Transformări geometrice

Formula generală pentru produsul tensorial a doi vectori este

$$\mathbf{a} \otimes \mathbf{b} = \mathbf{b} \cdot \mathbf{a}^t$$
.

Astfel, în plan

$$\mathbf{a} \otimes \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \cdot \begin{pmatrix} a_1 & a_2 \end{pmatrix} = \begin{pmatrix} a_1 b_1 & a_2 b_1 \\ a_1 b_2 & a_2 b_2 \end{pmatrix},$$

iar în spațiu

$$\mathbf{a} \otimes \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \cdot \begin{pmatrix} a_1 & a_2 & a_3 \end{pmatrix} = \begin{pmatrix} a_1b_1 & a_2b_1 & a_3b_1 \\ a_1b_2 & a_2b_2 & a_3b_2 \\ a_1b_3 & a_2b_3 & a_3b_3 \end{pmatrix}.$$

Transformări plane

Translația în plan

$$\operatorname{Trans}(\mathbf{w}) = \begin{bmatrix} 1 & 0 & w_1 \\ 0 & 1 & w_2 \\ 0 & 0 & 1 \end{bmatrix}. \tag{1}$$

Rotația

$$\operatorname{Rot}(Q,\theta) = \begin{bmatrix} \cos\theta & -\sin\theta & q_1(1-\cos\theta) + q_2\sin\theta \\ \sin\theta & \cos\theta & -q_1\sin\theta + q_2(1-\cos\theta) \\ 0 & 0 & 1 \end{bmatrix}. \tag{2}$$

Scalarea uniformă

Scale(Q, s) =
$$\begin{pmatrix} s & 0 & (1-s)q_1 \\ 0 & s & (1-s)q_2 \\ 0 & 0 & 1 \end{pmatrix}.$$
 (3)

Scalarea neuniformă

Scale(Q,
$$s_x$$
, s_y) =
$$\begin{pmatrix} s_x & 0 & (1 - s_x)q_1 \\ 0 & s_y & (1 - s_y)q_2 \\ 0 & 0 & 1 \end{pmatrix}.$$
 (4)

Reflexia

$$Mirror(Q, \mathbf{w}) = \begin{pmatrix} I_2 - 2(\mathbf{w}^{\perp} \otimes \mathbf{w}^{\perp}) & 2(\mathbf{w}^{\perp} \otimes \mathbf{w}^{\perp}) \cdot Q \\ 0 & 1 \end{pmatrix}.$$
 (5)

Forfecarea

Shear
$$(Q, \mathbf{w}, \theta) = \begin{pmatrix} I_2 + \operatorname{tg} \theta (\mathbf{w}^{\perp} \otimes \mathbf{w}) & -\operatorname{tg} \theta (\mathbf{w}^{\perp} \otimes \mathbf{w}) \cdot Q \\ 0 & 1 \end{pmatrix}.$$
 (6)

Transformări în spațiu

Translația

Trans(**w**) =
$$\begin{pmatrix} 1 & 0 & 0 & w_1 \\ 0 & 1 & 0 & w_2 \\ 0 & 0 & 1 & w_3 \\ 0 & 0 & 0 & 1 \end{pmatrix} .$$
 (7)

Rotația

$$Rot(Q, \mathbf{u}, \theta) = \begin{pmatrix} Rot(\mathbf{u}, \theta) & (I_3 - Rot(\mathbf{u}, \theta)) \cdot \mathbf{Q} \\ 0 & 1 \end{pmatrix}, \tag{8}$$

unde

$$\operatorname{Rot}(\mathbf{u},\theta) = \cos\theta \cdot I_3 + (1-\cos\theta)(\mathbf{u}\otimes\mathbf{u}) + \sin\theta \cdot (\mathbf{u}\times -) \quad \text{si} \quad \mathbf{u}\times - = \begin{pmatrix} 0 & -u_3 & u_2 \\ u_3 & 0 & -u_1 \\ -u_2 & u_1 & 0 \end{pmatrix}.$$

Scalarea uniformă

$$Scale(Q, s) = \begin{pmatrix} s & 0 & 0 & (1-s) \cdot q_x \\ 0 & s & 0 & (1-s) \cdot q_y \\ 0 & 0 & s & (1-s) \cdot q_z \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$
(9)

Scalarea neuniformă

$$Scale(Q, s_x, s_y, s_z) = \begin{pmatrix} s_x & 0 & 0 & (1 - s_x) \cdot q_x \\ 0 & s_y & 0 & (1 - s_y) \cdot q_y \\ 0 & 0 & s_z & (1 - s_z) \cdot q_z \\ 0 & 0 & 0 & 1 \end{pmatrix}.$$
(10)

Reflexia

$$Mirror(Q, \mathbf{n}) = \begin{pmatrix} I_3 - 2(\mathbf{n} \otimes \mathbf{n}) & 2(\mathbf{n} \otimes \mathbf{n}) \cdot Q \\ 0 & 1 \end{pmatrix}$$
 (11)

Forfecarea

Shear
$$(Q, \mathbf{n}, \mathbf{u}, \theta) = \begin{pmatrix} I_3 + \operatorname{tg} \theta \cdot (\mathbf{n} \otimes \mathbf{u}) & -\operatorname{tg} \theta \cdot (\mathbf{n} \otimes \mathbf{u}) \cdot Q \\ 0 & 1 \end{pmatrix}.$$
 (12)