"Iris"



Positioning system

GPS + INS

- Latitude & longitude
- Orientation
- Omnidirectional displacement

Function

- Start & end positions
- Facial orientation
- Real-time calculation of displacement



Air headphones

Camera

Technology

 Utilizing directional sound field technology

Advantage

- Perceive environmental sounds.
- Minimizes sound leakage



TOF + Wide-Lens

- Wide-angle
- · Depth + RGB + algorithms.

Computer vision

- Road orientation
- Object recognition
- Depth estimation



Hard Stop Pivot

· Fully conform to the face, adapting to different facial data

Damping Function

 Vibration isolation with localized damping.

LRA

- Customizable pattern
- Anti-noise capability

Confortable

- Skin sensitivity
- Comfort
- Perceptual accuracy

Vibrator

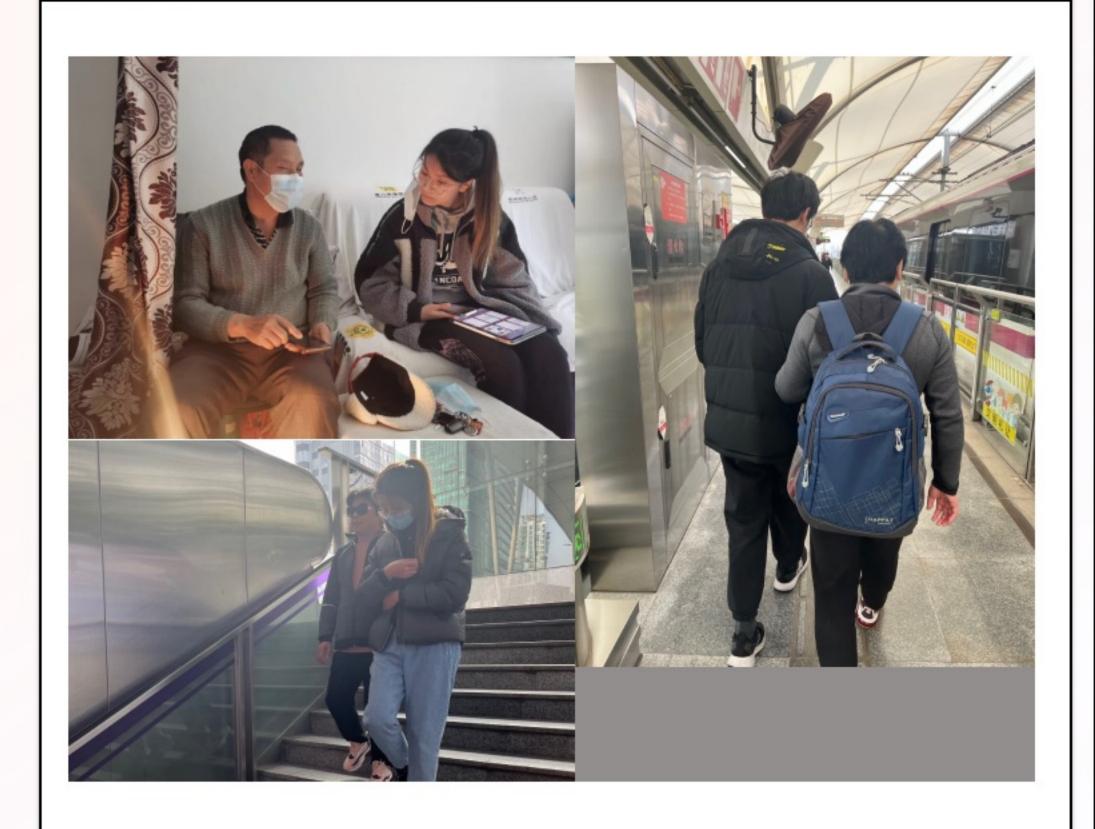


Wearable Tech for the Visually Impaired



Interview & User Research

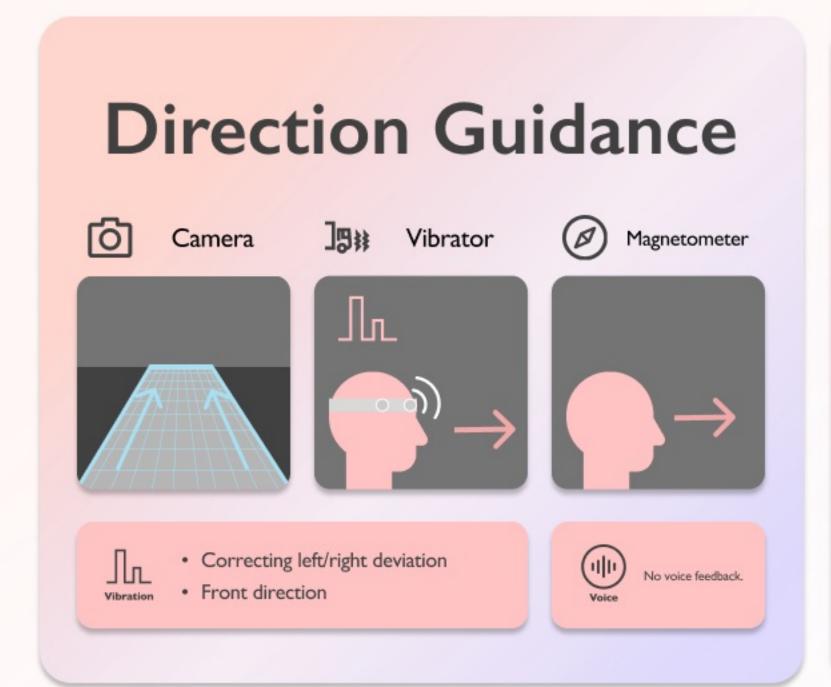
Research

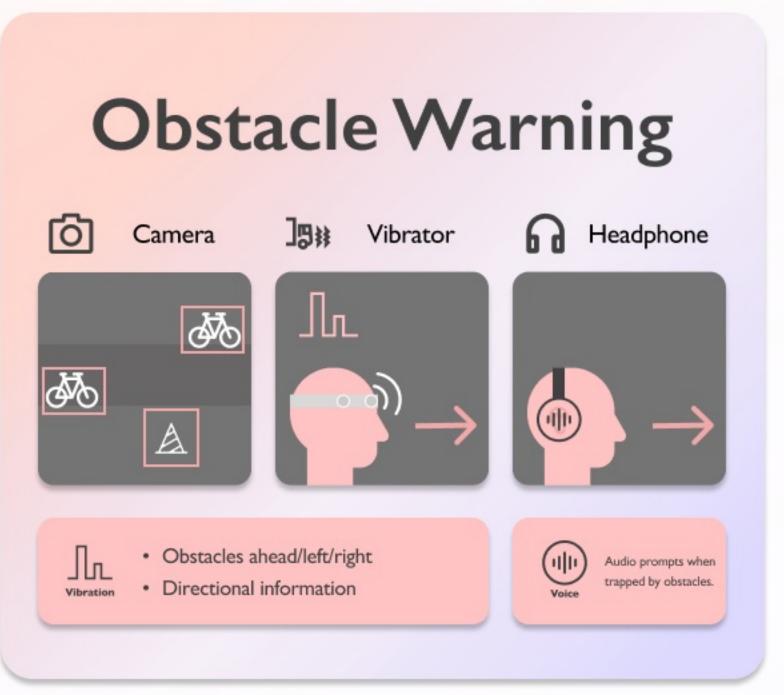


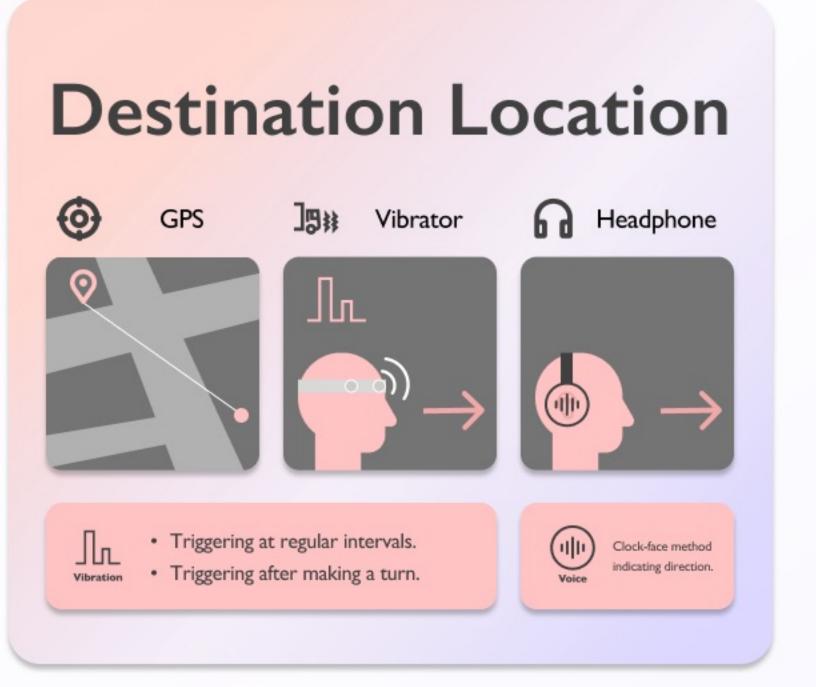
User Journey Map

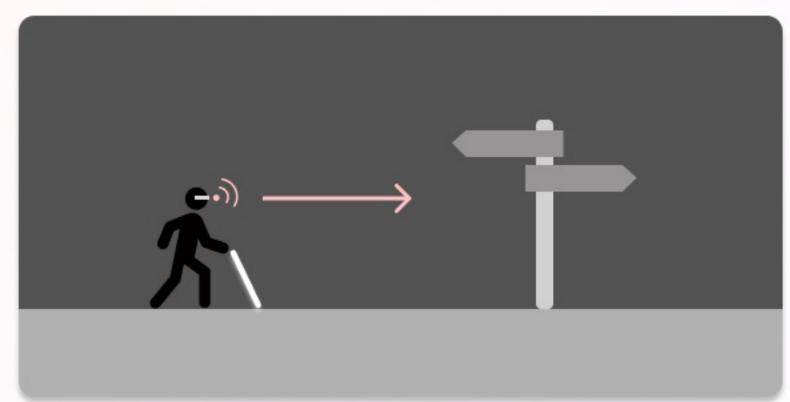
Going downstairs /elevator.	Walking in a straight line.	Obstacle avoidance.	Leaving the entrance gate	From the residential area to the subway entrance.
I.Exploring with cane movement from left to right.	I.Finding a small path in the grassland 2.Searching for the boundaries of the path	I.Navigating around parked cars on the roadside.	I.Standing directly in front of the facial recognition device. 2.Crossing over the gate.	I.Using a mental map to track the number of steps and locate landmarks.
I.Navigating with a cane can be challenging.	I.Getting disoriented while navigating around flower beds. 2.Having difficulty finding the boundaries of the road.	I.Getting disoriented while navigating around cars, making it difficult to maintain the correct direction.	I.Finding it difficult to walk diagonally and needing to walk straight before making a turn	I.The road conditions are constantly changing, making it more dangerous.

Scenario & Function

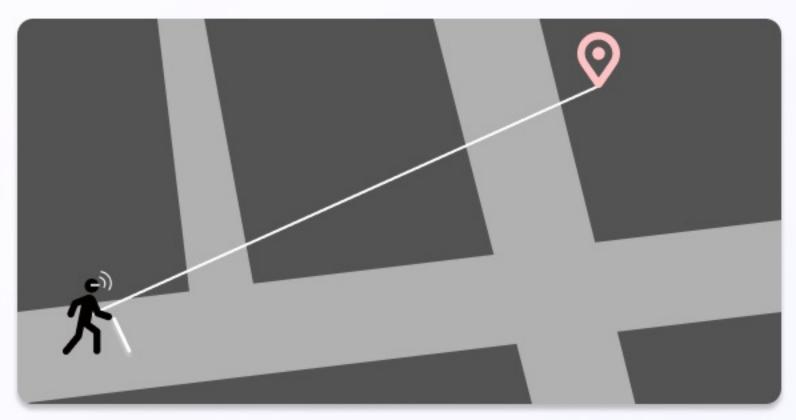










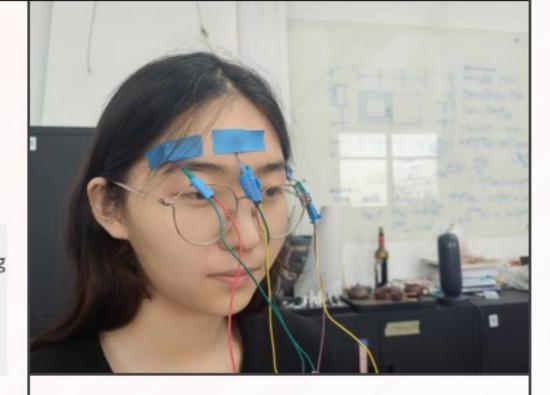


Modeling & Prototyping

Electronic Component Testing

#TEST I

Through testing, we have found that using three vibration components is sufficient to indicate direction.



#TEST 2

In the second testing, we validated the feasibility of acquiring road data using a camera. In this test, we successfully implemented road edge detection functionality.



Rough Form Testing

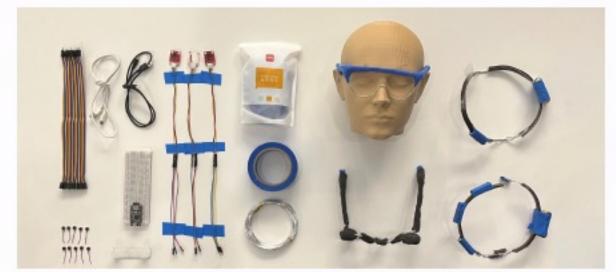
#TEST 3

In this test, we calculated the total weight of the product and created a clay model of equal mass.

Our model would not slide forward even when the user looked downward.



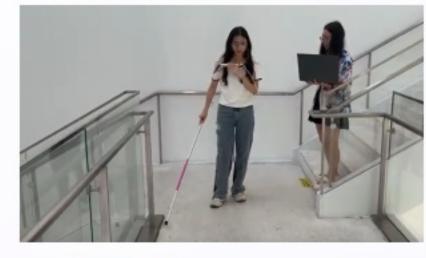




Walking Testing



Phase I: only white cane



Phase 2: use vibration and white cane



Phase 3: camera, vibration and white cane