## CO 250: Introduction to Optimization

Module 5: Integer Programs (Cutting Planes)

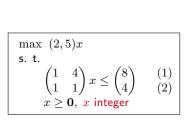
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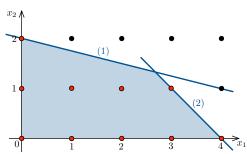
## **Overview**

In this lecture, we will:

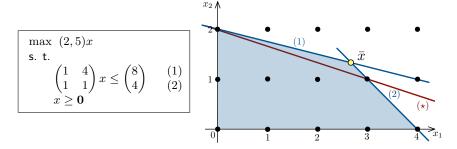
- 1. investigate a class of algorithms known as cutting planes,
- 2. restrict ourselves to pure Integer Programs, and
- 3. present a highly simplified view.

#### Our First Integer Program:





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Using Simplex, we find that  $\bar{x} = \left(\frac{8}{3}, \frac{4}{3}\right)^{\top}$  is optimal. NOT INTEGER!

We now search for a constraint  $\alpha^{\top} x \leq \beta$  that

- is satisfied for all feasible solutions to the IP, and
- is not satisfied for  $\bar{x}$ .

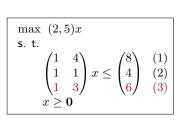
We will call this constraint a cutting plane for  $\bar{x}$ .

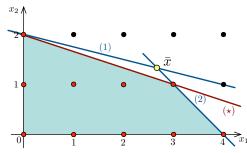
Example:

$$x_1 + 3x_2 \le 6. \tag{*}$$

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After adding  $(\star)$  to our relaxation, we get





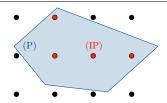
Using Simplex, we get:  $x' = (3,1)^{\top}$  is optimal. INTEGER!

Since x' is optimal for the IP relaxation, x' is also optimal for the IP!

We have now solved our first IP.

## **Cutting Plane Scheme**

$$\max\left\{c^{\top}x: Ax \le b, x \text{ integer}\right\} \tag{IP}$$



- Let (P) denote  $\max\{c^{\top}x : Ax \leq b\}$ .
- If (P) is infeasible, then STOP. (IP) is also infeasible.
- Let  $\bar{x}$  be the optimal solution to (P).
- If  $\bar{x}$  is integral, then STOP.  $\bar{x}$  is also optimal for (IP).
- Find a cutting plane  $a^{\top}x \leq \beta$  for  $\bar{x}$ .
- Add a constraint  $a^{\top}x \leq \beta$  to the system  $Ax \leq b$ .

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#### Question

How can we find cutting planes?

SIMPLEX DOES THIS FOR US!

#### **Definition**

Let  $a \in \Re$ , then |a| denotes the largest integer  $\leq a$ .

### **Example**

$$|3.7| = 3$$

$$[62] = 62$$

$$|-2.1| = -3$$

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## **Example**

$$\max \ (2,5)x$$
 s. t. 
$$\begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix} x \leq \begin{pmatrix} 8 \\ 4 \end{pmatrix} \qquad (2)$$
 
$$x \geq \mathbf{0}, \ x \text{ integer}$$

Add a slack variable,  $x_3 \ge 0$ , and rewrite (1) as  $x_1 + 4x_2 + x_3 = 8$ .

Add another slack variable,  $x_4 \ge 0$ , and rewrite (2) as  $x_1 + x_2 + x_4 = 4$ .

Since  $x_1$  and  $x_2$  are integers,  $x_3=8-x_1-4x_2$  and  $x_4=4-x_1-x_2$  are integers, too.

Thus, we can rewrite the IP as

$$\max (2,5,0,0)x$$
s. t.
$$\begin{pmatrix} 1 & 4 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} x \le \begin{pmatrix} 8 \\ 4 \end{pmatrix}$$

$$x \ge \mathbf{0}, x \text{ integer}$$

## Solving the IP

$$\max \ (2,5,0,0)x$$
 s. t. 
$$\begin{pmatrix} 1 & 4 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} x \leq \begin{pmatrix} 8 \\ 4 \end{pmatrix}$$
 
$$x \geq \mathbf{0}, \ x \text{ integer}$$

We will now find a relaxation for the integer program.

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# Solving the IP

$$\max (2,5,0,0)x$$
 s. t. 
$$\begin{pmatrix} 1 & 4 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{pmatrix} x \leq \begin{pmatrix} 8 \\ 4 \end{pmatrix}$$
 
$$x \geq \mathbf{0}$$

We will use the Simplex algorithm to solve this.

Get an optimal basis  $B = \{1, 2\}$  and rewrite the basis in canonical form for B:

$$\max_{\mathbf{s.\ t.}} \begin{array}{c} (0,0,-1,-1)x+12 \\ \text{s.\ t.} \\ \begin{pmatrix} 1 & 0 & -1/3 & 4/3 \\ 0 & 1 & 1/3 & -1/3 \end{pmatrix} x \leq \begin{pmatrix} 8/3 \\ 4/3 \end{pmatrix} \\ x \geq \mathbf{0} \end{array}$$

The basic solution is  $\bar{x} = (8/3, 4/3, 0, 0)^{\top}$ . NOT INTEGER

Let us use the canonical form to get a cutting plane for  $\bar{x}$ .

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$$\max_{\mathbf{s}.\ \mathbf{t}.} \ \begin{pmatrix} (0,0,-1,-1)x+12 \\ \mathbf{s}.\ \mathbf{t}. \\ \begin{pmatrix} 1 & 0 & -1/3 & 4/3 \\ 0 & 1 & 1/3 & -1/3 \end{pmatrix} x \leq \begin{pmatrix} 8/3 \\ 4/3 \end{pmatrix} \\ x \geq \mathbf{0}$$

The basic solution is  $\bar{x} = (8/3, 4/3, 0, 0)^{\top}$ .

Every feasible solution to the LP relaxation satisfies,

$$x_{1} - \frac{1}{3}x_{3} + \frac{4}{3}x_{4} \le \frac{8}{3}$$

$$x_{1} + \left[ -\frac{1}{3} \right]x_{3} + \left[ \frac{4}{3} \right]x_{4} \le \frac{8}{3}$$

$$x_{1} - x_{3} + x_{4} \le \frac{8}{3}$$

For every feasible solution to the IP,  $x_1 - x_3 + x_4$  is integer.

Hence, every feasible solution to the IP satisfies

$$x_1 - x_3 + x_4 \le \left| \frac{8}{3} \right| = 2$$

$$\max_{\mathbf{s}.\ \mathbf{t}.} \begin{array}{ccc} (0,0,-1,-1)x+12 \\ \text{s.\ t.} \\ \begin{pmatrix} \mathbf{1} & 0 & -1/3 & 4/3 \\ \mathbf{0} & \mathbf{1} & 1/3 & -1/3 \end{pmatrix} x \leq \begin{pmatrix} 8/3 \\ 4/3 \end{pmatrix} \\ x \geq \mathbf{0} \end{array}$$

The basic solution is  $\bar{x} = (8/3, 4/3, 0, 0)^{\top}$ .

Every feasible solution to the IP satisfies

$$x_1 - x_3 + x_4 \le 2 \tag{(\star)}$$

However,  $\bar{x}$  does not satisfy (\*) as

$$1 \times \frac{8}{3} - 1 \times 0 + 1 \times 0 > 2$$



 $(\star)$  is a cutting plane for  $\bar{x}$ .

We can rewrite (\*) as

$$x_1 - x_3 + x_4 + x_5 = 2$$
 where  $x_5 > 0$ .

We now add this to the relaxation.

$$\max \ (0,0,-1,-1,0)x+12$$
 s. t. 
$$\begin{pmatrix} 1 & 0 & -1/3 & 4/3 & 0 \\ 0 & 1 & 1/3 & -1/3 & 0 \\ 1 & 0 & -1 & 1 & 1 \end{pmatrix} x \leq \begin{pmatrix} 8/3 \\ 4/3 \\ 2 \end{pmatrix}$$
  $x \geq \mathbf{0}$ 

Solve this using the Simplex algorithm.

Get an optimal basis  $B=\{1,2,3\}$  and rewrite the basis in canonical form for B:

$$\max_{\mathbf{s.\ t.}} \begin{array}{c} (0,0,0,-\frac{1}{2},-\frac{3}{2})x+11 \\ \text{s.\ t.} \\ \begin{pmatrix} 1 & 0 & 0 & 3/2 & -1/2 \\ 0 & 1 & 0 & -1/2 & 1/2 \\ 0 & 0 & 1 & 1/2 & -3/2 \end{pmatrix} x \leq \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \\ x \geq \mathbf{0} \end{array}$$

The basic optimal solution is  $x' = (3, 1, 1, 0, 0)^{\mathsf{T}}$ . INTEGER!

Since x' is optimal for the IP relaxation, x' is also optimal for the IP!

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 $(3,1,1,0,0)^{\top}$  is optimal for

$$\max (0,0,-1,-1,0)x + 12$$

s. t.

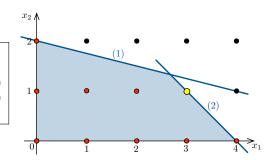
$$\begin{pmatrix} 1 & 0 & -1/3 & 4/3 & 0 \\ 0 & 1 & 1/3 & -1/3 & 0 \\ 1 & 0 & -1 & 1 & 1 \end{pmatrix} x \le \begin{pmatrix} 8/3 \\ 4/3 \\ 2 \end{pmatrix}$$

$$x \ge \mathbf{0} x \text{ integer}$$



### $(3,1)^{\top}$ is optimal for

$$\max_{\mathbf{s.\ t.}} \begin{array}{c} (2,5)x \\ \text{s.\ t.} \\ \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix} x \leq \begin{pmatrix} 8 \\ 4 \end{pmatrix} & (2) \\ x \geq \mathbf{0}, \ x \text{ integer} \end{array}$$



## **Getting Cutting Planes in General**

Solve the relaxation and get the LP in a canonical form for B.

$$\max \quad \bar{c}^{\top}x + \bar{z}$$
 s. t. 
$$x_B + A_N x_N = b$$
 
$$x \ge \mathbf{0}$$

$$N = \{j : j \notin B\}$$
  
 $\bar{x}$  basic  $(\bar{x}_N = \mathbf{0}, \bar{x}_B = b)$   
 $r(i)$  index of  $i^{th}$  basic variable

Suppose  $\bar{x}$  is NOT INTEGER. Then,  $b_i$  is fractional for some value i.

We know that every feasible solution to the LP relaxation satisfies

$$x_{r(i)} + \sum_{j \in N} A_{ij} x_j = b_i.$$

## **Getting Cutting Planes in General**

Solve the relaxation and get the LP in a canonical form for B.

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Suppose  $\bar{x}$  is NOT INTEGER. Then,  $b_i$  is fractional for some value i.

Every feasible solution to the LP relaxation satisfies

$$x_{r(i)} + \sum_{j \in N} A_{ij} x_j \le b_i. \implies x_{r(i)} + \sum_{j \in N} \lfloor A_{ij} \rfloor x_j \le b_i.$$
integer for all  $x$  integer

Hence, every feasible solution to IP satisfies

$$x_{r(i)} + \sum_{j \in N} \lfloor A_{ij} \rfloor x_j \le \lfloor b_i \rfloor$$

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Solve the relaxation and get the LP in a canonical form for B.

$$\max_{\bar{c}} \ \bar{c}^{\top} x + \bar{z}$$
 s. t. 
$$x_B + A_N x_N = b$$
 
$$x \ge \mathbf{0}$$

$$N = \{j: j \notin B\}$$
  $\bar{x}$  basic  $(\bar{x}_N = \mathbf{0}, \bar{x}_B = b)$   $r(i)$  index of  $i^{th}$  basic variable

Suppose  $\bar{x}$  is NOT INTEGER. Then,  $b_i$  is fractional for some value i.

Every feasible solution to IP satisfies

$$x_{r(i)} + \sum_{j \in N} \lfloor A_{ij} \rfloor x_j \le \lfloor b \rfloor$$

However,  $\bar{x}$  does not satisfy  $(\star)$  as

$$\underbrace{x_{r(i)}}_{b_i} + \sum_{j \in N} \lfloor A_{ij} \rfloor \underbrace{x_j}_{=0} = b_i > \lfloor b_i \rfloor.$$



 $(\star)$  is a cutting plane for  $\bar{x}$ .

### The Good and the Bad

#### THE GOOD NEWS:

• The Simplex based cutting plane algorithm eventually will terminate.

#### THE BAD NEWS

If implemented in this way, it will be terribly slow.

#### Ways we can Improve the Algorithm

- Do not use the 2-phase Simplex algorithm to reoptimize; work with the dual instead.
- Add more than one cutting plane at at time.
- Combine it with a divide and conquer strategy (branch and bound).

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### Recap

- We solved the LP relaxation of an integer program.
- If we get an integer solution, we know it is optimal for an integer program; otherwise, we add a cutting plane.
- Cutting planes can be obtained from the final canonical form.
- Careful implementation is key to success.

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