Notes on

Pseudo-Boolean Implication Proofs Version of February 21, 2023

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This notes describes some ideas on converting unsatisfiability proofs for pseudo-Boolean (PB) constraints into clausal proofs based on the DRAT proof system.

1 Notation

This section gives brief definitions of pseudo-Boolean constraints and their properties. A more extensive introduction is provided by Gocht in his PhD thesis [Gocht-Phd-2022].

Consider a set of Boolean variables $X = \{x_1, x_2, \dots, x_n\}$. For $x_i \in X$, literal ℓ_i can denote either x_i or its negation, written \overline{x}_i . We write $\overline{\ell}_i$ to denote \overline{x}_i when $\ell_i = x_i$ and x_i when $\ell_i = \overline{x}_i$.

A pseudo-Boolean constraint is a linear expression, viewing Boolean variables as ranging over integer values 0 and 1. That is, for a set of indices $I_C \subseteq \{1, 2, ..., n\}$, a constraint C has the form

$$\sum_{i \in I_C} a_i \ell_i \quad \# \quad b \tag{1}$$

where: 1) the relational operator # is <, \le , =, \ge , or >, and 2) the coefficients a_i , as well as the constant b, are integers, with the coefficients being nonzero. Constraints with relational operator = are referred to as *equational constraints*, while others are referred to as *ordering constraints*.

Constraint C denotes a Boolean function, written $\llbracket C \rrbracket$, mapping assignments to the set of variables X to 1 (true) or 0 (false). Constraints C_1 and C_2 are said to equivalent when $\llbracket C_1 \rrbracket = \llbracket C_2 \rrbracket$. Constraint C is said to be infeasible when $\llbracket C \rrbracket = \bot$, i.e., it always evaluates 0. C is said to be trivial when $\llbracket C \rrbracket = \top$, i.e., it always evaluates to 1.

As described in [Gocht-Phd-2022], the following are some properties of pseudo-Boolean constraints:

- Constraints with relational operators <, \le , and > can be converted to equivalent constraints with relational operator \ge .
- The logical negation of an ordering constraint C, written \overline{C} , can also be expressed as a constraint. That is, assume that C has been converted to a form where it has relational operator \geq . Then replacing \geq by < yields the negation of C.
- A constraint C with relational operator = can be converted to the pair of constraints C_{\leq} and C_{\geq} , formed by replacing # in (1) by \leq and \geq , respectively. These then satisfy $[\![C]\!] = [\![C_{<}\!]\!] \wedge [\![C_{>}\!]\!]$.

We will generally assume that constraints have relational operator \geq , since other forms can be translated to it. In some contexts, however, we will maintain equational constraints intact, to avoid replacing it by two ordering constraints.

We consider two normalized forms for ordering constraints: A coefficient-normalized constraint has only positive coefficients. A variable-normalized constraint has only positive literals. Converting between the two forms is straightforward using the identity $\overline{x}_i = 1 - x_i$. In reasoning about PB constraints, the two forms can be used interchangeably. Typically, the coefficient-normalized form is more convenient when viewing a PB constraint as a logical expression, while the variable-normalized form is more convenient when viewing a constraint as an arithmetic expression. In this document, we focus on the logical aspects, giving the general form of constraint C as

$$\sum_{i \in I_C} a_i \ell_i \geq b \tag{2}$$

with each $a_i > 0$.

Ordering constraint C in coefficient-normalized form is trivial if and only if $b \leq 0$. Similarly, C is infeasible if and only if $b > \sum_{i \in I_C} a_i$. By contrast, testing feasibility or triviality of an equational constraint is not straightforward, in that an instance of the subset sum problem [Garey] can be directly encoded as an equational constraint.

An assignment is a mapping $\rho: X' \to \{0,1\}$, for some $X' \subseteq X$. The assignment is total when X' = X and partial when $X' \subset X$. Assignment ρ can also be viewed as a set of literals, where $x_i \in \rho$ when $\rho(x_i) = 1$ and $\overline{x}_i \in \rho$ when $\rho(x_i) = 0$. Finally, assignment ρ can be viewed as the pseudo-Boolean constraint $\sum_{\ell_i \in \rho} \ell_i \geq |\rho|$. We use these three views interchangeably. Note also for assignments ρ_1 and ρ_2 over disjoint sets of variables X_1 and X_2 , their union is logically equivalent to their conjunction: $[\![\rho_1 \cup \rho_2]\!] = [\![\rho_1]\!] \wedge [\![\rho_2]\!]$.

We shall make use of constraints representing the negations of assignments. That is, the negation of assignment ρ , written $\overline{\rho}$ will is the constraint: $\sum_{\ell_i \in \rho} \overline{\ell}_i \geq 1$. Logically, this is equivalent to a clause in a CNF representation.

We let $\rho(C)$ denote the constraint resulting when C is simplified according assignment ρ . That is, assume ρ is defined over a set of variables X' and partition the indices $i \in I_C$ into three sets: I^+ , consisting of those indices i such that $\ell_i \in \rho$, I^- , consisting of those indices i such that $\ell_i \in \rho$, and I^X consisting of those indices i such that $x_i \notin X'$. With this, $\rho(C)$ can be written

$$\sum_{i \in I^X} a_i \ell_i \geq b - \sum_{i \in I^+} a_i \tag{3}$$

We will find cases where we want to condition a constraint C based on a partial assignment ρ , expressing the constraint $\rho \Rightarrow C$. In particular, if constraint C is of the form (2), then $\rho \Rightarrow C$ can be written as the PB constraint

$$\sum_{\ell \in \rho} b \, \bar{\ell} + \sum_{i \in I_C} a_i \ell_i \ge b \tag{4}$$

A pseudo-Boolean formula F is a set of pseudo-Boolean constraints. We say that F is satisfiable when there is some assignment ρ that satisfies all of the constraints in F, and unsatisfiable otherwise.

2 Pseudo-Boolean Implication Proofs

A Pseudo-Boolean Implication Proof (PBIP) provides a systematic way to prove that a PB formula F is unsatisfiable. It consists of a sequence of ordering constraints

$$C_1, C_2, \ldots, C_m, C_{m+1}, \ldots, C_t$$

such that the first m constraints are those of formula F, while the constraints i with i > m are implied by either one or two of the preceding constraints. That is, for each step i with $m < i \le t$, there is a set $H_i \subseteq \{C_1, C_2, \ldots, C_{i-1}\}$ such that $|H_i| \le 2$ and

$$\bigwedge_{C \in H_i} \llbracket C \rrbracket \quad \Rightarrow \quad \llbracket C_i \rrbracket \tag{5}$$

The proof completes with an infeasible constraint C_t . By the transitivity of implication, we have therefore proved that F is not satisfiable. We refer to the set H_i as the *hints* for step i.

Unless P=NP, we cannot guarantee that a proof checker can validate even a single step of a PBIP proof in polynomial time. In particular, consider an equational constraint C encoding an instance of the subset sum problem, and let C_{\leq} and C_{\geq} denote its conversion into a pair of ordering constraints such that $[\![C]\!] = [\![C_{\leq}]\!] \wedge [\![C_{\geq}]\!]$. Consider a PBIP proof step to add the constraint \overline{C}_{\leq} having the C_{\geq} as the only hint. Proving that $[\![C_{\geq}]\!] \Rightarrow [\![\overline{C}_{\leq}]\!]$, requires proving that $[\![C_{<}]\!] \wedge [\![C_{>}]\!] = \bot$, i.e., that C is unsatisfiable.

On the other hand, checking the correctness of a PBIP proof can be performed in pseudo-polynomial time, meaning that the complexity will be bounded by a polynomially sized formula over the numeric values of the integer parameters. This can be done using binary decision diagrams [BBH-2022]. In particular, an ordering constraint over n variables in coefficient-normalized form with constant b will have a BDD representation with at most $b \cdot n$ nodes. For proof step where the added constraints and the hints all have constants less than or equal to b, the number of BDD operations to validate the step will be $O(b^2 \cdot n)$ when there is a single hint and $O(b^3 \cdot n)$ when there are two hints. This complexity is polynomial in b, but it would be exponential in the size of a binary representation of b.

3 (Reverse) Unit Propagation

Consider constraint C in coefficient-normalized form. Literal ℓ is unit propagated by C when the assignment $\rho = \{\overline{\ell}\}$ causes the constraint $\rho(C)$ to become infeasible. Observe that a single constraint can unit propagate multiple literals. For example, $4x_1 + 3\overline{x}_2 + x_3 \ge 6$ unit propagates both x_1 and \overline{x}_2 . For constraint C, we let $\beta[C]$ denote the set of literals it unit propagates. This set can also be viewed as a partial assignment, and therefore also a constraint, having the property that $[\![C]\!] \Rightarrow [\![\beta[C]\!]\!]$.

For an ordering constraint C in coefficient-normalized form (2), detecting which literals unit propagate is straightforward. Let $A = \sum_{i \in I_C} a_i$. Then literal ℓ_i unit propagates if and only if $A - a_i < b$, i.e., $a_i > A - b$. For example, the constraint $4x_1 + 3\overline{x}_2 + x_3 \ge 6$ has A = 7 and b = 6, yielding A - b = 1. This justifies the unit propagations of both x_1 and \overline{x}_2 . A unit constraint is of the form $\ell \ge 1$. It unit propagates ℓ .

To perform unit propagation on constraint C in the context of a partial assignment ρ , we can use (3) to first generate the constraint representation of $\rho(C)$.

The reverse unit propagation (RUP) proof rule [Gocht-Phd-2022] uses unit propagation to prove that constraint C can be added to formula F while preserving its set of satisfying

assignments. It operates by finding a sequence of constraints C_0, C_1, \ldots, C_k , with $C_0 = \overline{C}$ and $C_i \in F$ for $1 \le i \le k$, and proving that this combination is unsatisfiable. We assume at this point in the derivation that we have a partial assignment α , consisting of the unit constraints that occurred as input constraints, as well as those that have been derived by prior RUP proofs.

A successful RUP proof generates a sequence of assignments $\rho_0, \rho_1, \ldots, \rho_{k-1}$ starting with $\rho_0 = \alpha \cup \beta[\alpha(C_0)]$. That is, it starts with the unit literals in α and uses these to simplify the negated target constraint. This can generate new unit literals, which are added to α to get the set ρ_0 . This pattern of simplifying and generating more unit literals continues for 1 < i < k with $\rho_i = \rho_{i-1} \cup \beta[\rho_{i-1}(C_i)]$. The final constraint C_k must then satisfy $\rho_{k-1}(C_k) = \bot$.

Given a RUP proof step, we can generate a sequence of PBIP proof steps that concludes with the addition of constraint C. In particular, the final assignment in the RUP proof yielded the result $\llbracket \rho_{k-1}(C_k) \rrbracket = \llbracket \rho_{k-1} \rrbracket \wedge \llbracket C_k \rrbracket \Rightarrow \bot$, and therefore $\llbracket C_k \rrbracket \Rightarrow \llbracket \overline{\rho}_{k-1} \rrbracket$. Starting with i=k and stepping downward to i=1, we can see $\llbracket \rho_i \rrbracket = \llbracket \rho_{i-1} \rrbracket \wedge \llbracket C_i \rrbracket$, but the previous step added $\overline{\rho}_i$, and therefore we can add the constraint $\overline{\rho}_{i-1}$, with the preceding constraint plus constraint C_i as hints. Once we reach i=1, we have added the constraint $\overline{\rho}_0$, and we can therefore add constraint $\alpha \Rightarrow C$, a weakened version of the target constraint, with the preceding constraint as its hint.

Summarizing, the PBIP proof steps will be as follows, leading to the addition of $\alpha \Rightarrow C$:

Added Constraint	Hints
$\overline{\rho}_{k-1}$	C_k
$\overline{\rho}_{k-2}$	$C_{k-1}, \overline{\rho}_{k-1}$
• • •	
$\overline{ ho}_i$	$C_{i+1}, \overline{\rho}_{i+1}$
• • •	
$\begin{array}{l} \overline{\rho}_0 \\ \alpha \Rightarrow C \end{array}$	$C_1, \overline{\rho}_1$
$\alpha \Rightarrow C$	$\overline{ ho}_0$

To remove the antecedent condition α , we then eliminate each literal $\ell \in \alpha$ in sequence, using the preceding constraint and the unit constraint $\ell \geq 1$ as hints. As an optimization, we can restrict α to those unit literals that were used in at least one unit propagation step during the RUP process.

4 RUP Example

As an example, consider the following three constraints:

ID	Constraint					
$C_1 \\ C_2 \\ C_3$	$\frac{x_1}{\overline{x}_1}$	+ + + + +	$ \begin{array}{c} 2x_2 \\ \overline{x}_2 \\ 2\overline{x}_2 \end{array} $	+ +	\overline{x}_3 $2x_3$ $3\overline{x}_3$	

Our goal is to add the constraint $C = 2x_1 + x_2 + x_3 \ge 2$ via RUP using these constraints. RUP proceeds as follows:

- 1. We can see that $\overline{C} = 2\overline{x}_1 + \overline{x}_2 + \overline{x}_3 \ge 3$, and this unit propagates assignment $\rho_0 = \overline{x}_1 \ge 1$.
- 2. With this, constraint C_1 simplifies to $2x_2 + \overline{x}_3 \ge 2$, and this unit propagates x_2 , giving $\rho_1 = \overline{x}_1 + x_2 \ge 2$.

- 3. Constraint C_2 simplifies to $2x_3 \ge 1$, which unit propagates x_3 , giving $\rho_2 = \overline{x}_1 + x_2 + x_3 \ge 3$.
- 4. Constraint C_3 simplifies to $0 \ge 3$, which is infeasible.

This single application of RUP results in the following PBIP proof steps:

ID	Constraint			
$ \begin{array}{ccc} C_4 & x_1 \\ C_5 & x_1 \\ C_6 & x_1 \\ C & 2x_1 \end{array} $	$\begin{array}{ccc} + & \overline{x}_2 \\ + & \overline{x}_2 \end{array}$ $+ & x_2$	$+$ \overline{x}_3 $+$ x_3		$C_3 \ C_2, C_4 \ C_1, C_5 \ C_6$