

# Rhian C. Preston

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CONTACT INFORMATION	Graduate Research Assistant <i>Oregon State University, SHARE Lab</i> <i>Robotics, Software, and Electrical Engineering</i>	mobile: (719) 332-9423 e-mail: prestonr@oregonstate.edu GitHub: reakain.github.com Thingiverse: thingiverse.com/reakain
RESEARCH INTERESTS	Human-robot interaction, socially assistive robotics, robot assisted human-human interaction, human perception of robot shape/motion	
PhD	<b>Oregon State University, ROBOTICS</b>	<b>September 2020 – Current</b>
MS	<b>Worcester Polytechnic Institute, ROBOTICS</b>	<b>January 2015 – Jun 2019</b>
MS	<b>University of Wisconsin - Madison, NUCLEAR ENGINEERING</b>	<b>Aug 2013 – Dec 2014</b>
BS	<b>Oregon State University, NUCLEAR ENGINEERING</b> <ul style="list-style-type: none"><li>• Minor in Physics</li></ul>	<b>January 2011 – Jun 2013</b>
WORK EXPERIENCE	<b>Framatome Inc., Lynchburg, VA</b> <i>Design Engineer, Voyager Rotational Program</i> Multi-year rotational program for accelerated development of young engineers.	<b>Sep 2016 – July 2020</b>
	<i>Software &amp; Electrical Engineer III, Non-Destructive Examination Team</i> Develop user tools for camera recording, snapshotting, and setup via remote client to third party multi-camera surveillance system.	<b>Aug 2019 – July 2020</b>
	<i>Electrical Engineer III, Stearns-Roger Services</i> Path planning, communication, and UI for smart crane system. Interface between Siemen's PLC and C# WPF application with persistent database. Simulation application for operator training for smart crane system. Schematics, interconnect, wiring diagram, and PLC design for a smart crane system.	<b>Aug 2018 – Aug 2019</b>
	<i>Software &amp; Electrical Engineer III, Non-Destructive Examination Team</i> Microcontroller specification, PCB troubleshooting, and software development and implementation for PoE inspection system. Included embedded C programming of PIC microcontrollers for variable number of motors as well as analog camera control. Development of C# inspection plugin with UI and SQLite database for inspection data. On-the-fly kinematics and feedback for UR-10 robot arm through a C++ with Qt plugin.	<b>Jan 2018 – Aug 2018</b>
	<i>Fuel Design Engineer II, Fuels Neutronics - Boiling Water Reactors</i> Boiling water reactor neutronic licensing analysis. Core and bundle fuel design.	<b>Nov 2015 – Dec 2017</b>
	<i>Engineering Intern, Fuels - Site Support</i> Python development of UI wrappers for Fortran code. Qt rebuild for Windows 7 of Java application for in-core monitoring.	<b>Jun 2013 – Aug 2013</b>
RESEARCH EXPERIENCE	<b>Oregon State University, Robotics Dept.</b> <i>Graduate Research Assistant, OSU SHARE Lab</i> <i>Workplace Companion Robot Project</i> Development and deployment of a desktop break-taking system utilizing the Anki Cozmo robot. Designed and ran a three-phase, two month long, in-situ human subject study where the desktop system acted autonomously in the participant's space for the two month period, and autonomously transitioned between study phases.	<b>July 2020 – Current</b> <b>July 2020 – Current</b>

*Graduate Research Assistant, Deep Pressure Therapy Vest* **August 2021 – Current**  
 Assisted in fabricating study hardware and testing the study design. Acted as a researcher and stress-stimuli in study of efficacy. Assisting with data analysis of qualitative results.

*Graduate Research Assistant, Robot Arm Visual Characteristics* **March 2022 – Current**  
 Designed visual stimuli, study procedure, and Qualtrics survey.

**Worcester Polytechnic Institute, Robotics Dept.**

*Graduate Capstone Project, Reversing Autonomous Tractor Trailer* **Jan 2019 – May 2019**  
 Team project to develop an autonomously reversing tractor trailer utilizing machine vision, 3D simulation, and inverse kinematics to simulate automated reversing up to a loading bay.

**University of Wisconsin - Madison, NEEP Dept., Madison, WI**

*Graduate Research Assistant, PEGASUS Toroidal Plasma Experiment* **Aug 2013 – Dec 2014**  
 Altium design and layout of FPGA twisted pair interconnect boards for signal noise filtering of a high power magnetic system.

**PUBLISHED  
ROBOTS**

- [1] “Generic Quest Giver”, Twitter: <https://twitter.com/QuestGiverBot>. Source: <https://github.com/reakain/QuestGiver>. Nov. 2019.
- [2] “Tarot Reader”, Twitter: <https://twitter.com/TarotReaderBot1>. Source: <https://github.com/reakain/TarotReader>. Nov. 2019.
- [3] “Storyteller”, Twitter: <https://twitter.com/BotStoryteller>. Source: <https://github.com/reakain/StoryTeller>. Nov. 2019.

**CONFERENCE  
PUBLICATIONS**

- [4] **Preston, R.C.**, Fitter, N.T. “Increasing personalization in long-term interactions with a workplace companion robot.” *Proceedings of the Lifelong Learning and Personalization in Long-Term Human-Robot Interaction (LEAP-HRI) Workshop, ACM/IEEE International Conference on Human-Robot Interaction (HRI)*. Boulder, Colorado, USA. March 2021.
- [5] **Preston, R.C.**, Bongard, M.W., Fonck, R.J., Lewicki, B.T. “Magnetics and Power System Upgrades for the Pegasus-U Experiment.” (poster) **56th Annual Meeting of the APS Division of Plasma Physics**. New Orleans, Louisiana, USA. October 2014.

**OTHER  
PUBLICATIONS**

- [6] **Preston, R.C.**, Drop. Short Story, Amazon Kindle Select. July 2018.

**MEDIA  
COVERAGE**

- [7] Morrow, J. “Engineers earn national kudos for creating nuclear fuel assembly model” **Tri-Cities Area Journal of Business** July 2018. <https://www.tricitiesbusinessnews.com/2018/07/framatome-award/>.

**ENGINEERING  
TEACHING**

**Oregon State University** **Fall 2021**  
 DEPT. OF MECHANICAL ENGINEERING **Summer 2022**  
*ME 351, Introduction to Instrumentation and Measurement Systems*  
 Function, operation, and application of common mechanical engineering instruments, measurement principles, and analysis labs, grading, troubleshooting, and exam question generation

**University of Wisconsin-Madison** **Fall 2013**  
 DEPT. OF ENGINEERING PHYSICS **Spring 2014**  
*EMA 201, Statics*  
 Engineering Statics recitation lectures, exam creation, and grading

**Oregon State University** **Fall 2011**  
 DEPT. OF ELECTRICAL & COMPUTER ENGINEERING **Winter 2012**  
*ENGR 201, Electrical Fundamentals I* **Spring 2012**  
 Analysis of linear circuits, circuit laws and theorems, DC responses of circuits, **Fall 2012**  
 operational amplifier characteristics and applications, recitation lectures, **Winter 2013**

**South Dakota School of Mines & Technology****Fall 2010**

DEPT. OF PHYSICS

*PHYS 111L, Introduction to Physics I Laboratory*

Algebra level fundamental physics concepts

COMPUTING SKILLS	<b>Languages</b>	C#, Qt, bash/csh, C++, FORTRAN, Python, XML, CSS, Javascript, R, Lua
	<b>Build Systems</b>	make, CMake, automake
	<b>Databases</b>	MySQL, SQLite, SQL Express
	<b>Version Control</b>	git
	<b>Physics Engines</b>	Unity, Godot, MCNP, RELAP
	<b>Other Development Tools</b>	ROS, Docker, LabView, L <sup>A</sup> T <sub>E</sub> X, Mathematica, MatLab, TIA Portal
	<b>3D CAD Tools</b>	Autodesk Inventor/Fusion360, SolidWorks, Blender, 3ds Max, StarCCM+
	<b>2D CAD Tools</b>	AutoCAD, Altium, Fritzing, Inkscape
HARDWARE SKILLS	<b>Shop Tools</b>	mill, lathe, table saw, various power tools/saws
	<b>Electronics</b>	soldering, oscilloscope
	<b>Other Tools</b>	FDM 3D printers, laser cutter
	<b>Metalwork</b>	blacksmithing, welding
	<b>Plastics</b>	casting and molding
PROFESSIONAL SERVICE	<b>Faculty Relations Officer</b> , Robots Graduate Student Association, OSU	<b>2022–Current</b>
	<b>Graduate Mentor</b> , NSF Research Experiences for Undergraduates, OSU	<b>Summer 2022</b>
	<b>Team Mentor</b> , EECE Senior Capstone Program, OSU	<b>2020–2021</b>
	<b>Chair</b> , Framatome-Lynchburg Chapter, NAYGN	<b>2018–2019</b>
	<b>Vice Chair</b> , Framatome-Lynchburg Chapter, NAYGN	<b>2018–2018</b>
	<b>Advocacy Chair</b> , Framatome-Richland Chapter, NAYGN	<b>2017–2018</b>
	<b>Member</b> , Framatome-Richland Chapter, NAYGN	<b>2015–2017</b>
	<b>Member</b> , American Nuclear Society	<b>2009–2017</b>
	<b>Member</b> , Enlight Computer Projects, University of Wisconsin-Madison	<b>2013–2014</b>