CSE 461 Programming Assignment 1

DUE

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Description

- This is an individual assignment. Please do not collaborate
- If you think that this document does not clearly describes the assignment, ask questions before its too late.

This assignment is about implementing a simple ray tracer.

Scene Description File

This file is in "xml" format. You can use xml parsers.

Definition of the elements which can be found in a scene description file:

- maxraytracedepth: This is positive integer which defines the maximum recursive ray tracing depth. Rays starting from camera have depth of 0.
- background: r, g, b values for the pixel in a no-hit case. You are going to set the color of the pixel to this value in case the ray does not intersect with any objects in the scene.

<background>r g b</background>

- camera: This defines a camera in the scene. It has the following subfields:
 - position: x,y,z coordinates of the camera.
 - gaze: gaze direction of the camera.
 - up: up vector of the camera.
 - nearplane: left, right, bottom, top values of the image plane.
 - neardistance: distance between the image plane and the camera. gaze vector is perpendicular to the image plane.
 - imageresolution: nx and ny dimensions of the image.

<camera>

```
<position>x y z</position>
  <gaze>x y z</gaze>
  <up>x y z</up>
  <nearplane>left right bottom top</nearplane>
  <neardistance> distance </neardistance>
  <imageresolution>nx ny</imageresolution>
</camera>
```

• ambientlight: r, g, b ambient light values. This is the amount of light received by the surface which in shadow.

<ambientlight>r g b</ambientlight>

• pointlight: point light source defined by a position vector and an intensity vector.

- material: This has the following subfields (the values are between 0.0 and 1.0):
 - ambient
 - diffuse
 - specular
 - mirrorreflactance
 - $\ {\tt phongexponent}$

```
<material id="someid">
    <ambient>x y z</ambinet>
    <diffuse>x y z</diffuse>
    <specular>x y z</specular>
    <phongexponent>e</phongexponent>
    <mirrorreflactance>x y z</mirrorreflanctance>
</material>
  • vertexdata: lists the x, y, z coordinates of the all the vertices defined in the scene. The vertices are referred
     by faces field under mesh
<vertexdata>
x1 y1 z1
x2 y2 z2
x3 y3 z3
</re>
  • mesh: Each mesh is a list of faces. Each face is a triangle. Triangles are defined by three vertex indices given
     in counter-clockwise direction.
<mesh id ="someid">
    <materialid>id</materialid>
    <faces>
        face1_vertex1_id face1_vertex2_id face1_vertex3_id
        face2_vertex1_id face2_vertex2_id face2_vertex3_id
        face3_vertex1_id face3_vertex2_id face3_vertex3_id
    </faces>
</mesh>
Here is the complete skeleton of the scene description file:
<scene>
    <maxraytracedepth>n</maxraytracedepth>
    <background>r g b</background>
    <camera>
        <position>x y z</position>
        <gaze>x y z</gaze>
        <up>x y z</up>
        <nearplane>left right bottom top</nearplane>
        <neardistance> distance </neardistance>
        <imageresolution>nx ny</imageresolution>
    </camera>
    dights>
        <ambientlight>r g b</ambientlight>
        <pointlight id="someid">
             <position> x y z </position>
             <intesity> x y z </intensity>
        </pointlight>
    </lights>
    <materials>
        <material id="someid">
```

<ambient>x y z</ambinet>
<diffuse>x y z</diffuse>
<specular>x y z</specular>

<phongexponent>e</phongexponent>

<mirrorreflactance>x y z</mirrorreflanctance>

```
</material>
    </materials>
    <vertexdata>
       x1 y1 z1
        x2 y2 z2
        x3 y3 z3
        . . .
    </re>
    <objects>
        <mesh id="someid">
            <materialid>id</materialid>
                <faces>
                    face1_vertex1_id face1_vertex2_id face1_vertex3_id
                    face2_vertex1_id face2_vertex2_id face2_vertex3_id
                    face3_vertex1_id face3_vertex2_id face3_vertex3_id
                </faces>
        </mesh>
    </objects>
</scene>
Below is a simple example scene:
    <maxraytracedepth>6</maxraytracedepth>
   <background>0 0 0</background>
    <camera>
        <position>0 0 0</position>
        <gaze>0 0 -1</gaze>
        <up>0 1 0</up>
        <nearplane>-1 1 -1 1</nearplane>
        <neardistance> 1 </neardistance>
        <imageresolution>800 800</imageresolution>
    </camera>
    dights>
        <ambientlight>25 25 25</ambientlight>
        <pointlight id="1">
            <position> 0 0 0 </position>
            <intesity> 1000 1000 1000 </intensity>
        </pointlight>
    </lights>
    <materials>
        <material id="1">
            <ambient>1 1 1</ambinet>
            <diffuse>1 1 1</diffuse>
            <specular>1 1 1</specular>
            <phongexponent>1</phongexponent>
            <mirrorreflactance>0 0 0</mirrorreflanctance>
        </material>
        . . .
    </materials>
```

```
<vertexdata>
        -0.5 0.5 -2
        -0.5 -0.5 -2
        0.5 -0.5 -2
        0.5 \ 0.5 \ -2
    </re>
    <objects>
        <mesh id="1">
            <materialid>1</materialid>
                <faces>
                    3 1 2
                    1 3 4
                </faces>
        </mesh>
        . . .
    </objects>
</scene>
```

Remarks

- There may be more than 1 material
- There may be more than 1 point light source
- There may be more than 1 mesh.
- It is a good idea to come with an object oriented solution.
- The performance of your solution is important. So, try to write efficient code.
- Discuss about the running time of your implementation. Test using different scenes and measure the render time.
- In order to calculate the shadow properly and avoid numeric errors, you may need to create an offset on surface points where the rays hit. For this, define a constant in your program.
- Intensity of the light sources are going to be positive numbers. They may exceed 255.
- Any pixel value cannot exceed 255. If the result of the calculation is greater than 255, set it to 255.
- The irradiance of the point light source is inversely proportional to the square of the distance to the light.

Turn in

- You are going to submit your implementation in a zip file. You will include a documentation about hot to compile and/or run your program.
- You are going to demonstrate the run of your program. It is going to be either through a teams meeting or in a face-to-face meeting.