



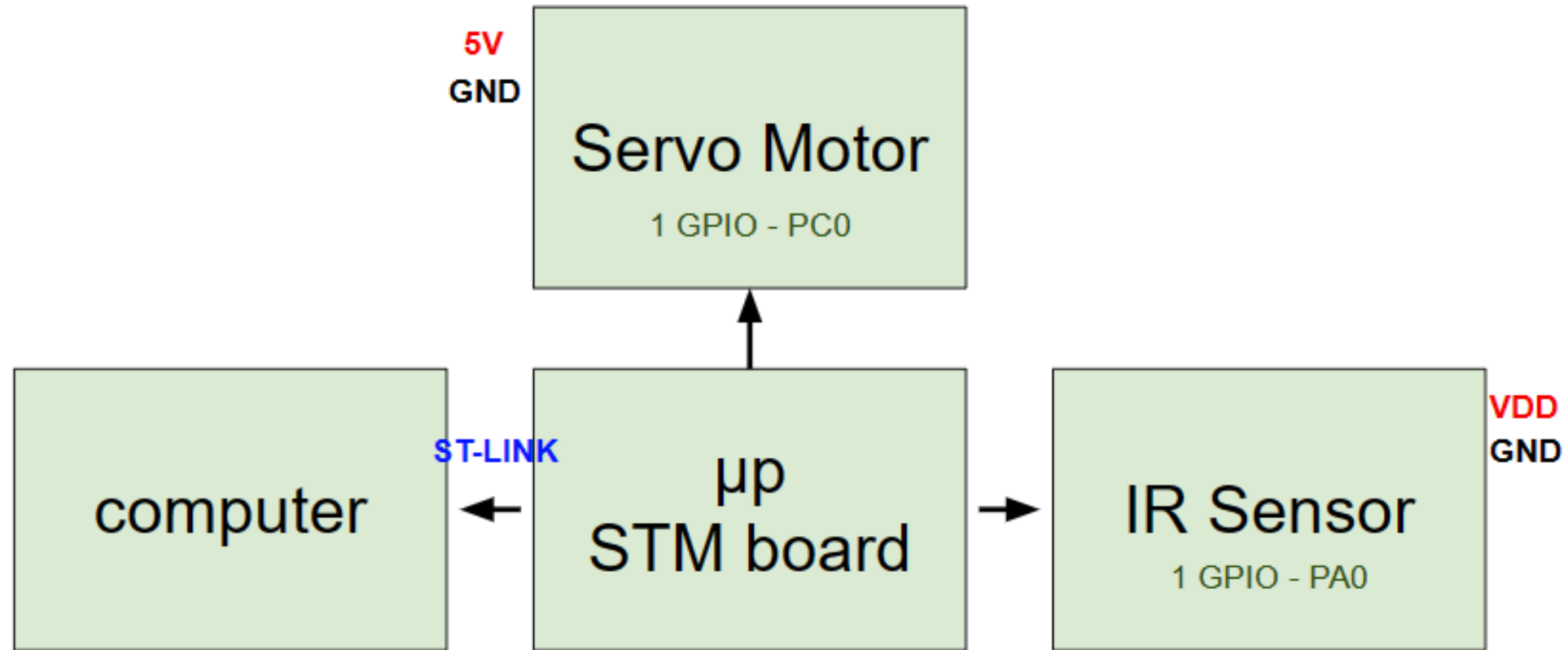
# Cooling System

REAGAN HARDY

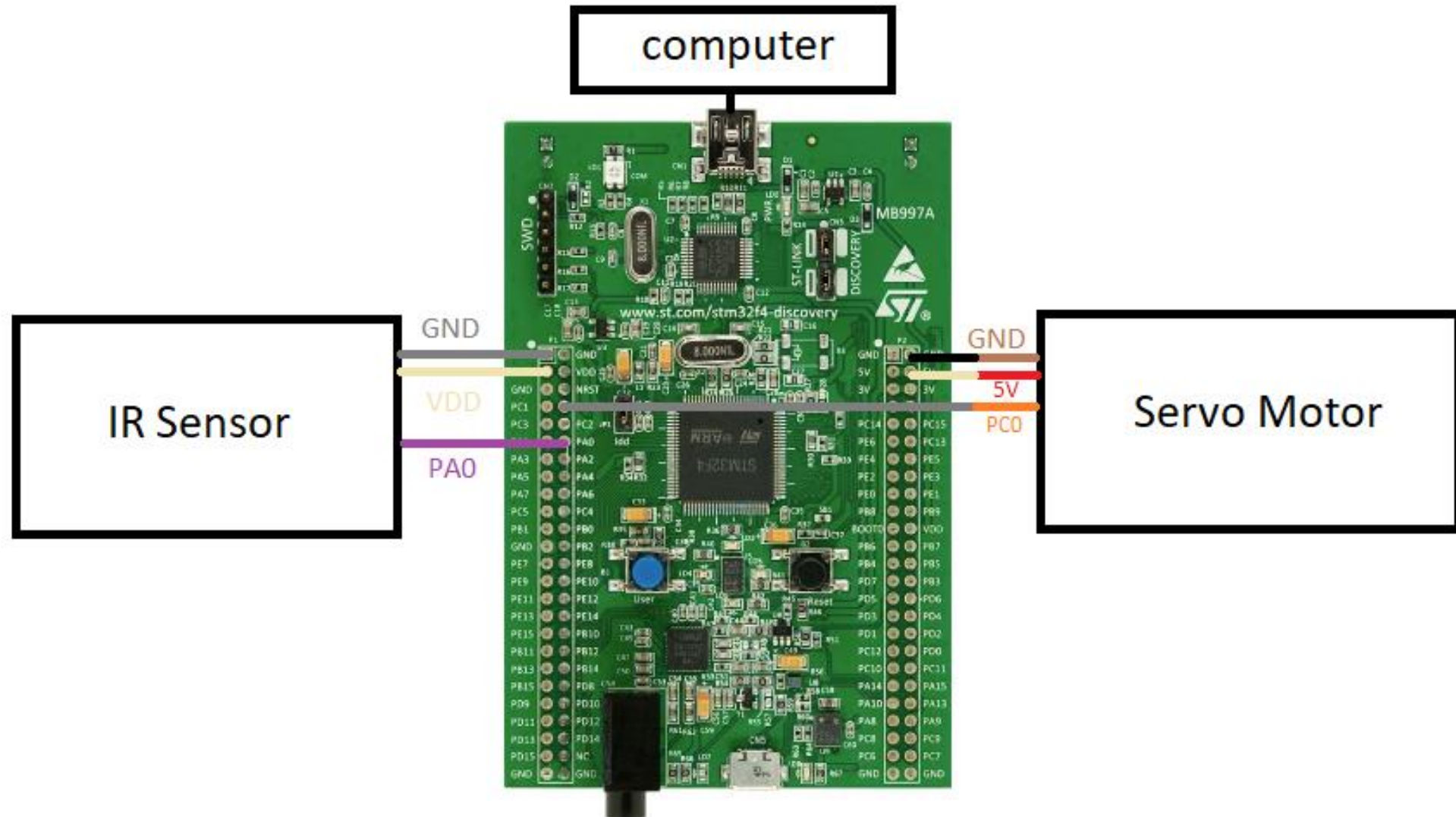
# Introduction

- **The automatic cooling system uses three components:**  
(STM32 Board, IR Sensor, Servo Motor)
- **The IR sensor is used to detect if an object is in close proximity. If an object is detected, the IR LED will turn on as well as the servo motor. This creates a "fan."**

# System Block Diagram

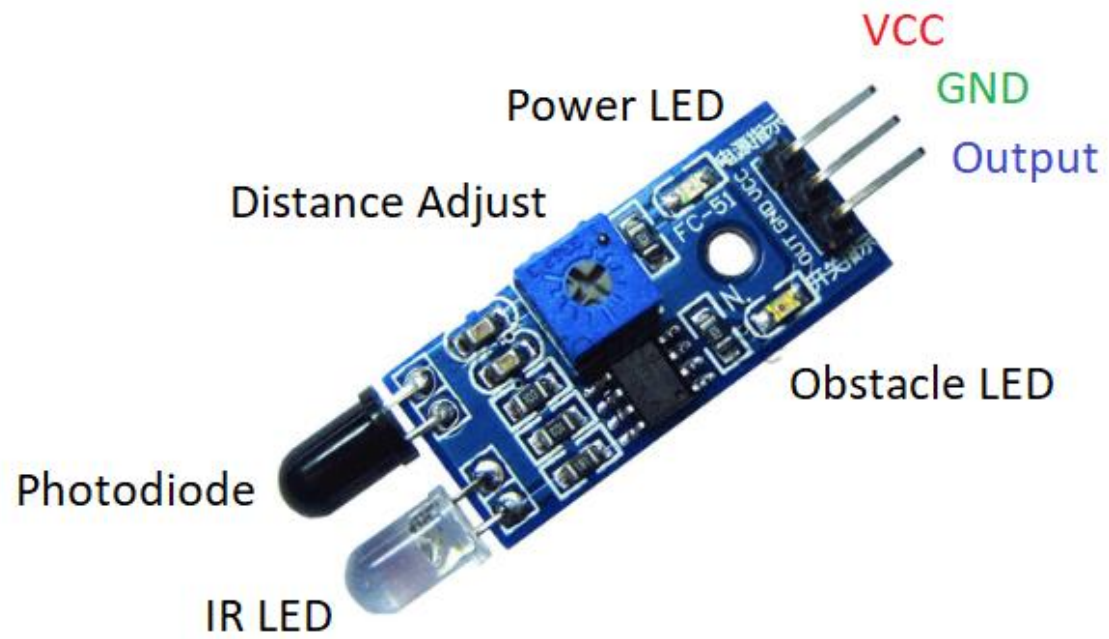


# Wiring

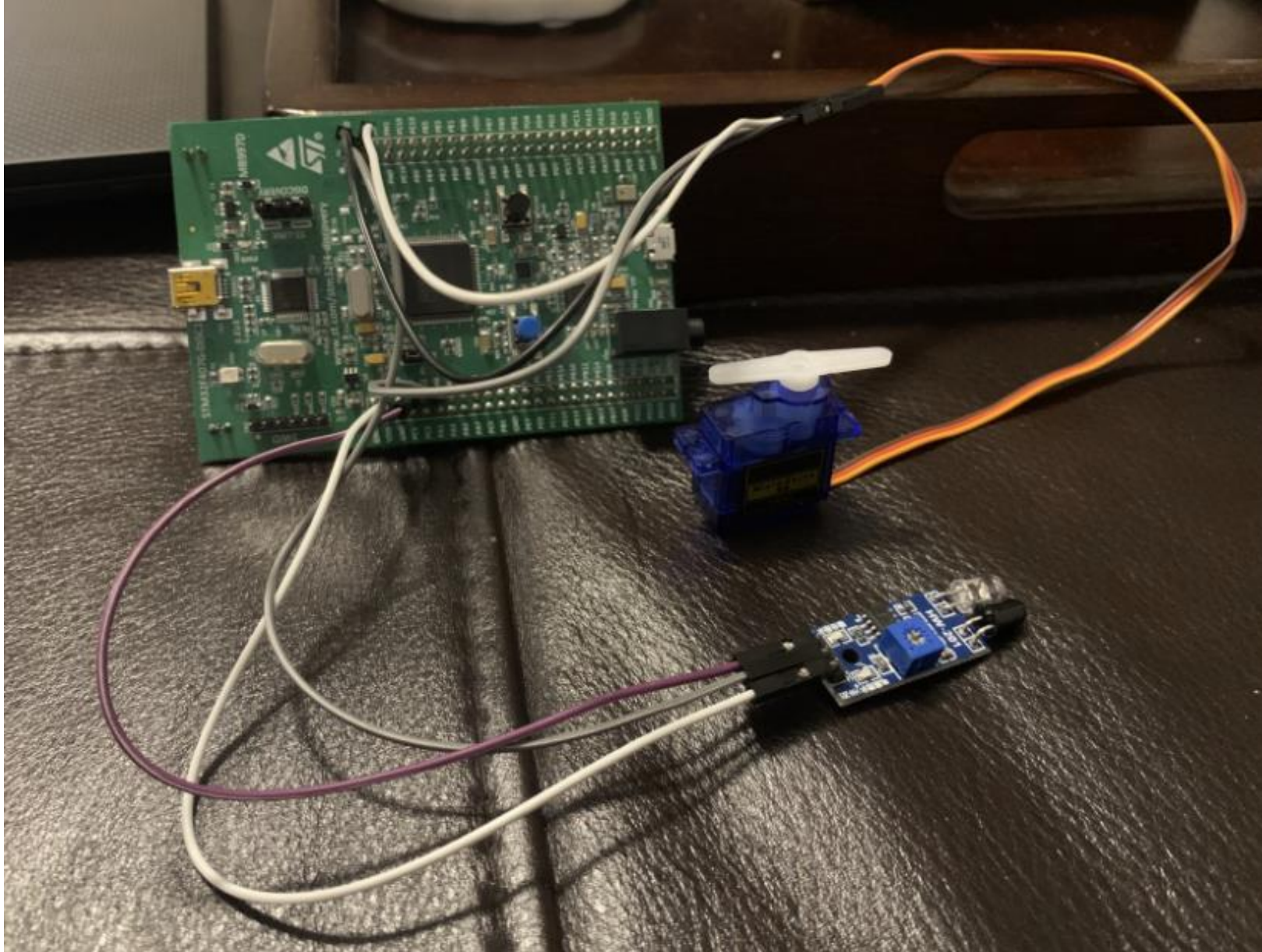




# Connections



# Build Prototype

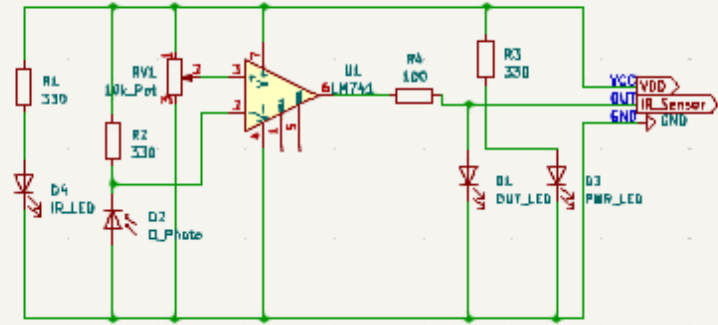


**J1**  
Discovery Board Conn 1

Pin	Signal
2	GND
3	VDD
4	
5	
6	
7	Servo_Motor
8	
9	
10	
11	IR_Sensor
12	
13	
14	
15	
16	
17	
18	
19	
20	
21	
22	
23	
24	
25	
26	
27	
28	
29	
30	
31	
32	
33	
34	
35	
36	
37	
38	
39	
40	
41	
42	
43	
44	
45	
46	
47	
48	

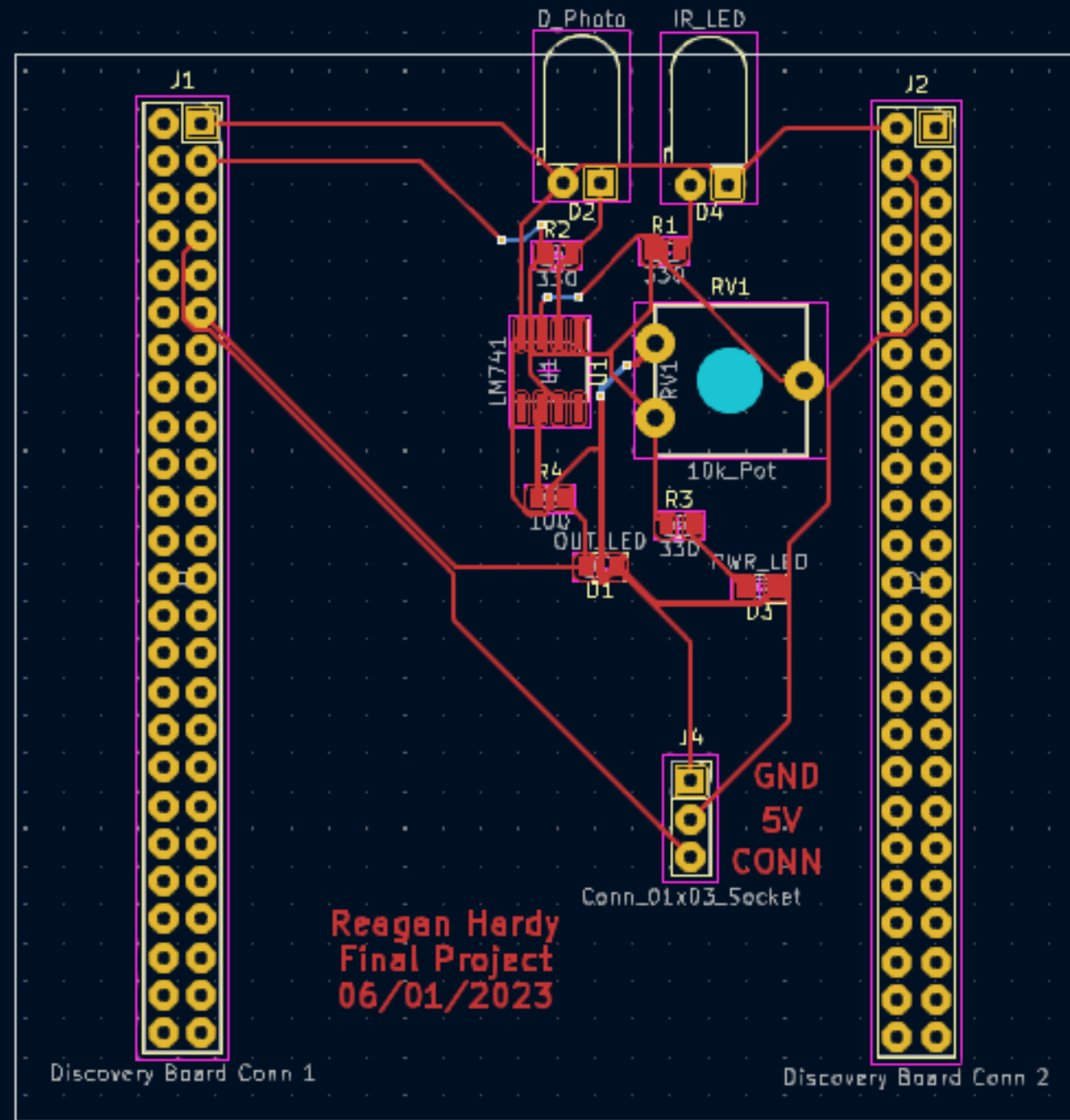
**J2**  
Discovery Board Conn 2

Pin	Signal
2	GND
3	+5V
4	
5	
6	
7	
8	
9	
10	
11	
12	
13	
14	
15	
16	
17	
18	
19	
20	
21	
22	
23	
24	
25	
26	
27	
28	
29	
30	
31	
32	
33	
34	
35	
36	
37	
38	
39	
40	
41	
42	
43	
44	
45	
46	
47	
48	



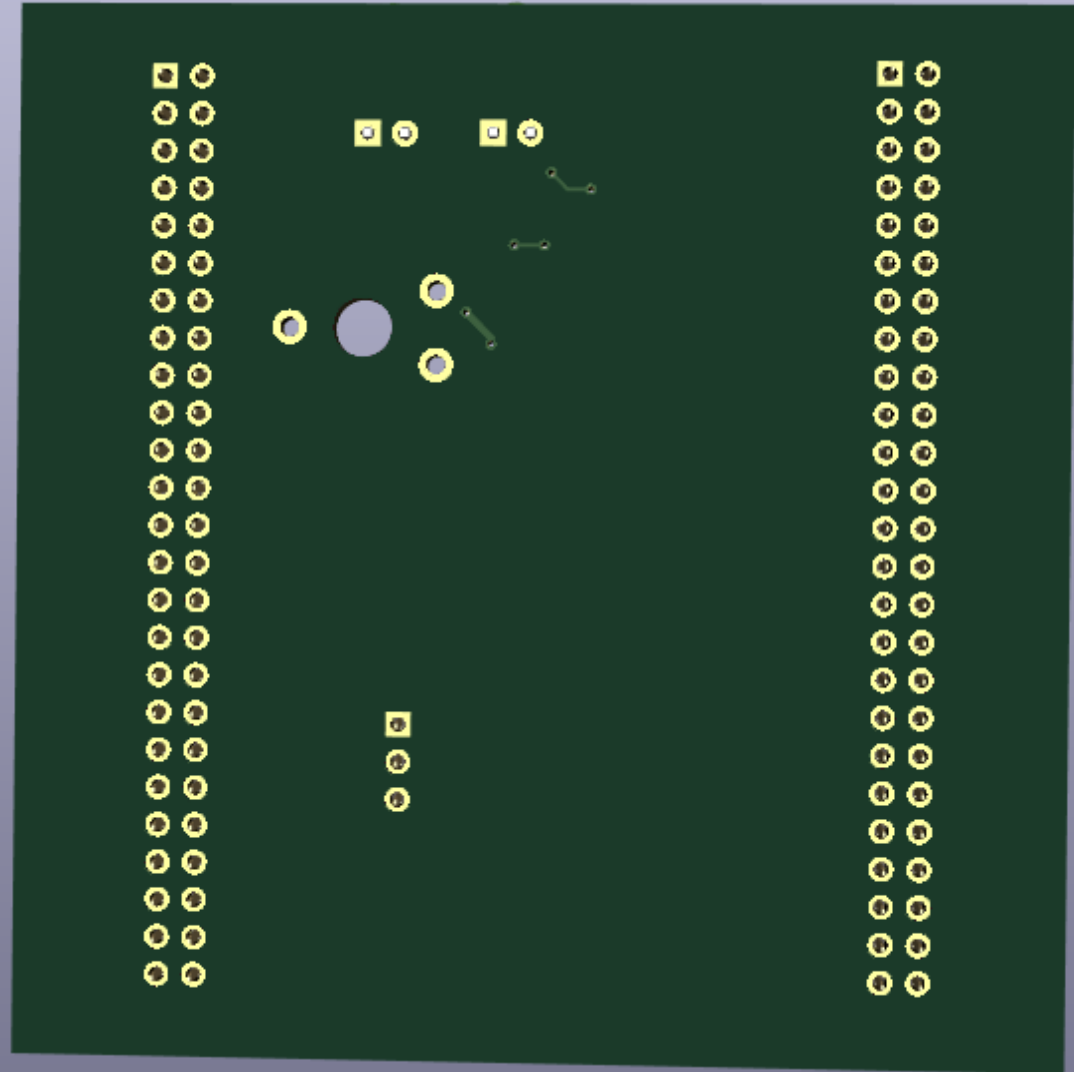
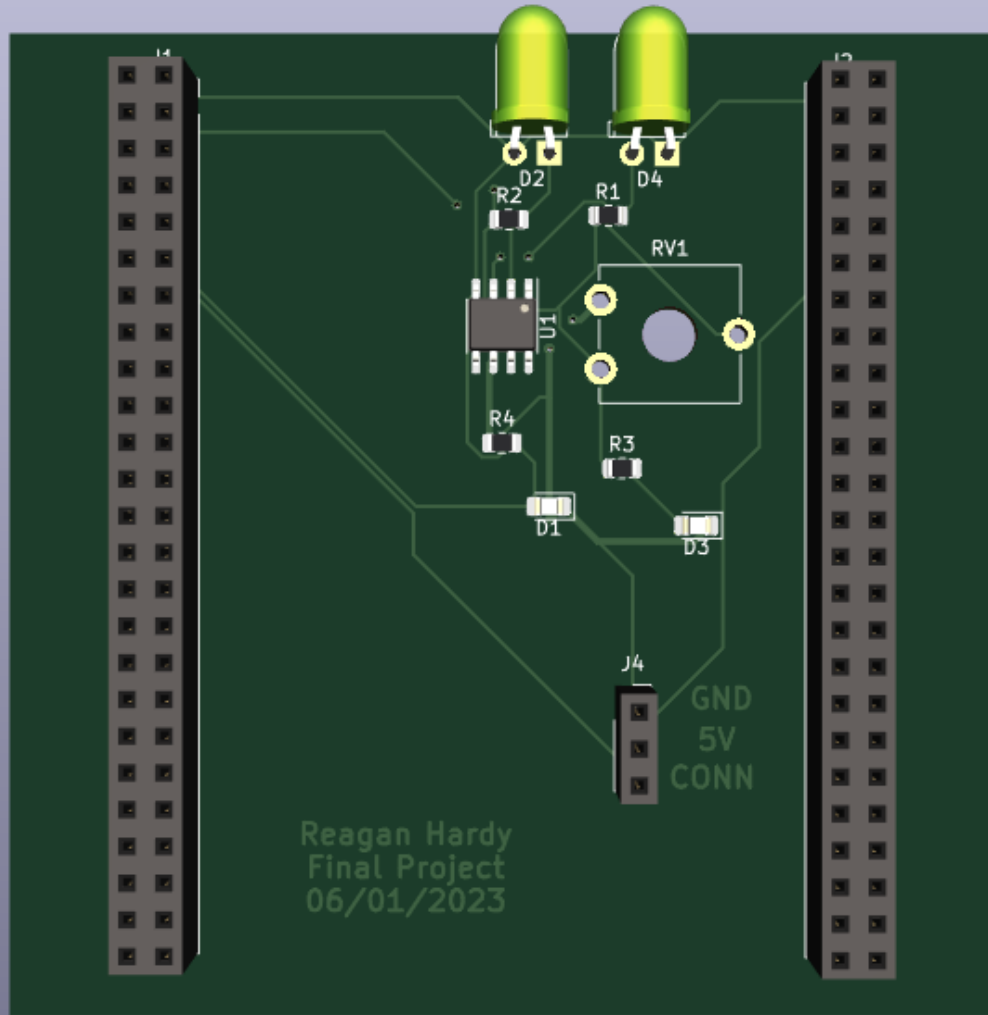
Rev:	
Id:	L/1

# PCB Layout

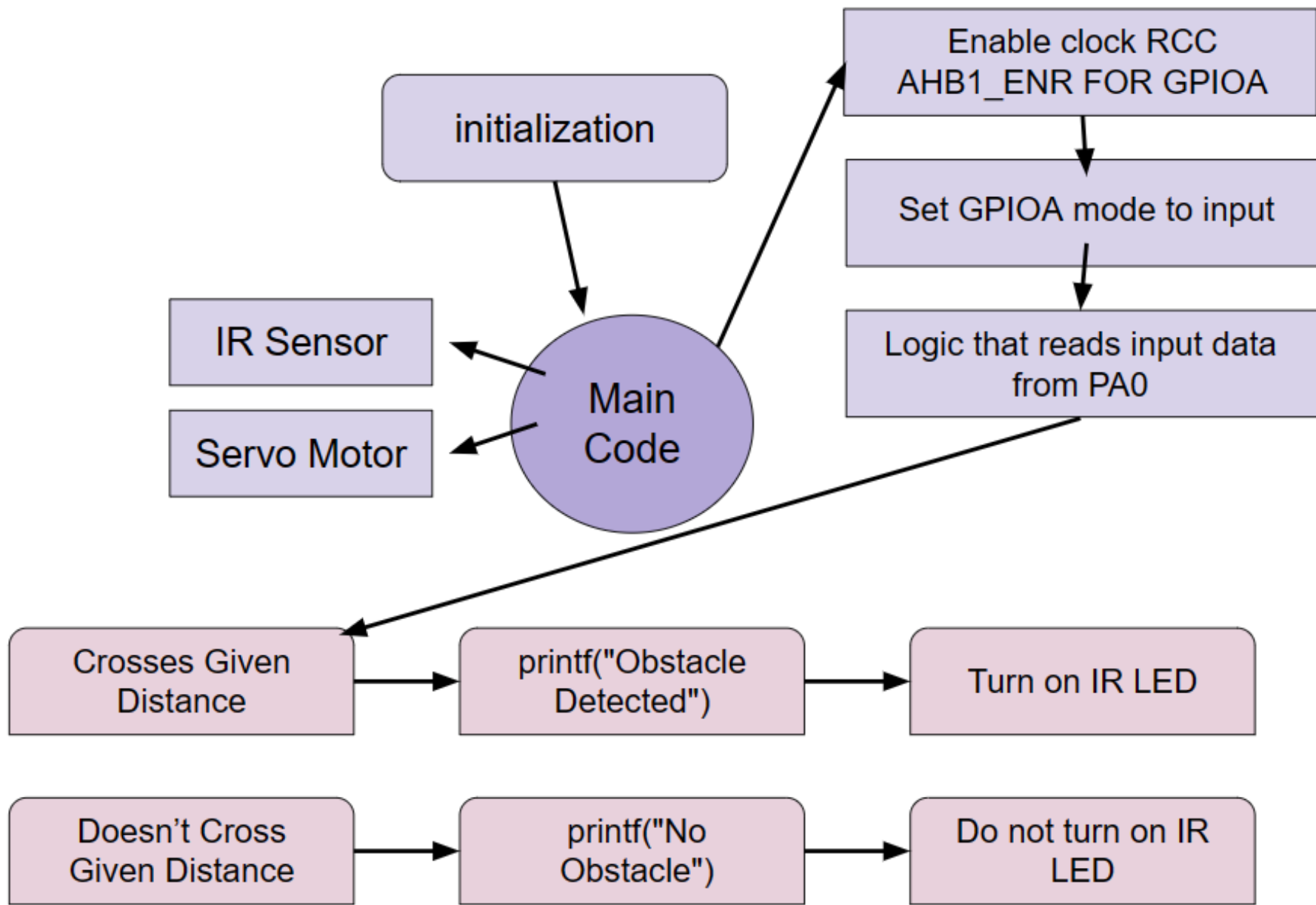




# 3D View



# Code Block Diagram



# Conclusion

- **The cooling systems is not currently fully functional.**
- **The IR Sensor is wired and working, but the servo motor is not yet integrated within the code.**
- **In future goal it to get both components working together to create the "fan" effect**

# Video Demonstration

