#### Modular Arithmetic

· Addition: O(n)

· Multiplication: O(n<sup>2</sup>) (naive)

· Multiplication: O(nlogn) (FFT)

· Euclid's Rule:  $gcd(x, y) = gcd(x \mod y, y)$ 

 $\cdot \#$  of bits in  $x^y = y \log_2 x \le n \cdot 2^n$ 

 $\frac{n}{2} \frac{n}{2} \leq n! \leq n^n$ 

 $\cdot$   $\tilde{f}$ : S  $\rightarrow$  T is 1-to-1 (injective) & onto (surjective)  $\Rightarrow$  | S |=| T

 $\cdot f: S \to T \text{ is 1-to-1 (injective)} \Rightarrow |T| \ge |S|$ 

 $\sum_{i=0}^{\infty} r^{i} = \frac{1}{1-r}$ , if r < 1

 $\sum_{i=0}^{n} i^{2} = \frac{\frac{1-r}{n}}{6}$   $\sum_{i=0}^{n} \frac{1}{i} = O(\log_{2}n)$ 

# Extended Euclid's GCD(x,v)

### Fermat's Little Theorem

if p is prime, then  $\forall 1 \leq a < p$  $a^{p-1} = 1 \mod p$ 

**Proof:** Start by listing first p-1 positive multiples of a:  $S = \{a, 2a, 3a, \cdots (p-1)a\}$ 

Suppose that ra and sa are the same mod p,  $\Rightarrow r = s \mod p$  $\therefore$  set S of p-1 multiples of a are distinct and nonzero, that is, they must be congruent to 1, 2, 3,  $\cdots$  p-1 after being sorted. Multiply all congruences together and we find  $a \cdot 2a \cdot 3a \cdot \cdot \cdot (p-1) \cdot a = 1 \cdot 2 \cdot 3 \cdot \cdot \cdot (p-1) \pmod{p}$  or better,  $a^{(p-1)}(p-1)! = (p-1)! \mod p$ . Divide both side by  $(p-1)! \blacksquare$ 

Primality Testing any 
$$a \to a^{N-1} = 1 \mod N$$
?  $\begin{cases} yes \Rightarrow "prime" \\ no \Rightarrow composite \end{cases}$ 

if N is not prime  $a^{N-1} = 1$  mod N < half values of a < N

#### Lagrange's Prime Theorem

Let  $\pi(x)$  be the # of primes leq x, then  $\pi(x) \approx \frac{x}{\ln(x)}$ , or more precisely  $\lim_{x\to\infty} \frac{\pi(x)}{(\frac{x}{x})} = 1$ 

# Modular Exponentiation

 $x^y \mod N \to \text{start with repeated squaring mod } N$  $x \mod N \to x^2 \mod N \to (x^2)^2 \cdots x^{\log_2 y} \mod N$ each step takes  $O(\log^2 N)$  times to compute and there are  $\log_2 y$  steps,  $:= O(n^3)$ ,

where n is the # of bits in N

### Formal Limit Proof

$$\lim_{n\to\infty}\frac{f(n)}{g(n)}\left\{ \begin{array}{l} \geq \ 0\ (\infty) \Rightarrow \ f(n) \ \in \ \Omega(g(n)) \\ < \infty\ (\theta) \Rightarrow \ f(n) \ \in \ O(g(n)) \\ = c_{|0 < c < \infty} \Rightarrow \ f(n) \ \in \ \Theta(g(n)) \end{array} \right.$$

# Logarithm Tricks

 $log_b x^p = plog_b x$  $\frac{ln(x)}{ln(m)} = \log_m x$  $\mathbf{x}^{log_b y} = \mathbf{y}^{log_b x}$ 

# Complexity

 $f \in O(g)$  if  $f \le c \cdot g$ 

 $f \in \Omega(q) \text{ if } f > c \cdot q$ 

 $f \in \Theta(g)$  if  $f \in O(g) \& \Omega(g)$ 

#### Hierarchy:

· Exponential

· Polvnomial

· Logarithmic

· Constant

#### Master's Theorem

$$T(n) = aT(\frac{n}{b}) + O(n^d), \text{ if } a > 0, b > 1, d \ge 0$$

$$T(n) = \begin{cases} O(n^d) & \text{if } d > \log_b a \\ O(n^d \log_b n) & \text{if } d = \log_b a \\ O(n^{\log_b n}) & \text{if } d < \log_b a \end{cases}$$

### Volker Strassen

faster matrix multiplication...

$$X = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \ \times \ Y = \begin{bmatrix} E & F \\ G & H \end{bmatrix} = \begin{bmatrix} AE + BG & AF + BH \\ CE + DG & CF + DH \end{bmatrix}$$

 $\in O(n^3)$  with recurrence  $T(n)=8T(\frac{n}{2})+O(n^2)$ but thanks to Stassen...

$$XY = \begin{bmatrix} P_5 + P_4 - P_2 + P_6 & P_1 + P_2 \\ P_3 + P_4 & P_1 + P_5 - P_3 + P_7 \end{bmatrix}$$

 $P_1 = A(F-H)$   $P_2 = (A+B)H$   $P_3 = (C+D)E$   $P_4 = D(G-E)$  $P_5 = (A+D)(E+H)$   $P_6 = (B-D)(G+H)$   $P_7 = (A-C)(E+F)$  $\in O(n^{\log_2 7}) \approx O(n^{2.81})$  with recurrence  $T(n) = 7T(\frac{n}{2}) + O(n^2)$ 

#### Polynomial Multiplication

$$\begin{array}{l} A(x) = a_0 + a_1 x + \dots + a_d x^d \quad B(x) = b_0 + b_1 x + \dots + b_d x^d \\ C(x) = A(x) \times B(x) = a_0 b_k + a_1 b_{k-1} + \dots + a_k b_0 = \sum_{i=0}^k a_i b_{k-i} \end{array}$$

#### Fast Fourier Transform

```
complex n<sup>th</sup> roots of unity are given by \omega = e^{\frac{2\pi i}{n}}, \omega^2, \omega^3, \cdots
      < values > = FFT(< coefficients >, \omega)
< coefficients > = \frac{1}{n} FFT(< values >, \omega^{-1}) \in O(nlogn)
```

Vandermonde Matrix,  $M_n(\omega) =$ 

#### Graphs

· graph - set of nodes & edges between select nodes

· tree - a connected graph with no cycles

· tree edge - part of DFS forest

 $\cdot$  forward edge – edge leading from node  $\rightarrow$  non-child descendant

· back edge - edge leading back to previously visited node

· cross edge - edge leading to neither descendant nor ancestor Given an Edge (u,v):

 $\cdot$  tree/forward edge: pre(u) < pre(v) < post(v) < post(u)

 $\cdot$  back edge: pre(v) < pre(u) < post(u) < post(v)

·  $cross\ edge:\ pre(v) < post(v) < pre(u) < post(u)$ 

#### Properties:

 $\cdot$ a tree on <br/>n nodes has n-1 edges

· any connected undirected graph with |E| = |V|-1 edges is a tree

· a directed graph has a cycle iff its DFS reveals a back edge

 $\cdot$ every DAG has at least 1 source & 1 sink

· in a DAG, every edge leads to a vertex with lower post #

· every directed graph is a DAG of its SCCs

 $\cdot$  acyclic, linearizability, & absence of back edges are all the same

· any path of DAG, vertices appear in increasing linearized order (linearize, topological sort DAG by DFS, then visit vertices in sorted order, updating edges out of each)

· if explore starts at u, it will terminate when all nodes reachable from u have been visited

 $\cdot$  node receives highest post order in DFS must lie in source SCC

 $\cdot$  if C & C ' are SCCs &  $\exists$  an edge from a node in C  $\rightarrow$  C '  $\Rightarrow$ 

highest post order number in C > than C''s highest post #

· min edges to make graph strongly connected with n-sinks & m-sources $\rightarrow max(n,m)$ 

Linearize (topologically sort from earliest  $\rightarrow$  latest)

· perform tasks in decreasing order of their post numbers (DFS)

· or find a source, output it, delete it, repeat until empty

Algorithm to Decompose G into SSCs Run DFS on  $G^R$ , then run DFS on G, every node it

reaches is in that SCC, pick next vertex to run DFS from in order of decreasing post  $\#\mathrm{s}$  discovered from DFS ordering on  $\mathrm{G}^R$ 

Shortest/Longest path in a DAG

Linearize DAG by DFS, visit vertices in sorted order, updating edges out of each. Note for longest paths, just negate all edge lengths.

## Depth First Search

explore (G, v)

```
discovers what nodes are reachable from a vertex \in O(|V| + |E|)
explore(G, v):
 v.visit = true
 previsit(v)
 for each edge (v, u) in E:
  if u.visit = false: explore(G, u)
 postvisit(v)
dfs(G):
 for all v \in V: v.visit = false
 for all v \in V: if v.visit = false:
```

#### Breadth First Search

```
 \in O(|V|+|E|) 
\mathbf{bfs}(G, s): 
for all u \in V: dist(u) = \infty 
dist(s) = 0 
Q = [s] (queue containing just s) 
while Q is not empty: 
u = eject(Q) 
for all edges (u, v) \in E: 
if dist(v) = \infty: 
inject(Q, v) 
dist(v) = dist(u) + 1
```

# Dijkstra's Algorithm

Implementation	deletemin	insert/ decreasekey	$\begin{array}{c}  V  \times \texttt{deletemin} \ + \\ ( V  +  E ) \times \texttt{insert} \end{array}$
Array	O( V )	O(1)	$O( V ^2)$
Binary heap	$O(\log  V )$	$O(\log  V )$	$O(( V  +  E )\log  V )$
d-ary heap	$O(\frac{d \log  V }{\log d})$	$O(\frac{\log  V }{\log d})$	$O(( V  \cdot d +  E ) \frac{\log  V }{\log d})$
Fibonacci heap	$O(\log  V )$	O(1) (amortized)	$O( V \log  V  +  E )$

# Bellman-Ford Algorithm

```
shortest path algorithm (+/- edge weights) \in O((|V| \cdot |E|))
bellman_ford(G, 1, s):
for all u \in V:
  dist(u) = \infty
  prev(u) = nil
  dist(s) = 0
  repeat |V| - 1 times:
  for all e \in E:
    update(e)

update(u, v):
  min{dist(v), dist(u) + l(u, v)}
note: negative cycle exists if any edge distance value is reduced on |V|^{th} iteration
```

# Kruskal's Algorithm

 $\label{eq:minimum_spanning_tree} \begin{tabular}{ll} Minimum_spanning_tree_Algorithm \in O(|E|log|V|). \end{tabular}$  Starts with an empty graph & selects edges from E repeatedly with lightest weight that does not produce a cycle Uses disjoint sets to determine whether a cycle exists in amortized constant time (see disjoint set data structure). \end{tabular}

### **Cut Property**

Suppose edges X are part of a minimum spanning tree G. Pick

any subset of nodes S for which X does not cross between S  $\mathscr E$  V-S,  $\mathscr E$  let e be the lightest edge across this partition. Then X U e is part of some MST.

#### Disjoint Set Data Structure

Directed tree, nodes are elements of the set, each has parent pointer eventually leading to the root of the tree whose parent pointer is itself.

- $\cdot$  a root node with rank k is created merging two trees rank k-1
- · any root node of rank k has  $\geq 2^k$  nodes in its tree
- · if there are n elements there are at most  $n/2^k$  nodes of rank k
- · trees have height  $\leq$  logn upper-bound on run time of find & union operations
- · path compression reduces average time per operation to amortized O(1)

## Prim's Algorithm

 $\label{eq:minimum Spanning Tree algorithm} &\in O((|V|+|E|)log|V|) \\ \text{Initialize a tree with a single vertex, chosen} \\ \text{arbitrarily from the graph. Grow the tree by one edge:} \\ \text{Of the edges that connect the tree to vertices not yet} \\ \text{in the tree, find the minimum-weight edge, and transfer} \\ \text{it to the tree. Repeat until all vertices are in tree.} \\$ 

### **Huffman Encoding**

A prefix-free encoding represented by a full binary tree, generated by a path from root to leaf, interpreting left as 0 & right as 1. cost of tree =  $\sum_{i=1}^n f_{i\cdot}(\text{depth of ith symbol in tree})$  or cost of tree = sum of frequencies of all leaves and internal nodes except root.

Construct tree greedily: Start with two symbols with smallest frequencies, continue branching upward constructing tree with next two smallest frequencies (consider sums also) until there are none left.