Analysis Notes

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1 Sequence and Series of Functions

1.1 Uniform Convergence

Definition 1.1 (Pointwise Convergence). A sequence of functions $(f_n)_n$ converges pointwise to a function f on E if for every $\varepsilon > 0$ and for all $x \in E$ there is an integer N (which depends on x) such that for all $n \ge N$

$$|f_n(x) - f(x)| < \varepsilon$$

Definition 1.2 (Uniform Convergence). A sequence of functions $(f_n)_n$ converges uniformly to a function f on E if for every $\varepsilon > 0$ there is an integer N such that for all $n \ge N$ and for all $x \in E$ we have

$$|f_n(x) - f(x)| < \varepsilon$$

Theorem 1.1 (Limit of uniformly convergent, bounded sequence of functions is bounded.). *If* $(f_n)_n$ *converges uniformly to f and each* f_n *is bounded, then f is bounded.*

Proof. Fix $\varepsilon > 0$. Uniform convergence implies that $\exists N \in \mathbb{N}$ such that $\forall n \geq N$ and $\forall x \in X$ we have $|f_n(x) - f(x)| < \varepsilon$. Further, boundedness of the sequence of functions implies that $\forall n \ \exists M_n \in [0, \infty)$ such that $|f_n(x)| \leq M_n \ \forall x \in X$. Fix an $n \geq N$. Then $\forall x \in X$

$$|f(x)| = |f(x) - f_n(x) + f_n(x)|$$

 $\leq |f(x) - f_n(x)| + f_n(x)$ (triangle inequality)
 $< \varepsilon + M_n$ (uniform convergence and boundedness)

Thus $|f(x)| < \varepsilon + M_n \ \forall x \in X$, so f(x) is bounded.

Theorem 1.2 (Limit of uniformly convergent, continuous sequence of functions is continuous.). *If* $(f_n)_n$ *converges uniformly to f and each* f_n *is continuous, then f is continuous.*

Proof. Fix $\varepsilon > 0$. Uniform convergence implies that $\exists N \in \mathbb{N}$ such that $\forall n \geq N$ and $\forall x \in X$ we have $|f_n(x) - f(x)| < \frac{\varepsilon}{3}$. Continuity of each function $f_n(x)$ at $x \in X$ in the sequence implies that $\exists \delta > 0$ such that $\forall y$ for which $|x - y| < \delta$ we have that $|f_n(x) - f_n(y)| < \frac{\varepsilon}{3}$. Then $\forall y$ for which $|x - y| < \delta$ we have that

$$|f(x) - f(y)| = |f(x) - f_n(x) + f_n(x) - f_n(y) + f_n(y) - f(y)|$$

$$\leq |f(x) - f_n(x)| + |f_n(x) - f_n(y)| + |f_n(y) - f(y)| \qquad (\Delta)$$

$$< \frac{\varepsilon}{3} + \frac{\varepsilon}{3} + \frac{\varepsilon}{3} \qquad \text{(uniform convergence and continuity of } f_n \text{ at } x)$$

$$= \varepsilon$$

Therefore *f* is continuous at x, $\forall x \in X$.

Definition 1.3 (Uniformly cauchy). A sequence of functions (f_n) is **uniformly cauchy** if $\forall \varepsilon > 0 \ \exists N \in \mathbb{N}$ such that $\forall n, m \geq N$ and $\forall x \in X$, we have $|f_n(x) - f_m(y)| < \varepsilon$.

Theorem 1.3 (Uniform convergence iff uniform cauchy). A sequence $(f_n)_n$ of functions on a metric space X converges uniformly if and only if it is uniformly Cauchy.

Proof. Fix $\varepsilon > 0$.

 \Rightarrow Uniform convergence implies $\exists N$ such that $\forall n \geq N$ and $\forall x \in X$ we have that $|f_n(x) - f(x)| < \frac{\varepsilon}{2}$. Then $\forall n, m \geq N$ and $\forall x \in X$ we have that

$$|f_n(x) - f_m(x)| = |f_n(x) - f(x) + f(x) - f_m(x)|$$

$$\leq |f_n(x) - f(x)| + |f(x) - f_m(x)|$$

$$< \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon$$

Therefore $(f_n)_n$ is uniformly cauchy.

 \leftarrow Notice that $(f_n)_n$ is a cauchy sequence in a complete metric space (\mathbb{R}), therefore it converges pointwise. We need to show uniform convergence. [[Incomplete]]

Theorem 1.4 (Weierstrass M-test). Let $(f_n)_n$ be a sequence of functions on a metric space X such that there exists a sequence of non-negative real numbers $(M_n)_n$ such that $\forall n$ we have that

$$|f_n(x)| \le M_n \tag{1.1}$$

If $\sum_{n=1}^{\infty} M_n$ converges, then the series $\sum_{n=1}^{\infty} f_n$ converges uniformly. That is, the sequence of partial sums $(\sum_{n=1}^{m} f_n)_m$ converges uniformly.

Proof. We will show that the sequence of partial sums is uniformly cauchy, which then implies that sequence of partial sums converges uniformly. Fix $\varepsilon > 0$. The Cauchy criterion (adapted for series: sequences of partial sums) implies that since $\sum_{n=1}^{\infty} M_n$ converges, there exists an N such that $\forall m, n \ m \ge n \ge N$ we have that

$$\left|\sum_{k=n}^{m} M_k\right| = \sum_{k=n}^{m} M_k < \varepsilon$$

Therefore $\forall m, n \ m \ge n \ge N$ and $\forall x \in X$ we have that

$$\left| \sum_{k=n}^{m} f_k(x) \right| \leq \sum_{k=n}^{m} |f_k(x)|$$

$$\leq \sum_{k=n}^{m} M_k$$

$$\leq \varepsilon$$
(\Delta)

Therefore $(\sum_{n=1}^{m} f_n)_m$ is uniformly cauchy, so the series converges uniformly.

1.2 Power Series

Definition 1.4 (Power Series). A **power series** is a function of the form

$$f(x) = \sum_{n=0}^{\infty} c_n x^n \tag{1.2}$$

where $c_n \in \mathbb{C}$ are complex coefficients.

Definition 1.5 (Radius of convergence). To a power series we can associate a number $R \in [0, \infty]$ (thus R is an *extended* real number) called its **radius of convergence** such that

- (i) $\sum_{n=0}^{\infty} c_n x^n$ converges for every |x| < R.
- (ii) $\sum_{n=0}^{\infty} c_n x^n$ diverges for every |x| > R.

Theorem 1.5 (Power series continuous on interval of convergence). A power series with radius of convergence R converges uniformly on $[-R + \varepsilon, R - \varepsilon]$ for every $0 < \varepsilon < R$, Therefore, power series are continuous on (-R, R).

Theorem 1.6 (Abel summation (summation by parts)).

$$\sum_{n=0}^{N} (a_n - a_{n-1})b_n = a_N b_N + \sum_{n=0}^{N-1} a_n (b_n - b_{n+1})$$
(1.3)

Proof. Assume that $a_{-1} = 0$. We can derive this formula by reordering terms:

$$\sum_{n=0}^{N} (a_n - a_{n-1})b_n = a_0b_0 + a_1b_1 - a_0b_1 + a_2b_2 - a_1b_2 + \dots + a_Nb_N - a_{N-1}b_N$$

$$= a_0(b_0 - b_1) + a_1(b_1 - b_2) + a_{N-1}(b_{N-1} - b_N) + a_Nb_N$$

$$= a_Nb_N + \sum_{n=0}^{N-1} a_n(b_n - b_{n+1})$$

Theorem 1.7 (Abel). Let $f(x) = \sum_{n=0}^{\infty} c_n x^n$ be a power series with radius of convergence R = 1. Assume $\sum_{n=0}^{\infty} c_n$ converges. Then

$$\lim_{x \to 1^{-}} f(x) = \sum_{n=0}^{\infty} c_n \tag{1.4}$$

Proof. We use summation by parts. Set $s_n = \sum_{k=0}^n c_k$ and by convention assume $s_{-1} = 0$.

1.3 ?

Definition 1.6 (Equicontinuous). A family \mathscr{F} of complex functions f defined on a set E in a metric space X is said to be **equicontinuous** on E if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that

$$|f(x) - f(y)| < \varepsilon$$

whenever $d(x,y) < \delta$, $x \in E$, $y \in E$, and $f \in \mathscr{F}$. (Notice: every member of an equicontinuous family is uniformly continuous)

2 Compactness in Metric Spaces

2.1 Review of Basic Topology

Definition 2.1 (Open, open relative to). Let $E \subset U \subset X$, where X is a metric space.

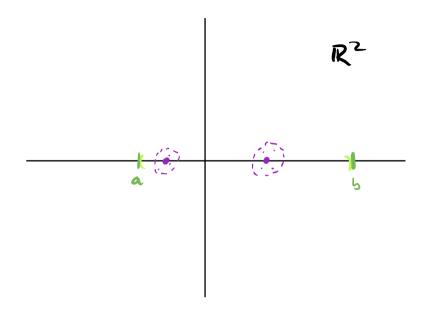
- (i) *E* is an **open** subset of *X* if for each point $p \in E$ there exists an r > 0 such that for all $q \in X$ for which d(p,q) < r we have that $q \in E$.
- (ii) *E* is **open relative to** *Y* if for each point $p \in E$ there exists an r > 0 such that for all $q \in Y$ for which d(p,q) < r we have that $q \in E$.

Example 2.1 (Relative open sets). Let (a,b) be an interval on the real line. Notice that $(a,b) \subset \mathbb{R} \subset \mathbb{R}^2$.

(i) (a, b) is an open subset of (or open relative to) \mathbb{R} .



(ii) (a, b) is *not* an open subset of \mathbb{R}^2 . Indeed, any ball around a point $x \in (a, b) \subset \mathbb{R}$ will leave the x-axis and intersect with points in the second dimension. Thus no point of (a, b) is interior relative to \mathbb{R}^2 .



Theorem 2.1 (Relative open sets). Let $Y \subset X$. A subset E of Y is open relative to Y if and only if $E = Y \cap G$ for some open subset G of X.

Proof. [[Todo]]

Example 2.2 (Relative open sets). Let $X = \mathbb{R}$ and A = [0,1]. Observe that $B = [0,\frac{1}{2}) \subset A \subset X$ is open in A, but not open in X. However, there exists a C open in X such that $B = C \cap A$. One example is $C = (-\frac{1}{2}, \frac{1}{2})$.

Definition 2.2 (Continuous). Suppose X and Y are metric spaces, $E \subset X$, $p \in E$, and f maps E into Y. Then f is **continuous** at p if for every $\varepsilon > 0$ there there exists a $\delta > 0$ such that for all $x \in E$ for which $d_X(x,p) < \delta$, we have that $d_Y(f(x),f(p)) < \varepsilon$.

Definition 2.3 (Uniformly Continuous). Let f be a mapping of a metric space X into a metric space Y. We say that f is **uniformly continuous** on X if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that for all $p, q \in X$ for which $d_X(p,q) < \delta$, we have $d_Y(f(p), f(q)) < \varepsilon$.

Definition 2.4 (Dense). TFAE: *E* is **dense** in *X* if

- (i) Every point of *X* is a limit point of *E* or a point of *E* (or both).
- (ii) $\bar{E} = X$.
- (iii) $\forall \varepsilon > 0$ and $\forall x \in X$ we have that $B(x, \varepsilon) \cap E \neq \emptyset$.

Theorem 2.2 (Functions, inverses, and subsets). *Let* $f : X \to Y$

(i)
$$E \subset Y \Rightarrow f(f^{-1}(E)) \subset E$$

(ii)
$$E \subset X \Rightarrow f(f^{-1}(E)) \supset E$$

2.2 Basic Definitions

Definition 2.5 (Open Cover). Let *I* be an arbitrary index set. A collection $(G_i)_{i \in I}$ of open sets $G_i \subset X$ is called an **open cover** of X if $X \subset \bigcup_{i \in I} G_i$.

Definition 2.6 (Compact). X is **compact** if every open cover of X contains a finite subcover. More explicitly, for every open cover $(G_i)_{i \in I}$ there exists $m \in \mathbb{N}$ and $i_1, i_2, \ldots, i_m \in I$ such that $X \subset \bigcup_{i=1}^m G_{i_i}$.

Remark. This is also called the Heine-Borel property.

Definition 2.7 (Compact subset). A subset $A \subset X$ is called **compact subset** if $(A, d|_{A \times A})$ is a compact metric space. $d|_{A \times A}$ is the restriction of d to $A \times A$.

Theorem 2.3 (Heine-Borel). A subset $A \subset \mathbb{R}^n$ is compact if and only if A is closed and bounded.

Definition 2.8 (Relatively compact or precompact). A subset $A \subset X$ is called **relatively compact** or **precompact** if the closure $\bar{A} \subset X$ is compact.

Example 2.3 (Any finite metric space is compact). Let $X = \{x_i\}_{i=1}^n$ be a finite metric space. Let J be an arbitrary index set, and let $(G_j)_{j \in J}$ be an open cover of X. Therefore, each x_i must be in at least one G_j . Suppose that $x_i \in G_j$, $j_i \in J$. Then $\bigcup_{i=1}^n G_{j_i}$ is a finite subcover.

Example 2.4 $(K = \{0\} \cup \{1/n\}_{n=1}^{\infty} \subset \mathbb{R} \text{ is compact.})$. Let J be an arbitrary index set, and let $(G_j)_{j \in J}$ be an open cover of K. First note that 0 must be contained in some element of the open cover; call it G_i . Since G_i is open, each element of G_i is an interior element, so there exists a ball around 0 of radius $\varepsilon > 0$ contained in G_i . The ball also contains all the elements of K for which $n > \frac{1}{\varepsilon}$. Then, each for each of the finitely many $n \leq \frac{1}{\varepsilon}$ there exists a G_{jn} that contains $\frac{1}{n}$. Therefore every open cover has a finite subcover.

Example 2.5 (Compactness and relative compactness in \mathbb{R}). Any closed and bounded interval [a,b] in \mathbb{R} is compact. Half open intervals [a,b), (a,b] and open intervals (a,b) in \mathbb{R} are relatively compact, since their closures are closed and bounded intervals (assuming b finite).

Example 2.6 (Unit circle in \mathbb{R}^n compact). The set $C = \left\{ x \in \mathbb{R}^n \ \middle| \ \sum_{i=1}^n |x_i|^2 = 1 \right\} \subset \mathbb{R}^n$ is compact. To show closedness, consider the map $f : \mathbb{R}^n \to \mathbb{R}$ defined by $f(\mathbf{x}) = \sum_{i=1}^n x_i^2$, $\mathbf{x} \in \mathbb{R}^n$. This map is continuous (since it is the sum of continuous functions). Then $C = f^{-1}(\{1\})$, and the singleton $\{1\}$ is a closed set in \mathbb{R} . To show boundedness, note that no single element of a vector can have an absolute value greater than one. Therefore $C \subset [-1,1]^n$. C is closed and bounded, and by Heine-Borel, compact.

Example 2.7 (Orthogonal matrices). The set of orthogonal $n \times n$ matrices with real entries (call this $O(n, \mathbb{R})$) is compact as a subset in \mathbb{R}^2 . To see this, let M_n be the set of all $n \times n$ matrices with real entries. Define a function $f: M_n \to M_n$ where $f(A) = A^T A$. This

mapping is continuous. To see this, first note that $f: A \to A$ is the identity map and hence continuous. Also $f: A \to A^T$ is continuous: this follows since $||A|| = ||A^t||$, so

$$||f(A) - f(B)|| = ||B^t - A^t||$$

= $||(B - A)^t||$
= $||B - A||$

Thus whenever $||B - A|| < \varepsilon$, we have $||f(A) - f(B)|| < \varepsilon$ (hence we set $\delta = \varepsilon$). The product of two continuous functions is continuous.

Since an orthogonal matrix O has inverse O^T , we have that $f^{-1}(I) = O(n, \mathbb{R})$. The continuity of f implies that $O(n, \mathbb{R})$ is closed since it is the preimage of a singleton (which is a closed set).

To show boundedness, recall that the columns of orthogonal matrices are orthonormal. Therefore, the absolute value of an element cannot be larger than 1 in absolute value. Thus $O(n, \mathbb{R}) \subset [-1, 1]^{n^2}$. Then by Heine-Borel, $O(n, \mathbb{R})$ is compact.

Theorem 2.4 (Compact subsets of metric spaces are closed.).

Proof. Let X be a metric space and K a compact subset of X. To show K is closed, we will show that its complement K^c is open. To do this, we must show that for all $p \in K^c$, there exists a neighborhood of p completely contained in K^c (and hence does *not* intersect K).

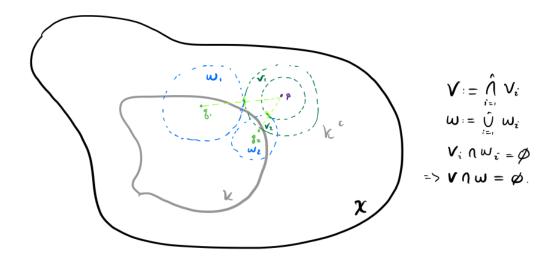
Let $q \in K$. We will construct two types of neighborhoods:

$$W_q = \left\{ x \in X \,\middle|\, d(x,q) < \frac{1}{2}d(p,q) \right\}$$
 (neighborhood of q)
$$V_q = \left\{ x \in X \,\middle|\, d(x,p) < \frac{1}{2}d(p,q) \right\}$$
 (neighborhood of p)

Notice that the union of all W_q forms an open cover of K. Since K is compact, this open cover must have a finite subcover, $W = \bigcup_{i=1}^n W_{q_i}$. Define $V = \bigcap_{i=1}^n V_i$, which is still a neighborhood of p. By construction (since we have used open balls), $V_{q_i} \cap W_{q_i} = \emptyset$. Since $V \subseteq V_{q_i}$, $V \cap W_{q_i} \subseteq V_{q_i} \cap W_{q_i} = \emptyset$. Therefore

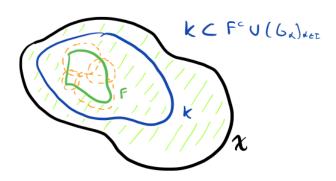
$$V \cap W = (V \cap W_1) \cup \cdots \cup (V \cap W_n) = \emptyset$$

Since $K \subseteq W$, we have that $V \subseteq K = \emptyset$. Thus V is a neighborhood of p completely contained in K^c . Since p was arbitrary, K^c is open, and K is closed.



Theorem 2.5 (Closed subsets of compact sets are compact.).

Proof with compactness. Let $F \subset K \subset X$, where F is closed (relative to X) and K is compact. Let $(G_{\alpha})_{\alpha \in I}$ be an open cover of F. Since F is closed, F^c is open and $F^c \cup (G_{\alpha})_{\alpha \in I}$ is an open cover of K. K is compact, so every open cover has a finite subcover: $K \subset F^c \cup (G_{\alpha_i})_{i=1}^n$. Since $F \subset K$, this finite open cover also covers F, but clearly we don't need F^c in the cover. Therefore F has a finite subcover: $F \subset (G_{\alpha_i})_{i=1}^n$.



Proof with sequential compactness. Let $F \subset K \subset X$, where F is closed (relative to X) and K is compact. Let (x_n) be a sequence of points in F (so is also in X). Since X is sequentially compact, there is a subsequence (x_{n_k}) converging to some point $x \in X$. Since F is closed, $x \in X$. Therefore F is sequentially compact since every sequence in F has a convergent subsequence.

Theorem 2.6 (The intersection of a nested sequence of compact nonempty sets is compact and nonempty.).

Proof. Let (A_n) be a sequence of compact nonempty sets. **Compact:** We know that each A_n is closed. The intersection of closed sets is closed, so $\cap A_n$ is closed. Notice that $\cap A_n \subset A_1$ is a closed subset of a compact set, so is also compact.

Nonempty: Since each A_n is nonempty, fix an $a_n \in A_n$. The sequence $(a_n) \subset A_1$. Sequential compactness of A_1 implies that there is a subsequence (a_{n_k}) converging to some point $a \in A_1$. Notice that this limit must also be in A_2 , since the sequence (a_{n_k}) is also in A_2 (except for potentially the first term, which does not affect convergence). This holds for all A_n , so $p \in \cap A_n$, which shows the intersection is nonempty.

Theorem 2.7. Let X be a compact metric space. Then there exists a countable, dense set $E \subset X$.

Proof. We will show that $\forall \varepsilon > 0$ and $\forall x \in X$ we can find a a set E such that for each open ball in X we have that $B(x, \varepsilon) \cap E \neq \emptyset$. Fix $\varepsilon > 0$ and define an open cover of X as follows:

$$B_n = \bigcup_{x \in X} B(x, \frac{1}{n}) \tag{2.1}$$

X is compact so the open cover B_n must have a finite subcover. Let E be the union of the centers of the balls of each finite subcover. E is the countable union of finite sets, so it is countable. Now fix $x \in X$. Choose n such that $\varepsilon < \frac{1}{n}$. Since B_n covers X, there must be some ball centered at a point of E, call it E, that contains E. Thus E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable. Now fix E is the countable union of finite sets, so it is countable.

2.3 Compactness and Continuity

Theorem 2.8 (Continuous mappings on compact sets are uniformly continuous.). Let X, Y be metric spaces and assume X is compact. If $f: X \to Y$ is continuous, then it is uniformly continuous.

Proof. Fix $\varepsilon > 0$. **Goal:** We need to find a $\delta > 0$ such that for all $x, y \in X$ for which $d_X(x,y) < \delta$, we have $d_Y(f(x),f(y)) < \varepsilon$.

Use continuity to create balls of points (which cover) X and are mapped by the function: Since f is continuous, we know that for each $x \in X$, there exists a number $\delta_x > 0$ such that for all $y \in X$ for which $d_X(x,y) < \delta_x$, we have that $d_Y(f(x), f(y)) < \varepsilon/2$. Now, let B_X be a ball of radius $\delta_X/2$ centered at x. Formally, we can write

$$B_x = B(x, \delta_x/2) = \{ y \in X | d_X(x, y) < \delta_x/2 \}$$

Then $(B_x)_{x \in X}$ is an open cover of X.

Use compactness to select a finite subcover of these balls and use the smallest radius to create uniformity: By compactness, there exists a finite subcover of X. Let x_1, \ldots, x_m

be the x which generate this finite subcover. Define $\delta > 0$ as follows

$$\delta = \frac{1}{2} \min(\delta_{x_1}, \dots, \delta_{x_m}) \tag{2.2}$$

(notice that δ is indeed positive, since we are taking the minimum of finitely many positive numbers).

Show that our choice of δ **works:** Fix $x, y \in X$ such that $d_X(x, y) < \delta$. There exists and index $i \in \{1, ..., m\}$ such that $x \in B_{x_i}$ (i.e., an element of X is in some ball of the finite subcover). Then

$$d_X(x_i, y) \le d_X(x_i, x) + d_X(x, y) < \frac{1}{2}\delta_{x_i} + \delta < \delta_{x_i}$$
 (2.3)

Now, using the definition of δ_{x_i} , we have that

$$d_Y(f(x), f(y)) \le d_Y(f(x), f(x_i)) + d_Y(f(x_i), f(y)) \le \varepsilon/2 + \varepsilon/2 = \varepsilon \tag{2.4}$$

since $d_X(x_i, x) < \delta_X/2 < \delta_X$ so continuity implies $d_Y(f(x), f(x_i)) < \varepsilon/2$, and $d_X(x_i, y) < \delta_{x_i}$ so continuity implies $d_Y(f(x_i), f(y)) < \varepsilon/2$.

Theorem 2.9 (The image of a continuous function which maps from a compact set is compact). Let X, Y be metric spaces and assume X is compact. If $f: X \to Y$ is continuous, then $f(X) \subset Y$ is compact.

Proof with compactness. Let $(V_i)_{i\in I}$ be an open cover of f(X). Since f is continuous, we have that $U_i = f^{-1}(V_i) \subset X$ is open for each i. Note that $U \subset f^{-1}(f(U))$ for every $U \subset X$. Therefore

$$X \subset f^{-1}(f(X)) \subset \bigcup_{i \in I} f^{-1}(V_i) = \bigcup_{i \in I} U_i$$
(2.5)

which shows that $\bigcup_{i \in I} U_i$ is an open cover of X (the second subset relation uses that applying f^{-1} preserves unions). Since X is compact, there are finitely many indices, say up to m, such

$$X \subset \bigcup_{j=1}^{m} U_{i_j} \tag{2.6}$$

Applying f preserves inclusions and $V \supset f(f^{-1}(V))$, so we have that

$$f(X) \subset \bigcup_{j=1}^{m} f(U_{i_j}) \subset \bigcup_{j=1}^{m} V_{i_j}$$
(2.7)

Thus every open cover of f(X) has a finite subcover, so f(X) is compact.

Proof with sequential compactness. Let (y_n) be a sequence in $f(X) \subset Y$. For each $n \in \mathbb{N}$ choose a point x_n such that $f(x_n) = y_n$. By sequential compactness of X, there is some subsequence (x_{n_k}) converging to a point $x \in X$. The continuity of f implies that $f(x_{n_k})$

converges to $f(p) \in f(X)$. Therefore every sequence in f(X) has a convergent subsequence, so f(X) is sequentially compact.

Theorem 2.10 (Functions from compact sets to the reals achieve their minimum and maximum values). Let X be a compact metric space and $f: X \to \mathbb{R}$ a continuous function. Then there exists $x_0 \in X$ such that $f(x_0) = \sup_{x \in X} f(x)$.

Proof. Since X is compact, we know that the image f(X) is also compact. Since $f(X) \subset \mathbb{R}$, the Heine-Borel theorem tells us that f(X) is closed and bounded. Completeness of the real numbers (every nonempty subset of the real numbers that is bounded above has a supremum in \mathbb{R}). Since f(X) is closed, this supremum must be contained in f(X). Therefore there exists $x_0 \in X$ such that $f(x_0) = \sup_{x \in X} f(x)$.

2.4 Sequential Compactness and Total Boundedness

Definition 2.9 (Sequentially compact). A metric space *X* is **sequentially compact** if every sequence in *X* has a convergent subsequence.

Remark. This is also called the Bolzano-Weierstrass property. Recall that the Bolzano-Weierstrass theorem states that every bounded sequence in \mathbb{R}^n has a convergent subsequence.

Example 2.8 (Finite sets are sequentially compact). Suppose (x_n) is a sequence contained in a finite set. Then this sequence must repeat a term infinitely often. Define the subsequence which is constant at this term: this subsequence clearly converges.

Theorem 2.11 ((Sequentially) compact sets are closed and bounded).

Proof. Let *A* be a sequentially compact subset of a metric space *X*.

Closed: Let p be a limit point of A. Then there is a sequence (a_n) in A that converges to p. Sequential compactness of A implies that there is a subsequence of (a_{n_k}) which converges to some $q \in A$. However every subsequence of a convergent sequence must converge to the same limit as the full sequence, which implies $p = q \in A$. Therefore A is closed.

Bounded: Fix a point $x \in X$. Suppose A is not bounded. Then for each $n \in \mathbb{N}$ there must be some point a_n such that $d(x,a_n) \geq n$. However, sequential compactness implies that some subsequence (a_{n_k}) must converge. Convergent sequences are bounded, so we cannot have that $d(x,a_{n_k}) \to \infty$ as $k \to \infty$. Thus the sequence (a_n) cannot behave as assumed, and it must be that A is bounded for some $r \in \mathbb{R}$.

Definition 2.10 (Bounded metric space). A metric space X is **bounded** if it fits in a single fixed ball. More precisely, there exists some $x_0 \in X$ and r > 0 such that $X \subseteq B(x_0, r)$.

Definition 2.11 (Totally bounded). A metric space X is **totally bounded** if for every $\varepsilon > 0$ there exist finitely many balls of radius ε that cover X.

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Claim 2.1 (Totally bounded implies bounded). Let *X* be a totally bounded metric space. Then it is bounded.

Proof. Fix $\varepsilon > 0$ and $x, y \in X$. Total boundedness implies there exists points $(x_i)_{i=1}^n$ such that $X \subseteq \bigcup_{i=1}^n B(x_i, \varepsilon)$. Suppose $x \in B(x_i, \varepsilon)$ and $y \in B(x_j, \varepsilon)$. Then

$$d(x,y) \le d(x,x_i) + d(x_i,x_j) + d(x_i,y) < d(x_i,x_j) + 2\varepsilon$$
 (2.8)

There are only finitely many values of $d(x_i, x_j)$ we can set $M = \max_{i,j} d(x_i, x_j)$. Therefore $d(x, y) < M + 2\varepsilon$. Therefore X is bounded.

Example 2.9 (Closed and bounded interval in \mathbb{R} is totally bounded). A closed and bounded interval $I = [a, b] \subset \mathbb{R}$ is totally bounded.

Example 2.10 (Bounded but not totally bounded). The following are examples of metric spaces which are bounded but not totally bounded.

(i) ℓ^1 -space is defined to be the collection of all sequences $(a_n)_n$ with $\sum_{n=1}^{\infty} |a_n| < \infty$. We define a distance d on ℓ^1 as follows: $d((a_n)_n, (b_n)_n) = \sum_{n=1}^{\infty} |a_n - b_n|$. The unit ball of ℓ^1 centered at the zero-element (call this call B_1) (i.e., the zero sequence) is bounded but not totally bounded. More precisely,

$$B_1 = \left\{ (a_n)_n \left| \sum_{n=1}^{\infty} |a_n| \le 1 \right. \right\}$$
 (2.9)

Boundedness is clear. Consider the set of sequences $A = \{a_n\}$ where each a_n is zero except for a 1 in the n-th entry. Each $a_n \in B_1$. However,

$$d(a_n, a_m) = \begin{cases} 2 & n \neq m \\ 0 & n = m \end{cases}$$
 (2.10)

If we take balls of radius $\varepsilon = \frac{1}{2}$, then a ball can cover at most one sequence in A. Therefore we can't cover A with finitely ε -balls and hence can't cover B_1 with finitely many ε -balls, so that B_1 is not totally bounded.

(ii) ℓ^{∞} -space is defined to be the collection of all sequences $(a_n)_n$ with $\sup_n |a_n| < \infty$. We define a distance d on ℓ^{∞} as follows: $d((a_n)_n, (b_n)_n) = \sup_n |a_n - b_n|$. Using the same set of sequences as the previous example, note that for all n we have that

$$d(a_n, \{0\}_{n=1}^{\infty}) = 1 (2.11)$$

so that $A \subset B_1$ (with the sup norm). Further,

$$d(a_n, a_m) = \begin{cases} 1 & n \neq m \\ 0 & n = m \end{cases}$$
 (2.12)

But again, if we take balls of radius $\varepsilon = \frac{1}{2}$, then a ball can cover at most one sequence in A. Therefore we can't cover A with finitely ε -balls and hence can't cover B_1 with finitely many ε -balls, so that B_1 is not totally bounded.

Theorem 2.12 (Characterizations of compactness). *Let X be a metric space. The following are equivalent:*

- (i) X is compact.
- (ii) X is sequentially compact.
- (iii) X is totally bounded and complete.

Proof of X is compact \Rightarrow *X is sequentially compact.* We argue by contradiction. Suppose *X* is compact but not sequentially compact. Thus there must exist some sequence $(x_n)_n \subset X$ without a convergence subsequence. Let *A* be the range of the sequence (more explicitly, $A = \{x_n \mid n \in \mathbb{N}\}$). Note that *A* has to be an infinite (if *A* were finite, then there would be a constant subsequence, which is convergent).

Further, A cannot have any limit points (by definition, a point is a limit point of a sequence if there exists a subsequence converging to it). Therefore for each x_n , we can find an open ball centered at x_n that only intersects A at x_n : $B_n \cap A = \{x_n\}$. A is also closed (since it has no limit points), so that X - A is open. We can construct an open cover of X as:

$$X \subseteq \bigcup_{n} B_n \cup \{X - A\} \tag{2.13}$$

Compactness of A implies this open cover has a finite subcover. Therefore the finite subcover can only contain finitely many of the sets in $\bigcup_n B_n$, so can only contain finitely many of the points in A, which is a contradiction to the covering.

Proof of X is sequentially compact \Rightarrow *X is totally bounded and complete.* Suppose *X* is sequentially compact.

Complete: Fix $\varepsilon > 0$. Let $(x_n)_n \subset X$ be a Cauchy sequence. Sequential compactness implies $(x_n)_n$ has a convergent subsequence. Call this subsequence (x_{n_k}) and its limit x. Then there exists an N such that $d(x_{n_k}, x) < \varepsilon$ for all $n_k \geq N$. Since $(x_n)_n$ is Cauchy, there exists an N such that $n, m \geq M$ implies that $d(x_n, x_m) < \varepsilon$. But then

$$d(x_n, x) \le d(x_n, x_{n_k}) + d(x_{n_k}, x) < 2\varepsilon \tag{2.14}$$

for all $n, n_k \ge \max\{N, M\}$. Therefore $(x_n)_n$ converges, so X is complete. In words, Cauchy sequences with convergence subsequences also converge.

Totally Bounded: We argue by contradiction. Suppose X is not totally bounded. Then there exists an $\varepsilon > 0$ such that X cannot be covered by finitely many balls of radius ε . We know that 1 ball of radius ε cannot cover X. Therefore there must be a point of X outside of this ball: call it x_1 . Similarly, 2 balls of radius ε cannot cover X, so pick a point outside of these two balls and call it x_2 . Proceeding in this manner generates an infinite sequence. Now consider the n-th term of this sequence. When we choose n + 1, we must be able to

choose a point such that $d(x_i, x_{n+1}) \ge \varepsilon$ for all $i \in \{1, ..., n\}$. Otherwise, we would have that $X \subseteq \bigcup_{i=1}^n B(x_i, \varepsilon)$, which would be a contradiction to X not being totally bounded. Thus we can construct such a sequence.

Next, since X is sequentially compact, we must be able to find a convergence subsequence. However, the sequence we've constructed has $d(x_i, x_j) \ge \varepsilon$ for all $i, j \in \mathbb{N}$ (hence no subsequence can be Cauchy, and we know that convergence sequences are Cauchy). Therefore we have reached a contradiction and it holds that X is totally bounded.

Proof of X is totally bounded and complete \Rightarrow *X is sequentially compact.* Suppose *X* is totally bounded and complete. Let $(x_n)_n \subset X$ be a sequence. We will construct an convergent subsequence. By the definition of total boundedness, for all $\varepsilon > 0$, *X* can be covered by finitely many balls of radius ε . Observation: One of these balls must contain infinitely many points of $(x_n)_n$. This inspires the following process:

- (i) **Step 1:** Cover *X* with balls of radius 1. One of these balls must contain infinitely many points of $(x_n)_n$. These infinitely many points form a subsequence, call it $(x_n^{(0)})_n$.
- (ii) **Step 2:** Cover *X* with balls of radius $\frac{1}{2}$. One of these balls must contain infinitely many points of $(x_n^{(0)})_n$. These infinitely many points form a subsequence, call it $(x_n^{(1)})_n$.
- (iii) **Step** n: Cover X with balls of radius $\frac{1}{2^n}$. One of these balls must contain infinitely many points of $(x_n^{(n-1)})_n$. These infinitely many points form a subsequence, call it $(x_n^{(n)})_n$.

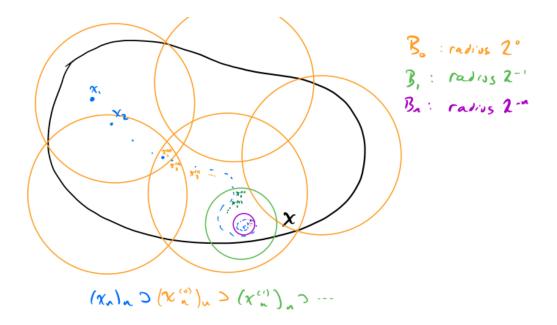
Therefore we have founded nested sequences: $(x_n^{(0)})_n \subset (x_n^{(1)})_n \subset \cdots \subset (x_n^{(n-1)})_n \cdots$. Set $a_n = x_n^{(n)}$ (which is a subsequence of $(x_n)_n$).

Now we show that a_n **is a Cauchy sequence.** Fix $\varepsilon > 0$ and choose N such that $2^{-N+1} < \varepsilon$. Now for $m > n \ge N$ we have that

$$d(a_m, a_n) < 2 \cdot 2^{-n} < 2^{-N+1} < \varepsilon \tag{2.15}$$

since a_m and a_n are contained in the same ball of radius 2^{-n} . Therefore $(a_n)_n$ is a Cauchy sequence, and completeness implies it converges.

We have found a convergence subsequence, so *X* is sequentially compact.



2.5 Equicontinuity and the Arzela-Ascoli Theorem

[[To prove relatively compact, we construct a sequence of functions that converges uniformly.]]

- 3 Approximation Theory and Fourier Series
- 4 Linear Operators and Derivatives
- 5 Differential Calculus in \mathbb{R}^n
- 6 The Baire category theorem

A Review From Elementary Analysis

A.1 The Real and Complex Number System

Definition A.1 (Supremum, Infimum). Let *S* be an ordered set, $E \subset S$, and *E* be bounded above. Suppose there exists an $\alpha \in S$ with the following properties:

- (i) α is an upper bound of E.
- (ii) $If \gamma < \alpha$ then γ is not an upper bound of E.

Then α is called the least upper bound of E or **supremum** of E and we write $\alpha = \sup E$. Similarly, α is the greatest lower bound of E or **infimum** of E if

- (i) α is a lower bound of E.
- (ii) $If \beta > \alpha$ then β is not a lower bound of E. and we write $\alpha = \inf E$.

Definition A.2 (Limit Superior, Inferior). Let (x_n) be a sequence of real numbers.

(i) The limit superior of the sequence is defined by

$$\limsup_{n \to \infty} x_n = \lim_{n \to \infty} \left(\sup_{m \ge n} x_m \right) \tag{A.1}$$

or

$$\limsup_{n \to \infty} x_n = \inf_{n \ge 0} \left(\sup_{m \ge n} x_m \right) = \inf \left\{ \sup \left\{ x_m \mid m \ge n \right\} \mid n \ge 0 \right\} \tag{A.2}$$

Alternatively, the limit superior of the sequence is the smallest $b \in \mathbb{R}$ such that $\forall \varepsilon > 0 \ \exists N$ such that $x_n < b + \varepsilon \ \forall n > N$. Thus, any number larger than the limit superior is an upper bound for the sequence after a finite number of terms (hence, only a finite number of elements are greater that $b + \varepsilon$).

Alternatively, the limit superior of the sequence is the supremum of the set of subsequential limits.

(ii) The limit inferior of the sequence is defined by

$$\liminf_{n \to \infty} x_n = \lim_{n \to \infty} \left(\inf_{m \ge n} x_m \right) \tag{A.3}$$

or

$$\liminf_{n \to \infty} x_n = \sup_{n > 0} \left(\inf_{m \ge n} x_m \right) = \sup \left\{ \inf \left\{ x_m \mid m \ge n \right\} \mid n \ge 0 \right\} \tag{A.4}$$

Theorem A.1 (Properties of limit superiors). Let (x_n) and (y_n) be sequence of real numbers. Then

(i) $\limsup_{n\to\infty} (x_n+y_n) \leq \limsup_{n\to\infty} x_n + \limsup_{n\to\infty} y_n$ (as long as the RHS is not of the form $\infty - \infty$)

Proof. We prove each item in turn.

(i) We have that

$$\limsup_{n\to\infty}(x_n+y_n) = \lim_{n\to\infty}\left(\sup_{m\geq n}\{x_m+y_m,x_{m+1}+y_{m+1},\ldots\}\right) \tag{A.5}$$

Then

$$M_n := \sup_{m \ge n} \{x_m + y_m, x_{m+1} + y_{m+1}, \ldots\} = \sup_{m \ge n} \{x_m + y_m\} \le \sup_{m \ge n} \{x_m\} + \sup_{m \ge n} \{y_m\}$$
(A.6)

Take the limit of both sides to get

$$\lim_{n \to \infty} M_n \le \lim_{n \to \infty} \sup_{m \ge n} \{x_m\} + \lim_{n \to \infty} \sup_{m \ge n} \{y_m\}$$
(A.7)

Thus

$$\limsup_{n\to\infty}(x_n+y_n)\leq \limsup_{n\to\infty}x_n+\limsup_{n\to\infty}y_n \tag{A.8}$$

A.2 Basic Topology

In what follows, assume *X* is a metric space.

Definition A.3 (Limit point). A point p is a **limit point** of the set E if every neighborhood of p contains a point $q \neq p$ such that $q \in E$.

Definition A.4 (Closed). *E* is **closed** if every limit point of *E* is a point of *E*.

Definition A.5 (Interior). A point p is an **interior point** of E if there is a neighborhood N of p such that $N \subset E$.

Definition A.6 (Open). *E* is **open** if every point of *E* is an interior point of *E*.

Definition A.7 (Bounded). *E* is **bounded** if there is a real number *M* and a point $q \in X$ such that d(p,q) < M for all $p \in E$.

Definition A.8 (Separated, Connected). Two subsets A and B of a metric space X are said to be **separated** if both $A \cap \overline{B}$ and $\overline{A} \cap B$ are empty (i.e., if no point of A lies in the closure of B and no point of B lies in the closure of A). A set $E \subset X$ is said to be **connected** if E is not a union of two nonempty separated sets.

A.3 Numerical Sequences and Series

A.3.1 Sequences

Definition A.9 (Convergent Sequence). A sequence (p_n) in a metric space X is said to **converge** if there is a point $p \in X$ such that for every $\varepsilon > 0$ there is an integer N such that $n \ge N$ implies $d(p_n, p) < \varepsilon$.

Definition A.10 (Subsequence, Subsequential Limit). Given a sequence (p_n) , consider a sequence (n_k) of positive integers such that $n_1 < n_2 < n_3 < \cdots$. Then the sequence (p_{n_i}) is called a **subsequence** of (p_n) . If (p_{n_i}) converges, its limit is called a **subsequential limit** of (p_n) .

Observations:

• (p_n) converges to p if and only if every subsequence of (p_n) converges to p.

Theorem A.2 (Sequences in compact metric spaces have a convergent subsequence). If (p_n) is a sequence in a compact metric space X, then some subsequence of (p_n) converges to a point of X.

Theorem A.3 (Bolzano-Weierstrass). Every bounded sequence in \mathbb{R}^k has a convergent subsequence.

Definition A.11 (Cauchy Sequence). A sequence (p_n) in a metric space X is said to be a **Cauchy Sequence** if for every $\varepsilon > 0$ there is an integer N such that $d(p_n, p_m) < \varepsilon$ if $n \ge N$ and $m \ge N$.

Definition A.12 (Diameter). Let *E* be a nonempty subset of a metric space *X*, and let *S* be the set of all real numbers of the form d(p,q) with $p \in E$ and $q \in E$. The sup of *S* is called the **diameter** of *E*.

Theorem A.4 (Facts about Cauchy sequences). We have that

- (i) In any metric space X, every convergent sequence is a Cauchy sequence.
- (ii) If X is a compact metric space and if (p_n) is a Cauchy sequence in X, then (p_n) converges to some point of X.

(iii) In \mathbb{R}^k , every Cauchy sequence converges.

Definition A.13 (Complete). A metric space in which every Cauchy sequence converges is **complete**.

Definition A.14 (Monotonically increasing, decreasing). A sequence (s_n) of real numbers is said to be

- (i) Monotonically increasing if $s_n \leq s_{n_1}$ for all n.
- (ii) Monotonically decreasing if $s_n \ge s_{n_1}$ for all n.

Theorem A.5 (Convergence of monotonic sequences). Let (s_n) be a monotonic sequence. Then (s_n) converges if and only if it is bounded.

A.3.2 Series

Definition A.15 (Convergent Series). Let $\sum_{n=1}^{\infty} a_n$ be an infinite series. Define $s_n = \sum_{k=1}^n a_k$ to be the nth partial sum of the series. If the sequence of partial sums $\{s_n\}$ converges to s_n we say the series **converges**.

Theorem A.6 (Cauchy Criterion for Series). $\sum a_n$ converges iff

$$\forall \varepsilon > 0 \; \exists N \; s.t. \; m, n \ge N \Rightarrow \left| \sum_{k=n}^{m} a_k \right| \le \varepsilon$$
 (A.9)

Theorem A.7 (Necessary condition for convergence: individual terms of series go to 0.). If $\sum a_n$ converges, then $\lim_{n\to\infty} a_n = 0$.

Theorem A.8. A series of nonnegative terms converges if and only if its partial sums form a bounded sequence.

Theorem A.9 (Root Test). Given $\sum a_n$, let $\alpha = \limsup_{n \to \infty} \sqrt[n]{|a_n|}$. Then

- (i) If $\alpha < 1$, $\sum a_n$ converges.
- (ii) If $\alpha > 1$, $\sum a_n$ diverges.
- (iii) If $\alpha = 1$, the test gives no information.

A.4 Continuity

Definition A.16 (Limit). Let X and Y be metric spaces, $E \subset X$, f map E into Y, and p be a limit point of E. We write $f(x) \to q$ as $x \to p$ or $\lim_{\mathbf{x} \to \mathbf{p}} \mathbf{f}(\mathbf{x}) = \mathbf{q}$ if there is a point $q \in Y$ such that for every $\varepsilon > 0$ there exists a $\delta > 0$ such that for all $x \in E$ for which $0 < d_X(x, p) < \delta$, we have $d_Y(f(x), q) < \varepsilon$.

Definition A.17 (Continuous). Suppose X and Y are metric spaces, $E \subset X$, $p \in E$, and f maps E into Y. Then f is **continuous** at p if for every $\varepsilon > 0$ there there exists a $\delta > 0$ such that for all $x \in E$ for which $d_X(x,p) < \delta$, we have that $d_Y(f(x),f(p)) < \varepsilon$.

Definition A.18 (Uniformly Continuous). Let f be a mapping of a metric space X into a metric space Y. We say that f is **uniformly continuous** on X if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that for all $p, q \in X$ for which $d_X(p, q) < \delta$, we have $d_Y(f(p), f(q)) < \varepsilon$.

Observations:

- Uniform continuity is a property of a function on a set, whereas continuity can be defined at a single point.
- If f is continuous on X, then for each $\varepsilon > 0$ and each $p \in X$, we can find a $\delta > 0$ that satisfies the condition in the definition. For uniform continuity, we can find one $\delta > 0$ that works for all points $p \in X$.
- Every uniformly continuous function is continuous. The two concepts are equivalent on compact sets.

A.5 Differentiation

Definition A.19 (Differentiable, Derivative). Let f be defined (and real-valued) on [a, b]. For any $x \in [a, b]$ define

$$f'(x) = \lim_{t \to x} \frac{f(t) - f(x)}{t - x}$$
 (A.10)

provided this limit exists. If f' is defined at a point x, we say that f is **differentiable** at x. f' is called the **derivative** of f.

Theorem A.10 (Mean Value Theorem). If f is a real continuous function on [a,b] which is differentiable on (a,b), then there is a point $x \in (a,b)$ at which

$$f(b) - f(a) = (b - a)f'(x)$$
 (A.11)

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