## Project Workbook Review

Subject: Project Based learning Class: S.E (DIV A & B)

Roll No.: <u>66, 67, 68, 69 and 70</u> Group No.: <u>G14</u>

## A) Literature Survey:

Sr. No.	Paper Title	Publica- tion Year	Objective	Methology	Hard- ware and Software	Out- comes	Conclu- sion
1	International Journal of Advance Re- search in En- gineering, Science & Technology's e-ISSN: 2393-9877, p-ISSN: 2394-2444 STARTER USING IOT	2018	The objective of the project is to control the motor from the remote places. The motor is turned on/off from the remote places it-self through GPRS.	IOT and Arduino microcontroller	Arduino Uno, SIM800 L, and Arduino IDE	The Arduino receives the signal from webserver either to turn on/off the motor. The motor can be turned on/off through relay driver circuit.	The following technology can be used to to turn ON/OFF any circuit from remote location.

2	International Journal of Advanced Research in Electrical, Electronics and Instrumentation Engineering's  ISSN (Print): 2320 - 3765  ISSN (Online): 2278 - 8875  Microcontroller Based Three phase Motor Control Using GSM	2016	This project has a Cell Phone Based Motor Control with Voice Acknowledgment, which will be used as the electronic device, and also a mobile phone having GSM modem, which is the latest technology used for communication between the mobile and the embedded devices.	Arduino, DTMF and GSM.	ATMEL AT89C51 , Nokia 5800 as GSM module, APR33A 3 IC,	The mobile phone gives command to the micro-controller to turn ON the relay and vice versa.	The mobile phone gives command to the micro-controller to turn ON the relay and vice versa.
3	International Journal of Engineering Research & Technology's  ISSN: 2278-0181  A Review Paper on Dual Tone Multi Frequency.	2017	The objective of this project is to control toy vehicle movement using DTMF technology	DTMF and micro-con- troller.	89S52 Microcontroller, DTMF decoder, DC motors and mobile phone.	The toy vehicle shall be controlled by the mobile phone using DTMF tech.	The movement of the toy car is controlled by the mobile phone.

4	International Journal of Scientific and Research Publication's  ISSN 2250-3153  Designing & Implementation of Mobile Operated Toy Car by DTMF.	2013	The objective of this project is to control toy vehicle movement using DTMF technology	DTMF and micro-con- troller.	MT8870 -DTMF decoder,  AT- MEGA1 6 micro- con- troller.	The toy car shall be controlled by the mobile phone using DTMF tech.	The movement of the toy car is controlled by the mobile phone.
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## B) Block Diagram:



**The Motor** 

## C) Circuit Diagram:

