# CO 250: Introduction to Optimization

Module 2: Linear Programs (Canonical Forms)

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$$\max\left\{c^{\top}x: Ax = b, x \ge 0\right\} \tag{P}$$

#### **Definition**

Let B be a basis of A. Then (P) is in canonical form for B if

(P1) 
$$A_B = I$$
, and

(P2) 
$$c_j = 0$$
 for all  $j \in B$ .

$$\max \quad \begin{pmatrix} 0 & 0 & 2 & 4 \end{pmatrix} x$$
 s.t. 
$$\begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$
 
$$x_1, x_2, x_3, x_4 \ge 0$$

Canonical form for  $B = \{1, 2\}$ 

$$\max\left\{c^{\top}x: Ax = b, x \ge 0\right\} \tag{P}$$

#### **Definition**

Let B be a basis of A. Then (P) is in canonical form for B if

(P1) 
$$A_B = I$$
, and

(P2) 
$$c_j = 0$$
 for all  $j \in B$ .

$$\begin{array}{llll} \max & (-2 & 0 & 0 & 6)x + 2 \\ \text{s.t.} & & \\ \begin{pmatrix} -1 & 1 & 0 & 3 \\ 1 & 0 & 1 & -1 \end{pmatrix} x = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ x_1, x_2, x_3, x_4 \geq 0 & & \end{array}$$

Canonical form for  $B = \{2, 3\}$ 

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$$\max\left\{c^{\top}x: Ax = b, x \ge 0\right\} \tag{P}$$

#### Idea

For any basis B we can "rewrite" (P) so that it is in canonical form for a basis B and such that the resulting LP behaves the same as (P).

More formally, we will show the following:

## **Proposition**

For any basis B, there exists (P') in canonical form for B such that

- (1) (P) and (P') have the same feasible region, and
- (2) feasible solutions have the same objective value for (P) and (P').

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### **Proposition**

For any basis B, there exists (P') in canonical form for B such that

- (1) (P) and (P') have the same feasible region, and
- (2) <u>feasible solutions</u> have the same objective value for (P) and (P').

## Example

(1)  $\bar{x} = (1, 2, 0, 0)^{\mathsf{T}}$  is feasible for both LPs.

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# Illustration with an Example

max 
$$\underbrace{\begin{pmatrix} 0 & 0 & 2 & 4 \end{pmatrix} x}_{c}$$
s.t.
$$\underbrace{\begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix}}_{A} x = \underbrace{\begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{b}$$

$$x_{1}, x_{2}, x_{3}, x_{4} \ge 0$$
(P)

### Question

How do we rewrite (P) in canonical form for basis  $B = \{2, 3\}$ ?

- (P1) Replace Ax = b by A'x = b' with  $A'_B = I$ .
- (P2) Replace  $c^{\top}x$  by  $\bar{c}^{\top}x + \bar{z}$  with  $\bar{c}_B = \emptyset$  ( $\bar{z}$  constant).

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# Rewriting Constraints – Example

$$\underbrace{\begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix}}_{A} x = \underbrace{\begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{b}$$

(P1) Replace Ax = b by A'x = b' with  $A'_B = I$  for  $B = \{2, 3\}$ .

$$\begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

 $\Leftrightarrow$ 

$$\begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

 $\Leftrightarrow$ 

$$\begin{pmatrix} -1 & 1 & 0 & 3 \\ 1 & 0 & 1 & -1 \end{pmatrix} x = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

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# Rewriting Constraints - General

Consider the system Ax = b with basis B of A.

(P1) Replace Ax = b by A'x = b' with  $A'_B = I$  for some basis B.

$$Ax = b$$



$$\underbrace{A_B^{-1}A}_{A'}x = \underbrace{A_B^{-1}b}_{b'}$$

#### Remarks

- $A'_{R} = I$ .
- Ax = b and A'x = b' have the same set of solutions.

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# Rewriting the Objective Function – Example

$$\max \quad z = \underbrace{\begin{pmatrix} 0 & 0 & 2 & 4 \end{pmatrix} x}_{c^{\top}}$$
 s.t. 
$$\underbrace{\begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix}}_{A} x = \underbrace{\begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{b}$$
 
$$x_{1}, x_{2}, x_{3}, x_{4} \geq 0$$

- (P2) Replace  $c^{\top}x$  by  $\bar{c}^{\top}x + \bar{z}$  with  $\bar{c}_B = \emptyset$  ( $\bar{z}$  constant) for  $B = \{2, 3\}$ .
- Step 1. Construct a new objective function by
  - multiplying constraint 1 by  $y_1$ ,
  - multiplying constraint 2 by  $y_2$ , and
  - adding the resulting constraints to the objective function.

**Step 2.** Choose  $y_1, y_2$  to get  $\bar{c}_B = 0$ .

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$$\begin{array}{llll} \max & z = (0 & 0 & 2 & 4)x \\ \text{s.t.} & & & \\ \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ & & \\ x_1, x_2, x_3, x_4 \geq 0 \\ \end{array}$$

$$(y_1, y_2) \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x = (y_1, y_2) \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\begin{array}{llll} \max & z = (0 & 0 & 2 & 4)x \\ \text{s.t.} & & & \\ \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ x_1, x_2, x_3, x_4 \geq 0 & & \end{array}$$

$$0 = -(y_1 \ y_2) \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} x + (y_1 \ y_2) \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$z = (0 \ 0 \ 2 \ 4)x$$

$$z = \begin{bmatrix} (0 & 0 & 2 & 4) - (y_1 & y_2) \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} \end{bmatrix} x + (y_1 & y_2) \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

### Remark

For any choice of  $y_1, y_2$  and any feasible solution x,

objective value of x for old objective function = objective value of x for new objective function

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$$z = \underbrace{\begin{bmatrix} (0 \quad \mathbf{0} \quad \mathbf{2} \quad 4) - (y_1 \quad y_2) \begin{pmatrix} 1 & \mathbf{0} & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} \end{bmatrix}}_{\bar{c}^\top} x + \underbrace{\begin{pmatrix} y_1 \quad y_2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{\bar{z}}$$

### Question

How do we choose  $y_1, y_2$  such that  $\bar{c}_B = 0$  for  $B = \{2, 3\}$ ?

$$(0 \quad 0) = \bar{c}_B^{\top} = \begin{pmatrix} 0 & 2 \end{pmatrix} - \begin{pmatrix} y_1 & y_2 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$$

 $\Leftrightarrow$ 

$$(y_1 \ y_2) \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} = (0 \ 2)$$

 $\Leftrightarrow$ 

$$\begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^{\top} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

 $\Leftrightarrow$ 

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$z = \underbrace{\begin{bmatrix} (0 & 0 & 2 & 4) - (y_1 & y_2) \begin{pmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} \end{bmatrix}}_{\bar{c}^{\top}} x + \underbrace{\begin{pmatrix} y_1 & y_2 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix}}_{\bar{z}}$$

#### Question

How do we choose  $y_1, y_2$  such that  $\bar{c}_B = 0$  for  $B = \{2, 3\}$ ?

Choose

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

 $\Rightarrow$ 

$$z = \begin{bmatrix} (0 & \mathbf{0} & \mathbf{2} & 4) - (2 & 0) \begin{pmatrix} 1 & \mathbf{0} & 1 & -1 \\ 0 & 1 & 1 & 2 \end{pmatrix} \end{bmatrix} x + (2 & 0) \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$z = (-2 \ 0 \ 0 \ 6)x + 2$$

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# Rewriting the Objective Function – General

$$\max \quad z = c^{\top} x$$
 s.t. 
$$Ax = b$$
 
$$x \ge 0$$

(P2) Replace  $c^{\top}x$  by  $\bar{c}^{\top}x + \bar{z}$  with  $\bar{c}_B = 0$  ( $\bar{z}$  constant) for some basis B.

$$\begin{array}{rcl} 0 & = & & -y^\top A x + y^\top b \\ z & = & c^\top x \end{array}$$

$$z \quad = \quad \left[ \boldsymbol{c}^\top - \boldsymbol{y}^\top \boldsymbol{A} \right] \boldsymbol{x} + \boldsymbol{y}^\top \boldsymbol{b}$$

#### Remark

For any choice of  $y_1, y_2$  and any feasible solution x,

objective value of x for old objective function = objective value of x for new objective function

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$$z = \underbrace{\left[\boldsymbol{c}^{\top} - \boldsymbol{y}^{\top}\boldsymbol{A}\right]}_{\bar{\boldsymbol{c}}^{\top}}\boldsymbol{x} + \underbrace{\boldsymbol{y}^{\top}\boldsymbol{b}}_{\bar{\boldsymbol{z}}}$$

## Question

How do we choose y such that  $\bar{c}_B = 0$  for a basis B?





$$\mathbb{0}^{\top} = \bar{c}_B^{\top} = c_B^{\top} - y^{\top} A_B$$

$$y^{\top}A_B = c_B^{\top}$$

$$A_B^{\top} y = c_B$$

$$y = \left(A_B^{\top}\right)^{-1} c_B = A_B^{-\top} c_B$$

#### Remark

For any non-singular matrix M,

$$(M^{\top})^{-1} = (M^{-1})^{\top} =: M^{-\top}$$

# Recap

## **Proposition**

Consider A with basis B,

$$\begin{array}{ccc}
\max & c^{\top} x \\
\text{s.t.} & \\
& Ax = b \\
& x \ge 0
\end{array}$$
(P)

$$\max \underbrace{\left[c^{\top} - y^{\top} A\right]}_{c} x + y^{\top} b$$
s.t.
$$\underbrace{A_{B}^{-1} A}_{A'} x = A_{B}^{-1} b$$

$$x \ge 0$$
(P')

where  $y = A_B^{-\top}$ . Then

- (1) (P') is in canonical form for basis B, i.e.,  $\bar{c}_B=0$  and  $A_B'=I$ .
- (2) (P) and (P') have the same feasible region.
- (3) Feasible solutions have the same objective value for (P) and (P').

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