

## Solution to Practice 2e

**B2(a):** We are looking for the set of vectors that satisfy  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = 0$ , which is the same as  $3x_1 + 2x_2 + x_3 = 0$ . Replacing the variable  $x_1$  with the parameter  $s$  and the variable  $x_2$  with the parameter  $t$ , we see that the general solution to this equation is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} s \\ t \\ -3s - 2t \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}$$

So  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix} \right\}$  is a basis for  $\mathbb{S}^\perp$ .

**B2(b):** We are looking for the set of vectors that satisfy  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ -4 \end{bmatrix} = 0$

and  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} = 0$ . This is the same as looking for solutions to the homogeneous system

$$\begin{array}{rrcr} x_1 & +2x_2 & -4x_3 & = 0 \\ -x_1 & +2x_2 & +2x_3 & = 0 \end{array}$$

To solve this system, we row reduce the coefficient matrix:

$$\begin{array}{l} \begin{bmatrix} 1 & 2 & -4 \\ -1 & 2 & 2 \end{bmatrix} \xrightarrow{R_2 + R_1} \begin{bmatrix} 1 & 2 & -4 \\ 0 & 4 & -2 \end{bmatrix} \xrightarrow{(1/4)R_2} \\ \sim \begin{bmatrix} 1 & 2 & -4 \\ 0 & 1 & -1/2 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & -1/2 \end{bmatrix} \end{array}$$

So our system is equivalent to the system

$$\begin{array}{rrcr} x_1 & & -3x_3 & = 0 \\ & x_2 & -(1/2)x_3 & = 0 \end{array}$$

Replacing the variable  $x_3$  with the parameter  $t$ , we see that the general solution to this equation is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3t \\ (1/2)t \\ t \end{bmatrix} = t \begin{bmatrix} 3 \\ 1/2 \\ 1 \end{bmatrix}$$

So  $\left\{ \begin{bmatrix} 3 \\ 1/2 \\ 1 \end{bmatrix} \right\}$  is a basis for  $\mathbb{S}^\perp$ .

**B2(c):** We are looking for the set of vectors that satisfy  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} = 0$ ,

$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = 0$ , and  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} = 0$ . This is the same as looking for solutions to the homogeneous system

$$\begin{array}{rrrr} x_1 & +2x_2 & -1x_3 & = 0 \\ 2x_1 & +x_2 & +x_3 & = 0 \\ -x_1 & +x_2 & +x_3 & = 0 \end{array}$$

To solve this system, we row reduce the coefficient matrix:

$$\begin{array}{l} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & 1 \\ -1 & 1 & 1 \end{bmatrix} \begin{array}{l} R_2 - 2R_1 \\ R_3 + R_1 \end{array} \sim \begin{bmatrix} 1 & 2 & -1 \\ 0 & -3 & 3 \\ 0 & 3 & 0 \end{bmatrix} \begin{array}{l} \\ (-1/3)R_2 \end{array} \\ \sim \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -1 \\ 0 & 3 & 0 \end{bmatrix} \begin{array}{l} \\ R_3 - 3R_2 \end{array} \sim \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 3 \end{bmatrix} \begin{array}{l} \\ (1/3)R_3 \end{array} \\ \sim \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} \begin{array}{l} R_1 + R_3 \\ R_2 + R_3 \end{array} \sim \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{array}{l} R_1 - 2R_2 \\ \end{array} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{array}$$

So the only solution to our system is  $x_1 = 0$ ,  $x_2 = 0$ ,  $x_3 = 0$ , which means that  $\mathbb{S}^\perp = \{\vec{0}\}$ , and thus the empty set is the basis for  $\mathbb{S}^\perp$ .

**B2(d):** We are looking for the set of vectors that satisfy  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 1 \\ -1 \\ 0 \end{bmatrix} = 0$ ,

$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \end{bmatrix} = 0$ , and  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ -1 \\ 3 \\ 1 \end{bmatrix} = 0$ . This is the same as looking for solutions to the homogeneous system

$$\begin{array}{rrrr} 2x_1 & +x_2 & -x_3 & = 0 \\ x_1 & +2x_2 & +x_3 & +x_4 = 0 \\ & -x_2 & +3x_3 & +x_4 = 0 \end{array}$$

To solve this system, we row reduce the coefficient matrix:

$$\begin{aligned}
& \begin{bmatrix} 2 & 1 & -1 & 0 \\ 1 & 2 & 1 & 1 \\ 0 & -1 & 3 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \sim \begin{bmatrix} 1 & 2 & 1 & 1 \\ 2 & 1 & -1 & 0 \\ 0 & -1 & 3 & 1 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \\
& \sim \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & -3 & -3 & -2 \\ 0 & -1 & 3 & 1 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \sim \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & -1 & 3 & 1 \\ 0 & -3 & -3 & -2 \end{bmatrix} \xrightarrow{-R_2} \\
& \sim \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 0 & -3 & -3 & -2 \end{bmatrix} \xrightarrow{R_3 + 3R_2} \sim \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & -12 & -5 \end{bmatrix} \xrightarrow{(-1/12)R_3} \\
& \sim \begin{bmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & 1 & 5/12 \end{bmatrix} \xrightarrow{\begin{matrix} R_1 - R_3 \\ R_2 + 3R_3 \end{matrix}} \sim \begin{bmatrix} 1 & 2 & 0 & 7/12 \\ 0 & 1 & 0 & 3/12 \\ 0 & 0 & 1 & 5/12 \end{bmatrix} \xrightarrow{\begin{matrix} R_1 - 2R_2 \\ \end{matrix}} \\
& \sim \begin{bmatrix} 1 & 0 & 0 & 1/12 \\ 0 & 1 & 0 & 3/12 \\ 0 & 0 & 1 & 5/12 \end{bmatrix}
\end{aligned}$$

So our system is equivalent to the system

$$\begin{aligned}
x_1 & + (1/12)x_4 = 0 \\
x_2 & + (3/12)x_4 = 0 \\
x_3 & + (5/12)x_4 = 0
\end{aligned}$$

Replacing the variable  $x_4$  with the parameter  $t$ , we see that the general solution to this equation is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} (-1/12)t \\ (-3/12)t \\ (-5/12)t \\ t \end{bmatrix} = t \begin{bmatrix} -1/12 \\ -3/12 \\ -5/12 \\ 1 \end{bmatrix} = t \begin{bmatrix} -1 \\ -3 \\ -5 \\ 12 \end{bmatrix}$$

So  $\left\{ \begin{bmatrix} -1 \\ -3 \\ -5 \\ 12 \end{bmatrix} \right\}$  is a basis for  $\mathbb{S}^\perp$ .

**D3** Suppose that  $\vec{s} \in \mathbb{S}$ , and  $\vec{t} \in \mathbb{S}^\perp$ . Then  $\vec{s} \cdot \vec{t} = 0$ , so  $\vec{s} \in (\mathbb{S}^\perp)^\perp$ . This shows that  $\mathbb{S} \subset (\mathbb{S}^\perp)^\perp$ . To see that  $(\mathbb{S}^\perp)^\perp \subset \mathbb{S}$ , let  $\{\vec{v}_1, \dots, \vec{v}_k\}$  be an orthonormal basis for  $\mathbb{S}$  and  $\{\vec{v}_{k+1}, \dots, \vec{v}_n\}$  be an orthonormal basis for  $\mathbb{S}^\perp$ , so that  $\{\vec{v}_1, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_n\}$  is an orthonormal basis for  $\mathbb{R}^n$ . Now, for any vector  $\vec{x} \in (\mathbb{S}^\perp)^\perp$ , there are scalars  $x_1, \dots, x_n$  such that

$$\vec{x} = x_1 \vec{v}_1 + \dots + x_k \vec{v}_k + x_{k+1} \vec{v}_{k+1} + \dots + x_n \vec{v}_n$$

Moreover, since  $\{\vec{v}_1, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_n\}$  is an *orthonormal* basis for  $\mathbb{R}^n$ , we know that the coefficients  $x_i$  are  $\vec{x} \cdot \vec{v}_i$ . But, since  $\vec{x} \in (\mathbb{S}^\perp)^\perp$ , we know that  $\vec{x} \cdot \vec{v} = 0$  for any  $\vec{v} \in \mathbb{S}^\perp$ . Thus, we specifically have  $\vec{x} \cdot \vec{v}_i = 0$  for  $k+1 \leq i \leq n$ . This means that  $x_i = 0$  for  $k+1 \leq i \leq n$ , so we can write

$$\vec{x} = x_1 \vec{v}_1 + \dots + x_k \vec{v}_k$$

Since  $\vec{x}$  is a linear combination of the vectors in our basis  $\{\vec{v}_1, \dots, \vec{v}_k\}$  for  $\mathbb{S}$ , we see that  $\vec{x} \in \mathbb{S}$ , as desired.