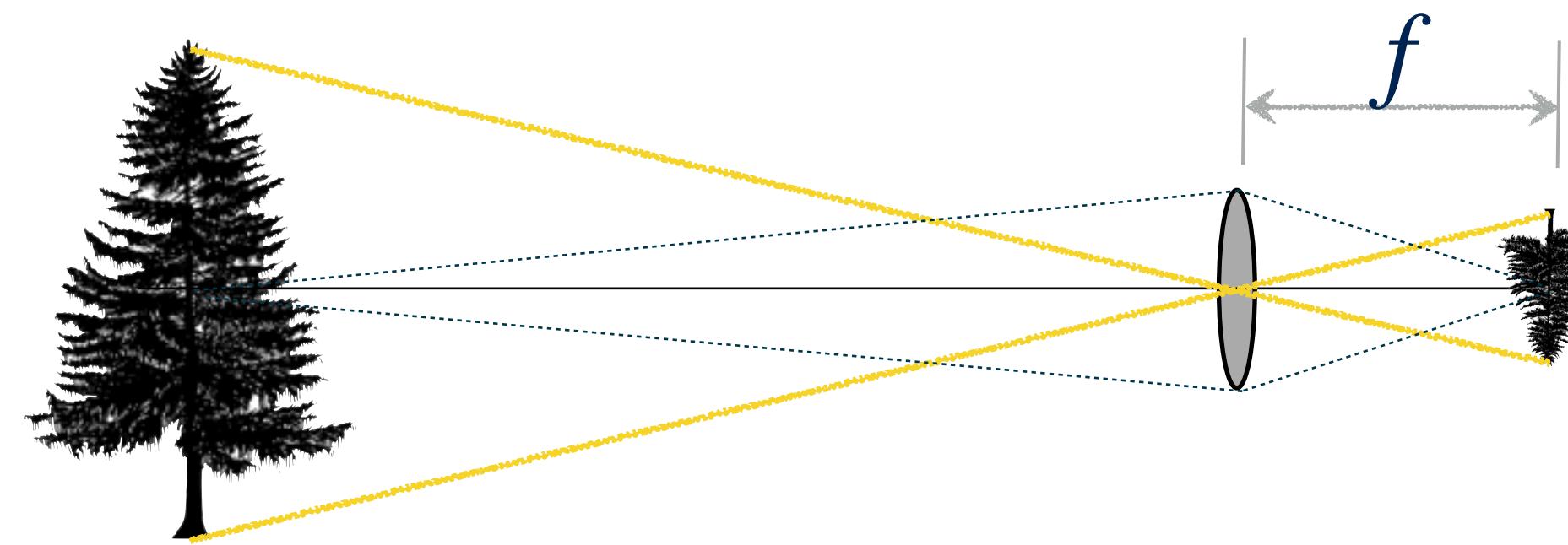


CONVEX

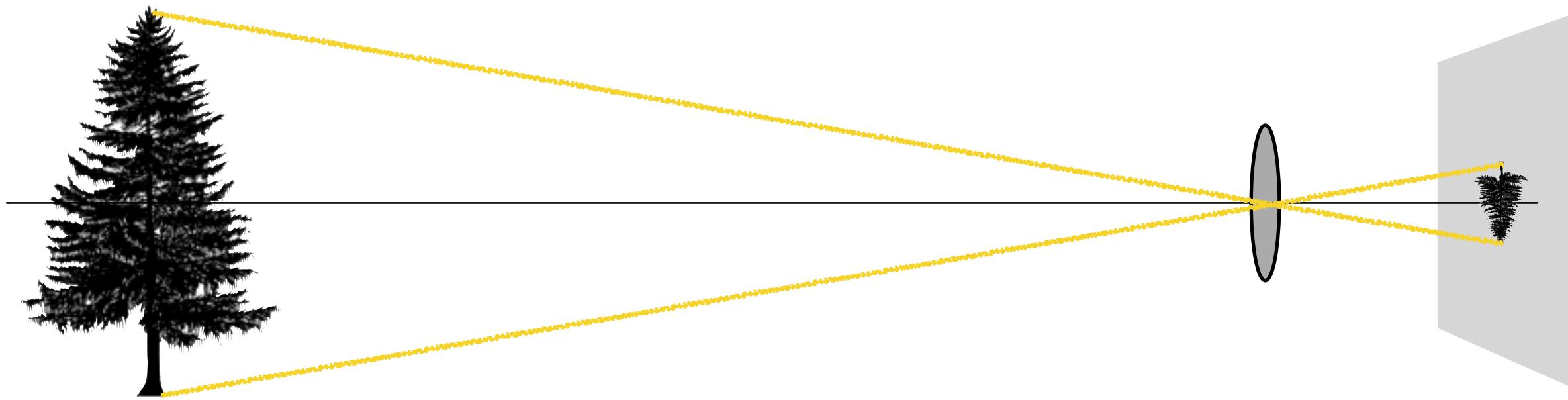
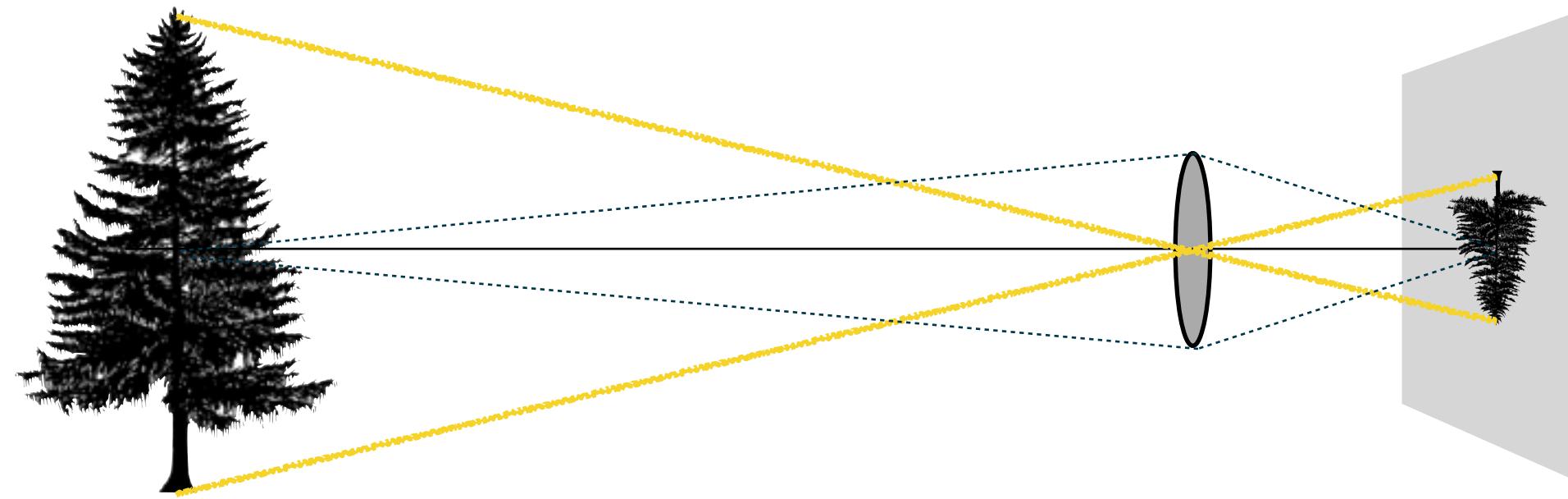


CONCAVE

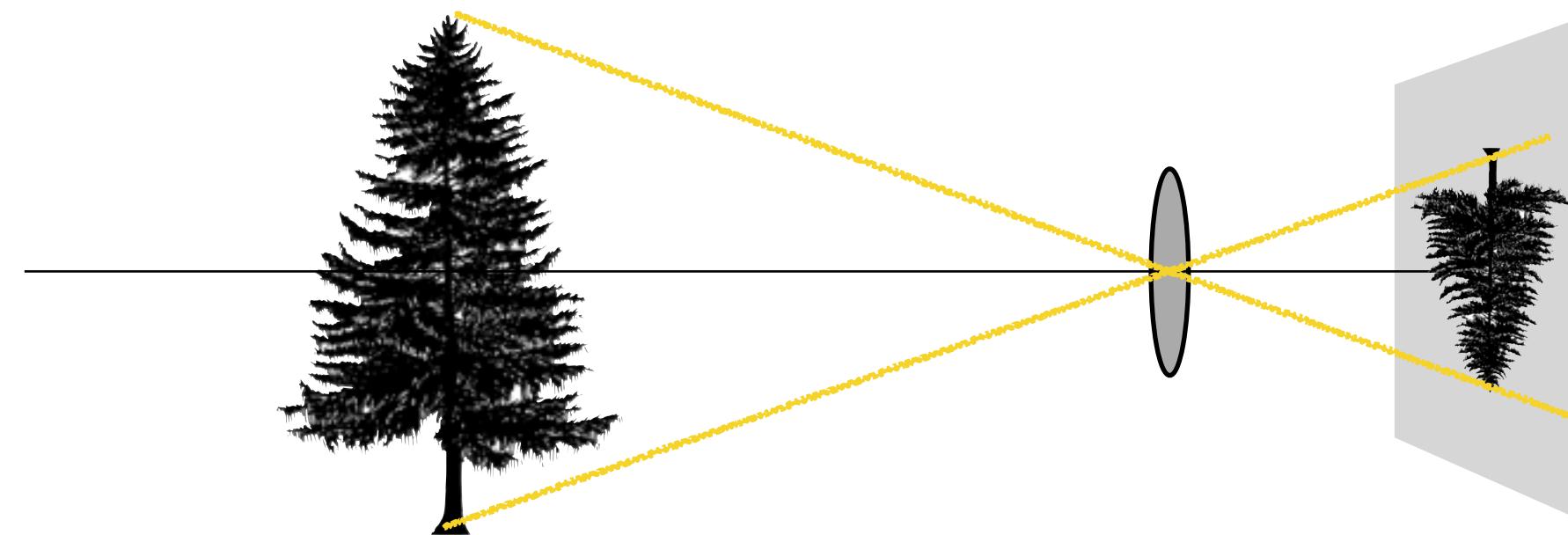
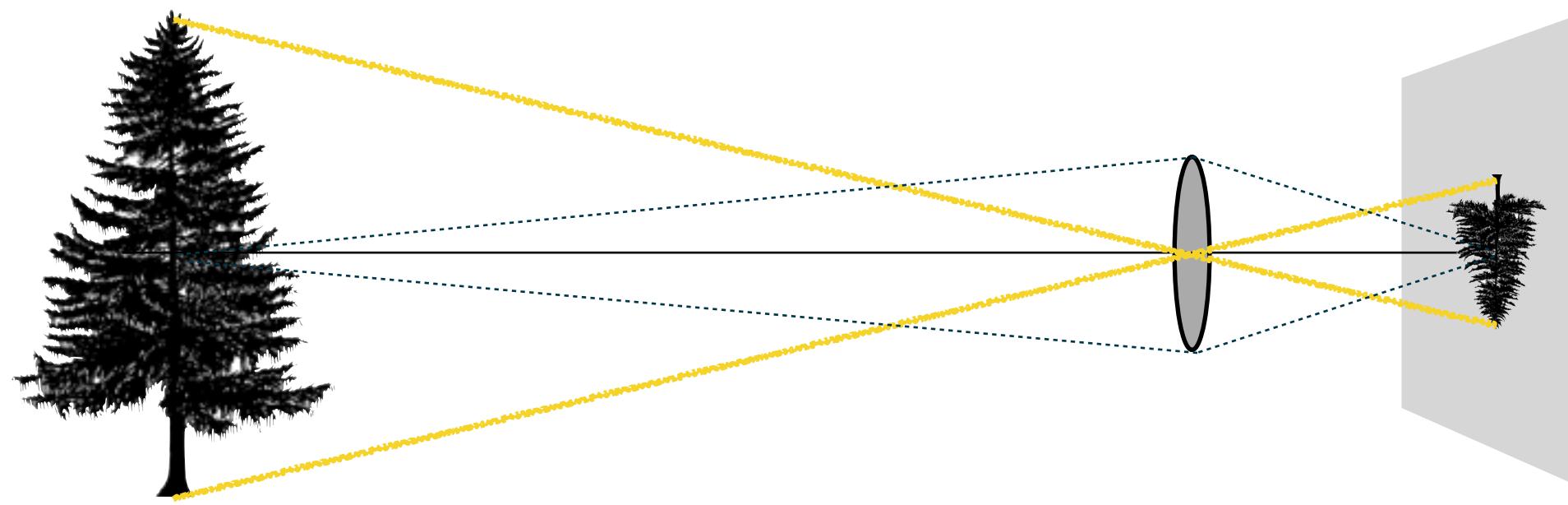
Image Formation



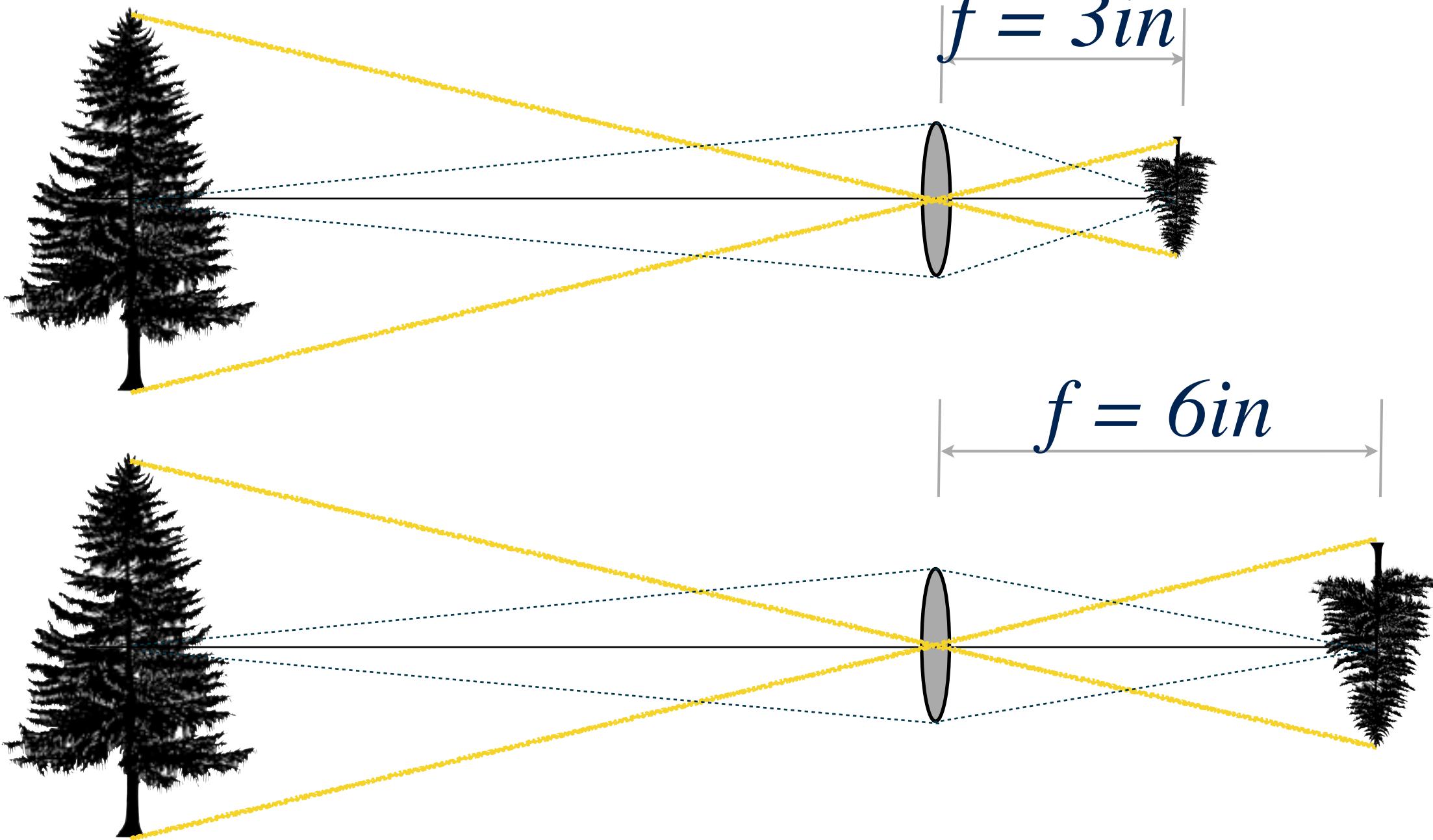
Changing object distance



Changing distances!



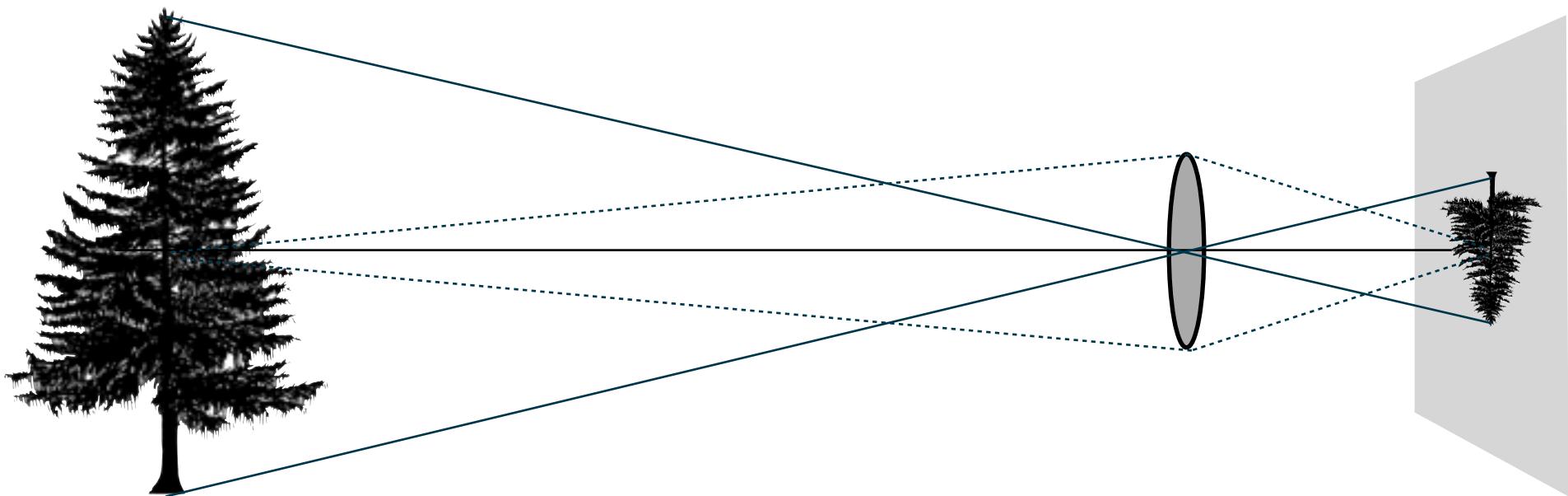
Changes in Focal Length



* Longer or shorter f

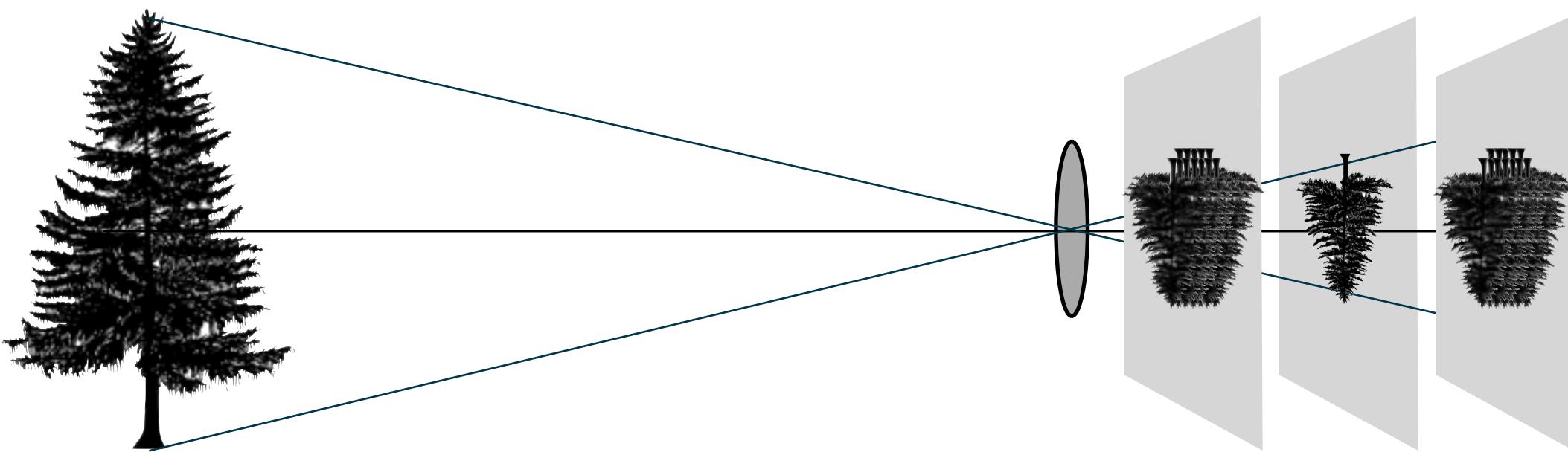
* focal lengths are specific to lenses

Focussing

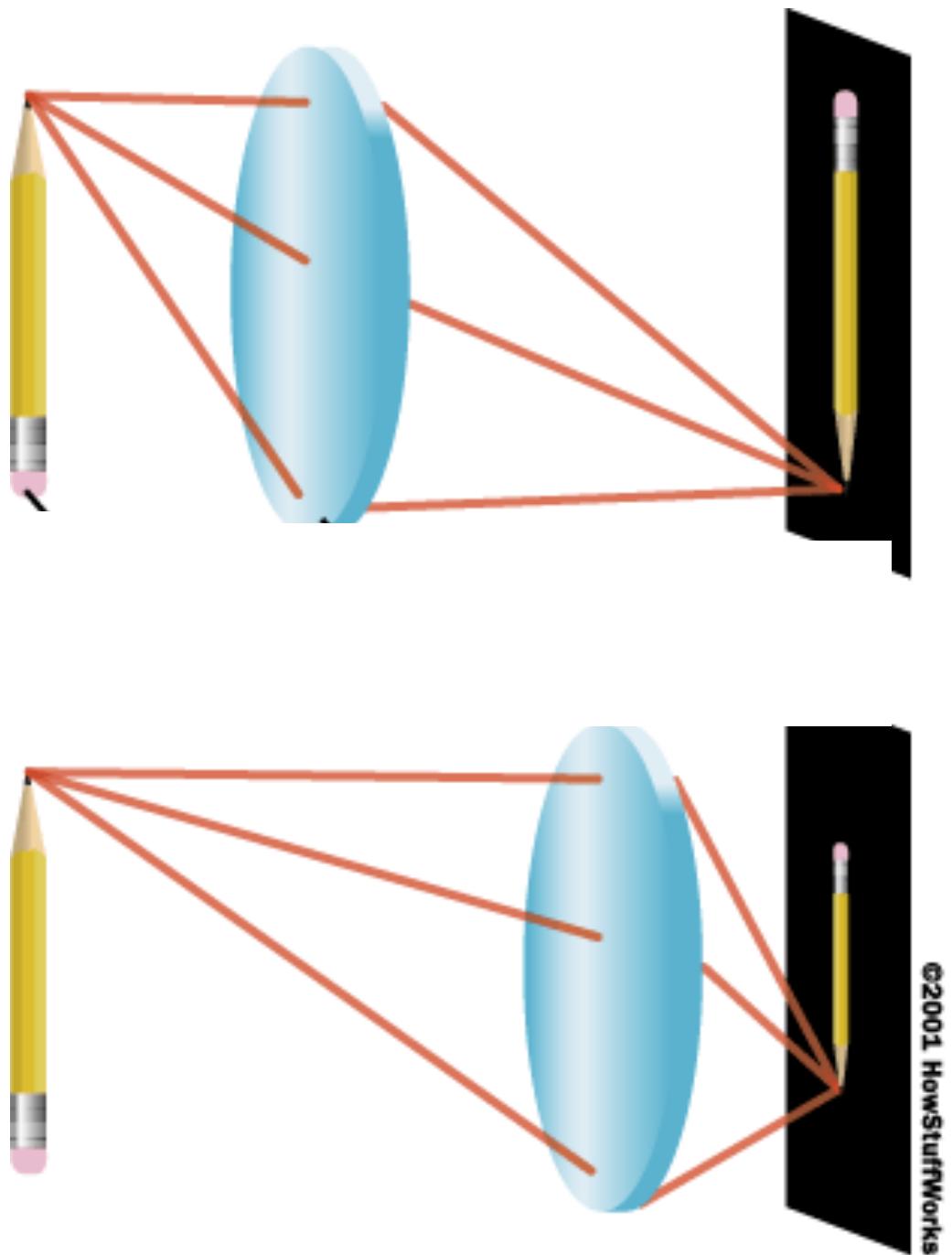


*

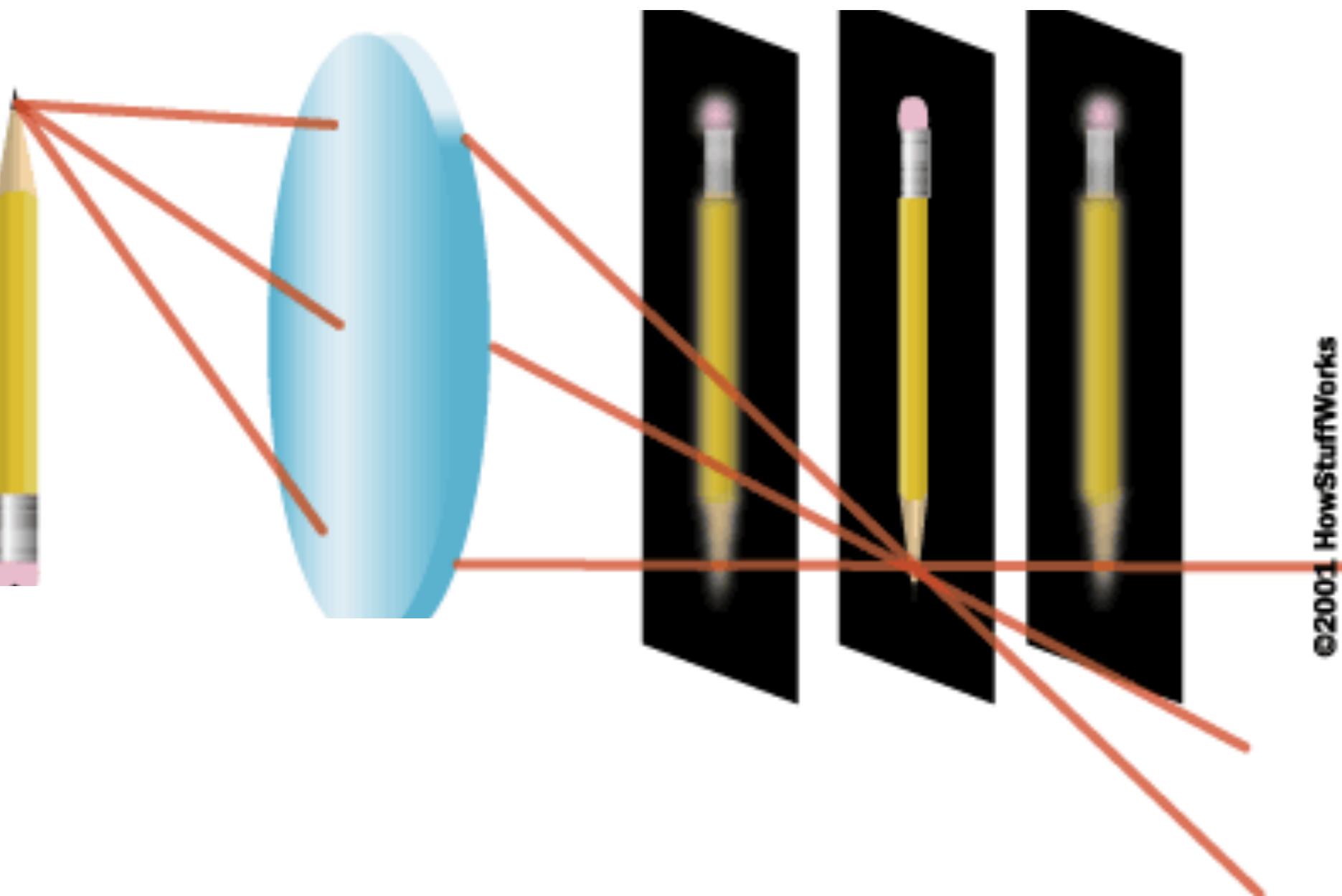
focusing:
moving
sensor back
(or
forward)
wrt to lens



Focussing

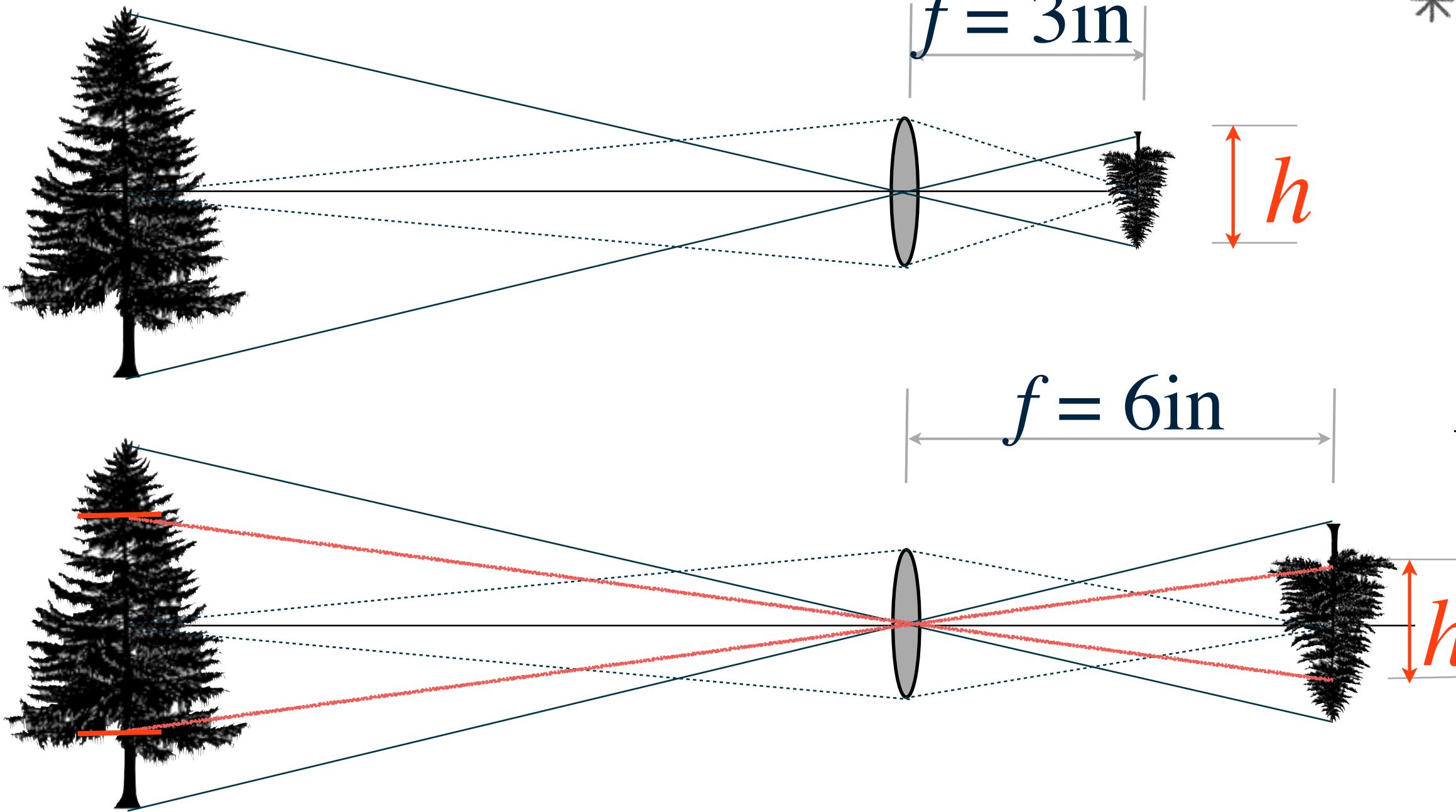


©2001 HowStuffWorks



from howstuffworks.com

Field of View (FOV)

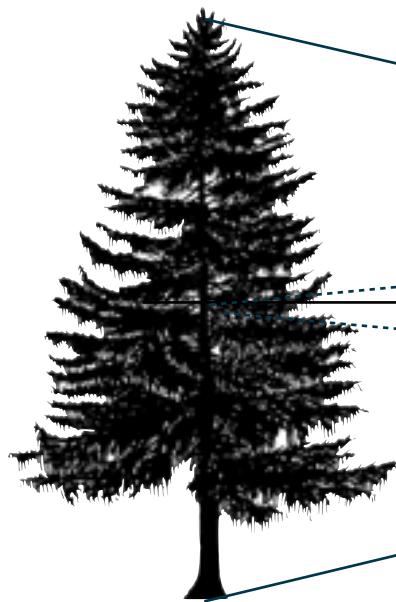


* Field of View (FOV) depends on sensor size, h

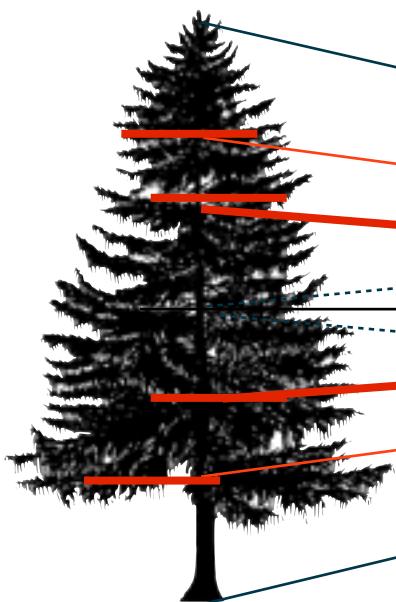
$$FOV = 2 \tan^{-1} \frac{h}{2f}$$

Slide adapted from mark Levoy

Field of View (FOV) Sensor Size



* sensor size
small, FOV is
small too



* smaller
sensors have
fewer pixels,
or noisier
pixels

$$FOV = 2 \tan^{-1} \frac{h}{2f}$$

Slide adapted from Mark Levoy

12 mm

24mm

50mm

85mm

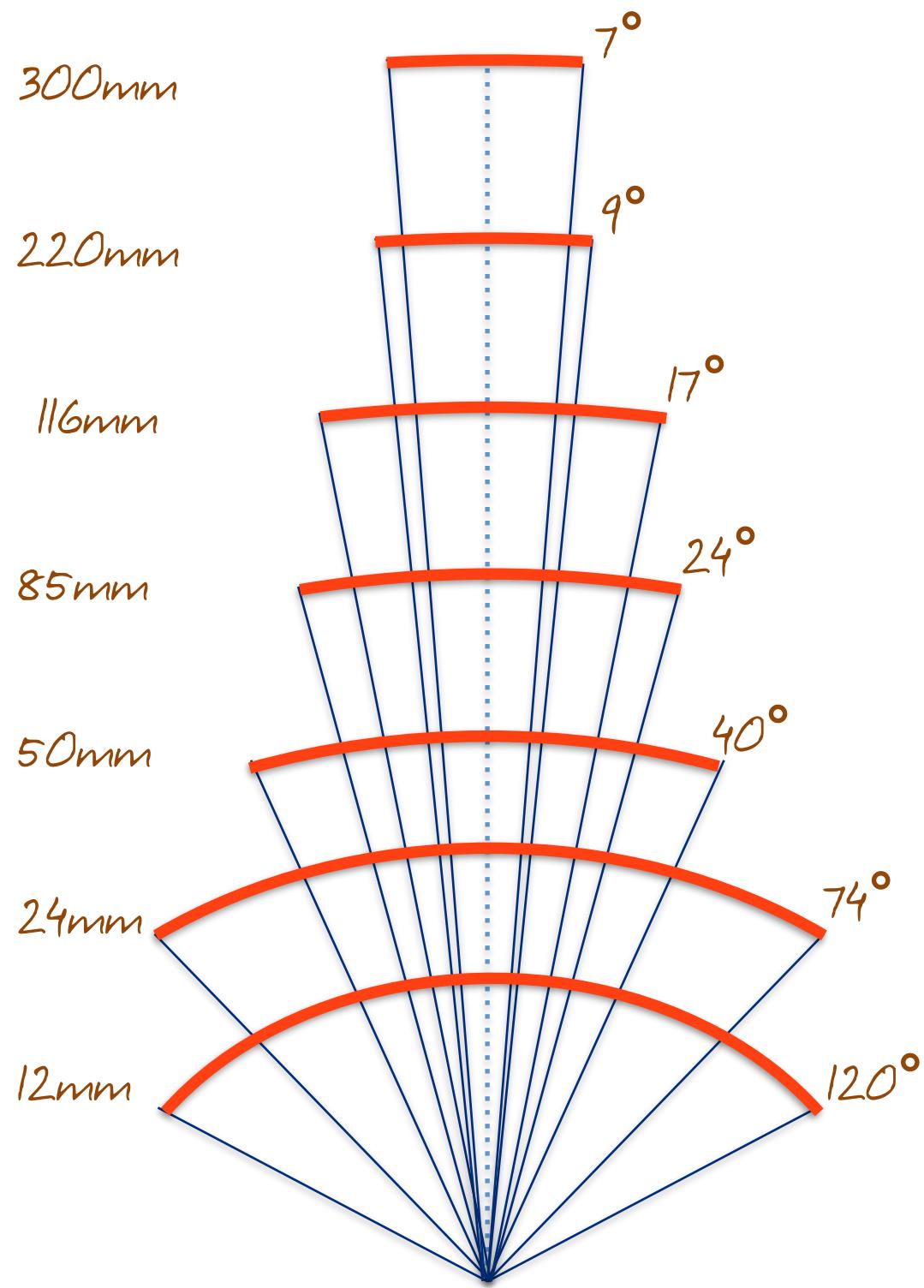
116mm

220mm

300mm



Focal Length and Field of View (FOV)



Photos by Henrik Christensen

Sensor Sizes

8.8 X 6.6 mm
(1:2) micro 2/3

4.54 X 3.52mm
(iPhone 5)

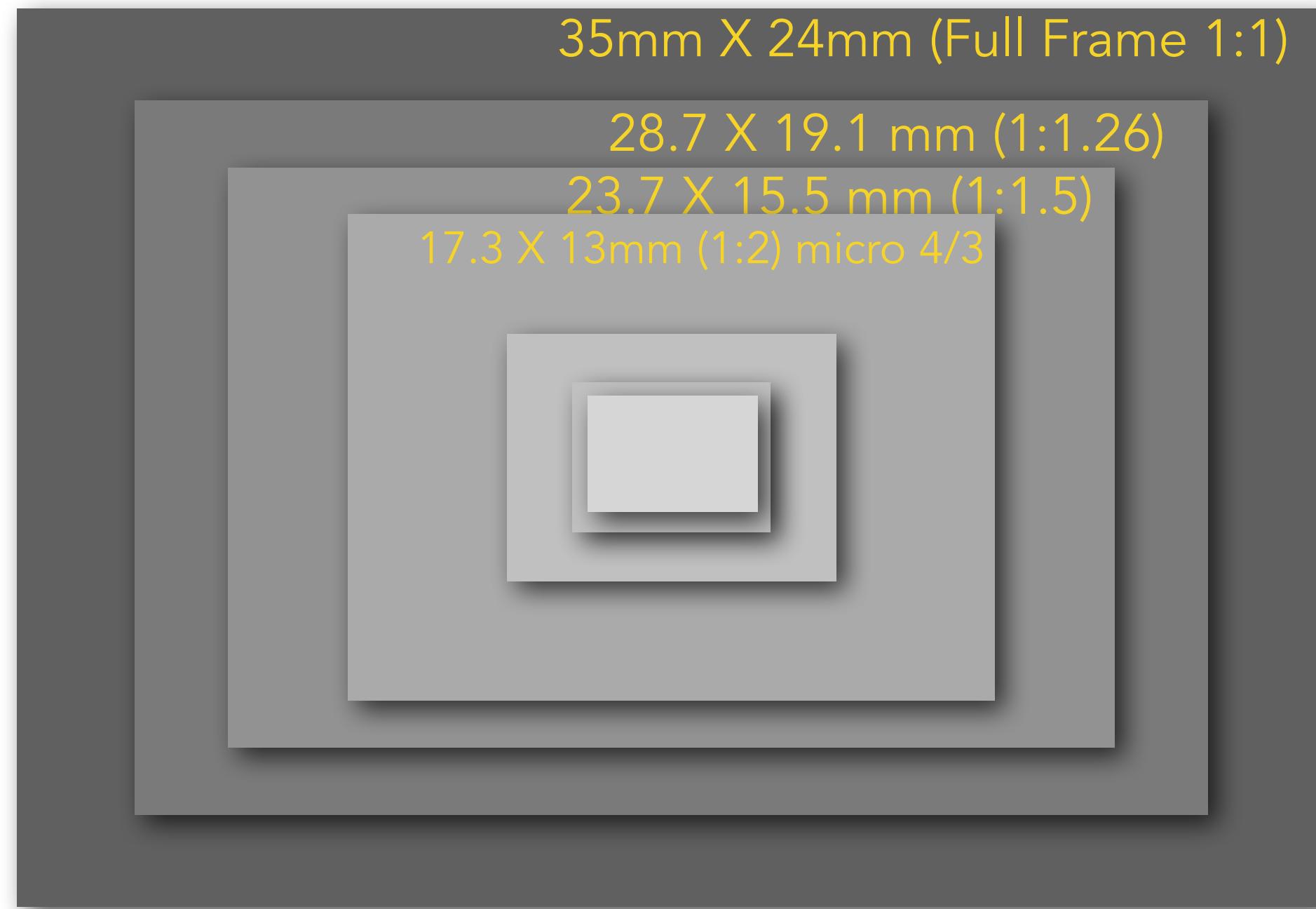
35mm X 24mm (Full Frame 1:1)

28.7 X 19.1 mm (1:1.26)

23.7 X 15.5 mm (1:1.5)

17.3 X 13mm (1:2) micro 4/3

7.25 X 5.33mm



Focal Length vs. Viewpoint



$f = 18\text{mm}$, 35mm sensor

Distance to 1st Subject = 0.5m Distance to 1st Subject = 3.0m

Distance to 2nd Subject = 2.0m Distance to 2nd Subject = 4.5m



$f = 180\text{mm}$, 35mm sensor

- * Changing focal length allows us to move back, and still capture the scene
- * Changing viewpoint causes perspective changes
- * See the "vertigo" effect from Hitchcock movies

Camera as a Window in a 3D World



Geometry (Perspective)

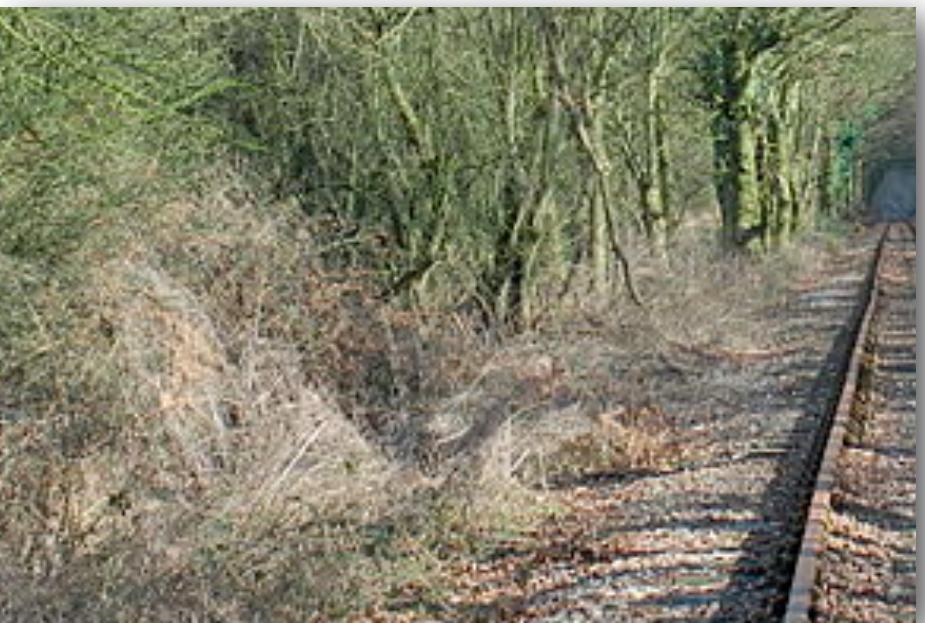
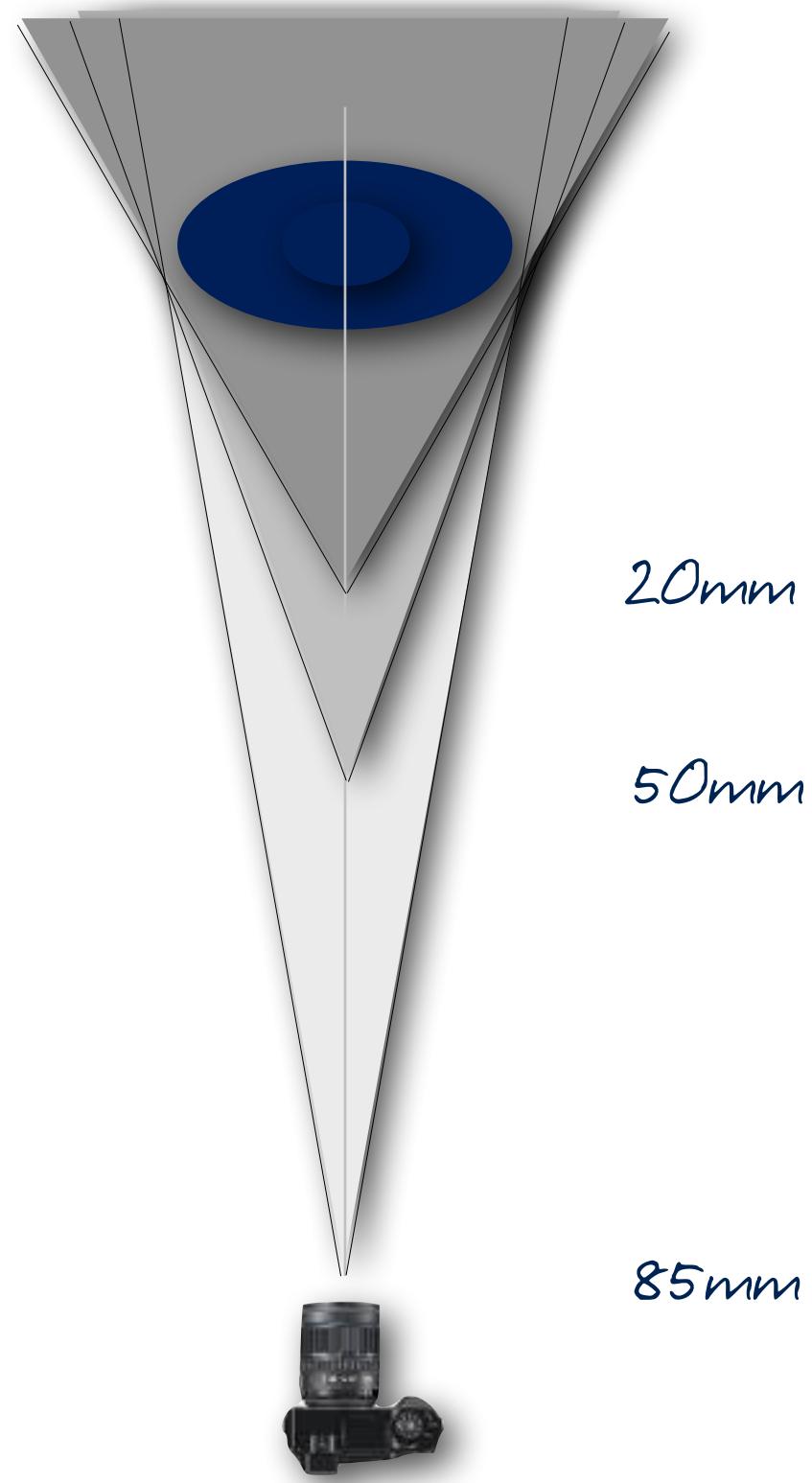
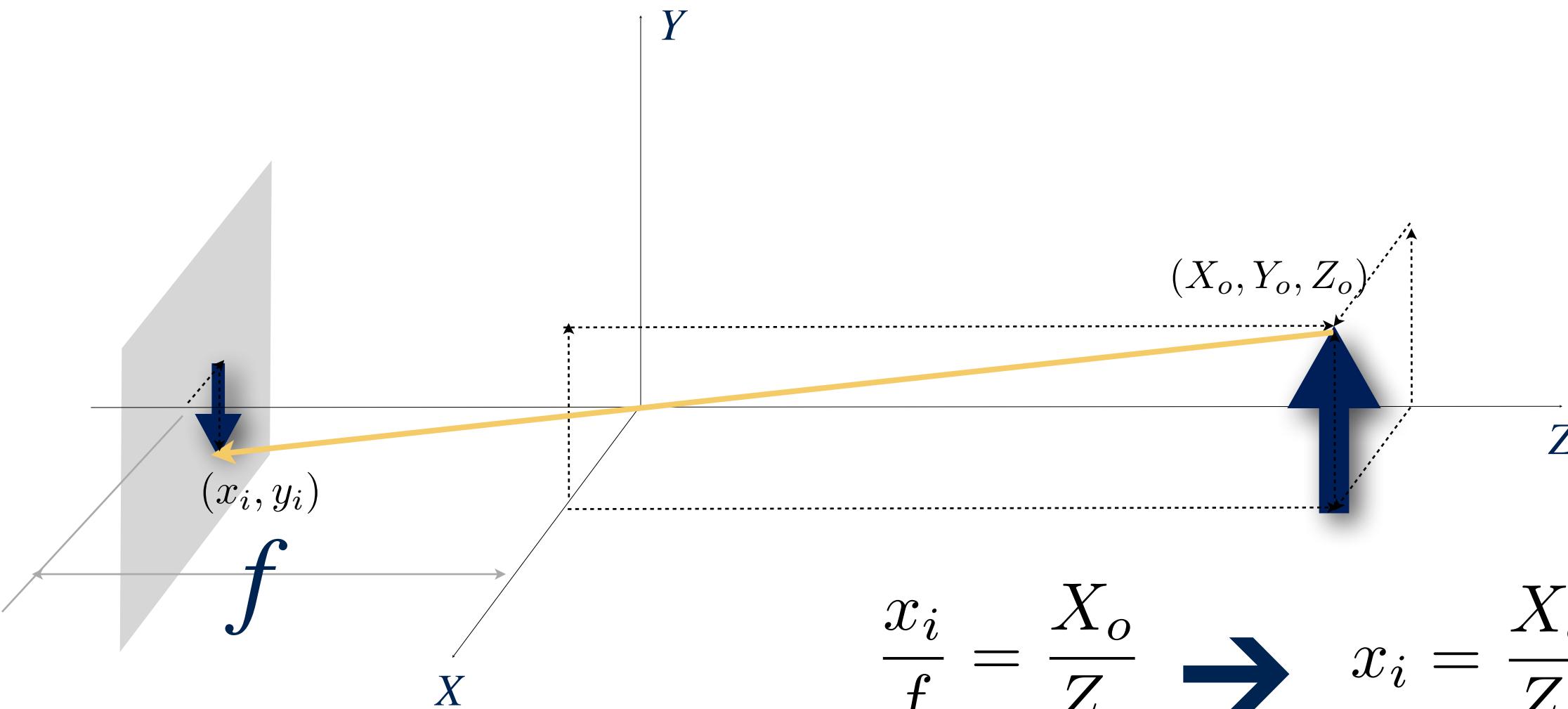


Image: Wikimedia Commons



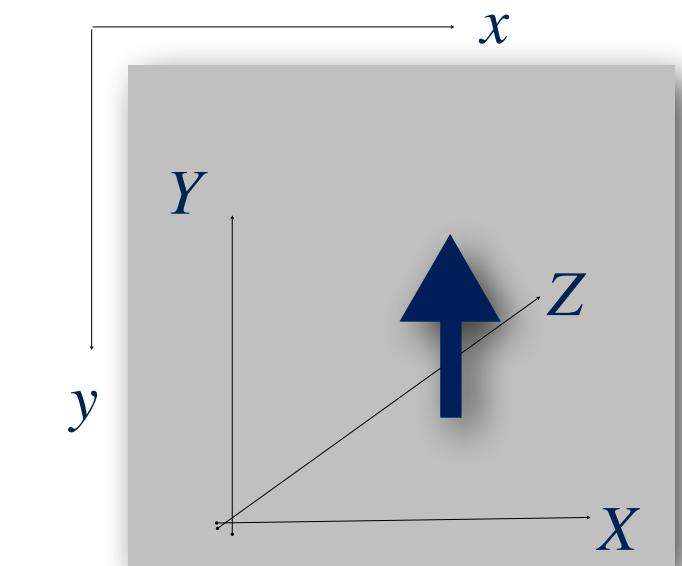
A Camera Model



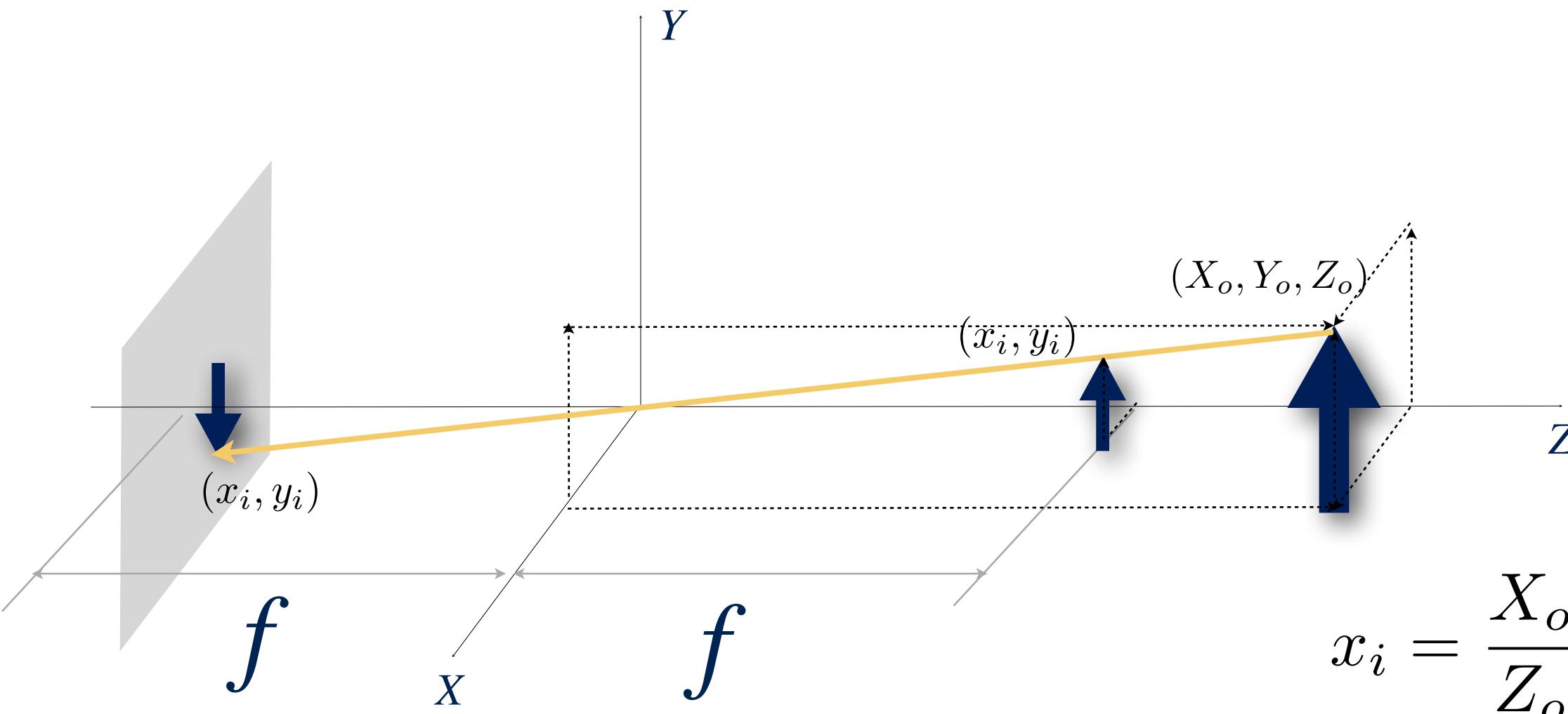
Using similar triangles

$$\frac{x_i}{f} = \frac{X_o}{Z_o} \rightarrow x_i = \frac{X_o}{Z_o} f$$

$$\frac{y_i}{f} = \frac{Y_o}{Z_o} \rightarrow y_i = \frac{Y_o}{Z_o} f$$

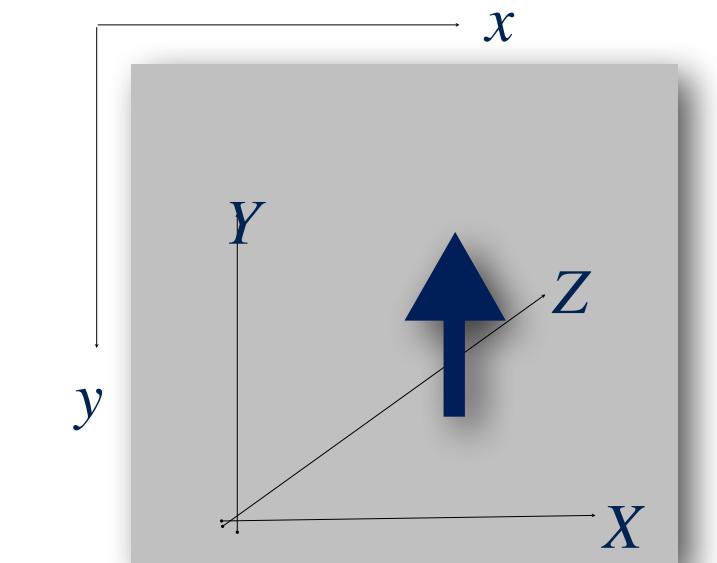


A Camera Model: Perspective

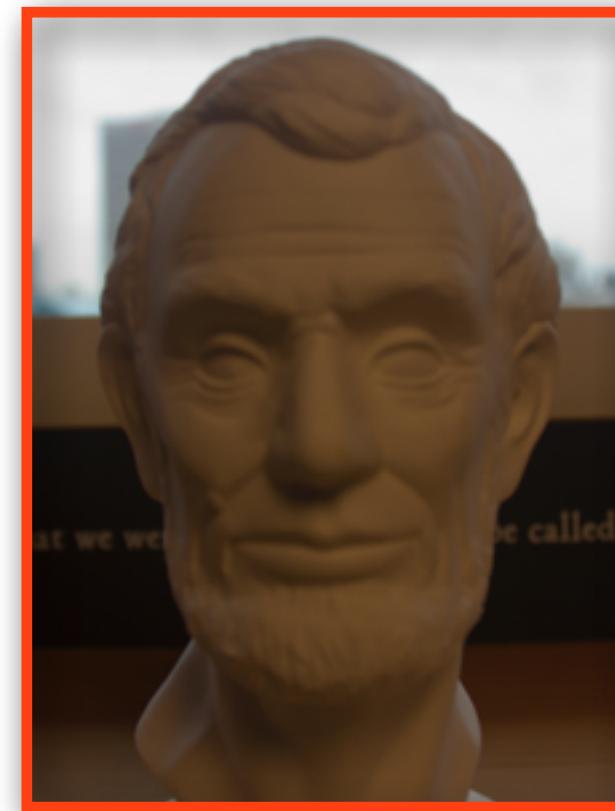
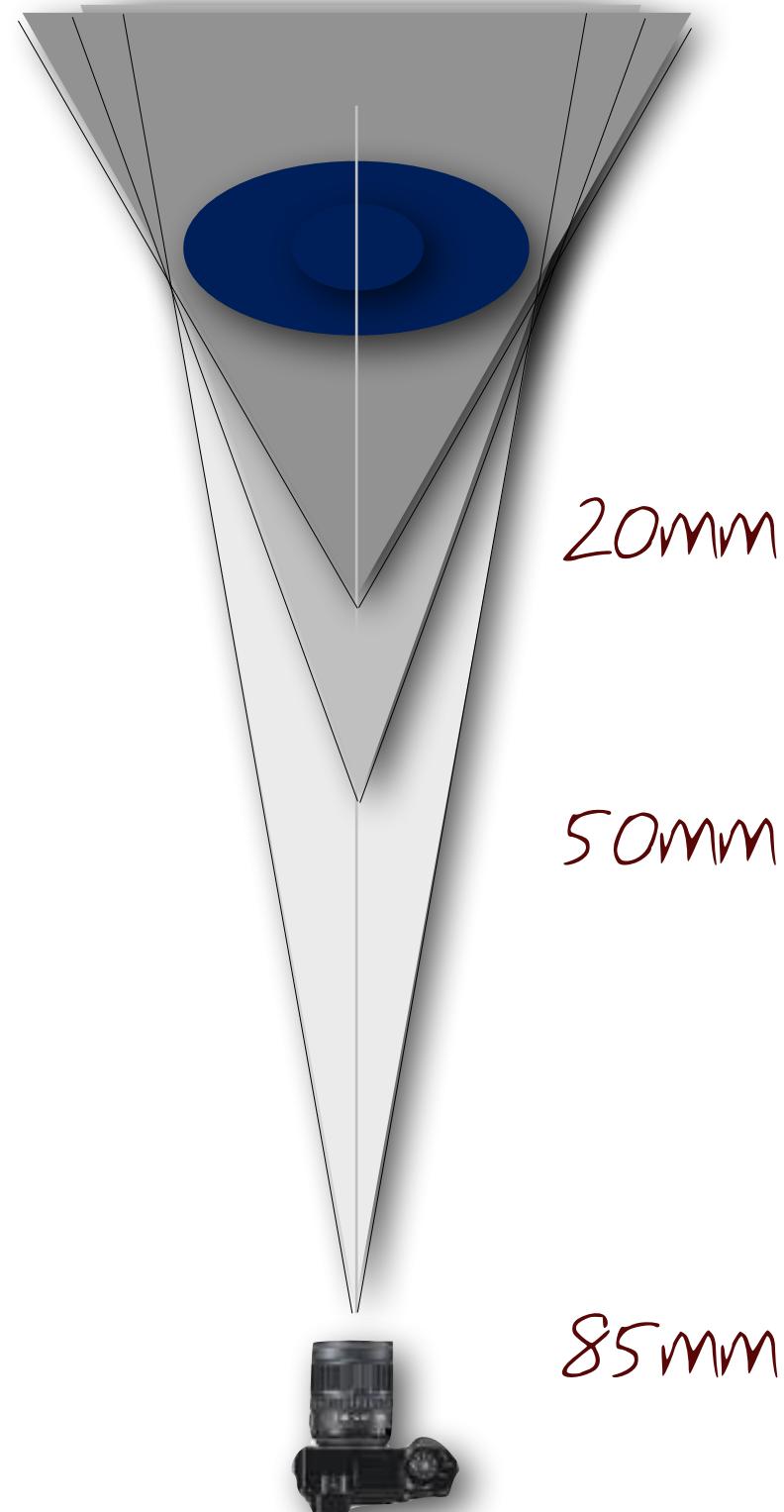


$$x_i = \frac{X_o}{Z_o} f$$

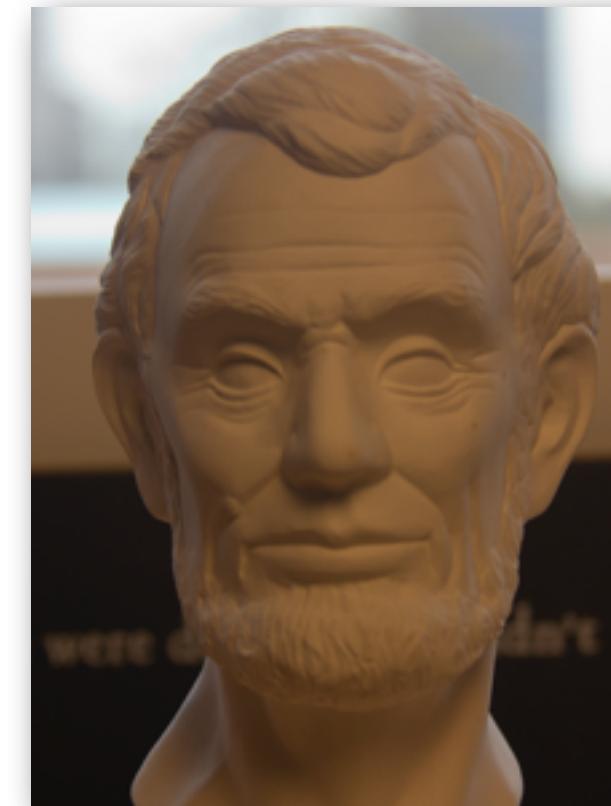
$$y_i = \frac{Y_o}{Z_o} f$$



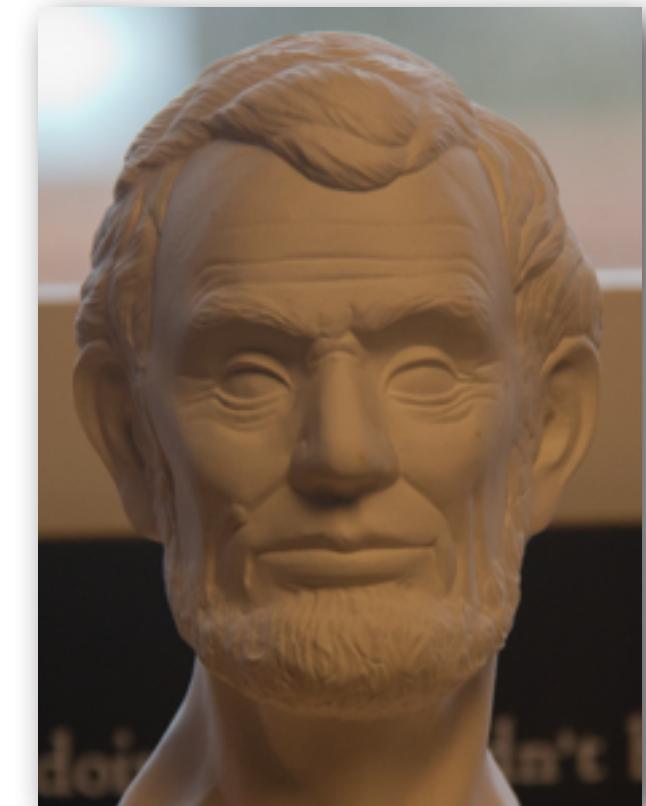
Focal Length for Portraits



20
mm



50
mm



85
mm

Traditionally, 75-135mm focal length
(I prefer 85mm) are used for Portraits

Summary



- * Brought together the concepts of Focal Length, FOV and Sensor Size
- * Discussed the impact of Focal Length on Image Formation/Capture
- * Explained Perspective Projection for a camera with a Focal Length

Neat Class

- * Camera
- * Exposure Triangle
- * Aperture
- * Shutter Speed
- * ISO





Credits

- * For more information, see
 - * Hecht, E. (2002) Optics, 4th ed. Reading, MA: Addison-Wesley and
 - * London, B., Stone, J., & Upton, J. (2011), Photography, 10th ed. Upper Saddle River, NJ: Prentice Hall.
- * Some images retrieved from
 - * <http://commons.wikimedia.org/>.
 - * <http://electronics.howstuffworks.com/camera1.htm>
 - * List available on website.
- * Some Slides adapted from mark Levoy.
- * Photos by Henrik Christensen and Irfan Essa.

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Cameras, Optics, and Sensors

* Cameras: Aperture, Shutter speed Controls of a Camera.



Lesson
Objectives

Exposure Triangle

- * Aperture
- * Shutter Speed
- * ISO

Recall: Focal Length vs. Viewpoint



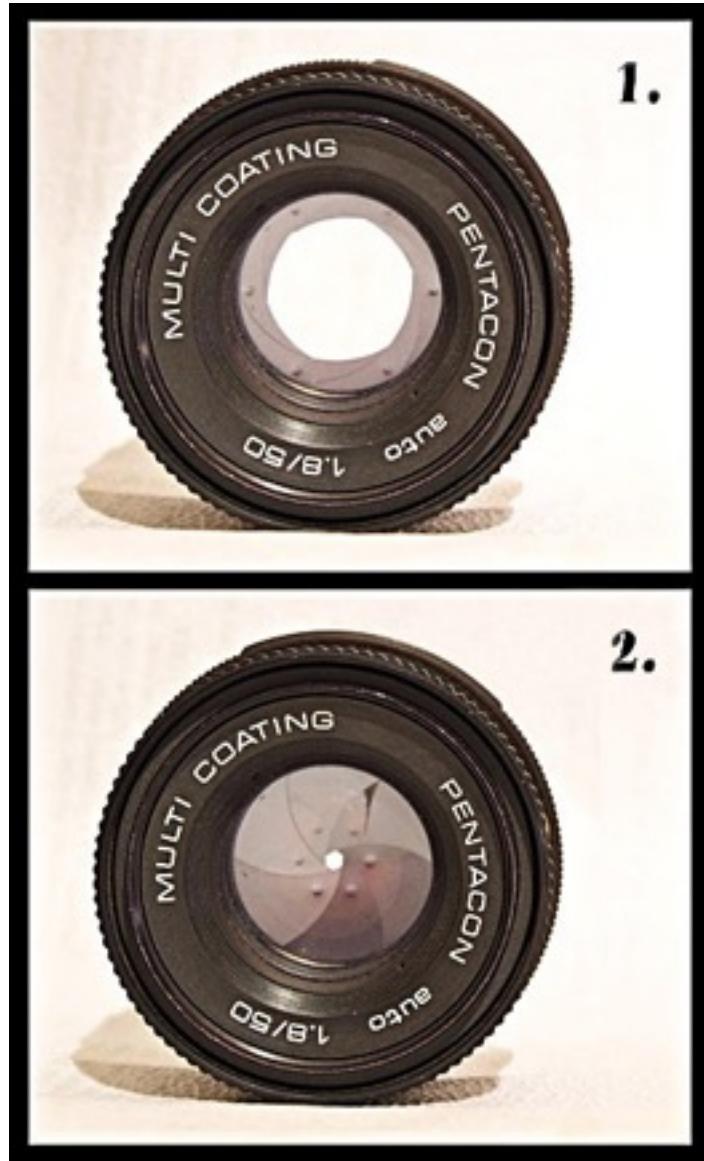
$f = 18\text{mm}$, 35mm sensor
1st Subject: 0.5m away
2nd Subject: 2.0m away



$f = 180\text{mm}$, 35mm sensor
1st Subject: 3.0m away
2nd Subject: 4.5m away

- * Changing focal length allows us to move back, and still capture the scene
- * Changing viewpoint causes perspective changes

Exposure (H)



Exposure = Irradiance \times Time

$$H = E * T$$

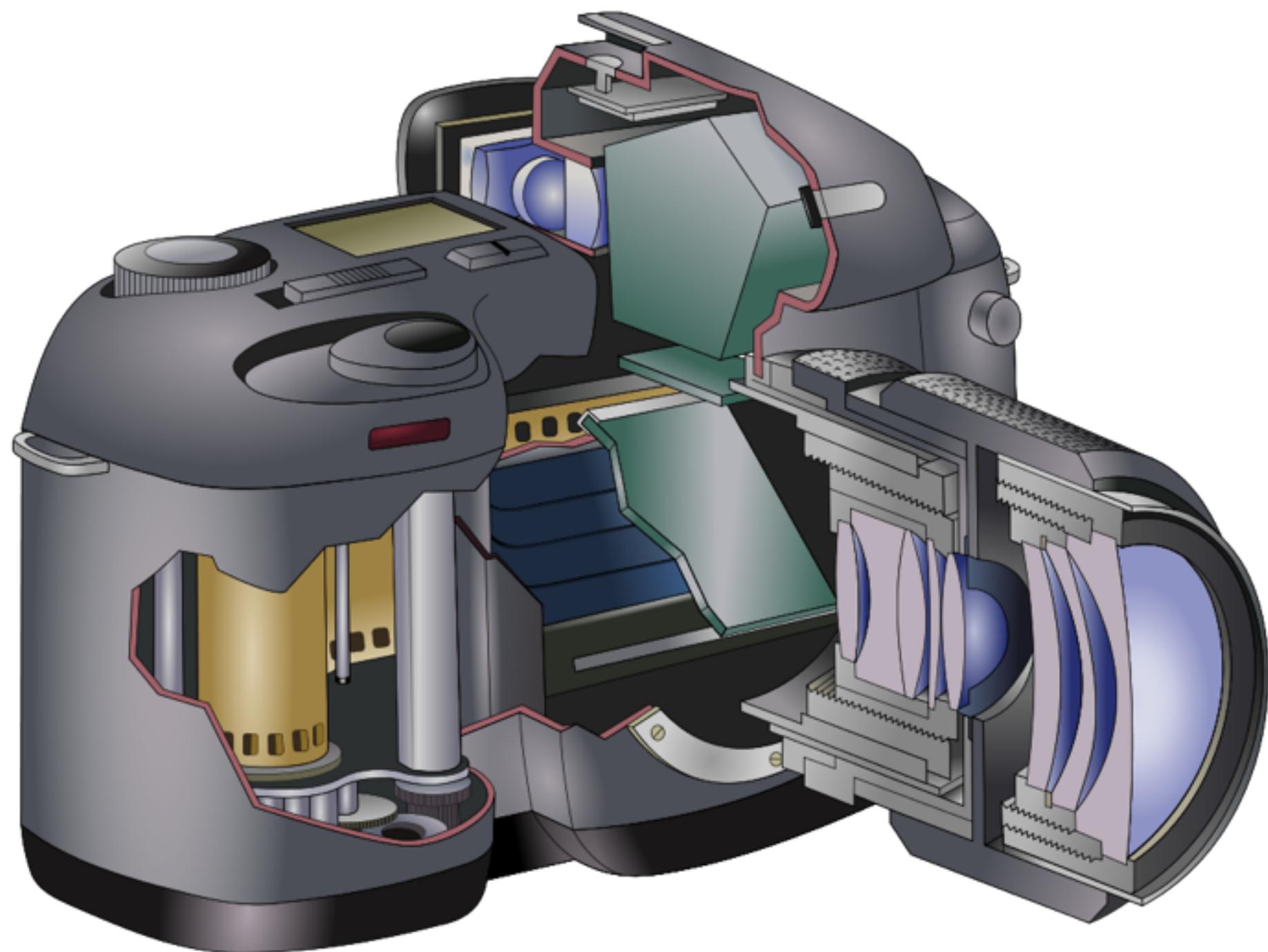
Irradiance (E)

- * Amount of light falling on a unit area of sensor per second
- * Controlled by lens aperture

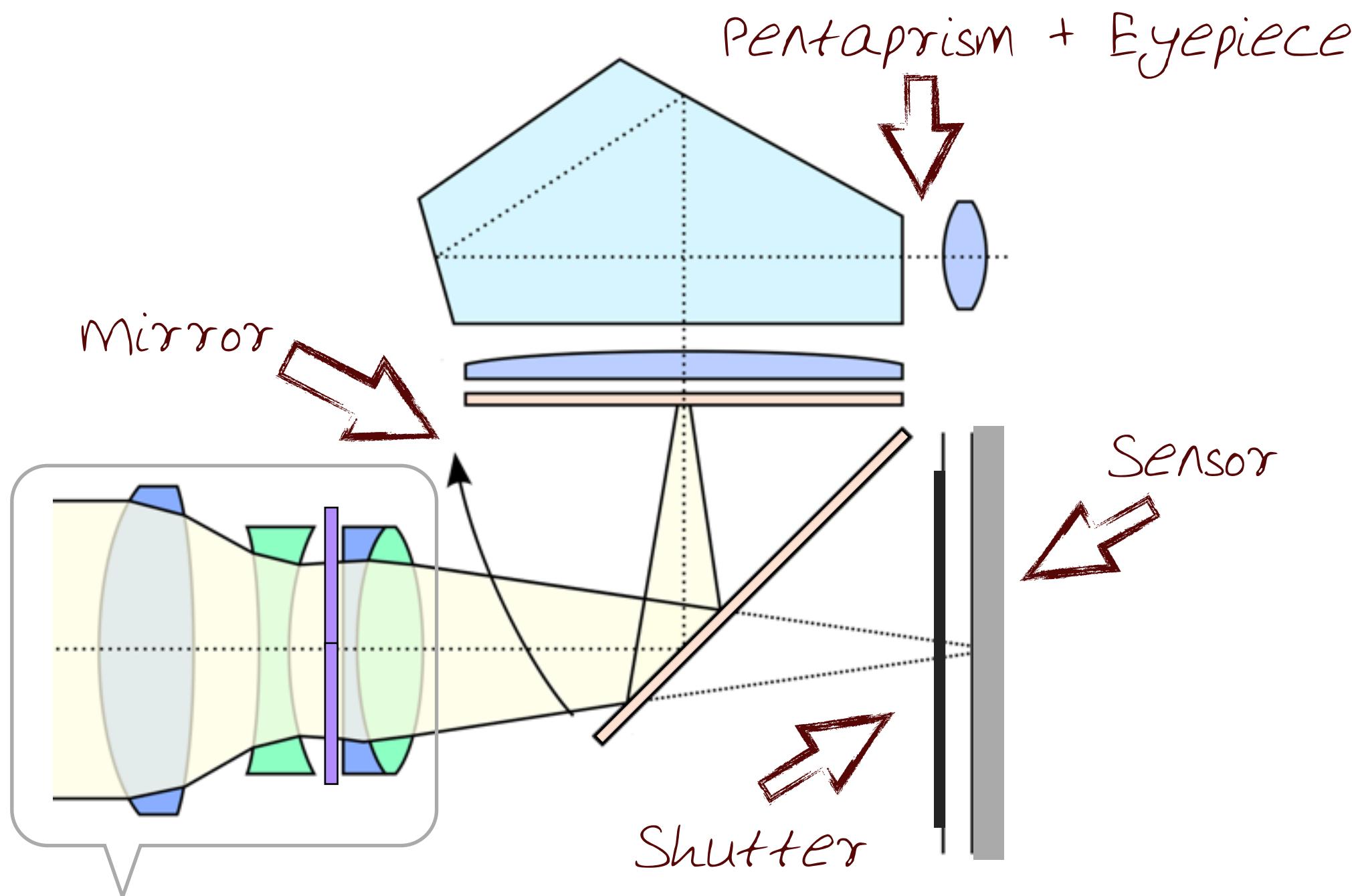
Exposure Time (T)

- * How long the shutter is kept open

Inside a Camera (an SLR)



Inside a Camera (an SLR)



Lens Assembly (includes Aperture)

Adapted from commons.wikimedia.org/

Shutter Speed (1st Example)



- * Amount of time the sensor is exposed to light
- * Usually denoted in fractions of a second ($1/2000, 1/1000, \dots, 1/250, \dots, 1/60, \dots, 1/15, \dots, 15, 30, \text{Bulb}$)
- * Effects of Motion Blur to Streaks

http://commons.wikimedia.org/wiki/File:Shutter_speed_waterfall.gif

Shutter Speed (2nd example)



1/125 second

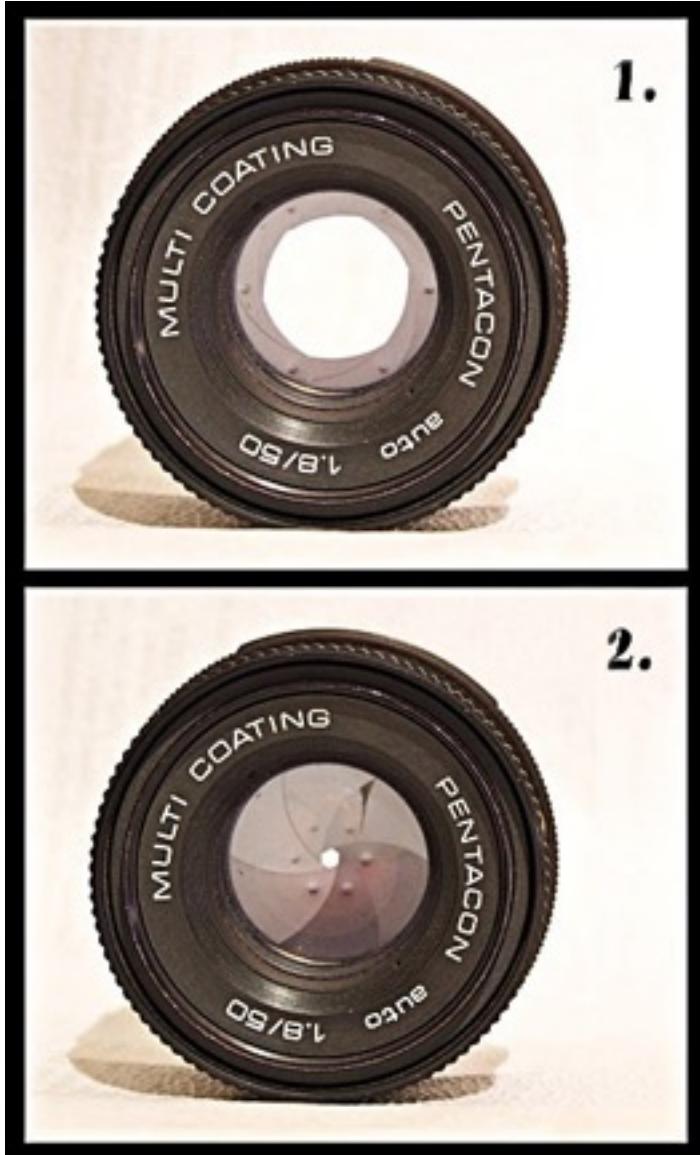
<http://everydayhdr.com/wp-content/uploads/2012/09/Waterfall-Aperture-Compare.jpg>

Shutter Speed (3rd Example)



<http://commons.wikimedia.org/wiki/File:Windflower-05237-nevit.JPG>

Aperture



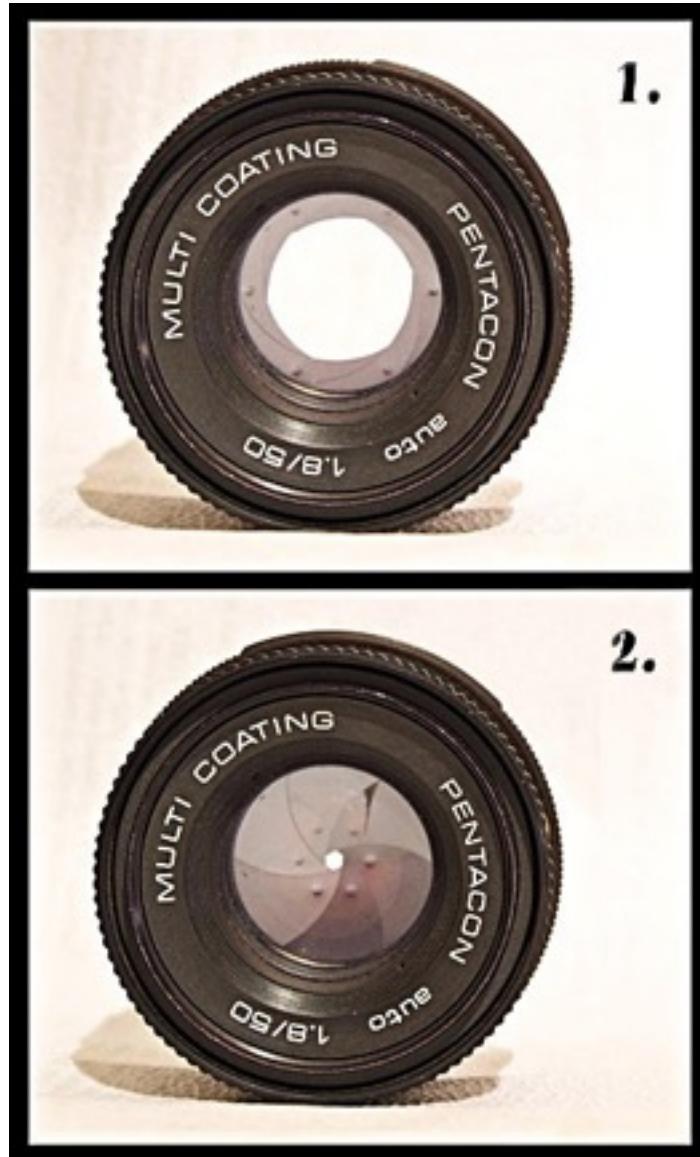
commons.wikimedia.org

Irradiance on Sensor → The amount of light captured is proportional to the Area of the Aperture (opening):

$$\text{Area} = \pi \left(\frac{f}{2N} \right)^2$$

- * f is the focal length. What is the diameter of the Aperture?
- * Aperture Number N usually written as f/N

Aperture

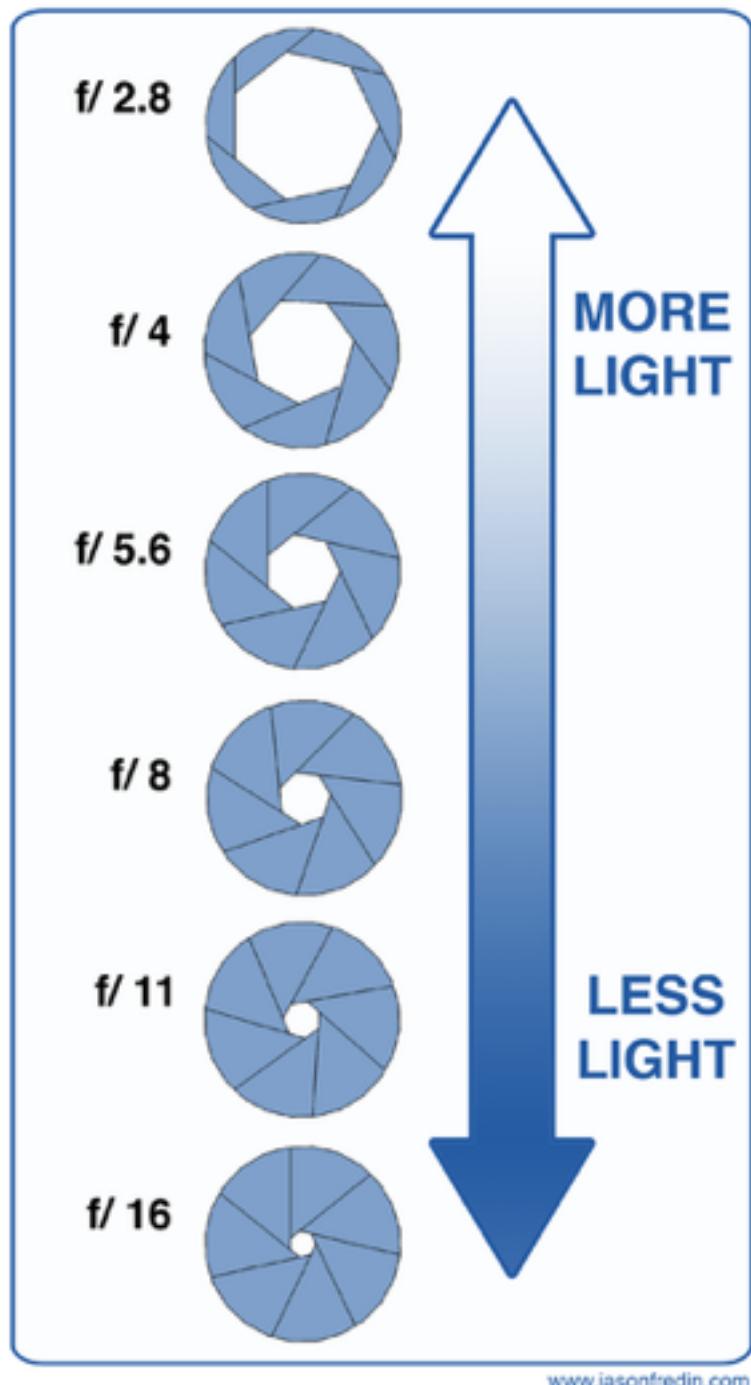


commons.wikimedia.org

- * Focal length: f
- * Aperture Number: N (usually written f/N)
- * Aperture Number gives irradiance
irrespective of the lens in use
$$\text{Area} = \pi \left(\frac{r^2}{2N} \right)$$
- * $f/2.0$ on 50mm lens \rightarrow aperture = 25mm
- * $f/2.0$ on 200mm lens \rightarrow aperture = 100mm
- * Low f-number (N) on telephoto lens
means BIG lens

Aperture

$$Area = \pi \left(\frac{f}{2N} \right)^2$$



- * Doubling N reduces A by $4X$, and therefore reduces light by $4X$
- * from $f/2.8$ to $f/5.6$ cuts light by $4X$
- * to cut light by $2X$, increase N by $\sqrt{2}$

f/22
f/18
f/14
f/11
f/8
f/5.6
f/4.0
f/3.5

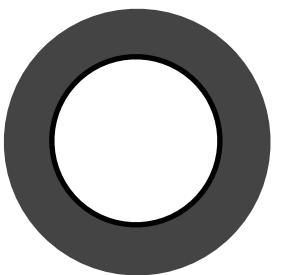




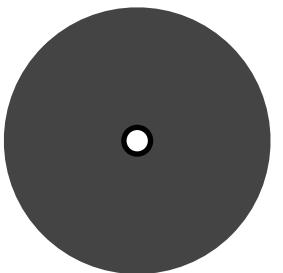
f/22

f/11

f/3.5



$f/3.5$

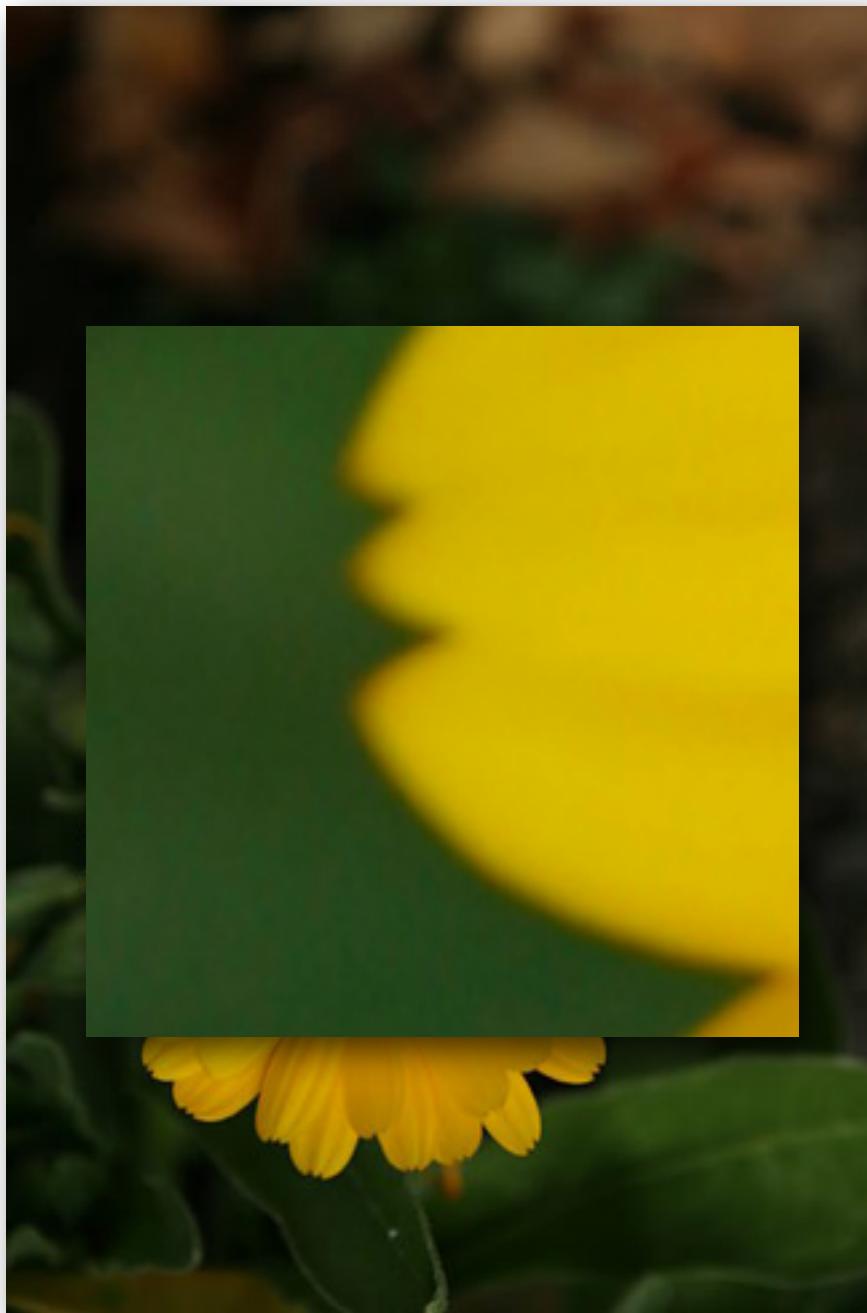


$f/22$

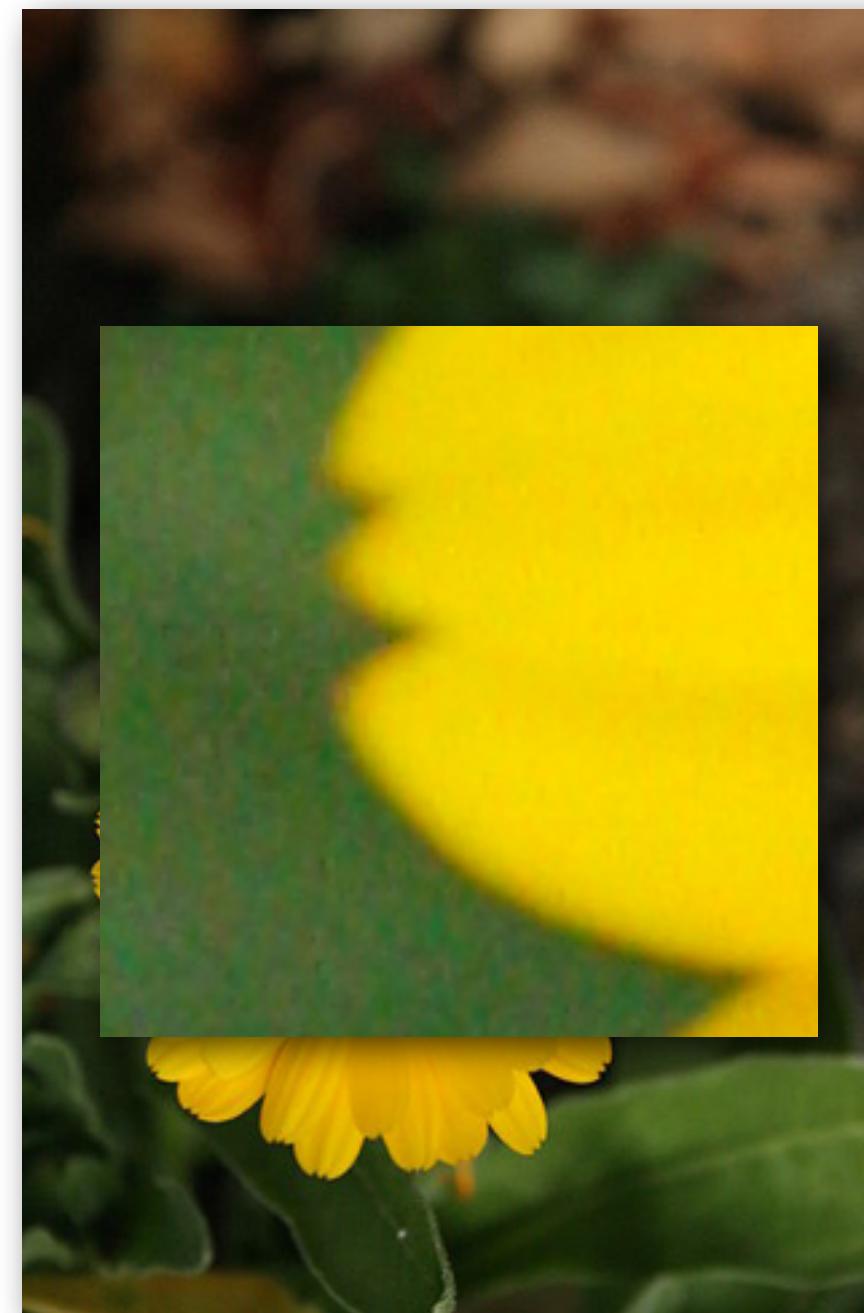
Photographic Values of Aperture/Shutter/Focal L.



ISO (Sensitivity)



ISO 100



ISO 1600

- * Third Variable in getting the right Exposure
- * Film: Sensitivity vs. Grain (of film)
- * Digital: Sensitivity vs. Noise (of sensor)
- * Linear: 200 ISO needs half the light of 100 ISO

Images: commons.wikimedia.org

f/15.6



1/10



1/20



1/40



f/14.0

f/15.0

f/17.1

f/19.0

f/13.0

f/20.0

1/100

f/5.6



1/10

1/20

1/40

1/160

1/320

1/640

1/1250

1/2500

100

200

800

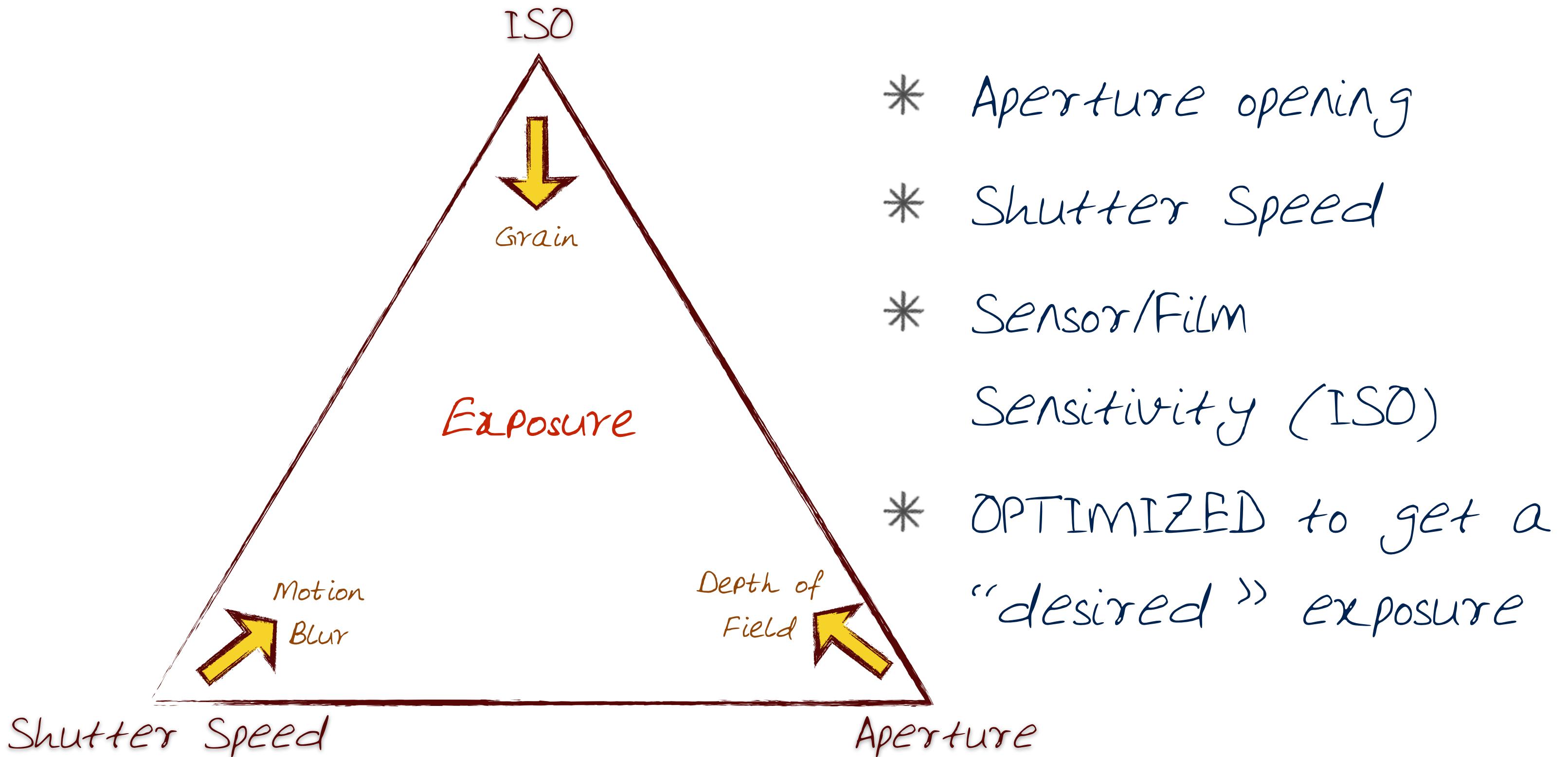
1600

3200

6400

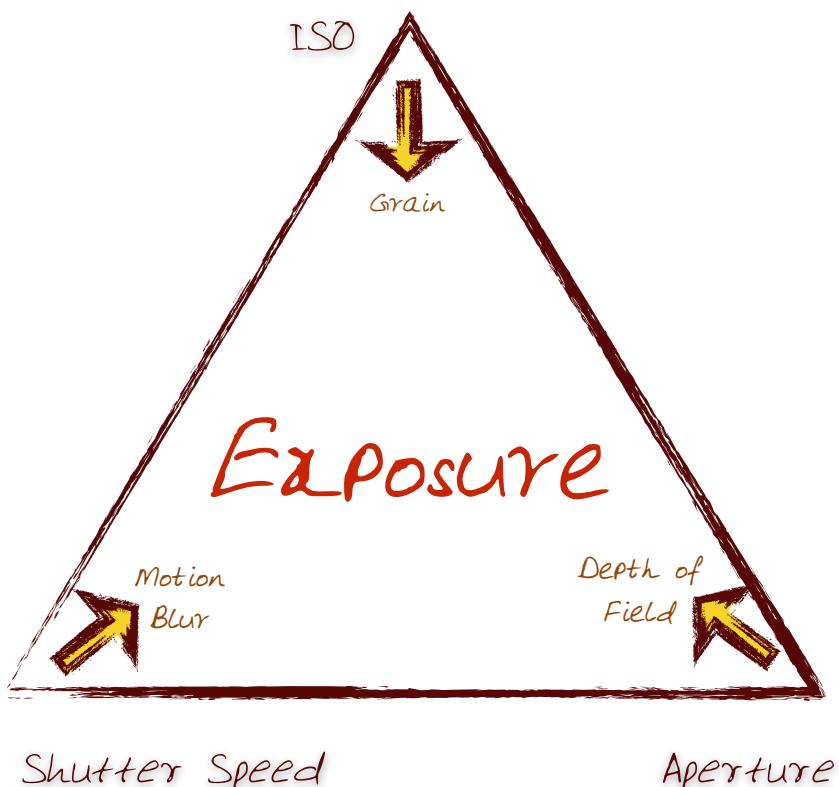
1/100

Exposure Triangle



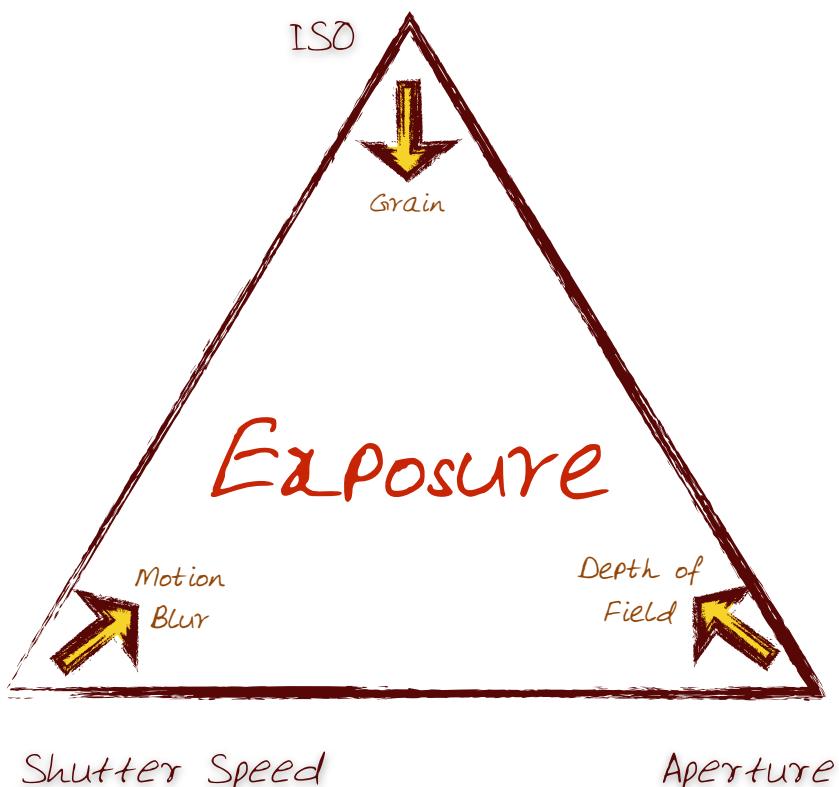
Recap: Exposure

- * $\text{Exposure } (H) = \text{Irradiance } (E) \times \text{Time } (T)$
- * Irradiance (E): Controlled by Aperture opening
- * Lowering by $1/f$ stop doubles H (as Aperture opens more)
- * Lowering by $2/f$ stops doubles depth of field (DoF).



Recap: Exposure

- * Exposure (H) = Irradiance (E) \times Time (T)
- * Exposure Time (T): Controlled by Shutter Speed
 - * Doubling T doubles H
 - * Doubling T doubles Motion Blur
- * ISO: Doubling ISO needs half the light



Summary



- * Presented how a camera operates
- * Brought together the concepts Aperture Opening, Shutter Speed and Film Sensitivity (ISO) for optimizing Photographic Exposure
- * Discussed the Exposure Triangle and how it combines various aspects of photography

Neat Class

Cameras' Sensors



Credits



- * For more information, see
 - * Hecht, E. (2002), Optics, 4th ed. Reading, MA: Addison-Wesley and
 - * London, B., Stone, J., & Upton, J. (2011), Photography, 10th ed. Upper Saddle River, NJ: Prentice Hall.
- * Some images retrieved from
 - * <http://commons.wikimedia.org/>.
- * List will be available on website.
- * Some Slides adapted from mark LevoY.

Computational Photography

- * Study the basics of computation and its impact on the entire workflow of photography, from capturing, manipulating and collaborating on, and sharing photographs.



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Cameras, Optics, Lenses, and Sensors

- * Cameras: Sensors (and Film),
where Rays of Light become
Pixels



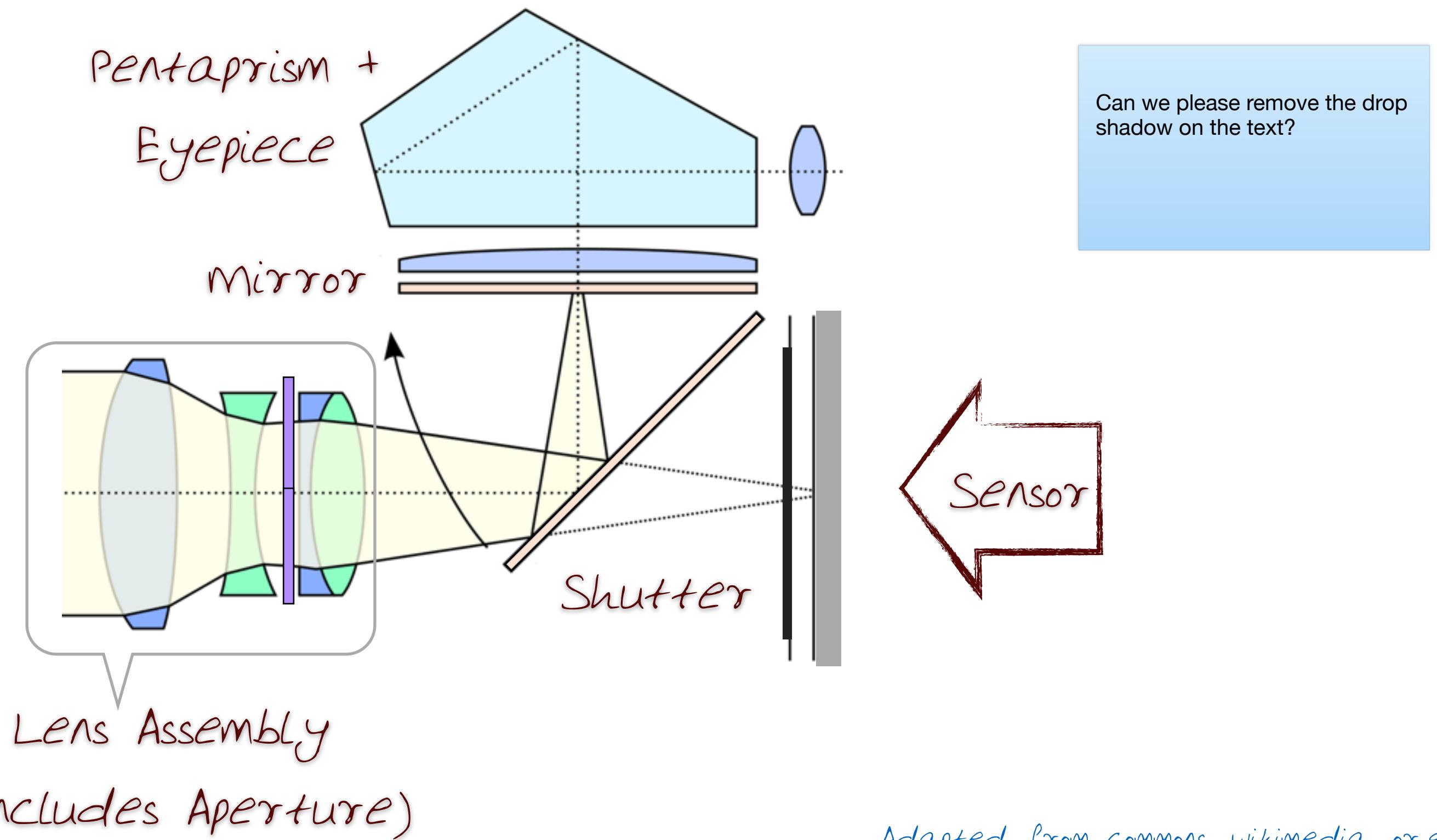
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Lesson Objectives

1. Photographic Processes for Digital and Film Capture
2. Eight layers of Color Film
3. Five layers of a CCD
4. Differences between a CCD and CMOS Sensor
5. Two benefits of using the Camera Raw Format

Recall: Inside a Camera (an SLR)



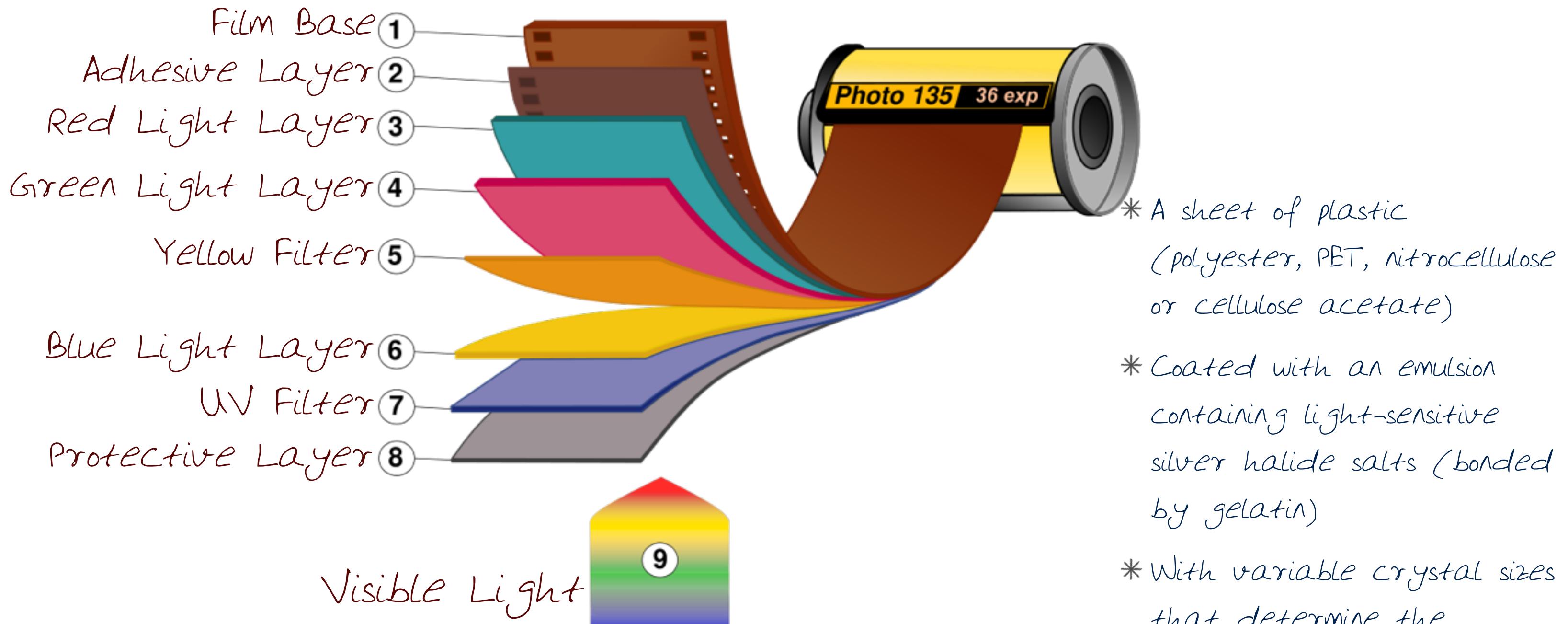
Adapted from commons.wikimedia.org/

Film vs. Digital

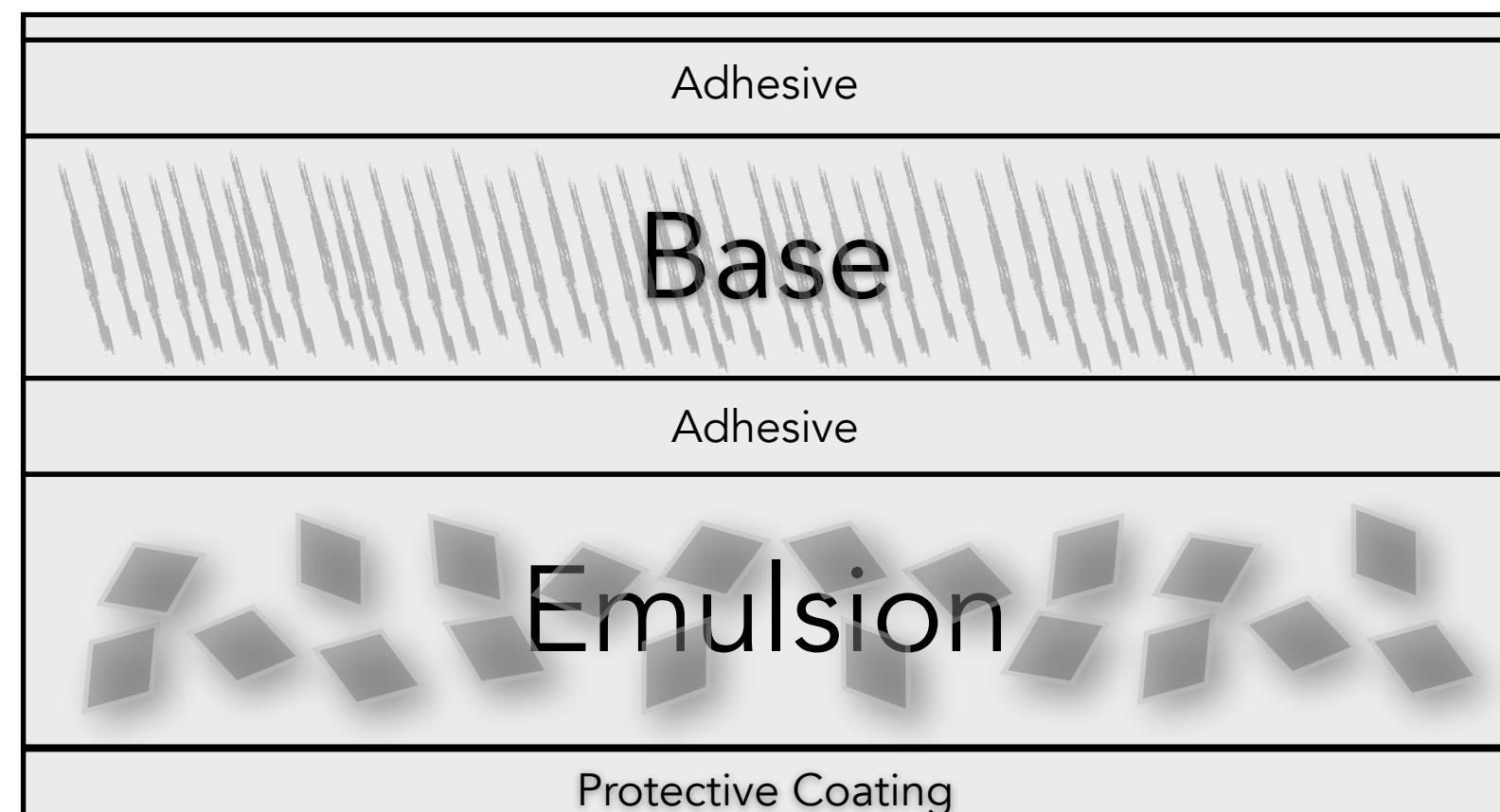
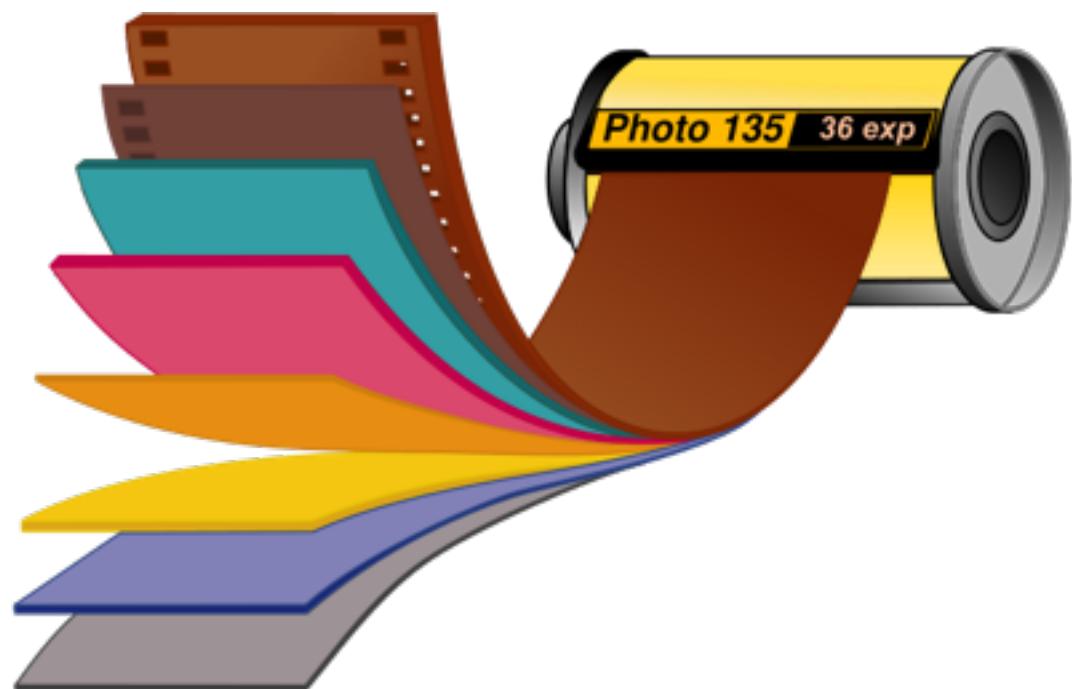


- * Film and Digital Cameras are the same
- * There have been significant improvements in actuators, and lenses
- * Difference is how light is trapped and preserved
- * Chemical process for Film, and Electronic for Digital capture the moment in Time and Space

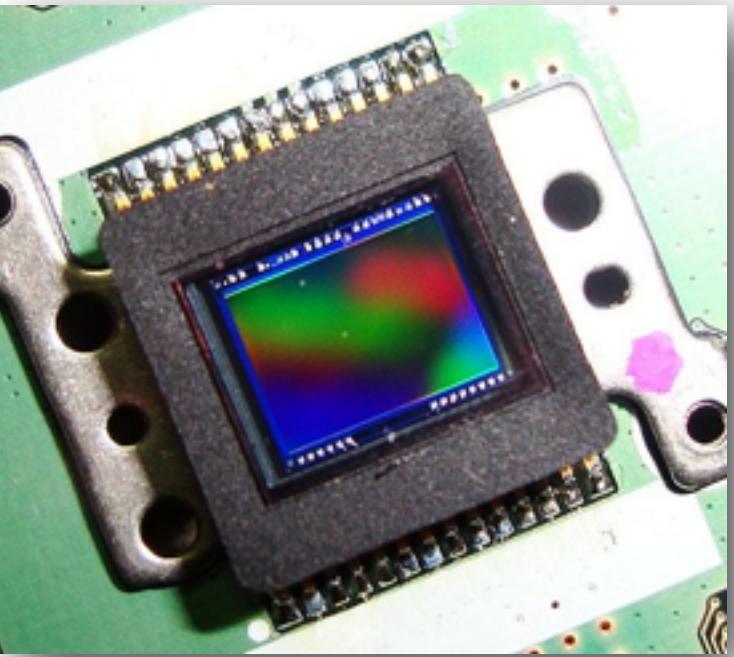
Film: Reaction between Light and Chemicals



Film: Reaction Between Light and Chemicals



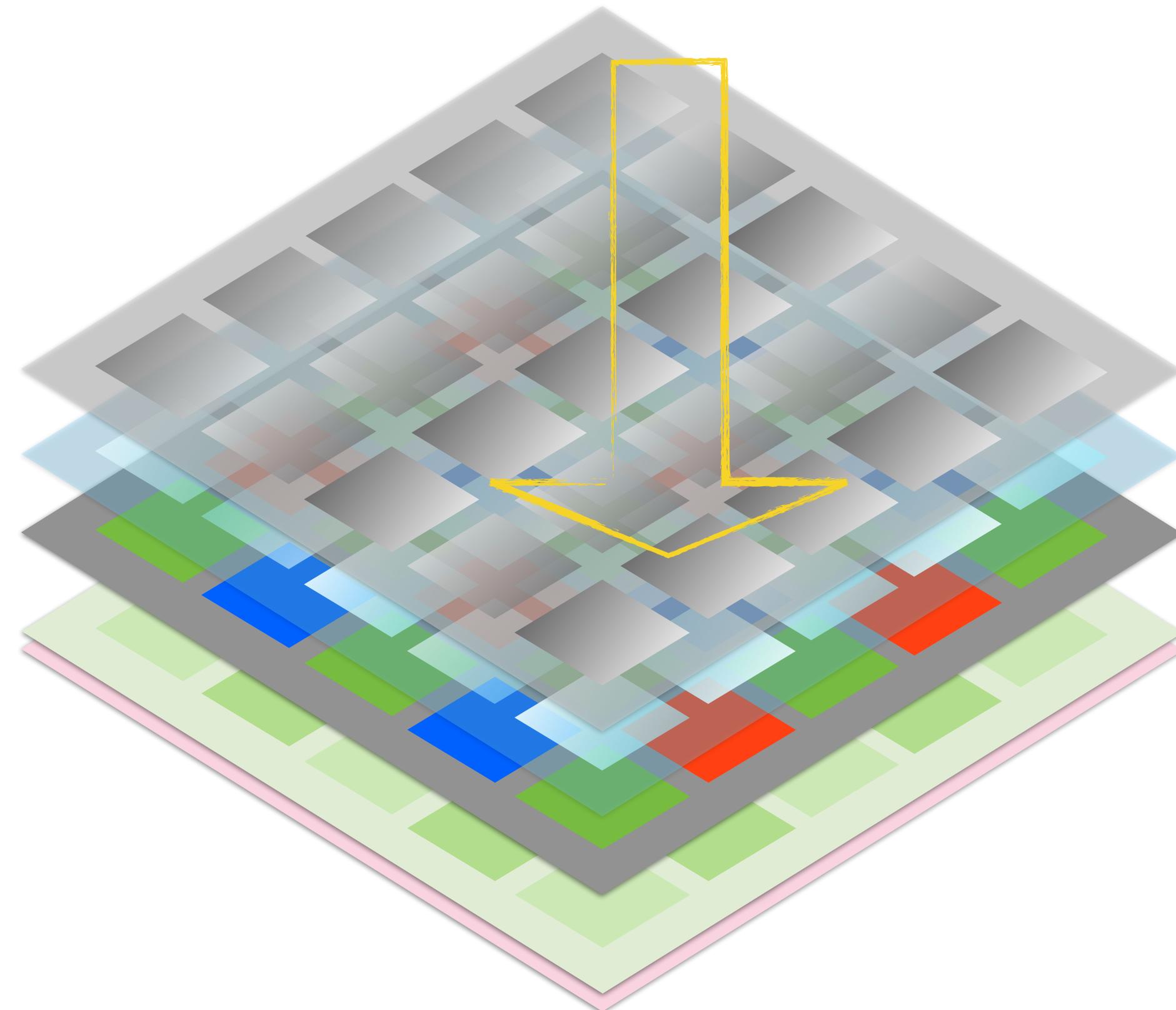
Digital: Converting Light to Data



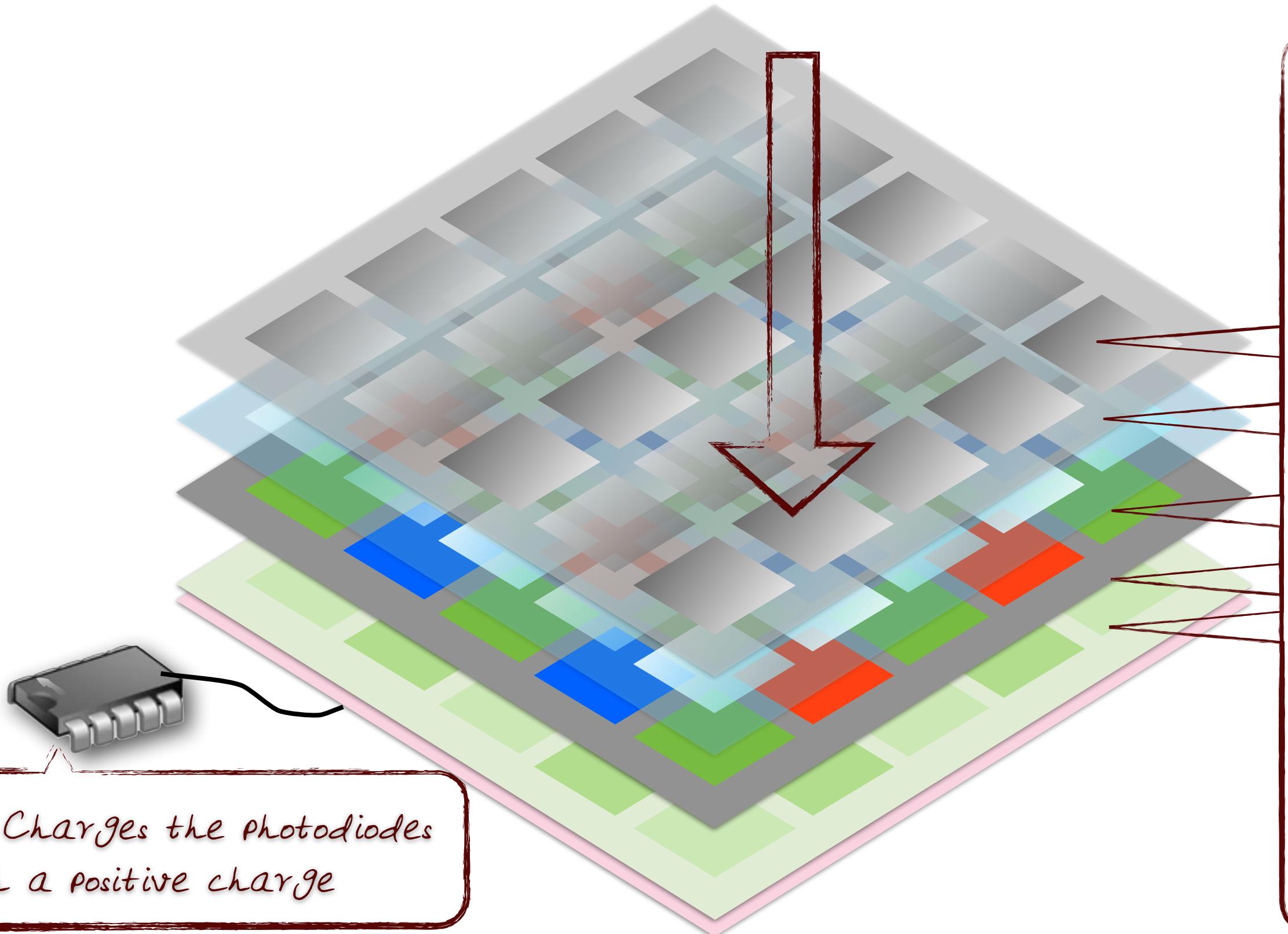
Smith and Boyle

- * CCD: Charge-Coupled Device, a device for converting electrical charge, into a digital value
- * Pixels are represented by capacitors, which convert and store incoming photons as electron charges
- * Willard Boyle and George E. Smith, 1969 (Won a Nobel Prize in Physics in 2009).

Digital: Converting Light to Data



Digital: Converting Light to Data



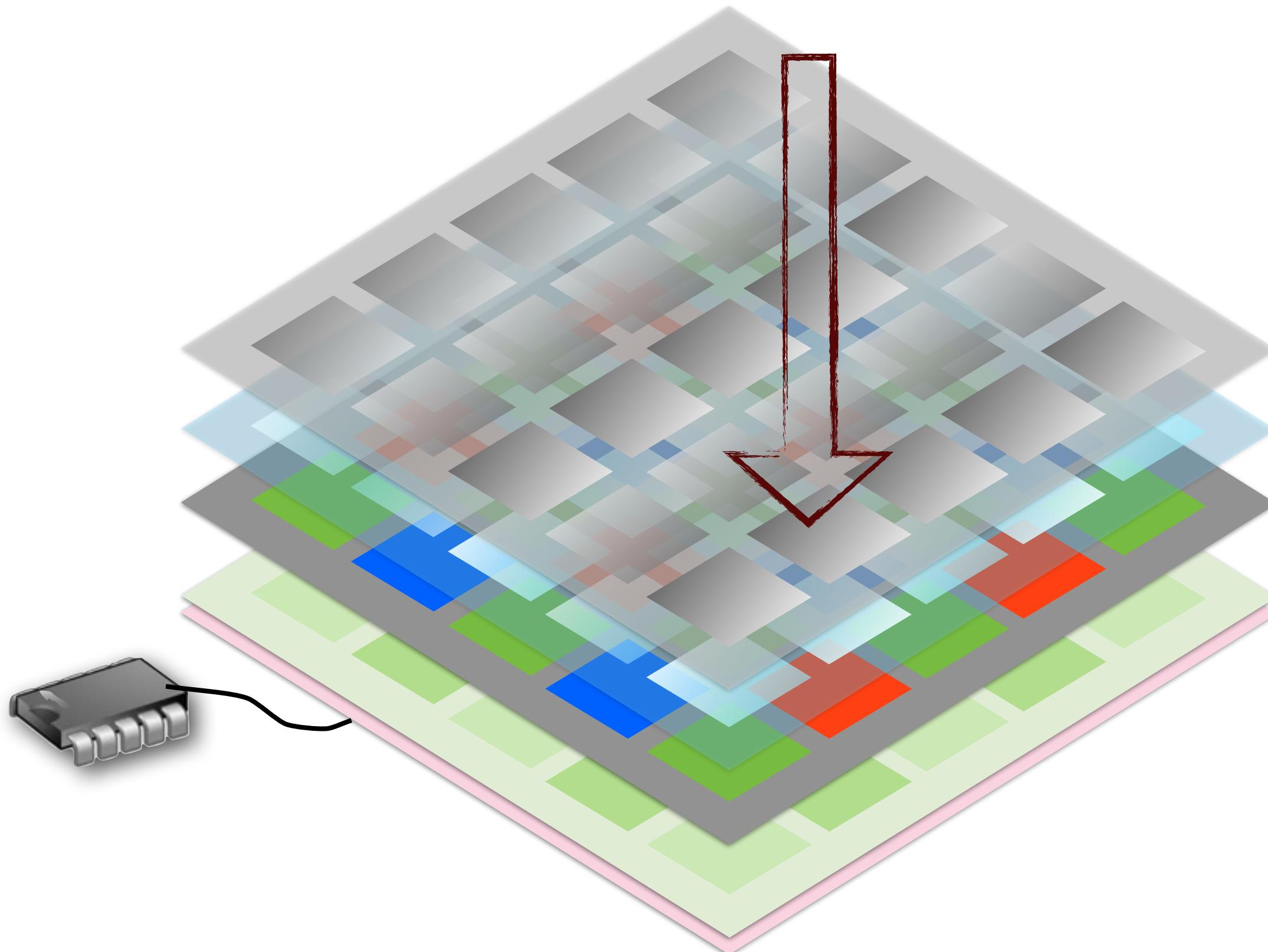
Histogram

Photodiodes
Photo diodes

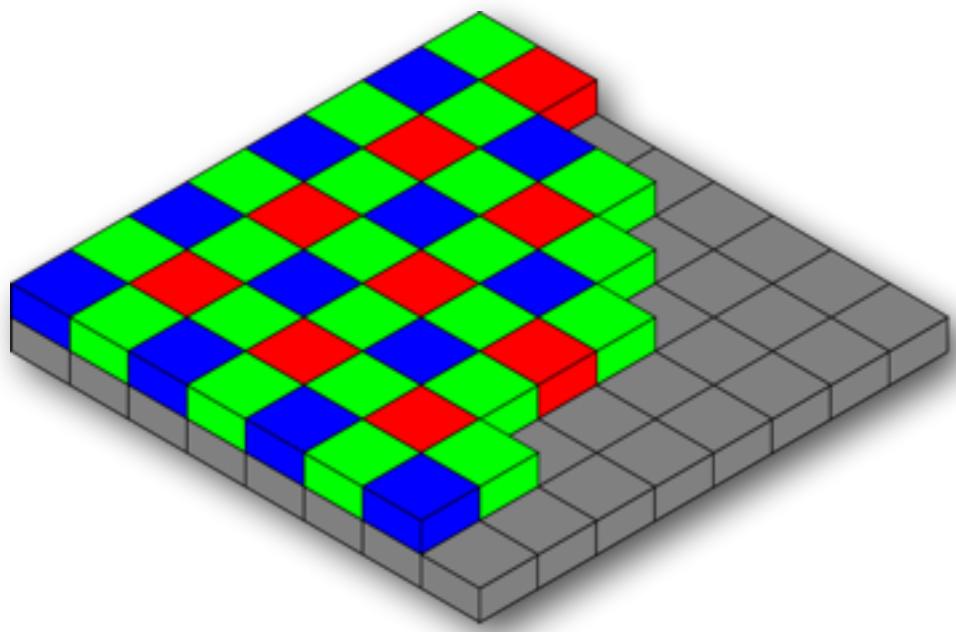
Microlenses
This is where the
Color filtered light
is reflected off of
in light insensitve
is converted
part of the
sensitive parts of the
spectra of the
light into Red
exceptional good
light, green, blue
which is kind of
what kind of
aspects.

reflected off as
backgrounds.

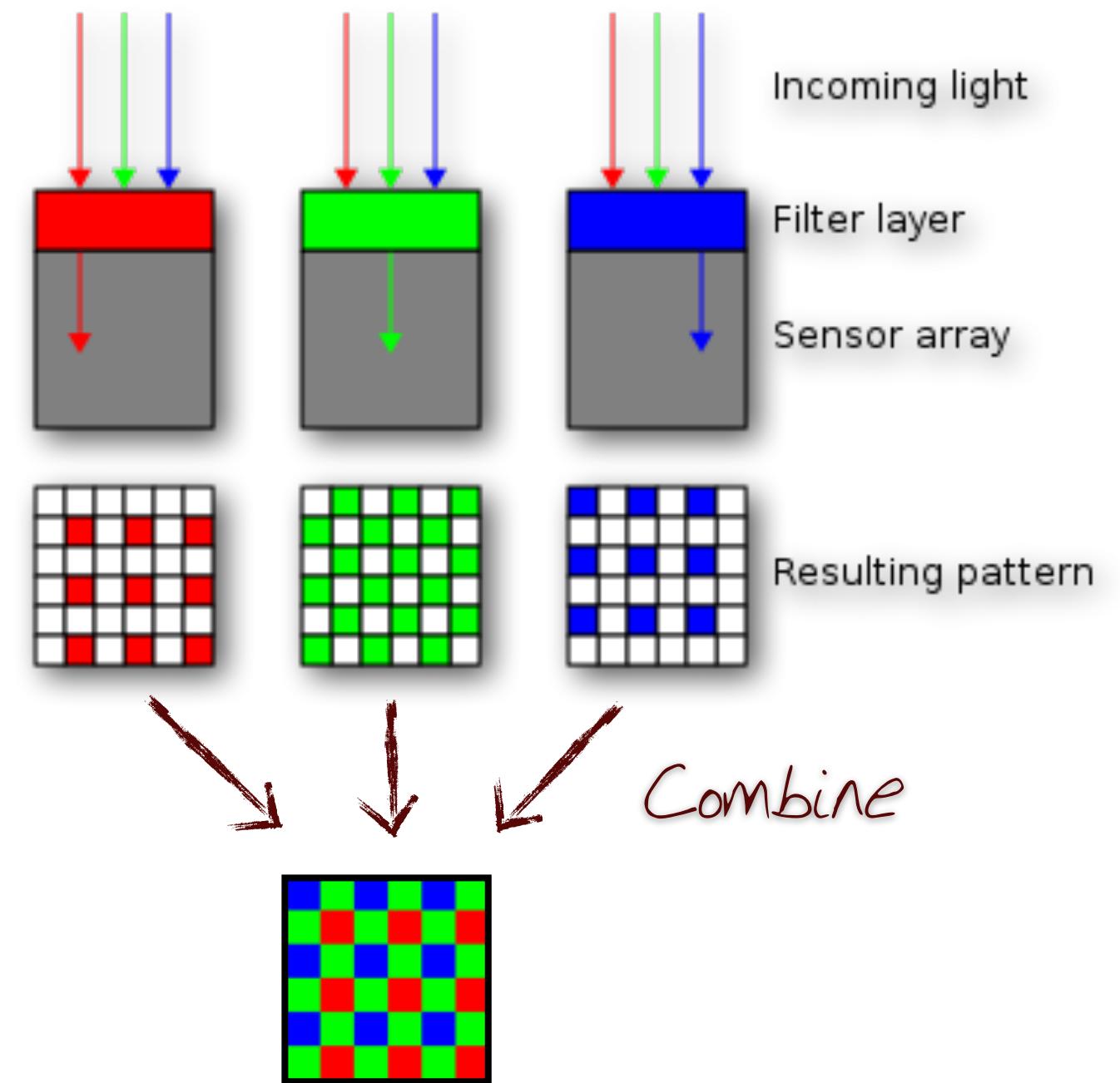
Digital: Converting Light to Data



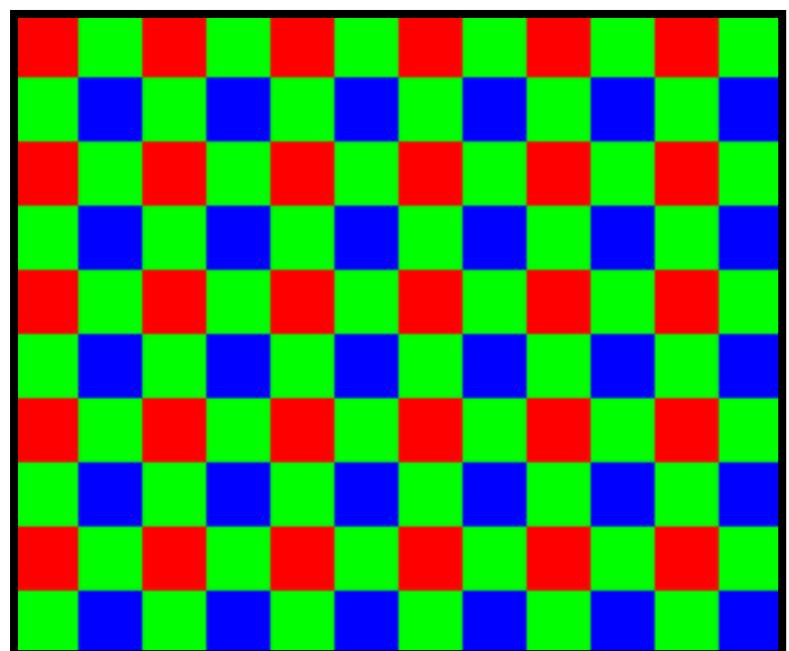
Digital: Converting Light to Data



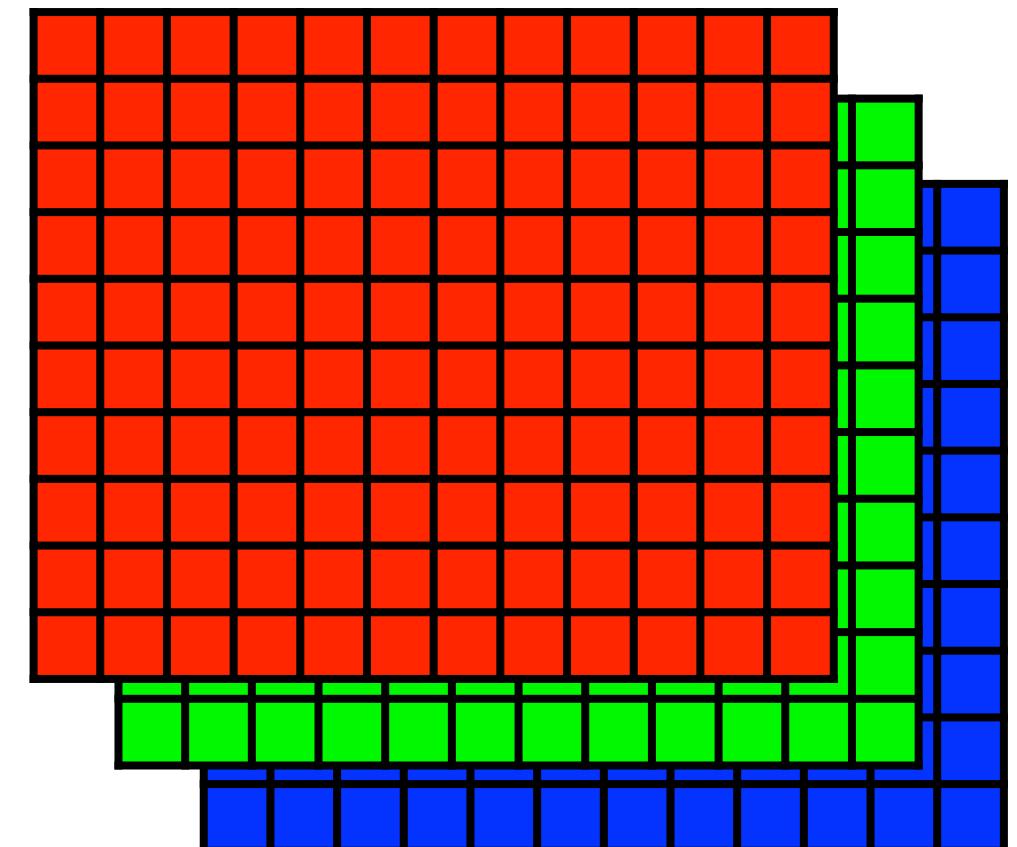
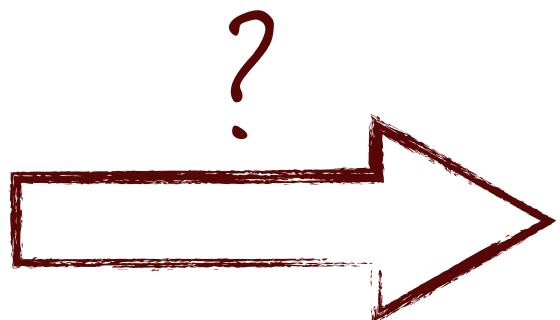
Bayer filter on a sensor



Digital: Converting Light to Data

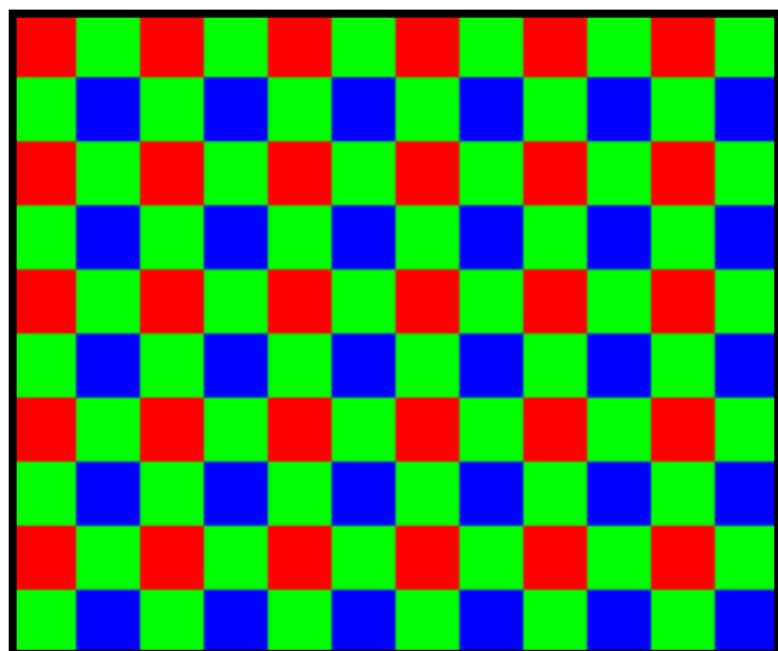


Raw input in Bayer
mosaic format

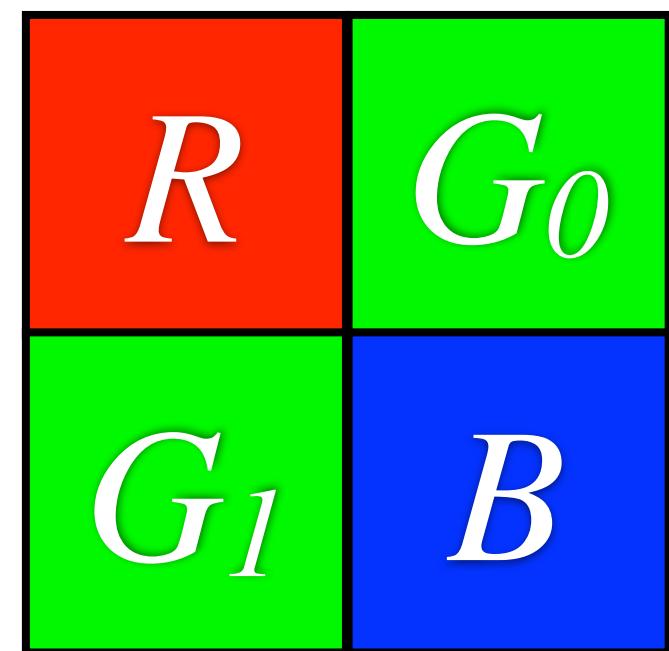


RGB color planes

Bayer to RGB “Demosaicing”

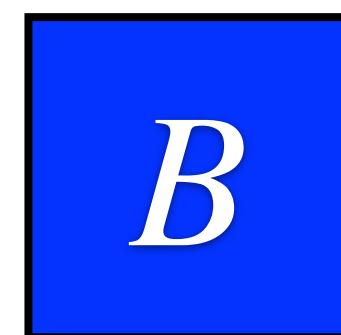
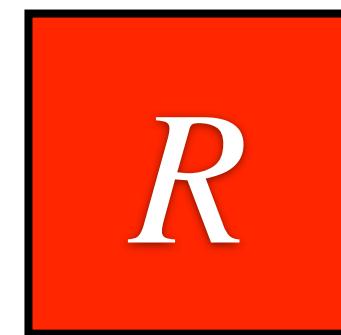


Raw input in Bayer
mosaic format



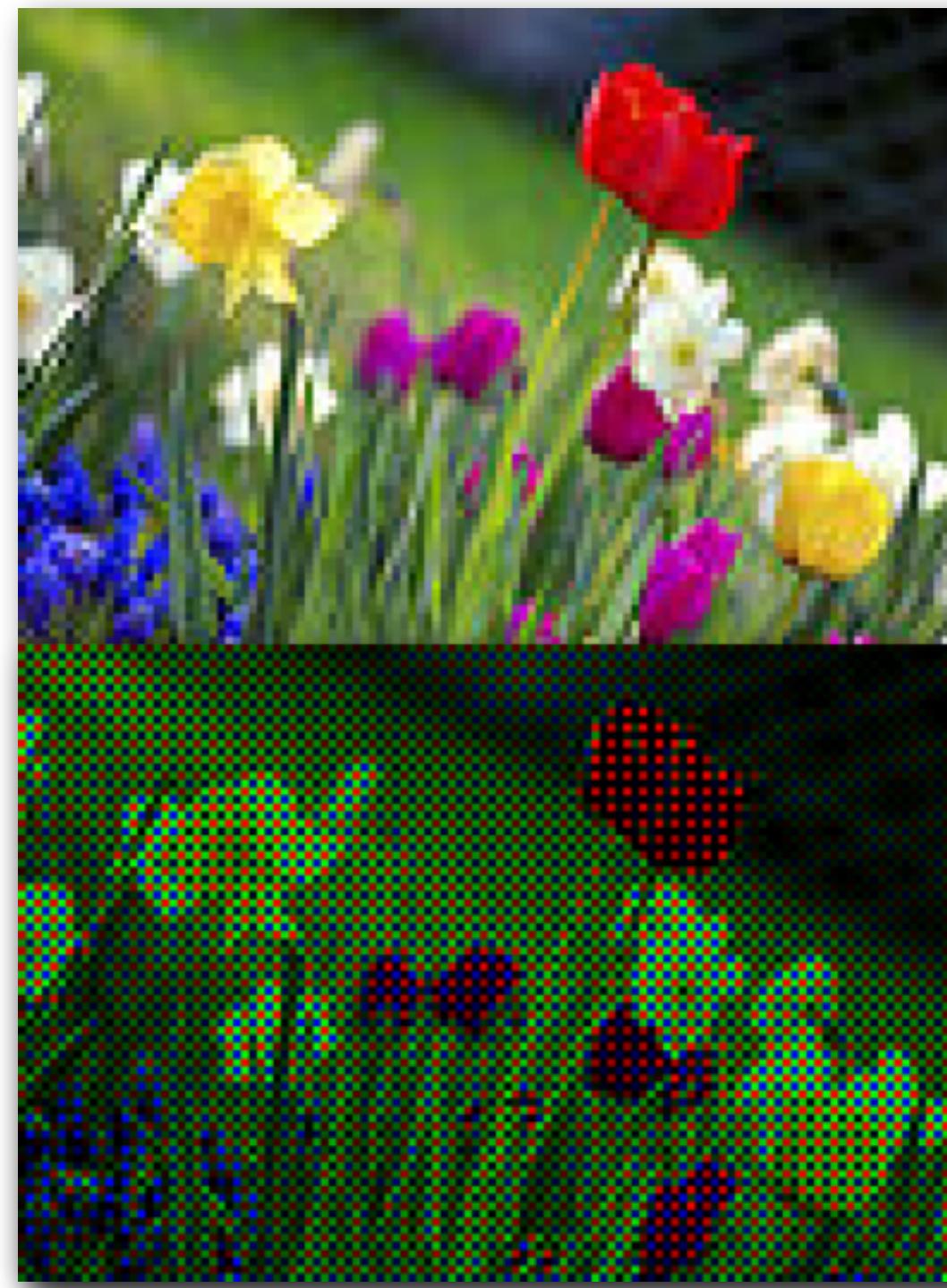
A 4x4 subset

$$R = R \quad G = (G_0 + G_1) / 2 \quad B = B$$



Resulting RGB triple

Digital: Converting Light to Data

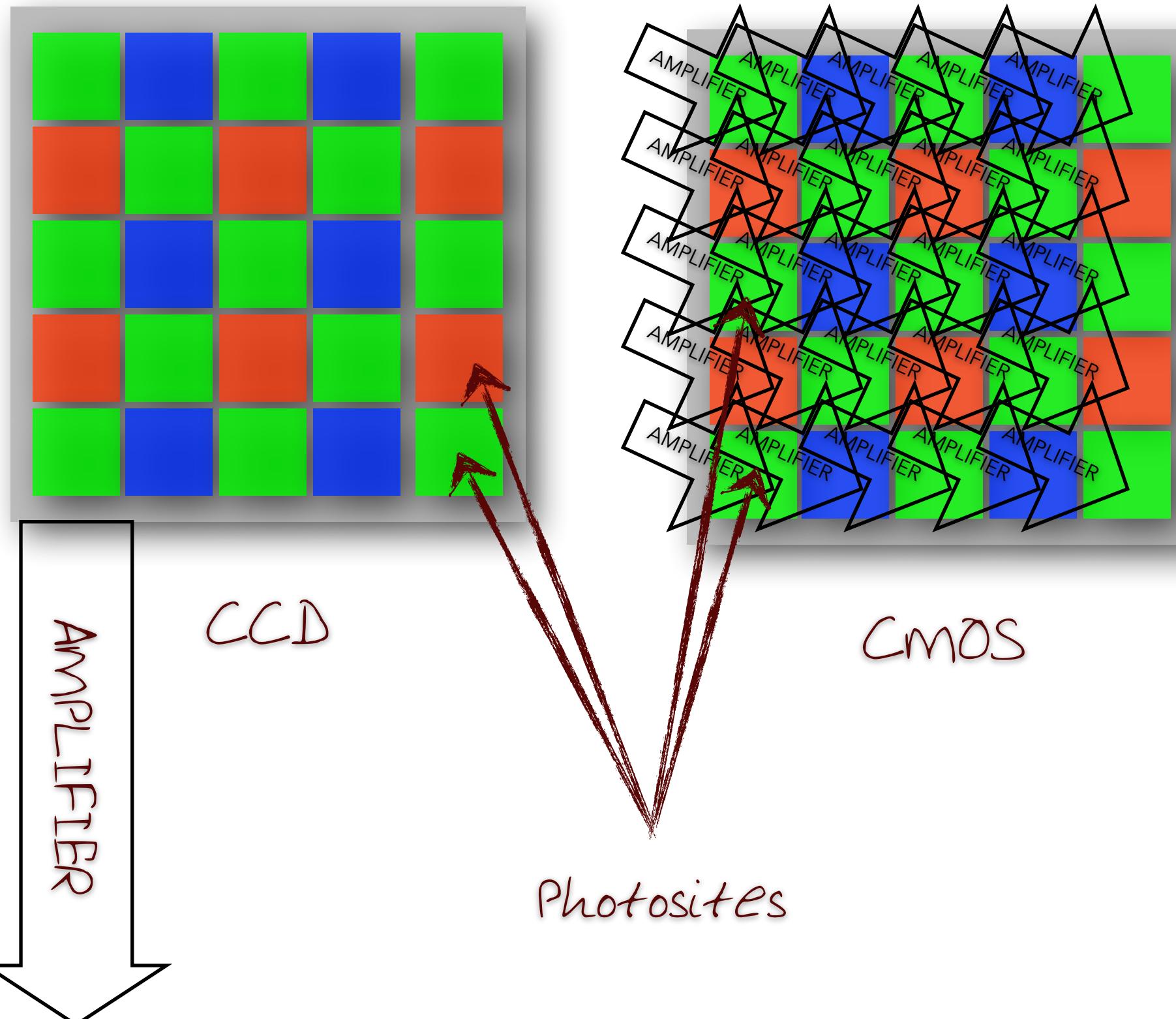


Reconstructed
Image after
Interpolation

Actual Sensor
Information
with Bayer Filter

Images: Wikipedia

CCD vs. CMOS Sensors



- * CMOS: Complementary metal Oxide Semiconductor
- * Photosites in CCD are passive and do no "work"
- * Photosites in CMOS are amplifiers and can do local processing



Camera RAW File Format

- * Contains minimally processed data from the sensor
- * Image encoded in a device-dependent colorspace
- * Captures radiometric characteristics of the scene
- * Viewable image from the camera's sensor data
- * Like a photographic negative
 - * has a wider dynamic range or color; preserves most of the information of the captured image



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Summary



- * Described the Photographic Processes for Digital and Film Capture
- * Presented how sensors work in cameras
- * Discussed how a Color filter works in a sensor
- * Presented CCD and CMOS sensors
- * Discussed the benefits of the Camera Raw Format

Neat Class

- * Doing Computational Photography
- * Blending/Fading
- * Panoramas
- * High-Dynamic Range Imaging





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 - * White, R. (2006), How Digital Photography Works, Que Publishers
- * Some images retrieved from
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