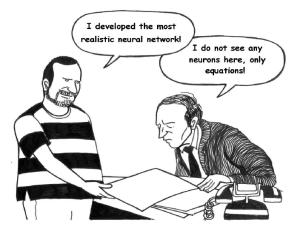


Objectives [M. Yamakou]

 To derive the Hodgkin-Huxley neuron model, obtained from experiments on a squid giant axon, and which provides us with the most biophysically realistic equations for describing neuronal dynamics.



 The neuron model was developed by Alan L. Hodgkin and Andrew F. Huxley in 1952 using the giant squid axon, earning them a Nobel Prize in Physiology or Medicine 1963. This approach was refined over the next 50 years and is now known as the conductance-based approach to modeling neurons.

The Nobel Prize in Physiology or Medicine 1963



Photo from the Nobel Foundation archive.
Sir John Carew Eccles
Prize share: 1/3



Photo from the Nobel Foundationarchive.

Alan Lloyd Hodgkin
Prize share: 1/3



Photo from the Nobel Foundation archive.

Andrew Fielding Huxley

Prize share: 1/3

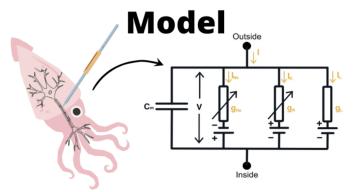




Memorial University at http://www.mun.ca/biology/

 The model simplifies the electrochemical mechanism by representing the neuron membrane as a capacitor, ionic gates, and ionic pumps as conductance-battery pairs. The figure below illustrates the electrical circuit.

Hodgkin-Huxley



Circuit diagram for Hodgkin-Huxley (HH) equations.

 Hodgkin and Huxley found that there are three main types of currents describing the dynamics of a neuron: Sodium (Na⁺), Potassium (K⁺), and a leak current (consisting of Chloride (Cl⁻) ions).

- Hodgkin and Huxley found that there are three main types of currents describing the dynamics of a neuron: Sodium (Na⁺), Potassium (K⁺), and a leak current (consisting of Chloride (Cl⁻) ions).
- There are biological constructs in a neuron's membrane that gate the flow of specific ions depending on the membrane potential V.

- Hodgkin and Huxley found that there are three main types of currents describing the dynamics of a neuron: Sodium (Na⁺), Potassium (K⁺), and a leak current (consisting of Chloride (Cl⁻) ions).
- There are biological constructs in a neuron's membrane that gate the flow of specific ions depending on the membrane potential V.
- Voltage-gated ion channels control the flow of these ions.
 When the neuron's membrane reaches a specific voltage, it opens up, allowing these ions to move in and out of the neuron.

- Hodgkin and Huxley found that there are three main types of currents describing the dynamics of a neuron: Sodium (Na⁺), Potassium (K⁺), and a leak current (consisting of Chloride (Cl⁻) ions).
- There are biological constructs in a neuron's membrane that gate the flow of specific ions depending on the membrane potential V.
- Voltage-gated ion channels control the flow of these ions.
 When the neuron's membrane reaches a specific voltage, it opens up, allowing these ions to move in and out of the neuron.
- To mimic the probabilistic dynamics of the ion channels in the neuron, Hodgkin and Huxley proposed that channels consist of four components that can be opened or closed.

• For potassium channels, the four components have identical probability n to be open, resulting in a probability $\mathbb{P}_K = n^4$. Opening and closing of these components depend on the membrane potential V, which determines their transition from open to closed position.

- For potassium channels, the four components have identical probability n to be open, resulting in a probability $\mathbb{P}_K = n^4$. Opening and closing of these components depend on the membrane potential V, which determines their transition from open to closed position.
- Thus, a component passes from the closed (with probability 1-n) to the open state (with probability n) following coefficients α_n and β_n , themselves dependent on V,

$$1-n \rightleftharpoons_{\beta_n}^{\alpha_n} n$$
,

obeying the Boltzmann equations describing the stochastic behavior of K^+ ions channels and have the general form

$$\alpha_{n}(V) = \frac{\theta_{n,1}(V - \theta_{n,2})}{\theta_{n,4} + \exp\left(\frac{\theta_{n,2} - V}{\theta_{n,3}}\right)} , \quad \beta_{n}(V) = \theta_{n,5} \exp\left(-\frac{V}{\theta_{n,6}}\right),$$

where $\theta_{n,i}$, $i = \{1, 2, 3, 4, 5, 6\}$ values are found experimentally (by fine-tuning) to fit the neuron's behavior best.

 If the initial value of the probability n that the K⁺ is opened is known, the values of n in time are given by the dynamical system:

$$\frac{dn}{dt} = \alpha_n(1-n) - \beta_n n.$$

 If the initial value of the probability n that the K⁺ is opened is known, the values of n in time are given by the dynamical system:

$$\frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n.$$

Let

$$n_{\infty} = rac{lpha_{\scriptscriptstyle n}}{lpha_{\scriptscriptstyle n} + eta_{\scriptscriptstyle n}} \qquad ext{and} \qquad au_{\scriptscriptstyle n} = rac{1}{lpha_{\scriptscriptstyle n} + eta_{\scriptscriptstyle n}}.$$

 n_{∞} is the *n* value of equilibrium and the constant τ_n the approaching time of this equilibrium. As α_n and β_n , these values depend on the membrane potential V. We can then rewrite the equation describing the evolution of n as follows,

$$\frac{dn}{dt} = \frac{n_{\infty} - n}{\tau_{-}}.$$

 If the initial value of the probability n that the K⁺ is opened is known, the values of n in time are given by the dynamical system:

$$\frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n.$$

Let

$$n_{\infty} = rac{lpha_{\scriptscriptstyle n}}{lpha_{\scriptscriptstyle n} + eta_{\scriptscriptstyle n}} \qquad ext{and} \qquad au_{\scriptscriptstyle n} = rac{1}{lpha_{\scriptscriptstyle n} + eta_{\scriptscriptstyle n}}.$$

 n_{∞} is the n value of equilibrium and the constant τ_n the approaching time of this equilibrium. As α_n and β_n , these values depend on the membrane potential V. We can then rewrite the equation describing the evolution of n as follows,

$$\frac{dn}{dt} = \frac{n_{\infty} - n}{\tau_n}.$$

• Let I_{κ} be the number of K^+ ions that flow through the membrane per unit time. In the HH model, I_{κ} is given by,

• where in the last equation of the previous slide, V represents the membrane potential, E_{κ} is the equilibrium potential of the K^+ ions, g_{κ} is conductivity of K^+ ions, and n have been previously defined.

- where in the last equation of the previous slide, V represents the membrane potential, E_{κ} is the equilibrium potential of the K^+ ions, g_{κ} is conductivity of K^+ ions, and n have been previously defined.
- If all K^+ ion channels are opened (i.e., n=1), they will transmit currents with a maximum conductance g_{ν}^{max} .

- where in the last equation of the previous slide, V represents the membrane potential, E_{κ} is the equilibrium potential of the K^+ ions, g_{κ} is conductivity of K^+ ions, and n have been previously defined.
- If all K^+ ion channels are opened (i.e., n=1), they will transmit currents with a maximum conductance g_{ν}^{max} .
- If the conductance is minimum (i.e., $g_k := \frac{1}{R} = 0$), we will have no flow of K^+ ions because all the K^+ ion channels will be closed i.e., 1 n = 1. Hence, the resistance R becomes infinitely large, therefore, zero current ($I_K = 0$).

- where in the last equation of the previous slide, V represents the membrane potential, E_{κ} is the equilibrium potential of the K^+ ions, g_{κ} is conductivity of K^+ ions, and n have been previously defined.
- If all K^+ ion channels are opened (i.e., n=1), they will transmit currents with a maximum conductance g_{ν}^{max} .
- If the conductance is minimum (i.e., $g_k := \frac{1}{R} = 0$), we will have no flow of K^+ ions because all the K^+ ion channels will be closed i.e., 1 n = 1. Hence, the resistance R becomes infinitely large, therefore, zero current ($I_K = 0$).
- Note, however, that, most of the time, some of the K^+ ion channels are blocked, and thus we mostly have g_k^{max} and very rarely have g_k^{max} .

- where in the last equation of the previous slide, V represents the membrane potential, E_{κ} is the equilibrium potential of the K^+ ions, g_{κ} is conductivity of K^+ ions, and n have been previously defined.
- If all K^+ ion channels are opened (i.e., n=1), they will transmit currents with a maximum conductance g_{ν}^{max} .
- If the conductance is minimum (i.e., $g_k := \frac{1}{R} = 0$), we will have no flow of K^+ ions because all the K^+ ion channels will be closed i.e., 1 n = 1. Hence, the resistance R becomes infinitely large, therefore, zero current ($I_K = 0$).
- Note, however, that, most of the time, some of the K^+ ion channels are blocked, and thus we mostly have g_k and very rarely have g_k^{max} .
- If the membrane potential equals the ion's equilibrium potential $(V = E_{\kappa})$, there is no circulation, and the current I_{κ} is also zero.
- In the HH model, I_K is given by,

$$I_K = n^4 g_{\kappa} (V - E_K) \tag{2}$$

A similar approach to describe the sodium current (I_{Na}).
 However, Unlike other channels, sodium (Na⁺) channels can be open and active, open and inactive, or closed.

- A similar approach to describe the sodium current (I_{Na}) . However, Unlike other channels, sodium (Na^+) channels can be open and active, open and inactive, or closed.
- To model these states, a Na⁺ channel consisting of four components is considered: three controlling opening and closing and the fourth one controlling activation or inactivation.

- A similar approach to describe the sodium current (I_{Na}) . However, Unlike other channels, sodium (Na^+) channels can be open and active, open and inactive, or closed.
- To model these states, a Na⁺ channel consisting of four components is considered: three controlling opening and closing and the fourth one controlling activation or inactivation.
- The opening and closing components each have a probability
 m of being open, while the activation/inactivation component
 has a probability h of being active.

- A similar approach to describe the sodium current (I_{Na}) . However, Unlike other channels, sodium (Na^+) channels can be open and active, open and inactive, or closed.
- To model these states, a Na⁺ channel consisting of four components is considered: three controlling opening and closing and the fourth one controlling activation or inactivation.
- The opening and closing components each have a probability
 m of being open, while the activation/inactivation component
 has a probability h of being active.
- The probability of a Na^+ channel being open and active is thus $\mathbb{P}_{Na} = m^3 h$, and both m and h depend on membrane potential V.

- A similar approach to describe the sodium current (I_{Na}) . However, Unlike other channels, sodium (Na^+) channels can be open and active, open and inactive, or closed.
- To model these states, a Na⁺ channel consisting of four components is considered: three controlling opening and closing and the fourth one controlling activation or inactivation.
- The opening and closing components each have a probability
 m of being open, while the activation/inactivation component
 has a probability h of being active.
- The probability of a Na^+ channel being open and active is thus $\mathbb{P}_{Na} = m^3 h$, and both m and h depend on membrane potential V.
- Let I_{Na} be the Na^+ flux, i.e., the amount of Na ions flowing through the membrane. I_{Na} is represented by,

$$I_{Na} = m^3 h g_{Na} (V - E_{Na}), (3)$$

• Where in the last equation in the previous slide, V is the membrane potential and E_{Na} is the equilibrium potential of Na^+ ions, and g_{Na} is the conductance of the Na^+ channel.

- Where in the last equation in the previous slide, V is the membrane potential and E_{Na} is the equilibrium potential of Na^+ ions, and g_{Na} is the conductance of the Na^+ channel.
- As we saw for the evolution of the variable n of the K^+ channels, the transition from the open position (with probability m) or closed (with probability 1-m) of each component of the Na^+ channels is given by the V-dependent coefficients α_m and β_m ,

$$1-m \rightleftharpoons_{\beta_m}^{\alpha_m} m,$$

obeying the Boltzmann equations describing the stochastic behavior of the Na^+ channels and have the general form

$$\alpha_m(V) = \frac{\theta_{n,7}(V - \theta_{n,8})}{\theta_{n,10} + \exp\left(\frac{\theta_{n,8} - V}{\theta_{n,9}}\right)}, \quad \beta_m(V) = \theta_{n,11} \exp\left(-\frac{V}{\theta_{n,12}}\right),$$

where $\theta_{m,i}$, $i = \{7, 8, 9, 10, 11, 12\}$ values are found experimentally (by fine-tuning) to fit the neuron's behavior best.

• In a similar fashion, for h, transitions from the active position (with probability h) to the inactive position (with probability 1-h) are given by the coefficients α_h and β_h ,

$$1-h \rightleftharpoons_{\beta_h}^{\alpha_h} h.$$

and which obey the Boltzmann equations describing the stochastic behavior of the channels and have the general form

$$\alpha_h(V) = \theta_{n,13} \exp\left(-\frac{V}{\theta_{n,14}}\right)$$
, $\beta_h(V) = \frac{\theta_{n,15}}{\theta_{n,16} + \exp\left(\frac{\theta_{n,17} - V}{\theta_{n,17}}\right)}$

where $\theta_{m,i}$, $i = \{13, 14, 15, 16, 17\}$ values are found experimentally (by fine-tuning) to fit the neuron's behavior best.

 In the same way as for n, the evolutions of m and h are given by the differential equations,

$$\frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m},$$

$$\frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}.$$

• From where we extract the following notations:

$$egin{aligned} m_{\infty} &= rac{1}{lpha_{m} + eta_{m}} \quad , \quad au_{m} &= rac{1}{lpha_{m} + eta_{m}}, \ h_{\infty} &= rac{1}{lpha_{h} + eta_{h}} \quad , \quad au_{h} &= rac{1}{lpha_{h} + eta_{h}}. \end{aligned}$$

 A similar approach to describe the leak current (I_L). However, Unlike other K⁺ and Na⁺ channels, leakage channels are always opened. (Hence the term leak current.)

- A similar approach to describe the leak current (I_L). However, Unlike other K⁺ and Na⁺ channels, leakage channels are always opened. (Hence the term leak current.)
- The opening components each have a probability 1 of being opened. The probability of a CI^- channel being open and active is thus $\mathbb{P}_L = 1 \times 1 \times 1 \times 1 = 1$.

- A similar approach to describe the leak current (I_L) . However, Unlike other K^+ and Na^+ channels, leakage channels are always opened. (Hence the term leak current.)
- The opening components each have a probability 1 of being opened. The probability of a CI^- channel being open and active is thus $\mathbb{P}_I = 1 \times 1 \times 1 \times 1 = 1$.
- Let I_L be the CI^- flux, .i.e., the amount of CI^- ions flowing through the membrane. I_L is represented by,

$$I_{L} = g_{L}(V - E_{L}), \tag{4}$$

where V is the membrane potential and E_L is the equilibrium potential of the leakage ions (mostly Cl^-).

 From the conservation of electric charges, Kirchhoff's current law applied to the circuit in the Figure 3 given slide 4 above

$$I = I_0 = C\frac{dV}{dt} + I_K + I_{Na} + I_L,$$

• Where I_0 is the input current, I_K is the potassium current, I_{Na} is the sodium current, I_L is the leak current, which models all ions that flow through the ion channels, which are always open, the capacitance of the membrane is represented by C_m , and V represents the voltage of the membrane potential. We therefore have

$$-C_m \frac{dV}{dt} = I_K + I_{Na} + I_L - I_0,$$

which, after dropping the subscript m in C_m , is given more explicitly by

$$-C\frac{dV}{dt} = n^4 \bar{g}_{_K} (V - E_{_K}) + m^3 h g_{_{Na}} (V - E_{Na}) + \bar{g}_{L} (V - E_{L}) - I_{_0}.$$

 Thus, the full model of the nerve impulse proposed by Hodgkin and Huxley is

$$\begin{cases}
C \frac{dV}{dt} = n^4 g_K(E_K - V) + m^3 h g_{Na}(E_{Na} - V) + g_L(E_L - V) + I_0, \\
\frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_\infty - n}{\tau_n}, \\
\frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m}, \\
\frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}.
\end{cases}$$

 Thus, the full model of the nerve impulse proposed by Hodgkin and Huxley is

$$\begin{cases}
C \frac{dV}{dt} = n^4 g_K (E_K - V) + m^3 h g_{Na} (E_{Na} - V) + g_L (E_L - V) + I_0, \\
\frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_\infty - n}{\tau_n}, \\
\frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m}, \\
\frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}.
\end{cases}$$

• Where t is the time in ms. Note that conductances g_{κ} and g_{Na} do not remain constant: they depend on V (in a very complicated way). They are both only constant when the corresponding ion channels are all opened, in which case g_{κ} and g_{Na}^{max} becomes g_{κ}^{max} and g_{Na}^{max} , respectively. g_{L} is a constant. (Why is it always a constant?)

 Thus, the full model of the nerve impulse proposed by Hodgkin and Huxley is

$$\begin{cases}
C \frac{dV}{dt} = n^4 g_K(E_K - V) + m^3 h g_{N_a}(E_{N_a} - V) + g_L(E_L - V) + I_0, \\
\frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_\infty - n}{\tau_n}, \\
\frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m}, \\
\frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}.
\end{cases}$$

- Where t is the time in ms. Note that conductances g_{κ} and g_{Na} do not remain constant: they depend on V (in a very complicated way). They are both only constant when the corresponding ion channels are all opened, in which case g_{κ} and g_{Na} becomes g_{κ}^{max} and g_{Na}^{max} , respectively. g_{L} is a constant. (Why is it always a constant?)
- The so-called gating variables *m*, *n*, *h* are all bounded in the unit interval [0, 1]. (Why do you think it is so?)

• The Boltzmann equations give the expressions of the so-called rate constants of the HH neuron model, $\alpha_j(V)$ and $\beta_j(V)$, where $j = \{n, m, h\}$, together with the values of the other parameters $\theta_{j,i}$, are determined experimentally by using the Voltage Clamp experiments.

$$\alpha_{n}(V) = \frac{0.01(10 - V)}{\exp\left(\frac{10 - V}{10}\right) - 1}, \quad \alpha_{m}(V) = \frac{0.1(25 - V)}{\exp\left(\frac{25 - V}{10}\right) - 1}$$

$$\alpha_{h}(V) = 0.07 \exp\left(\frac{-V}{20}\right), \quad \beta_{n}(V) = 0.125 \exp\left(\frac{-V}{80}\right),$$

$$\beta_{m}(V) = 4.0 \exp\left(\frac{-V}{18}\right), \quad \beta_{h}(V) = \frac{1}{\exp\left(\frac{30 - V}{30}\right) + 1}.$$

• The Boltzmann equations give the expressions of the so-called rate constants of the HH neuron model, $\alpha_j(V)$ and $\beta_j(V)$, where $j = \{n, m, h\}$, together with the values of the other parameters $\theta_{j,i}$, are determined experimentally by using the Voltage Clamp experiments.

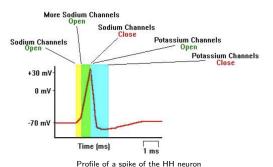
$$\alpha_{n}(V) = \frac{0.01(10 - V)}{\exp\left(\frac{10 - V}{10}\right) - 1}, \quad \alpha_{m}(V) = \frac{0.1(25 - V)}{\exp\left(\frac{25 - V}{10}\right) - 1}$$

$$\alpha_{h}(V) = 0.07 \exp\left(\frac{-V}{20}\right), \quad \beta_{n}(V) = 0.125 \exp\left(\frac{-V}{80}\right),$$

$$\beta_{m}(V) = 4.0 \exp\left(\frac{-V}{18}\right), \quad \beta_{h}(V) = \frac{1}{\exp\left(\frac{30 - V}{30}\right) + 1}.$$

$$\begin{split} C &= 1.0 \mu \; F/cm^2, \;\; E_{Na} = 115.0 \; mV, \;\; E_{K} = -12.0 \; mV, \\ E_{L} &= 10.6 \; mV, \;\; g_{Na} = g_{Na}^{max} = 120.0 \; mS/cm^2, \\ g_{K} &= g_{K}^{max} = 36.0 \; mS/cm^2 \;, \;\; g_{L} = g_{L}^{max} = 0.3 \; mS/cm^2 \end{split}$$

- In the absence of external current l_0 : equilibrium.
- After a weak impulse from I_0 : rapid relaxation to equilibrium.
- After a sufficiently strong (short) from impulse \(\begin{small}
 \limits_0 : Fires for the corresponding short duration.
- With constant, sufficiently strong I₀: The pulses occur periodically (limit cycle!)
- Immediately after repolarization, the HH neuron cannot fire again immediately (refractory period).



$$\begin{cases} C\frac{dV}{dt} = n^4 g_K(E_K - V) + m^3 h g_{Na}(E_{Na} - V) + g_L(E_L - V) + I_0, \\ \frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_\infty - n}{\tau_n}, \\ \frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m}, \\ \frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}. \end{cases}$$

 Dynamics of the HH equations are relatively simple. However, their explicit analysis (fixed points (equilibria), stability, bifurcations, etc) is extremely difficult because of the "unwieldy" right-hand sides, (i.e.,

strong nonlinearity, high dimensionality, & large parameter space.)

$$\begin{cases} C\frac{dV}{dt} = n^4 g_K(E_K - V) + m^3 h g_{Na}(E_{Na} - V) + g_L(E_L - V) + I_0, \\ \frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_\infty - n}{\tau_n}, \\ \frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m}, \\ \frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}. \end{cases}$$

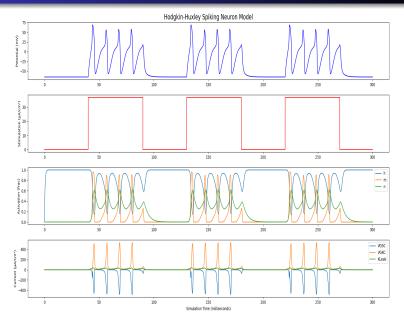
- Dynamics of the HH equations are relatively simple. However, their explicit analysis (fixed points (equilibria), stability, bifurcations, etc) is extremely difficult because of the "unwieldy" right-hand sides, (i.e., strong nonlinearity, high dimensionality, & large parameter space.)
- The search for equilibria and their stability properties is impossible without computer numerics.

$$\begin{cases} C\frac{dV}{dt} = n^4 g_K(E_K - V) + m^3 h g_{Na}(E_{Na} - V) + g_L(E_L - V) + I_0, \\ \frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_\infty - n}{\tau_n}, \\ \frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_\infty - m}{\tau_m}, \\ \frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_\infty - h}{\tau_h}. \end{cases}$$

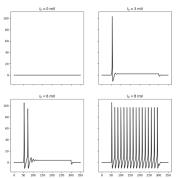
- Dynamics of the HH equations are relatively simple. However, their explicit analysis (fixed points (equilibria), stability, bifurcations, etc) is extremely difficult because of the "unwieldy" right-hand sides, (i.e., strong nonlinearity, high dimensionality, & large parameter space.)
- The search for equilibria and their stability properties is impossible without computer numerics.
- Thus, one would like to have the system of equations of V made up of simpler equations but with similar properties to the HH model.

$$\begin{cases} C\frac{dV}{dt} = n^4 g_{\kappa}(E_{\kappa} - V) + m^3 h g_{Na}(E_{Na} - V) + g_L(E_L - V) + I_0, \\ \frac{dn}{dt} = \alpha_n (1 - n) - \beta_n n = \frac{n_{\infty} - n}{\tau_n}, \\ \frac{dm}{dt} = \alpha_m (1 - m) - \beta_m m = \frac{m_{\infty} - m}{\tau_m}, \\ \frac{dh}{dt} = \alpha_h (1 - h) - \beta_h h = \frac{h_{\infty} - h}{\tau_h}. \end{cases}$$

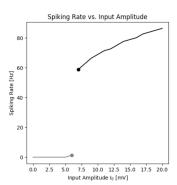
- Dynamics of the HH equations are relatively simple. However, their explicit analysis (fixed points (equilibria), stability, bifurcations, etc) is extremely difficult because of the "unwieldy" right-hand sides, (i.e., strong nonlinearity, high dimensionality, & large parameter space.)
- The search for equilibria and their stability properties is impossible without computer numerics.
- Thus, one would like to have the system of equations of *V* made up of simpler equations but with similar properties to the HH model.
- This can be via timescale separation analysis and exploiting similarities between the HH variables.



- By simulating the neuron, we can observe that the membrane potential begins to generate action potentials (spikes) once the input current increases above a certain threshold.
- As shown below, we can visualize the membrane potential V
 at different input currents. Additionally, we can look at the
 steady-state spiking rate (in Hz) of the HH neuron.

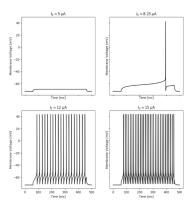


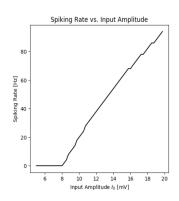
Responses of the simulated neuron at different input currents.



Spiking rate of a neuron as a function of the input current.

• By simulating the neuron, we can observe that the neuron's firing rate is a function of the input current. In this standard model, the firing rate $r(I_0)$ could be approximated by a Heaviside function. However, different types of functions can be obtained by different neuron types.





 Based on the activation of the neuron, you can observe that there are two states: firing and not firing. The firing state can be defined by the activation function f.

- Based on the activation of the neuron, you can observe that there are two states: firing and not firing. The firing state can be defined by the activation function f.
- In the case of the standard model, the activation function is a Heaviside function with a similar property current to the ReLU function. The neuron sums the inputs I_i, and the final firing rate results from passing the sum through an activation function f.

$$r(I_0) = f\left(\sum_{i=1}^{N} I_i\right). \tag{5}$$

- Based on the activation of the neuron, you can observe that there are two states: firing and not firing. The firing state can be defined by the activation function f.
- In the case of the standard model, the activation function is a Heaviside function with a similar property current to the ReLU function. The neuron sums the inputs I_i, and the final firing rate results from passing the sum through an activation function f.

$$r(I_0) = f\left(\sum_{i=1}^N I_i\right). \tag{5}$$

 This abstraction is used to move from the complex and computationally expensive model to a simpler and cheaper rate-based models. As a result, it is easier to model networks of neurons. This transition has formed the basis for today's popular artificial neural networks (ANN).